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On the Largest Dynamic Monopolies of Graphs with a Given Average Threshold

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Abstract. Let *G* be a graph and let τ be an assignment of nonnegative integer thresholds to the vertices of *G*. A subset of vertices, *D*, is said to be a τ -dynamic monopoly if V(G) can be partitioned into subsets D_0, D_1, \ldots, D_k such that $D_0 = D$ and for any $i \in \{0, \ldots, k-1\}$, each vertex v in D_{i+1} has at least $\tau(v)$ neighbors in $D_0 \cup \cdots \cup D_i$. Denote the size of smallest τ -dynamic monopoly by $dyn_{\tau}(G)$ and the average of thresholds in τ by $\overline{\tau}$. We show that the values of $dyn_{\tau}(G)$ over all assignments τ with the same average threshold is a continuous set of integers. For any positive number *t*, denote the maximum $dyn_{\tau}(G)$ taken over all threshold assignments τ with $\overline{\tau} \leq t$, by $Ldyn_t(G)$. In fact, $Ldyn_t(G)$ shows the worst-case value of a dynamic monopoly when the average threshold is a given number *t*. We investigate under what conditions on *t*, there exists an upper bound for $Ldyn_t(G)$ of the form c|G|, where c < 1. Next, we show that $Ldyn_t(G)$ is coNP-hard for planar graphs but has polynomial-time solution for forests.

1 Introduction

In this paper we deal with simple undirected graphs. For any such graph G = (V, E), we denote the cardinality of its vertex set by |G| and the edge density of graph G by $\epsilon(G) := |E|/|G|$. We denote the degree of a vertex v in G by deg_G(v). For other graph theoretical notations we refer the reader to [2]. By a threshold assignment for the vertices of G we mean any function $\tau: V(G) \to \mathbb{N} \cup \{0\}$. A subset of vertices D is said to be a τ -dynamic monopoly of G or simply τ -dynamo of G, if for some nonnegative integer k, the vertices of G can be partitioned into subsets D_0, D_1, \ldots, D_k such that $D_0 = D$ and for any $i, 1 \le i \le k$, the set D_i consists of all vertices v which has at least $\tau(v)$ neighbors in $D_0 \cup \cdots \cup D_{i-1}$. Denote the smallest size of any τ -dynamo of G by $dyn_{\tau}(G)$. Dynamic monopolies are in fact modeling the spread of influence in social networks. The spread of innovation or a new product in a community, the spread of opinion in Yes-No elections, the spread of a virus on the internet, and the spread of disease in a population are some examples of these phenomena. Obviously, if for a vertex v we have $\tau(v) = \deg_G(v) + 1$, then v should belong to any dynamic monopoly of (G, τ) . We call such a vertex *v* self-opinioned (from another interpretation it can be called vaccinated vertex). Irreversible dynamic monopolies and the equivalent concepts target set selection and conversion sets have been the subject of active research in recent years by many authors [3, 4, 6-8, 10-13].

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In this paper, by (G, τ) we mean a graph G and a threshold assignment for the vertices of G. The average threshold of τ , denoted by $\overline{\tau}$, is $\sum_{v \in V(G)} \tau(v)/|G|$. In Proposition 2.2 we show that the values of $\operatorname{dyn}_{\tau}(G)$ over all threshold assignments with the same average threshold form a continuous set of integers. The maximum element of this set was studied for first time in [10], where the following notation was introduced. Let t be a non-negative rational number such that t|G| is an integer, then $\operatorname{Dyn}_{t}(G)$ is defined as $\operatorname{Dyn}_{t}(G) = \max_{\tau:\overline{\tau}=t} \operatorname{dyn}_{\tau}(G)$. The smallest size of dynamic monopolies with a given average threshold was introduced and studied in [13]. Dynamic monopolies with given average threshold was also recently studied in [5]. In the definition of $\operatorname{Dyn}_{t}(G)$, it is assumed that t|G| is integer. In order to consider all values of t, we modify the definition slightly, but we are forced to make a new notation, *i.e.*, $\operatorname{Ldyn}_{t}(G)$ (which stands for the largest dynamo). The formal definition is as follows.

Definition 1.1 Let G be a graph and let t be a positive number. We define $Ldyn_t(G) = max\{dyn_\tau(G)|\overline{\tau} \le t\}$. Assume that a subset $D \subseteq V(G)$ and an assignment of thresholds τ_0 are such that $\overline{\tau_0} \le t$, $|D| = dyn_{\tau_0}(G) = Ldyn_t(G)$ and D is a τ_0 -dynamic monopoly of (G, τ_0) . Then we say that (D, τ_0) is a t-Ldynamo of G.

