

ON POWERS OF HALF-TWISTS IN $M(0, 2n)$

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Abstract. We use elementary skein theory to prove a version of a result of Stylianakis (Stylianakis, The normal closure of a power of a half-twist has infinite index in the mapping class group of a punctured sphere, arXiv:1511.02912) who showed that under mild restrictions on m and n , the normal closure of the m th power of a half-twist has infinite index in the mapping class group of a sphere with $2n$ punctures.

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1. Introduction. Let $M(0, 2n)$ be the mapping class group of the 2-sphere S^2 fixing (setwise) a set of $2n$ points $p_1, \dots, p_{2n} \in S^2$. It is well-known [2] that $M(0, 2n)$ is a quotient of the braid group B_{2n} on $2n$ strands, where the braid generator σ_i ($i = 1, \dots, 2n - 1$) maps to the mapping class $h_i \in M(0, 2n)$ which is a *half-twist* permuting p_i and p_{i+1} and fixing all other points p_j . Stylianakis recently showed the following:

THEOREM 1.1 (Stylianakis [10]). *For $2n \geq 6$ and $m \geq 5$, the normal closure of h_i^m has infinite index in $M(0, 2n)$.*

(Note that the normal closure does not depend on i , as the h_i are all conjugate.)

For $2n = 6$, this result was known and is due to Humphries [5], as it is equivalent (by the Birman–Hilden Theorem) to Humphries’ result [5, Theorem 4] that the normal closure of the m th power of a non-separating Dehn twist has infinite order in the genus 2 mapping class group for $m \geq 5$. Humphries’ method was to employ the Jones representation [4] of the genus 2 mapping class group together with an explicit computation. Stylianakis’ generalization proceeds by using certain Jones representations of $M(0, 2n)$, but his proof involves some non-trivial representation theory.

In this paper, we give an elementary skein-theoretic proof of the following:

THEOREM 1.2. *For $2n \geq 4$ and $m \geq 6$, the normal closure of h_i^m has infinite index in $M(0, 2n)$.*

The key point in the proof of Theorem 1.2 is a simple 2×2 matrix calculation that I essentially did in [8]. Note that Theorem 1.2 implies Stylianakis’ result for $m \geq 6$. Theorem 1.2 does not hold when $m = 5$ and $2n = 4$, as $M(0, 4)/(h_i^5 = 1)$ is a finite group (the alternating group A_5). I believe that the remaining case ($m = 5$, $2n \geq 6$) of Stylianakis’ theorem can also be proved using the skein-theoretic method exposed below, but it would require a calculation with 5×5 matrices which I have not done (see Remark 3.5).

2. Strategy of the proof. The proof will be based on the representation of the braid group B_{2n} on the Kauffman bracket [6] skein module of the 3-ball relative to $2n$ marked points on the boundary. We will show that for an appropriate choice of Kauffman's skein variable A , this representation induces a projective-linear representation

$$\rho : M(0, 2n) \rightarrow \text{PGL}_d(\mathbb{C})$$

(where d depends on n) so that

- (i) $\rho(h_i^m) = 1$, and
- (ii) the image $\rho(M(0, 2n))$ is an infinite group.

Clearly, this will imply that the normal closure of h_i^m has infinite index in $M(0, 2n)$.

REMARK 2.1. Stylianakis used the same strategy applied to a certain Jones representation of $M(0, 2n)$. Actually, up to normalization and change of variables, the representation ρ is equivalent to the Jones representation for the rectangular Young diagram with two rows of length n . (We shall not make use of this fact in this paper.) For the purpose at hand, I find the skein-theoretic approach much easier.

REMARK 2.2. Funar [3] showed that the normal closure of the m th power of a Dehn twist has infinite index in the mapping class group of a genus g surface (with some restrictions on m and g) using the above strategy applied to TQFT-representations of mapping class groups. Our representation ρ can also be viewed as a TQFT representation of $M(0, 2n)$. But for us, TQFT is not actually needed. We shall only need Birman's presentation [2, Theorem 4.5] of $M(0, 2n)$ as a quotient of B_{2n} and elementary skein theory.

3. Proof of Theorem 1.2. We start with the representation of the braid group B_{2n} on the Kauffman bracket skein module of the 3-ball relative to $2n$ marked points on the boundary. Let us recall how this representation, which we denote by ρ , is defined. The skein module is a free $\mathbb{Z}[A, A^{-1}]$ -module of dimension

$$d = \frac{1}{n+1} \binom{2n}{n}$$

(the Catalan number).¹ Its elements are represented by $\mathbb{Z}[A, A^{-1}]$ -linear combinations of $(0, 2n)$ -tangle diagrams, that is, tangle diagrams in a rectangle relative to $2n$ marked points at the top of the rectangle. The diagrams are considered modulo the Kauffman skein relations (which will be stated shortly). The skein module has a standard basis given by tangle diagrams without crossings and without closed circles. For example, if the number of points is $2n = 4$, the dimension is $d = 2$ and the basis is given by the two diagrams

$$D_1 = \cup \cup \quad D_2 = \cup \cup$$

Below we specialize A to a non-zero complex number, so that the skein module with this basis (ordered in some arbitrary fashion) is identified with \mathbb{C}^d .

