# ADMISSIBLE SIGNIFICANCE TESTS IN SIMULTANEOUS EOUATION MODELS 

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#### Abstract

Consider testing the null hypothesis that a single structural equation has specified coefficients. The alternative hypothesis is that the relevant part of the reduced form matrix has proper rank, that is, that the equation is identified. The usual linear model with normal disturbances is invariant with respect to linear transformations of the endogenous and of the exogenous variables. When the disturbance covariance matrix is known, it can be set to the identity, and the invariance of the endogenous variables is with respect to orthogonal transformations. The likelihood ratio test is invariant with respect to these transformations and is the best invariant test. Furthermore it is admissible in the class of all tests. Any other test has lower power and/or higher significance level. In particular, this likelihood ratio test dominates a test based on the Two-Stage Least Squares estimator.


## 1. INTRODUCTION

There is a considerable literature on statistical inference concerning a single structural equation in a simultaneous equation model. Much of the literature concerns estimation of the coefficients of the single equation. Anderson and Rubin (1949) developed the Limited Information Maximum Likelihood (LIML) estimator on the basis of normality of the disturbances. When the disturbance covariance matrix is known, the corresponding estimator is known as LIMLK. Anderson, Stein, and Zaman (1985) showed that the LIMLK estimator is admissible for a suitable loss function in a model corresponding to two simultaneous equations. They showed that the LIMLK estimator was the best estimator invariant under linear transformations that leave the model and loss function invariant. It follows that the LIMLK estimator is admissible in the class of all estimators including randomized estimators.

Anderson and Rubin (1949) also suggested a test of the null hypothesis, say, $H_{0}$, that the vector of coefficients of the endogenous variables, say, $\boldsymbol{\beta}$, is a specified vector, say, $\boldsymbol{\beta}^{0}$; the alternative hypothesis, say $H_{2}$, is that $\boldsymbol{\beta}$ is unrestricted. The

[^0]test is admissible if the equation is just identified, but not if the equation is overidentified. Anderson and Kunitomo (2007) derived an alternative test by testing $H_{0}$ against $H_{1}$ : the equation is identified. This likelihood ratio criterion is the ratio of the likelihood ratio criterion for testing $H_{0}$ vs $H_{2}$ to the likelihood ratio criterion for testing $H_{1}$ vs $H_{2}$. (These two likelihood ratio criteria were given in Anderson and Rubin, 1949; see also Anderson and Kunitomo, 2009.)

Anderson $(1976,1984)$ pointed out that a structural equation in a simultaneous equation model is the same as a linear functional relationship in the statistical literature. Creasy (1956) derived the likelihood ratio test of the slope parameter in this model. Moreira (2003) derived the test in more generality; he called the test the conditional likelihood ratio test.

The current paper treats the testing problem when the disturbance covariance matrix is known and the number of endogenous variables in the single equation is two. It is anticipated that the theorems are valid when the disturbance covariance matrix is estimated by the usual sample covariance matrix of residuals and when the number of endogeneous variables in the equation is arbitrary. The admissibility in general is anticipated, but has yet to be proved.

When the disturbance covariance matrix is known, a sufficient statistic is the sample regression of the dependent variables on the independent variables, say $\boldsymbol{P}$, and the sample covariance of the independent variables, say $\boldsymbol{A}$. The likelihood ratio criterion is a function of $\boldsymbol{P}^{\prime} \boldsymbol{A} \boldsymbol{P}$, the distribution of which depends only on a noncentrality parameter, say $\lambda$. It is shown that the likelihood ratio test is identical to a Bayes test of $H_{0}$ vs $H_{1}$ conditional on this parameter $\lambda$. Thus for each $\lambda$ this conditional test of $H_{0}$ vs $H_{1}$ is the uniformly most powerful invariant test; that is, the (conditional) test is admissible among tests for a specific noncentrality parameter $\lambda$. Since this comparison does not depend on the value of $\lambda$, it holds for every $\lambda$.

Now consider the class of all tests of $H_{0}$ vs $H_{1}$, not necessarily invariant, but including randomized tests. By a version of the "Hunt-Stein theorem" the likelihood ratio test is admissible among all tests. This means that there is no test with better significance level and/or better power. In particular, Two-Stage Least Squares is inferior as an estimator and yields an inferior test procedure.