 $\operatorname{Ldyn}_t(G)$ does in fact show the worst-case value of a dynamic monopoly when the average threshold is a prescribed given number. The following concept is motivated by the concept of dynamo-unbounded family of graphs, defined in [12], concerning the smallest size of dynamic monopolies in graphs.

Definition 1.2 For any $n \in \mathbb{N}$, let G_n be a graph and t_n be a number such that $0 \le t_n \le 2\epsilon(G_n)$. We say $\{(G_n, t_n)\}_{n \in \mathbb{N}}$ is *Ldynamo*-bounded if there exists a constant $\lambda < 1$ such that for any n, Ldyn_{$t_n}(<math>G_n$) $\le \lambda |G_n|$.</sub>

The outline of the paper is as follows. In Section 2, we show that the values of $dyn_{\tau}(G)$ over all assignments τ with the same average threshold is a continuous set of integers (Proposition 2.2). Then we obtain a necessary and sufficient condition for a family of graphs to be Ldynamo-bounded (Propositions 2.4 and 2.5). In Section 3, it is shown that the decision problem Ldynamo(k) (to be defined later) is coNP-hard for planar graphs (Theorem 3.1) but has polynomial-time solution for forests (Theorem 3.8).

2 Some Results on $Ldyn_t(G)$

We first show that the values of $dyn_{\tau}(G)$ over all threshold assignments τ with the same average threshold are continuous. We need the following lemma from [11].

Lemma 2.1 ([11]) Let G be a graph and let τ and τ' be two threshold assignments to the vertices of G such that $\tau(u) = \tau'(u)$ for all vertices u of G except for exactly one vertex, say v. Then

$$\begin{cases} \operatorname{dyn}_{\tau}(G) - 1 \le \operatorname{dyn}_{\tau'}(G) \le \operatorname{dyn}_{\tau}(G), & \text{if } \tau(v) > \tau'(v), \\ \operatorname{dyn}_{\tau}(G) \le \operatorname{dyn}_{\tau'}(G) \le \operatorname{dyn}_{\tau}(G) + 1, & \text{if } \tau(v) < \tau'(v). \end{cases}$$

The continuity result is as follows.

Proposition 2.2 Let τ and τ' be two threshold assignments for the vertices of G such that $\overline{\tau} = \overline{\tau}'$. Let also r be an integer such that $dyn_{\tau}(G) \leq r \leq dyn_{\tau'}(G)$. Then there exists τ'' with $\overline{\tau} = \overline{\tau}''$ such that $dyn_{\tau''}(G) = r$.

Proof For any two threshold assignments τ and τ' with the same average threshold, define $\delta(\tau, \tau') = \sum_{\nu:\tau(\nu)>\tau'(\nu)}(\tau(\nu) - \tau'(\nu))$. We prove the proposition by the induction on $\delta(\tau, \tau')$. If $\delta(\tau, \tau') = 0$, then for any vertex $\nu, \tau(\nu) \leq \tau'(\nu)$. But the average thresholds are the same, hence $\tau = \tau'$, and the assertion is trivial. Let $k \geq 1$ and assume that the proposition holds for any two τ and τ' with the same average threshold such that $\delta(\tau, \tau') \leq k$. We prove it for k + 1. Assume that τ and τ' are given such that $\delta(\tau, \tau') = k + 1$ and $\tau \neq \tau'$. Define $W = \{\nu: \tau(\nu) > \tau'(\nu)\}$. Let $w \in W$. There exists a vertex u such that $\tau(u) < \tau'(u)$, since otherwise by $\overline{\tau} = \overline{\tau}'$ we would have $\tau = \tau'$. Define a new threshold τ'' as follows. For any vertex ν with $\nu \notin \{u, w\}$ set $\tau''(\nu) = \tau(\nu)$. Also, set $\tau''(w) = \tau(w) - 1$ and $\tau''(u) = \tau(u) + 1$. We have $\delta(\tau'', \tau') = k$, and the average threshold of τ'' is the same as that of τ . So the assertion holds for τ'' and τ' .

Let *G* be a graph and let *t* be a positive number such that t|G| is integer. Let τ be any assignment with average *t* such that $\tau(v) \leq \deg_G(v)$ for any vertex *v*. Let $d_1 \leq d_2 \leq \cdots \leq d_n$ be a degree sequence of *G* in increasing form. It was proved in [10] that the size of any τ -dynamic monopoly of *G* is at most

$$\max\left\{k:\sum_{i=1}^k (d_i+1) \le nt\right\}.$$

The proof of this result in [10] shows that if we allow $\tau(v) = \deg_G(v) + 1$ for some vertices v of G, then the same assertion still holds. We have the following proposition concerning this fact.

