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ORIENTED MATROIDS AND GEOMETRIC SORTING

BY

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ABSTRACT. Recently Goodman and Pollack [3] have proved a theorem which can be applied to encode in a compact form the order properties of an arbitrary configuration of points in \mathbb{R}^d . In this note we generalise this theorem to oriented matroids.

1. Introduction. We suppose that the reader has some familiarity with the fundamentals of the oriented matroid theory (see [1, 2, 4, 5, 6, 7, 8]). We will be using Las Vergnas' notation with only a small difference. We consider a matroid M(E) oriented, and denote by \mathcal{O} its orientation, if we know the families of their oriented circuits and oriented cocircuits. We remark, however, that the structure \mathcal{O} is uniquely determined if we know only the family of oriented circuits [resp. oriented cocircuits] of M(E) (see [1, 2]).

For a perfect understanding of our results we will need some terminology. We remark nevertheless that the paragraph 2 is self-contained: Theorem 2.6 (the main theorem of this note) is any easy consequence of our definition of orientations of the bases of a matroid (see Definition 2.1).

An element of the cartesian product X^{n+1} of a set X will be called an *n*-simplex (or simplex of dimension n). If $\sigma_1, \sigma_2, \ldots, \sigma_m$ are simplexes respectively of dimensions d_1, d_2, \ldots, d_m then we denote by $(\sigma_1, \sigma_2, \ldots, \sigma_m)$ the $(d_1+d_2+\cdots+d_m+m-1)$ -simplex obtained by their concatenation.

DEFINITION 1.1 [8, 9]. A *n*-ordered set (for $n \ge 0$) is a pair (X, Φ) , where X is a set and $\Phi, \Phi: X^{n+1} \rightarrow \{-1, 0, 1\}$, is a function not identically zero satisfying the conditions 1.2 and 1.3 below:

1.2. Φ is *alternating*, i.e. if the *n*-simplex σ is obtained from the *n*-simplex τ by interchanging two entries, then $\Phi(\sigma) = -\Phi(\tau)$;

1.3. If $\sigma = (a_0, a_1, \dots, a_n)$ and $\tau = (b_0, b_1, \dots, b_n)$ are two *n*-simplexes and $\Phi(\sigma) \cdot \Phi(\tau) = -1$, then for some *i*, $0 \le i \le n$,

 $\Phi(b_i, a_1, \ldots, a_n) \cdot \Phi(b_0, \ldots, b_{i-1}, a_0, b_{i+1}, \ldots, b_n) = -1.$

If (X, Φ) is a *n*-ordered set we denote by $(X, -\Phi)$ the *n*-ordered set such that for every *n*-simplex $\sigma, -\Phi(\sigma) = -(\Phi(\sigma))$.

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The notion of *n*-ordered set was introduced by L. G. Novoa [9] as a natural generalization of that of a totally ordered set. J. Lawrence [8] has proved that a *n*-ordered set (E, Φ) , where E is a finite set, has a canonical structure of oriented matroid $(M(E), \mathbb{O})$ and conversely, for every oriented matroid $(M(E), \mathbb{O})$ there exists exactly two *n*-ordered sets (E, Φ) and $(E, -\Phi)$ having $(M(E), \mathbb{O})$ as associate structure. For convenience of the reader we summarise these results.

PROPOSITION 1.4 [8]. Let (E, Φ) be a *n*-ordered set, where *E* is a finite set. Then $\mathcal{B} = \{B: B \in E^{n+1}, \Phi(B) \neq 0\}$ is the set of ordered bases of a matroid M(E) of rank n+1.

Proof. The set \mathscr{B} is nonempty, because Φ is not identically zero. If n = 0, 1 the proposition is trivialy true. Suppose $n \ge 2$ and let $B_1, B_2 \in \mathscr{B}$ and $x \in B_1 - B_2$. By reordering, if necessary, the elements of B_1 and B_2 we can suppose that $B_1 = \{x, a_1, \ldots, a_n\}$ and $\Phi(B_1) \cdot \Phi(B_2) = -1$. But in this case, by the condition 1.3, there exists $b_i, b_i \in B_2 - B_1$, such that $(b_i, a_1, \ldots, a_n) \in \mathscr{B}$. \Box

Theorem 1.5 below is equivalent to two of Lawrence's theorems (see [8], Theorems 3 and 6).

THEOREM 1.5 [8]. Let (E, Φ) be a *n*-ordered set, where *E* is a finite set. Then there exists an orientation \mathcal{O} of the matroid M(E), determined by (E, Φ) , such that:

1.6. For every cocircuit X of M and for every ordered base B of the hyperplane $E - \mathbf{X}$ the elements $x, y \in \mathbf{X}$ have the same sign in X if and only if $\Phi(x, B) = \Phi(y, B)$.