The i th braid generator σ_i acts on a diagram D by gluing the usual braid diagram of σ_i^{-1} on top of D (that is, the braid diagram which has a crossing \times at the i th and

¹A proof of this formula can be found in [7, p. 661].

$(i + 1)$ -st strand and all other strands are vertical). (We use inverses here so as to get a left action of B_{2n} on the skein module.) The Kauffman bracket skein relation

$$\times = A \smile + A^{-1} \succ \langle$$

implies that

$$\rho(\sigma_i) = A \rho(E_i) + A^{-1} \text{Id} ,$$

where E_i has \smile at the appropriate place and all other strands are vertical. The second Kauffman skein relation, which fixes the value of an unknot diagram to $-A^2 - A^{-2}$, implies that

$$\rho(E_i)^2 = (-A^2 - A^{-2}) \rho(E_i) .$$

A simple recursion now establishes that

$$\rho(\sigma_i^m) = P_m(A) \rho(E_i) + A^{-m} \text{Id} ,$$

where $P_m(A) = A^{2-m}(1 - A^4 + A^8 - \dots + (-1)^{m-1} A^{4m-4})$. Thus, we have the following:

PROPOSITION 3.1. *If $A \in \mathbb{C}$ satisfies $P_m(A) = 0$, then $\rho(\sigma_i^m) = A^{-m} \text{Id}$ is the identity element in $\text{PGL}_d(\mathbb{C})$.*

From now on, we assume that A is a zero of the polynomial $P_m(A)$. Note that all zeros of $P_m(A)$ are roots of unity. We shall make a precise choice of A later.

PROPOSITION 3.2. *For any $A \in \mathbb{C}^*$, the homomorphism $\rho : B_{2n} \rightarrow \text{PGL}_d(\mathbb{C})$ factors through $M(0, 2n)$.*

Proof. This is well-known but here is a proof. The group $M(0, 2n)$ is the quotient of B_{2n} by the relations $R_1 = R_2 = 1$, where

$$R_1 = \sigma_1 \sigma_2 \cdots \sigma_{2n-1} \sigma_{2n-1} \sigma_{2n-2} \cdots \sigma_1$$

$$R_2 = (\sigma_1 \sigma_2 \cdots \sigma_{2n-1})^{2n}$$

(see [2, Theorem 4.5]). Using the isotopy invariance of the Kauffman bracket, it is easy to check that

$$\rho(R_1) = (-A^3)^2 \text{Id} ,$$

$$\rho(R_2) = (-A^3)^{2n} \text{Id} .$$

(see [9, Section 1.3]). This proves the proposition. □

REMARK 3.3. For appropriate roots of unity A , the induced projective-linear representation of $M(0, 2n)$ is a TQFT representation, as follows from the skein-theoretic construction of Witten–Reshetikhin–Turaev TQFT in [1].

By abuse of notation, we denote the induced homomorphism $M(0, 2n) \rightarrow \text{PGL}_d(\mathbb{C})$, which sends h_i to $\rho(\sigma_i)$, again by ρ . Thus, we have realized condition (i)

of the strategy outlined in §2. To realize condition (ii), it suffices to find an element $\phi \in B_{2n}$ so that $\rho(\phi)$ has infinite order in $\text{PGL}_d(\mathbb{C})$. We now show that $\phi = \sigma_1^2 \sigma_2^{-2}$ works.

Recall the diagrams D_i ($i = 1, 2$) depicted above. By taking disjoint union of D_i with some fixed $(0, 2n - 4)$ -tangle diagram \tilde{D} (so that the first four points are the boundary of D_i , and the remaining $2n - 4$ points are the boundary of \tilde{D}), we get two diagrams D'_1 and D'_2 which form part of a basis of our skein module. The two-dimensional subspace spanned by D'_1 and D'_2 is preserved by both $\rho(\sigma_1)$ and $\rho(\sigma_2)$. On this subspace, $\rho(\sigma_1)$ and $\rho(\sigma_2)$ act by the following matrices:

$$\rho(\sigma_1) = \begin{bmatrix} -A^3 & A \\ 0 & A^{-1} \end{bmatrix}, \quad \rho(\sigma_2) = \begin{bmatrix} A^{-1} & 0 \\ A & -A^3 \end{bmatrix}.$$

(This follows immediately from the Kauffman relations.) A straightforward calculation now gives that the matrix of $\rho(\sigma_1^2 \sigma_2^{-2})$ acting on this two-dimensional subspace is

$$M = \begin{bmatrix} 2 - A^4 - A^{-4} + A^8 & -A^{-2} + A^{-6} \\ A^{-2} - A^{-6} & A^{-8} \end{bmatrix}$$

Clearly, if M has infinite order in $\text{PGL}_2(\mathbb{C})$, then $\rho(\sigma_1^2 \sigma_2^{-2})$ has infinite order in $\text{PGL}_d(\mathbb{C})$.