Proposition 2.3 Let t be a positive number. Assume that the threshold assignments in the definition of $Ldyn_t(G)$ are allowed to have self-opinioned vertices. Then $Ldyn_t(G)$ can be easily obtained by a polynomial-time algorithm.

Proof Let $d_1 \le d_2 \le \cdots \le d_n$ be a degree sequence of *G* in increasing form. By the argument we made before Proposition 2.3, we have

$$\operatorname{Ldyn}_t(G) \leq \max\left\{k: \sum_{i=1}^k (d_i+1) \leq nt\right\}.$$

Let $k_0 = \max\{k : \sum_{i=1}^k (d_i + 1) \le nt\}$. We obtain a threshold assignment τ as follows:

$$\tau(\nu_i) = \begin{cases} \deg_G(\nu_i) + 1 & i \le k_0, \\ 0 & \text{otherwise} \end{cases}$$

Let $D = \{v_1, v_2, \dots, v_{k_0}\}$. It is clear that (D, τ) is a *t*-Ldynamo of *G*.

In [10], it was proved that there exists an infinite sequence of graphs $G_1, G_2, ...$ such that $|G_n| \to \infty$ and $\lim_{n\to\infty} Ldyn_{\epsilon(G_n)}(G_n)/|G_n| = 1$. In the following proposition, we show that a stronger result holds. In fact we show that not only the same result holds for $Ldyn_{k\epsilon(G_n)}(G_n)$, where k is any constant with $0 < k \le 2$, but also it holds for any sequence k_n for which $k_n|G_n| \to \infty$. In the opposite direction, Proposition 2.5 shows that if $k_n = O(1/|G_n|)$, then $\lim_{n\to\infty} Ldyn_{k_n\epsilon(G_n)}(G_n)/|G_n| \ne 1$.

Proposition 2.4 There exists an infinite sequence of graphs $\{(G_n, \tau_n)\}_{n=1}^{\infty}$ satisfying $|G_n| \to \infty$ and $\epsilon(G_n)/|G_n| = o(\overline{\tau}_n)$ such that

$$\lim_{n \to \infty} \frac{\mathrm{Ldyn}_{\overline{\tau}}(G_n)}{|G_n|} = 1$$

Proof We construct G_n as follows. The vertex set of G_n is disjoint union of a complete graph K_n and n copies of complete graphs K_{n+1} . There exists exactly one edge between each copy of K_{n+1} and K_n . Set $\tau_n(v) = 0$ for each vertex v in K_n and $\tau_n(v) = \deg(v)$ for each vertex v in any copy of K_{n+1} . It is clear that any dynamic monopoly of G_n includes at least n vertices of each copy of K_{n+1} and hence $\operatorname{Ldyn}_{\overline{\tau}}(G_n) \ge n^2$. Then we have

$$1 \ge \lim_{n \to \infty} \frac{\mathrm{Ldyn}_{\overline{\tau}}(G_n)}{|G_n|} \ge \lim_{n \to \infty} \frac{n^2}{n(n+2)} = \lim_{n \to \infty} \frac{n}{n+2} = 1.$$

To complete the proof we show that $\frac{\overline{\tau}_n}{|E(G_n)|/|V(G_n)|^2} \to \infty$:

$$\lim_{n \to \infty} \frac{\overline{\tau}_n}{|E(G_n)|/|V(G_n)|^2} = \lim_{n \to \infty} \frac{(n^2 + n + 1)/(n + 2)}{(n^2 + n + n(n + n^2))/2(n^2 + 2n)^2} = \infty.$$

Proposition 2.4 shows that if t_n is such that $\epsilon(G_n)/|G_n| = o(t_n)$, then $\{(G_n, t_n)\}_n$ is not necessarily Ldynamo-bounded. In the opposite direction, the next proposition shows that if there exists a positive number c such that t_n satisfies $t_n \le c\epsilon(G_n)/|G_n|$, then any family $\{(G_n, t_n)\}_n$ is Ldynamo-bounded.