Conversely, if \mathcal{O} is an orientation of a matroid M(E) of rank n+1, then there exist exactly two n-ordered sets (E, Φ) and $(E, -\Phi)$ such that the function Φ [resp. $-\Phi$] satisfy the condition 1.6. \Box

We remark that the converse part of Theorem 1.5 is an easy consequence of Las Vergnas' characterisation of oriented matroids in terms of orientations of their bases [6].

EXAMPLE 1.7. Let V be a n-dimensional vector space over an ordered field with a distinguished (ordered) base B. Let $\Phi: V^n \to \{1, -1, 0\}$ be the function such that $\Phi(B') = 1$ [resp. $\Phi(B') = -1$] when the transition matrix P from B to B' has positive determinant |P| > 0 [resp. negative determinant |P| < 0]. It is clear that the pair (V, Φ) is a (n-1)-ordered set. Likewise the pair (E, Φ) where E is a finite set spanning set of V and Φ' is the restriction of Φ to E^n , is a (n-1)-ordered set. Let $(M(E), \mathcal{O})$ be the oriented matroid determined by (E, Φ') . Then, for every base B" of the (n-1)-dimensional subspace of V spanned by $E-\mathbf{X}$, the elements x, y, x, $y \in \mathbf{X}$, have the same sign in X if and only if $\Phi(x, B'') = \Phi(y, B'')$. (I.e. x, $y \in \mathbf{X}$ have the same sign in the cocircuit X if and only if they are on the same side of the vector subspace of V generated by $E-\mathbf{X}$.) The matroid M is called the oriented matroid on E determined by linear dependence in V [1].

2. The basic theorem of geometric sorting

DEFINITION 2.1. Let *E* be a finite set and let \mathscr{B} be a set of ordered subsets of size *n* of *E* (i.e., $\mathscr{B} \subseteq E^n$). By definition we say that the triple $(\mathscr{B}, \mathscr{B}_1, \mathscr{B}_2)$, where $\mathscr{B}_1 \cup \mathscr{B}_2$ is a partition of \mathscr{B} , is an *orientation of the bases* (of a matroid) if the conditions 2.2 and 2.3 below are satisfied. (If $B, B' \in \mathscr{B}$ we write $B \sim B'$ [resp. $B \neq B'$] when $B, B' \in \mathscr{B}_i$ [resp. $B \in \mathscr{B}_i, B' \in \mathscr{B} - \mathscr{B}_i$], i = 1 or 2.):

2.2. If B' is obtained from B by interchanging two entries, then $B \neq B'$;

2.3. If $(a_1, a_2, ..., a_n) \neq (b_1, b_2, ..., b_n)$ there exists $i, 1 \le i \le n$, such that $(b_i, a_2, ..., a_n) \neq (b_1, ..., b_{i-1}, a_1, b_{i+1}, ..., b_n)$.

REMARK 2.4. If $(\mathcal{B}, \mathcal{B}_1, \mathcal{B}_2)$ is an orientation of the bases (of a matroid) then \mathcal{B} is the set of (ordered) bases of a matroid M. (The proof is similar to the proof of Proposition 1.4.) By Theorem 1.5 it is also clear that an orientation \mathcal{O} of the matroid M is also determined. Example 1.7 establishes that this notion of orientation of bases reduces to the usual one when (M, \mathcal{O}) is an oriented matroid determined by linear dependence in a vector space over an ordered field. (In this last case it is possible to prove shortly the Conditions 2.2 and 2.3. See [8] for more details.)

Proposition 2.5 below is a technical result necessary to prove our main result (Theorem 2.6). If X is a set and $\mathcal{B} \subseteq X^n$, $a \in X$ then we note by \mathcal{B}/a [resp. $\mathcal{B} \setminus a$] the set $\{B - \{a\}: B = (a = b_1, \dots, b_n) \in \mathcal{B}\}$ [resp. $\{B: B \in \mathcal{B} \text{ and } a \notin B\}$].

PROPOSITION 2.5. Let $(M(E), \mathcal{O})$ be an oriented matroid and let $(\mathcal{B}, \mathcal{B}_1, \mathcal{B}_2)$ be the orientation of the bases of M determined by \mathcal{O} . Then $(\mathcal{B}/a, \mathcal{B}_1/a, \mathcal{B}_2/a)$ [resp. $(\mathcal{B} \setminus a, \mathcal{B}_1 \setminus a, \mathcal{B}_2 \setminus a)$] is the orientation of the bases of the matroid M/a [resp. $M \setminus a$] determined by the orientation \mathcal{O}/a [resp. $\mathcal{O} \setminus a$].