It should be noted that the admissibility properties in this paper are "exact," that is, the results are not asymptotic or approximate. However, the admissibility property is a comparison of tests; it does not establish a distribution or significance point.

## 2. A SIMULTANEOUS EOUATION MODEL

The observed data consist of a $T \times G$ matrix of endogenous or dependent or nonstochastic variables $\boldsymbol{Y}$ and a $T \times K$ matrix of exogenous or independent variables $Z(G<K)$. A linear model (the reduced form) is

$$
\begin{equation*}
\boldsymbol{Y}=\boldsymbol{Z} \Pi+V \tag{2.1}
\end{equation*}
$$

where $\boldsymbol{\Pi}$ is a $K \times G$ matrix of parameters and $\boldsymbol{V}$ is a $T \times G$ matrix of unobservable disturbances. The rows of $\boldsymbol{V}$ are assumed independent; each row has a normal distribution $N(\mathbf{0}, \boldsymbol{\Omega})$.

The coefficient matrix $\Pi$ can be estimated by the sample regression

$$
\begin{equation*}
\boldsymbol{P}=\left(\boldsymbol{Z}^{\prime} \boldsymbol{Z}\right)^{-1} \boldsymbol{Z}^{\prime} \boldsymbol{Y} \tag{2.2}
\end{equation*}
$$

The covariance matrix $\boldsymbol{\Omega}$ can be estimated by $(1 / T) \boldsymbol{H}$, where
$\boldsymbol{H}=(\boldsymbol{Y}-\boldsymbol{Z} \boldsymbol{P})^{\prime}(\boldsymbol{Y}-\boldsymbol{Z} \boldsymbol{P})=\boldsymbol{Y}^{\prime} \boldsymbol{Y}-\boldsymbol{P}^{\prime} \boldsymbol{A} \boldsymbol{P}$
and $\boldsymbol{A}=\boldsymbol{Z}^{\prime} \boldsymbol{Z}$. The matrices $\boldsymbol{P}$ and $\boldsymbol{H}$ constitute sufficient statistics for the model.
A structural or behavioral equation may involve a $T \times G_{1}$ subset of the endogenous variables $\boldsymbol{Y}_{1}$, a $T \times K_{1}$ subset of the exogenous variables $\boldsymbol{Z}_{1}$, and a $T \times G_{1}$ subset of disturbances $\boldsymbol{V}_{1}$. The structural equation of interest is
$\boldsymbol{Y}_{1} \boldsymbol{\beta}_{1}=\boldsymbol{Z}_{1} \gamma_{1}+\boldsymbol{u}$,
where $\boldsymbol{u}=\boldsymbol{V}_{1} \boldsymbol{\beta}_{1}$ and $\boldsymbol{V}=\left(\boldsymbol{V}_{1}, \boldsymbol{V}_{2}\right)$. A component of $\boldsymbol{u}$ has the normal distribution $N\left(0, \sigma^{2}\right)$, where $\sigma^{2}=\boldsymbol{\beta}_{1}^{\prime} \boldsymbol{\Omega}_{11} \boldsymbol{\beta}_{1}$ and $\boldsymbol{\Omega}_{11}$ is the $G_{1} \times G_{1}$ upper-left submatrix of
$\boldsymbol{\Omega}=\left[\begin{array}{ll}\boldsymbol{\Omega}_{11} & \boldsymbol{\Omega}_{12} \\ \boldsymbol{\Omega}_{21} & \boldsymbol{\Omega}_{22}\end{array}\right]$
When $\boldsymbol{Y}, \boldsymbol{Z}, \boldsymbol{V}$, and $\boldsymbol{\Pi}$ are partitioned similarly, the reduced form (2.1) can be written
$\left(\boldsymbol{Y}_{1}, \boldsymbol{Y}_{2}\right)=\left(\boldsymbol{Z}_{1}, \boldsymbol{Z}_{2}\right)\left[\begin{array}{ll}\boldsymbol{\Pi}_{11} & \boldsymbol{\Pi}_{12} \\ \boldsymbol{\Pi}_{21} & \boldsymbol{\Pi}_{22}\end{array}\right]+\left(\boldsymbol{V}_{1}, \boldsymbol{V}_{2}\right)$,
where $\left(\boldsymbol{Y}_{1}, \boldsymbol{Y}_{2}\right)$ is a $T \times\left(G_{1}+G_{2}\right)$ matrix. The relation between the reduced form and the structural equation is
$\left[\begin{array}{c}\boldsymbol{\gamma}_{1} \\ \mathbf{0}\end{array}\right]=\left[\begin{array}{ll}\boldsymbol{\Pi}_{11} & \boldsymbol{\Pi}_{12} \\ \boldsymbol{\Pi}_{21} & \boldsymbol{\Pi}_{22}\end{array}\right]\left[\begin{array}{c}\boldsymbol{\beta}_{1} \\ \mathbf{0}\end{array}\right]=\left[\begin{array}{l}\boldsymbol{\Pi}_{11} \boldsymbol{\beta}_{1} \\ \boldsymbol{\Pi}_{21} \boldsymbol{\beta}_{1}\end{array}\right]$.
The second submatrix of (2.7),
$\boldsymbol{\Pi}_{21} \boldsymbol{\beta}_{1}=\mathbf{0}$,
defines $\boldsymbol{\beta}_{1}$ except for a multiplicative constant if and only if the rank of $\boldsymbol{\Pi}_{21}$ is $G_{1}-1\left(G_{1}<K_{1}\right)$. In that case the structural equation is said to be identified.