Proposition 2.5 Let G be a graph and let c and t be two constants such that $t \le c \frac{\epsilon(G)}{|G|}$. Then

$$\operatorname{Ldyn}_t(G) < \frac{c}{c+1}|G|.$$

Proof Let *n* be the order of *G*. If n < c/2, then $\lceil cn/(c+1) \rceil = n$, and hence the inequality $\operatorname{Ldyn}_t(G) < c|G|/(c+1)$ is trivial. Assume now that $n \ge c/2$. Let $d_1 \le d_2 \le \cdots \le d_n$ be a degree sequence of *G* in increasing form and set $k_0 = \max\{k : \sum_{i=1}^k (d_i + 1) \le nt\}$. As we mentioned before, by a result from [10] we have $\operatorname{Ldyn}_t(G) \le k_0$. The assumption $t \le c(\epsilon(G)/n)$ implies that $nt \le (c/2n)\sum_{i=1}^n d_i$ and hence $\sum_{i=1}^k (d_i + 1) \le (c/2n)\sum_{i=1}^n d_i$ or equivalently

$$(2n/c) \leq \left(\sum_{i=1}^n d_i\right) / \sum_{i=1}^{k_0} (d_i + 1).$$

Assume on the contrary that $k_0 \ge cn/(c+1)$. Then

$$\frac{2n}{c} \le \frac{\sum_{i=1}^{k_0} d_i + \sum_{i=k_0+1}^{n} d_i}{\left(\sum_{i=1}^{k_0} d_i\right) + \frac{c}{c+1}n} \le \frac{\left(\sum_{i=1}^{k_0} d_i\right) + \frac{n^2}{c+1}}{\left(\sum_{i=1}^{k_0} d_i\right) + \frac{c}{c+1}n}$$

Therefore,

$$\frac{2n-c}{c}\sum_{i=1}^{k_0}d_i \le \frac{n^2}{c+1} - \frac{2n^2}{c+1}.$$

The left-hand side of the last inequality is nonnegative, but the other side is negative. This contradiction implies $k_0 < cn/(c+1)$, as required.

3 Algorithmic Results

Algorithmic results concerning determining $dyn_{\tau}(G)$, with various types of threshold assignments such as constant thresholds or majority thresholds, were studied in [4, 6, 7]. In this section, we first show that to compute the size of D such that (D, τ) is a $k\epsilon(G)$ -Ldynamo of G is a coNP-hard problem on planar graphs. Then we prove that the same problem has a polynomial-time solution for forests. The formal definition of the decision problem concerning Ldynamo is the following, where k is any arbitrary but fixed real number with $0 < k \le 2$.

Name: LARGEST DYNAMIC MONOPOLY (Ldynamo(k))

Instance: A graph G on say n vertices and a positive integer d.

Question: Is there an assignment of thresholds τ to the vertices of *G* with $n\overline{\tau} = |nk\epsilon(G)|$ such that dyn_{τ}(*G*) $\geq d$?

The following theorem shows coNP-hardness of the above problem. Recall that the Vertex Cover (VC) asks for the smallest number of vertices *S* in a graph *G* such that *S* covers any edge of *G*. Denote the smallest cardinality of any vertex cover of *G* by $\beta(G)$. The problem VC is NP-complete for planar graphs [9].

Theorem 3.1 For any fixed k, where $0 < k \le 2$, Ldynamo(k) is coNP-hard even for planar graphs.

Proof We make a polynomial time reduction from VC (planar) to our problem. Let $\langle G, l \rangle$ be an instance of VC, where *G* is planar. Define $s = 4|E(G)| \times \max\{1, 1/k\} + 14$ and set $p = \lfloor (ks - 2)/(2 - k) \rfloor - |E(G)|$. Construct a graph *H* from *G* as follows. To each vertex *v* of *G* attach a star graph $K_{1,s-1}$ in such a way that *v* is connected to the central vertex of the star graph. Consider one of these star graphs and let *y* be a vertex of degree one in it. Add a path *P* of length p - 1 starting from *y* (see Figure 1). The path *P* intersects the rest of the graph only in *y*. Call the resulting graph *H*. Since *G* is planar, *H* is planar too.

We claim that (G, l) is a yes-instance of VC if and only if $(H, l + \lfloor p/2 \rfloor + 1)$ is a no-instance of Ldynamo(k). We have |E(H)| = |E(G)| + s + p from the construction

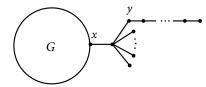


Figure 1: The graph H.

of *H*. Then since $p = \lfloor (ks - 2)/(2 - k) \rfloor - |E(G)|$, we have $p \le (ks - 2)/(2 - k) - |E(G)|$ $\Rightarrow 2p + 2|E(G)| + 2 \le k(s + p + |E(G)|)$ $\Rightarrow 2p + 2|E(G)| + 2 \le \lfloor k|E(H)| \rfloor.$