Proof. The proof of the statement concerning the matroid $M \setminus a$ is routine. We prove that concerning M/a. It is clear that $(\mathscr{B}/a, \mathscr{B}_1/a, \mathscr{B}_2/a)$ verifies Condition 2.2. We prove 2.3. If n = 1, 2 then 2.3 is trivially true. Suppose $n \ge 3$ and let $(s_1, \ldots, s_{n-1}) \in (\mathscr{B}_1/a), (t_1, \ldots, t_{n-1}) \in (\mathscr{B}_2/a)$. Then $(a, s_1, \ldots, s_{n-1}) \in \mathscr{B}_1,$ $(a, t_1, \ldots, t_{n-1}) \in \mathscr{B}_2$ and by the Condition 2.2 $(s_1, a, s_2, \ldots, s_{n-1}) \in \mathscr{B}_2$ and $(t_1, a, t_2, \ldots, t_{n-1}) \in \mathscr{B}_1$. But in this case, by the Conditions 2.2 and 2.3 related to $(\mathscr{B}, \mathscr{B}'_1 = \mathscr{B}_2, \mathscr{B}'_2 = \mathscr{B}_1)$ there exists $t_i, 1 \le i \le n$, such that $(t_i, a, s_2, \ldots, s_{n-1}) \in \mathscr{B}_2$ and $(t_1, a, t_2, \ldots, t_{i-1}, s_1, t_{i+1}, \ldots, t_{n-1}) \in \mathscr{B}_1$. Then $(t_i, s_2, \ldots, s_{n-1}) \in \mathscr{B}_1/a$ and $(t_1, \ldots, t_{i-1}, s_1, t_{i+1}, \ldots, t_{n-1}) \in \mathscr{B}_2/a$.

We leave to the reader the proof that $(\mathcal{B}/a, \mathcal{B}_1/a, \mathcal{B}_2/a)$ is the orientation of the bases of the matroid M/a determined by \mathcal{O}/a .

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We remark that in the proof of Theorem 2.6 below we use only the fact that if $(\mathcal{B}, \mathcal{B}_1, \mathcal{B}_2)$ is an orientation of bases then $(\mathcal{B}/a, \mathcal{B}_1/a, \mathcal{B}_2/a)$ and $(\mathcal{B} \setminus a, \mathcal{B}_1 \setminus a, \mathcal{B}_2 \setminus a)$ are also orientation of bases. Theorem 2.6 generalises the "basic theorem of geometric sorting" of Goodman and Pollack (see [3] Theorem 1.8).

THEOREM 2.6. Let $(\mathcal{B}, \mathcal{B}_1, \mathcal{B}_2)$ be an orientation of bases. Suppose $\mathcal{B} \subseteq E^n$ and let $\mathcal{T} = \bigcup_{x \in E} \mathcal{B}/x$. Then $(\mathcal{B}, \mathcal{B}_1, \mathcal{B}_2)$ is uniquely determined if we know \mathcal{B} , and for every $I, I \in \mathcal{T}$, we know the number of elements y of E such that $I \in \mathcal{B}_1/y$.

Proof. The proof is by induction on |E| = m. If m = 1 the theorem is trivially true. Suppose $m \ge 2$ and let a be an element of E. By hypothesis, for every $I \in E^{n-2}$, we know the number of elements x fo E such that $(a, I) \in \mathcal{B}_1/x$ and also the number of elements y of E such that $(y, a, I) \in \mathcal{B}$. But in this case we know also the number of elements z of E such that $(a, I) \in \mathcal{B}_2/z$. By Condition 2.2 this is equivalent to the knowledge of the number of elements z of E such that $(z, I) \in \mathcal{B}_1/a$. By Proposition 2.5 $(\mathcal{B}/a, \mathcal{B}_1/a, \mathcal{B}_2/a)$ is an orientation of bases. Then, by induction hypothesis relative to $(\mathcal{B}/a, \mathcal{B}_1/a, \mathcal{B}_2/a)$, \mathcal{B}_1/a is uniquely determined. i.e. we know the ordered bases $B, B \in \mathcal{B}_1$, such that their first element is a. As, by Proposition 2.5, $(\mathcal{B} \setminus a, \mathcal{B}_1 \setminus a, \mathcal{B}_2 \setminus a)$ is also an orientation of bases, Theorem 2.6 follows by induction hypothesis relative to $(\mathcal{B} \setminus a, \mathcal{B}_1 \setminus a, \mathcal{B}_2 \setminus a)$. \Box

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