In this paper we derive the likelihood ratio test of the null hypothesis
$H_{0}: \boldsymbol{\beta}_{1}=\boldsymbol{\beta}^{0}$
against the alternative
$H_{1}: \boldsymbol{\beta}_{1}$ is identified.
The goal of this paper is to show that this test is admissible. See Section 6. Roughly speaking, it means that there is no other test that can have better power everywhere. In developing this thesis it will be convenient to carry out the details when $\gamma_{1}$ is vacuous, that is, $K_{1}=0$. Furthermore, we set $G_{2}=0$ so that $G=G_{1}$. Then the reduced form and structural equation are
$\boldsymbol{Y}=\boldsymbol{Z} \Pi+\boldsymbol{V}, \quad \boldsymbol{Y} \boldsymbol{\beta}=\boldsymbol{u}$.

## 3. INVARIANCE AND NORMALIZATION

Exogenous Variables. The model (2.1) and $H_{0}: \boldsymbol{\beta}=\boldsymbol{\beta}^{0}$ are invariant with respect to linear transformations of the exogenous variables
$\boldsymbol{Z}^{+}=\boldsymbol{Z} \boldsymbol{C}, \quad \boldsymbol{\Pi}^{+}=\boldsymbol{C}^{-1} \boldsymbol{\Pi}$
for $\boldsymbol{C}$ being nonsingular. Then
$\boldsymbol{Z}^{+} \boldsymbol{\Pi}^{+}=\boldsymbol{Z} \boldsymbol{\Pi}, \quad \boldsymbol{A}^{+}=\boldsymbol{C}^{\prime} \boldsymbol{A C}, \quad \boldsymbol{P}^{+}=\boldsymbol{C}^{-1} \boldsymbol{P}$,
and
$\boldsymbol{G}^{+}=\boldsymbol{P}^{+\prime} \boldsymbol{A}^{+} \boldsymbol{P}^{+}=\boldsymbol{P}^{\prime} \boldsymbol{A P}=\boldsymbol{G}, \quad \boldsymbol{H}^{+}=\boldsymbol{Y}^{\boldsymbol{\prime}} \boldsymbol{Y}-\boldsymbol{P}^{+\prime} \boldsymbol{A}^{+} \boldsymbol{P}^{+}=\boldsymbol{H}$.