Also, from the value of *p* we have

$$p \ge (ks-2)/(2-k) - |E(G)| - 1$$

$$\Rightarrow 2p + 2|E(G)| + 2 + (2-k) > k(s+p+|E(G)|)$$

$$\Rightarrow 2p + 2|E(G)| + 2 + [2-k] \ge \lfloor k|E(H)| \rfloor$$

$$\Rightarrow 2p + 2|E(G)| + 3 \ge \lfloor k|E(H)| \rfloor.$$

Assume first that (G, l) is a no-instance of VC. Then $\beta(G) \ge l + 1$. We construct a threshold assignment τ for graph *H* as follows:

$$\tau(\nu) = \begin{cases} \deg_H(\nu) & \nu \in G \cup P, \\ 0 & \text{otherwise.} \end{cases}$$

It is easily seen that $\overline{\tau} \leq k\epsilon(H)$ and also $dyn_{\tau}(H) = \beta(G) + \lfloor p/2 \rfloor$. Therefore, $\langle H, l + \lfloor p/2 \rfloor + 1 \rangle$ is a yes-instance for Ldynamo(k).

Let (G, l) be a yes-instance of VC. Then $\beta(G) < l+1$. Assume that (D, τ) is a $(k\epsilon(H))$ -Ldynamo of H. The assumption that s > 4|E(G)| + 14 implies $|D \cap (H \setminus G)| \le \lfloor p/2 \rfloor$. On the other hand, $|D \cap G| \le \beta(G) < l+1$. Hence, $|D| < l + \lfloor p/2 \rfloor + 1$. This shows that $\langle H, l + \lfloor p/2 \rfloor + 1 \rangle$ is a no-instance for Ldynamo(k). This completes the proof.

In the rest of this section we obtain a polynomial-time solution for forests (Theorem 3.8). We will need some prerequisites. We will make use of the concept of a resistant subgraph, defined in [12] as follows. Given (G, τ) , any induced subgraph $K \subseteq G$ is said to be a τ -resistant subgraph in G, if for for any vertex $v \in K$ the inequality $\deg_K(v) \ge \deg_G(v) - \tau(v) + 1$ holds, where $\deg_G(v)$ is the degree of v in G. The following proposition in [12] shows the relation between resistant subgraphs and dynamic monopolies.

Proposition 3.2 ([12]) A set $D \subseteq G$ is a τ -dynamo of graph G if and only if $G \setminus D$ does not contain any resistant subgraph.

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The following lemma provides more information on resistant subgraphs that are also triangle-free.

Lemma 3.3 Assume that (G, τ) is given. Let also H be a triangle-free τ -resistant subgraph in G and e = uv be any arbitrary edge with $u, v \in H$. Let τ' be defined as follows:

$$\tau'(w) = \begin{cases} \tau(w) & \text{if } w \notin H, \\ 0 & \text{if } w \in H \smallsetminus \{u, v'\}, \\ \deg_G(v) & \text{if } w = v, \\ \deg_G(u) & \text{if } w = u. \end{cases}$$

Then $\overline{\tau'} \leq \overline{\tau}$.

Proof Since *H* is triangle-free, then $|H| \ge \deg_H(u) + \deg_H(v)$. From the definition of the resistant subgraphs, for any vertex $w \in H$, one has $\tau(w) \ge \deg_{G \setminus H}(w) + 1$. Hence the following inequalities hold:

$$\sum_{w \in H} \tau(w) \ge \sum_{w \in H} (\deg_{G \setminus H}(w) + 1) \ge |H| + \deg_{G \setminus H}(u) + \deg_{G \setminus H}(v)$$
$$\ge \deg_H(u) + \deg_H(v) + \deg_{G \setminus H}(u) + \deg_{G \setminus H}(v)$$
$$= \deg_G(u) + \deg_G(v).$$

It turns out that $\sum_{w \in G} \tau'(w) \leq \sum_{w \in G} \tau(w)$, and hence $\overline{\tau'} \leq \overline{\tau}$.

By a (*zero,degree*)-*assignment* we mean any threshold assignment τ for the vertices of a graph *G* such that for each vertex $v \in V(G)$, either $\tau(v) = 0$ or $\tau(v) = \deg_G(v)$. The following remark is useful and easy to prove. We omit its proof.

Remark 3.4 Assume that (G, τ) is given where τ is (zero,degree)-assignment. Let G_1 be the subgraph of G induced on $\{v \in G | \tau(v) = \deg_G(v)\}$. Then every minimum vertex cover of G_1 is a minimum τ -dynamo of G, and vice versa.

The following theorem concerning (zero,degree)-assignments in forests is essential in obtaining an algorithm for *t*-Ldynamo of forests for a given *t*.