LEMMA 3.4. *M has infinite order in $\text{PGL}_2(\mathbb{C})$ provided the order r of the root of unity $q = A^4$ satisfies $r \geq 3$ and $r \notin \{4, 6, 10\}$.*

Proof. For $r \geq 5$ and $r \notin \{6, 10\}$, this is shown in [8], as one can check that the matrix M is conjugate to the one computed in [8]. We can also apply the argument of [8] directly to our matrix, as follows. Note that M has determinant 1 and trace

$$t = 2 - q - q^{-1} + q^2 + q^{-2}$$

where $q = A^4$. If M has finite order in $\text{PGL}_2(\mathbb{C})$, then its eigenvalues λ and λ^{-1} must satisfy $\lambda^N = \lambda^{-N}$ for some N , so λ is a root of unity. But this is impossible, as we can find a primitive r th root $q \in \mathbb{C}$ such that $|t| = |\lambda + \lambda^{-1}| > 2$ (see [8]). Thus, M has infinite order in $\text{PGL}_2(\mathbb{C})$.

In the remaining case $r = 3$, it suffices to observe that in this case we have $t = 2$, so M is conjugate to

$$\begin{bmatrix} 1 & c \\ 0 & 1 \end{bmatrix}$$

with $c \neq 0$ (since M is not the identity matrix). □

The proof of Theorem 1.2 is now completed as follows. For $m \geq 6$, we choose A to be a primitive N th root of unity, as follows:

- For $m = 6$, we take $N = 12$.
- For $m = 10$, we take $N = 20$.
- For odd $m \geq 7$, we take $N = 8m$.
- For even $m \geq 8$, $m \neq 10$, we take $N = 4m$.

Then, $P_m(A) = 0$, so Proposition 3.1 applies. Also, $q = A^4$ has order $r \geq 3$, $r \notin \{4, 6, 10\}$, so Lemma 3.4 applies. Thus, ρ satisfies condition (i) because of

Proposition 3.1, and ρ satisfies condition (ii) because the matrix $\rho(\sigma_1^2\sigma_2^{-2})$ has infinite order in $\mathrm{PGL}_d(\mathbb{C})$. This completes the proof.

REMARK 3.5. I expect that the remaining case ($m = 5$, $2n \geq 6$) of Stylianakis' theorem (see Theorem 1.1) can also be proved using the skein-theoretic representation ρ evaluated at a root of unity A so that $P_5(A) = 0$. It suffices to find $\phi \in B_6$ so that the 5×5 matrix $\rho(\phi)$ has infinite order in $\mathrm{PGL}_5(\mathbb{C})$. This will imply the result for $M(0, 2n)$ with $2n \geq 6$ for the same reason as above. Stylianakis describes such an element ϕ and shows that it has infinite order in the Jones representation he uses. Actually ϕ is closely related to the element originally used by Humphries [5]. Note that *modulo* identifying our skein-theoretic representation of $M(0, 6)$ with the Jones representation used by Humphries, the fact that $\rho(\phi)$ has infinite order is already shown by Humphries. There seems to be no advantage in redoing the relevant 5×5 matrix computation directly from the skein-theoretic approach, and I have not attempted to do so.

REMARK 3.6. The proof of Proposition 3.2 shows that one can rescale ρ to get a representation $\hat{\rho}$ of B_{2n} which descends to $M(0, 2n)$ as a *linear* representation: put

$$\hat{\rho}(\sigma_i) = \theta^{-1}\rho(\sigma_i),$$

where $\theta^{4n-2} = (-A^3)^2 = A^6$; then $\hat{\rho}(R_1) = \hat{\rho}(R_2) = \mathrm{Id}$. Note that

$$\hat{\rho}(\sigma_i^m) = (\theta A)^{-m} \mathrm{Id}.$$

One may wonder whether θ can be chosen so that $(\theta A)^{-m} = 1$. In general, the answer is no. For example, if m is odd, then $P_m(A) = 0$ implies $A^{4m} = -1$, and one computes (using $\theta^{4n-2} = A^6$) that

$$((\theta A)^{-m})^{4n-2} = A^{-4m(n+1)} = (-1)^{n+1}.$$

Thus, $(\theta A)^{-m} \neq 1$ if m is odd and n is even.

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