Endogenous Variables. If the rank of $\boldsymbol{\Pi}$ is $G-1(\leq K)$, the equation $\boldsymbol{\Pi} \boldsymbol{\beta}=\mathbf{0}$ determines $\boldsymbol{\beta}$ except for a multiplicative constant. The "natural normalization" is
$\boldsymbol{\beta}^{\prime} \boldsymbol{\Omega} \boldsymbol{\beta}=1$,
which determines the constant except for sign. The model $\boldsymbol{Y}=\boldsymbol{Z} \boldsymbol{\Pi}+\boldsymbol{V}, \boldsymbol{\Pi} \boldsymbol{\beta}=\mathbf{0}$, and (3.4) is invariant with respect to transformations
$\boldsymbol{Y}^{*}=\boldsymbol{Y} \Phi, \quad \Pi^{*}=\Pi \Phi, \quad \beta^{*}=\Phi^{-1} \beta, \quad V^{*}=V \Phi$,
and
$\Omega^{*}=\Phi^{\prime} \Omega \Phi, \quad \beta^{0 *}=\Phi^{-1} \boldsymbol{\beta}^{0}$,
where $\boldsymbol{\Phi}$ is nonsingular. Then
$\boldsymbol{P}^{*}=\boldsymbol{P} \Phi, \quad \boldsymbol{G}^{*}=\boldsymbol{P}^{* \prime} A \boldsymbol{P}^{*}=\boldsymbol{\Phi}^{\prime} \boldsymbol{P}^{\prime} \boldsymbol{A P} \boldsymbol{P}=\boldsymbol{\Phi}^{\prime} \boldsymbol{G} \Phi$,
and
$\boldsymbol{H}^{*}=\boldsymbol{\Phi}^{\prime} \boldsymbol{H} \boldsymbol{\Phi}, \quad \boldsymbol{\Pi}^{*} \boldsymbol{\beta}^{*}=\boldsymbol{\Pi} \boldsymbol{\beta}=\mathbf{0}, \quad \boldsymbol{\beta}^{* \prime} \boldsymbol{\Omega}^{*} \boldsymbol{\beta}^{*}=1$.

Now we consider the model (2.1) and $\boldsymbol{\Pi} \boldsymbol{\beta}=\mathbf{0}$ when $\boldsymbol{\Omega}$ (the covariance matrix of a row of $\boldsymbol{V}$ ) is known. In this case we can make a transformation (3.5) and (3.6) so $\boldsymbol{\Omega}=\boldsymbol{I}$. Then the first equation in (3.6) is
$\boldsymbol{I}=\boldsymbol{O}^{\prime} \boldsymbol{O}$,
that is, the invariance with respect to transformations (3.7) and (3.8) is with respect to orthogonal transformations. We shall use $\boldsymbol{O}$ to indicate an orthogonal matrix. We can write (3.5) and (3.6) as

$$
\begin{gather*}
\boldsymbol{Y}^{*}=\boldsymbol{Y} \boldsymbol{O}, \quad \boldsymbol{\Pi}^{*}=\boldsymbol{\Pi} \boldsymbol{O}, \quad \boldsymbol{\beta}^{*}=\boldsymbol{O}^{\prime} \boldsymbol{\beta}, \quad \boldsymbol{V}^{*}=\boldsymbol{V} \boldsymbol{O} \\
\boldsymbol{\beta}^{0 *}=\boldsymbol{O}^{\prime} \boldsymbol{\beta}^{0}, \quad \boldsymbol{\beta}^{* \prime} \boldsymbol{\beta}^{*}=\boldsymbol{\beta}^{\prime} \boldsymbol{\beta}=1 \tag{3.10}
\end{gather*}
$$

$$
\begin{gather*}
\boldsymbol{P}^{*}=\boldsymbol{P O}, \quad \boldsymbol{H}^{*}=\boldsymbol{O}^{\prime} \boldsymbol{H O} \\
\boldsymbol{P}^{* \prime} \boldsymbol{A} \boldsymbol{P}^{*}=\boldsymbol{O}^{\prime} \boldsymbol{P}^{\prime} \boldsymbol{A} \boldsymbol{P} \boldsymbol{O} \tag{3.11}
\end{gather*}
$$

The null hypothesis is $\boldsymbol{\beta}=\boldsymbol{\beta}^{0}$.
The reader's intuition can be helped by thinking of the case $G=2$. A row of $\boldsymbol{Y}$ is a point on a two-dimensional graph, say a map. The rotation by $\boldsymbol{O}$ corresponds to rotating the map, that is, looking at the map from a different point of view. In this study there is no preferred coordinate system.