Theorem 3.5 Let F be a forest and let t be a positive constant. There exists a (zero, degree)-assignment τ' such that $\overline{\tau'} \leq t$ and

$$\operatorname{Ldyn}_t(F) = \operatorname{dyn}_{\tau'}(F).$$

Proof Let (D, τ) be a *t*-Ldynamo of *F*. We prove the theorem by induction on |D|. Assume first that |D| = 1. Then by Proposition 3.2, *F* has at least one τ -resistant subgraph, say *F'*. Let *u* and *v* be two adjacent vertices in *F'*. Let τ' be the threshold assignment constructed in Lemma 3.3 such that $\tau'(u) = \deg_F(u)$ and $\tau'(v) = \deg_F(v)$. Modify τ' so that $\tau'(w) = 0$ for every vertex $w \in F \setminus \{u, v\}$. It is clear that τ' is a (zero,degree)-assignment. The edge uv is a τ' -resistant subgraph in *F*, and hence $dyn_{\tau}(F) = Ldyn_{t}(F) = 1$. This proves the induction assertion in this case.

Now assume that the assertion holds for any forest *F* with |D| < k. Let *F* be a forest with $Ldyn_t(F) = k$ and let *D* be a *t*-Ldynamo of *F* with |D| = k. Also let *F*₁ be the

largest τ -resistant subgraph of F. For any $v \in F_1$, set $\phi(v) = \tau(v) - \deg_{F \setminus F_1}(v)$. By the definition of resistant subgraphs, $\phi(v) \ge 0$. It is clear that $dyn_{\phi}(F_1) = k$. We show that there exists a (zero,degree)-assignment τ'_1 for F_1 such that (D_1, τ'_1) is a $\overline{\phi}$ -Ldynamo of F_1 with $|D_1| = k$.

Let *T* be a connected component of F_1 . Consider *T* as a top-down tree, where the topmost vertex is considered as the root of *T*. Since *T* is a ϕ -resistant subgraph in F_1 , it implies that $D_1 \cap T$ is not the empty set. We argue that D_1 can be chosen in such a way that it does not contain any vertex $w \in T$ with $\phi(w) = 1$, except possibly the root. The reason is that if $w \in D_1 \cap T$ with $\phi(w) = 1$, then we replace *w* by its nearest ancestor (with respect to the root of *T*) whose threshold is not 1, and if there is no such ancestor, then we replace *w* by the root. Let $v \in D_1 \cap T$ be the farthest vertex from the root of *T*. Let T_v be the subtree of *T* consisting of *v* and its descendants. Obviously, $T_v \cap D_1 = \{v\}$.

Now we show that T_v is a ϕ -resistant subgraph in F_1 . For each vertex $w \in T_v \setminus \{v\}$, since $\phi(w) \ge 1$ and $\deg_{F_1 \setminus T_v}(w) = 0$, then $\phi(w) \ge \deg_{F_1 \setminus T_v}(w) + 1$. We also have $\phi(v) \ge \deg_{F_1 \setminus T_v}(v) + 1$. Since $\phi(v) = 1$, v is the root of T and $T_v = T$ and hence $\deg_{F_1 \setminus T_v}(v) = 0$. And if $\phi(v) > 1$, then $\deg_{F_1 \setminus T_v}(v) \le 1$. This proves that T_v is a ϕ resistant subgraph in F_1 . Let v' be an arbitrary neighbor of v in T_v . We construct the threshold assignment τ_1 for F_1 as follows:

$$\pi_1(w) = \begin{cases} \phi(w) & \text{if } w \notin T_v, \\ 0 & \text{if } w \in T_v \setminus \{v, v'\}, \\ \deg_{F_v}(w) & \text{if } w \in \{v, v'\}. \end{cases}$$

By Lemma 3.3, we have $\overline{\tau_1} \leq \overline{\phi}$. Since edge vv' is a τ_1 -resistant subgraph in F_1 , then $dyn_{\tau_1}(F_1) = dyn_{\phi}(F_1) = k$, and so D_1 is a minimum τ_1 -dynamo of F_1 . Set $F_2 = F_1 \setminus T_v$. Let u be the parent of the vertex v. Construct the threshold assignment τ_2 for F_2 as follows:

$$\tau_2(w) = \begin{cases} \tau_1(w) & \text{if } w \in F_2 \smallsetminus \{u\}, \\ \tau_1(w) - 1 & \text{if } w = u. \end{cases}$$

It is easily seen that the union of any τ_2 -dynamo of F_2 and $\{v\}$ is a τ_1 -dynamo of F_1 and also $D_1 \setminus \{v\}$ is a τ_2 -dynamo of F_2 . Hence, $dyn_{\tau_2}(F_2) = dyn_{\tau_1}(F_1) - 1 = k - 1$. Let ϕ_2 be any threshold assignment for F_2 with $\overline{\phi_2} = \overline{\tau_2}$. Now construct the threshold assignment ϕ_1 for F_1 as follows:

$$\phi_1(w) = \begin{cases} \phi_2(w) & \text{if } w \in F_2 \setminus \{u\}, \\ \tau_1(w) & \text{if } w \in T_\nu, \\ \phi_2(w) + 1 & \text{if } w = u. \end{cases}$$

Because the union of any ϕ_2 -dynamo of F_2 and $\{v\}$, forms a ϕ_1 -dynamo of F_1 and also for any ϕ_1 -dynamo P of F_1 , the set $P \cap F_2$ is a ϕ_2 -dynamo of F_2 then $P \notin F_2$. This result and dyn_{τ_2}(F_2) = k - 1 imply that Ldyn_{$\overline{\tau}_2$}(F_2) = k - 1. From the induction hypothesis there exists a (zero,degree)-assignment τ'_2 for F_2 with $\overline{\tau'_2} \leq \overline{\tau_2}$ such that

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 $dyn_{\tau'_2}(F_2) = k-1$. Now we construct the (zero, degree)-assignment τ'_1 for F_1 as follows:

$$\tau_1'(w) = \begin{cases} \tau_2'(w) & \text{if } w \in F_2 \setminus \{u\}, \\ \tau_1(w) & \text{if } w \in T_\nu, \\ \tau_2'(w) + 1 & \text{if } w = u \text{ and } \tau_2'(u) \neq 0, \\ 0 & \text{if } w = u \text{ and } \tau_2'(u) = 0. \end{cases}$$

It is easily seen that $dyn_{\tau'_1}(F_1) = k$. We finally obtain the desired (zero,degree)-assignment τ' for *F* as follows:

$$\tau'(w) = \begin{cases} \deg_F(w) & \text{if } w \in F_1, \tau'_1(w) = \deg_{F \setminus F_1}(w), \\ 0 & \text{if } w \in F_1, \tau'_1(w) = 0, \\ 0 & \text{if } w \notin F_1. \end{cases}$$

In the following proposition we show that for any forest there exists a (zero, degree)-assignment that is zero outside the vertices of a matching.

Proposition 3.6 Let F be a forest and let t a positive constant. Then there exists a matching M such that for the (zero,degree)-assignment τ defined below, we have $\overline{\tau} \leq t$ and $\operatorname{Ldyn}_t(F) = \operatorname{dyn}_{\tau}(F) = |M|$,

$$\tau(w) = \begin{cases} \deg_F(w) & \text{if } w \text{ is a vertex saturated by } M, \\ 0 & \text{otherwise.} \end{cases}$$

Proof By Theorem 3.5, there exists a (zero,degree)-assignment τ' such that $\overline{\tau'} \le t$ and $\operatorname{Ldyn}_t(F) = \operatorname{dyn}_{\tau'}(F)$. Let F_1 be a subgraph induced on all vertices w, with $\tau'(w) = \operatorname{deg}_F(w)$. Let D be a minimum vertex cover of F_1 . Remark 3.4 implies that Dis a minimum τ' -dynamic monopoly of F. Assume that M is a maximum matching of F_1 . We show that M satisfies the conditions of the theorem. Each edge of M forms a τ -resistant subgraph in F. Hence $\operatorname{dyn}_{\tau}(F) \ge |M|$. Using the so-called König Theorem on bipartite graphs, we have |D| = |M|. Consequently, $\operatorname{dyn}_{\tau}(F) \ge |D| = \operatorname{dyn}_{\tau'}(F) =$ $\operatorname{Ldyn}_t(F)$. It is easily seen that $\overline{\tau} \le \overline{\tau'} \le t$. The proof is complete.

To prove Theorem 3.8, we will need the following proposition, whose proof is given in the appendix.

Proposition 3.7 Let G be a bipartite graph, where each edge e has a cost $c(e) \ge 0$. Let also d be a positive number. Then there is a polynomial time algorithm that finds a maximum matching M in G with $cost(M) \le d$, where $cost(M) = \sum_{e \in M} c(e)$.

Theorem 3.8 Given a forest F and a positive number t, there exists an algorithm that computes $Ldyn_t(F)$ in polynomial-time.

Proof For each edge e = uv of F define $cost(e) = deg_F(u) + deg_F(v)$, and for each $S \subseteq E(F)$ define $cost(S) = \sum_{e \in S} cost(e)$. Let M be any arbitrary matching and let τ be a (zero,degree)-assignment constructed from M as obtained in Proposition 3.6. It is easily seen that $\overline{\tau} \leq t$ if and only if $cost(M) \leq t|F|$. Now, if M is a maximum matching satisfying $cost(M) \leq t|F|$, then Proposition 3.6 implies $Ldyn_t(F) = dyn_{\tau}(F) = |M|$.

By Proposition 3.7, there is a polynomial-time algorithm that finds maximum matching *M* in *F* with $cost(M) \le c$ for any value *c*. Then using Proposition 3.6 for given forest *F* and constant *t*, there is a polynomial time algorithm that finds a (zero,degree)assignment τ such that $Ldyn_t(F) = dyn_\tau(F)$. From the other side, finding a minimum vertex cover in bipartite graphs is a polynomial-time problem. Therefore, using Remark 3.4 a minimum τ -dynamic monopoly for *F* can be found in polynomialtime.

For further research, it would be interesting to obtain other families of graphs for which Ldynamo(k) has polynomial-time solution. Also, we do not yet know whether $Ldynamo(k) \in NP \cup coNP$, but our guess is that it is not.

Appendix A

We prove Proposition 3.7 using the minimum cost flow algorithm. The minimum cost flow problem (MCFP) is as follows (see *e.g.*, [1] for details).

Let G = (V, E) be a directed network with a cost $c(i, j) \ge 0$ for any of its edges (i, j). Also for any edge $(i, j) \in E$ there exists a capacity $u(i, j) \ge 0$. We associate with each vertex $i \in V$ a number b(i) that indicates its source or sink depending on whether b(i) > 0 or b(i) < 0. The minimum cost flow problem (MCFP) requires the determination of a flow mapping $f: E \to \mathbb{R}$ with minimum cost $z(f) = \sum_{(i,j)\in E} c(i, j)f(i, j)$ subject to the following two conditions:

(a) $0 \le f(i, j) \le u(i, j)$ for all $(i, j) \in E$ (capacity restriction);

(b) $\sum_{\{j:(i,j)\in E\}} f(i,j) - \sum_{\{j:(j,i)\in E\}} f(j,i) = b(i)$ for all $i \in V$ (demand restriction).

In [1], a polynomial-time algorithm is given such that determines if such a mapping f exists. And in case of existence, the algorithm outputs f. Furthermore, if all values u(i, j) and b(i) are integers, then the algorithm obtains an integer-valued mapping f. In the following theorem, we prove Proposition 3.7.

Theorem A.1 Let G[X, Y] be a bipartite graph with $cost(ij) \ge 0$ for each edge $ij \in G$ and let d be a positive number. Then there exists a polynomial-time algorithm that finds maximum matching M in G with $cost(M) \le d$.

Proof Construct a directed network *H* from bipartite graph G[X, Y] as follows. Add two new vertices *s* and *t* as the source and the sink of *H*, respectively and directed edges (s, x) for each $x \in X$ and (y, t) for each $y \in Y$. Make all other edges directed from *X* to *Y*. For each edge (i, j) set u(i, j) = 1 and define c(i, j) as follows:

$$c(i,j) = \begin{cases} 0 & i = s \text{ or } j = t, \\ cost(ij) & i \in X, j \in Y. \end{cases}$$

For each vertex $i \in X \cup Y$, set b(i) = 0 and define b(s) = -b(t) = k, where k is an arbitrary positive integer. We now have an instance of MCFP. Assume that there exists a minimum cost flow mapping for this instance (obtained by the above-mentioned algorithm of [1]). Since u(i, j) and b(i) are integers, f is an integer-valued mapping. Therefore, f(i, j) is either 0 or 1. Let M be the set of edges (i, j) with f(i, j) = 1,

where $i \in X$ and $j \in Y$. Clearly *M* is a matching of size *k* having cost(M) = z(f), where z(f) is as defined in MCFP above.

Conversely, let M' be any arbitrary matching in G with |M'| = k. We construct a flow mapping f as follows:

$$f(i,j) = \begin{cases} 1 & i \in X, j \in Y, ij \in M', \\ 1 & i = s, jl \in M' \text{ for some } l \in Y, \\ 1 & j = t, li \in M' \text{ for some } l \in X, \\ 0 & \text{otherwise.} \end{cases}$$

The conditions of MCFP are satisfied for f. Also, z(f) = cost(M'). We conclude that to obtain a matching of size k with the minimum cost is equivalent to obtaining a minimum cost flow mapping for the associated MCFP instance (note that k is a parameter of this instance). We conclude that in order to find a matching M satisfying $cost(M) \le d$ and with the maximum size, it is enough to run the corresponding algorithm for the above-constructed MCFP instance for each k, where k varies from 1 to |G|/2. Note that |G|/2 is an upper bound for the size of any matching. This completes the proof.

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