## 4. A CANONICAL FORM FOR $G=2$ AND POLAR COORDINATES

The main part of this paper concerns the model for $\Omega=\sigma^{2} \boldsymbol{I}_{2}$ and
$G_{1}=G=2, \quad G_{2}=0, \quad K_{1}=0, \quad K_{2}=K \geq 2$.
Then the vector $\boldsymbol{\beta}$ with natural parameterization satisfies
$\boldsymbol{\Pi} \boldsymbol{\beta}=\mathbf{0}, \quad \boldsymbol{\beta}^{\prime} \boldsymbol{\beta}=1$.
We can parameterize $\boldsymbol{\beta}$ as
$\boldsymbol{\beta}=\left[\begin{array}{c}\cos \theta \\ \sin \theta\end{array}\right], \quad-\pi \leq \theta \leq \pi$.
This is the polar or angular representation of the coefficient vector.
When the $K \times 2$ matrix $\Pi$ has rank 1, it can be parameterized as
$\Pi=\boldsymbol{\gamma} \boldsymbol{\alpha}^{\prime}$,
where $\gamma$ is a $K \times 1$ vector and
$\boldsymbol{\alpha}=\left[\begin{array}{c}-\sin \theta \\ \cos \theta\end{array}\right]$.

Note that
$(\boldsymbol{\beta}, \boldsymbol{\alpha})=\left[\begin{array}{cc}\cos \theta & -\sin \theta \\ \sin \theta & \cos \theta\end{array}\right]=\boldsymbol{O}$
is an orthogonal matrix. The model is identified when $\gamma \neq \mathbf{0}$. Since $\Omega$ is known, a sufficient statistic in the model is $\boldsymbol{P}$.

Now make a transformation (3.1) so $\boldsymbol{A}^{+}=\boldsymbol{C}^{\prime} \boldsymbol{A} \boldsymbol{C}=\boldsymbol{I}_{K}$; define $\boldsymbol{Q}=\boldsymbol{P}^{+}=\boldsymbol{C}^{-1} \boldsymbol{P}$ and $\boldsymbol{W}=\boldsymbol{C}^{\prime} \boldsymbol{Z}^{\prime} \boldsymbol{V}$,
$\Pi^{+}=\boldsymbol{\nu} \boldsymbol{\alpha}^{\prime}, \quad \boldsymbol{P}^{\prime} \boldsymbol{A P}=\boldsymbol{Q}^{\prime} \boldsymbol{Q}, \quad \boldsymbol{\nu}=\boldsymbol{C}^{-1} \gamma$,
and $\boldsymbol{\alpha}^{\prime} \boldsymbol{\alpha}=1$. The model is
$Q=\boldsymbol{\nu} \boldsymbol{\alpha}^{\prime}+\boldsymbol{W}$.
Here $\boldsymbol{W}=\left(\boldsymbol{w}_{1}, \boldsymbol{w}_{2}\right), \mathscr{E}(\boldsymbol{W})=\mathbf{0}$,
$\mathscr{E}\left(\boldsymbol{w}_{1} \boldsymbol{w}_{1}^{\prime}\right)=\mathscr{E}\left(\boldsymbol{w}_{2} \boldsymbol{w}_{2}^{\prime}\right)=\sigma^{2} \boldsymbol{I}_{K}, \quad \mathscr{E}\left(\boldsymbol{w}_{1} \boldsymbol{w}_{2}^{\prime}\right)=\mathbf{0}$.
The hypothesis $\boldsymbol{\beta}=\boldsymbol{\beta}^{0}$ is equivalent to the hypothesis $\theta=\theta^{0}$ when $\boldsymbol{\beta}=(\cos \theta, \sin \theta)^{\prime}$ and is equivalent to the hypothesis $\boldsymbol{\alpha}=\boldsymbol{\alpha}^{0}$ when $\boldsymbol{\alpha}=$ $(-\sin \theta, \cos \theta)^{\prime}$ and $\theta=\theta^{0}$.

Define $\lambda$ by $\boldsymbol{\nu}^{\prime} \boldsymbol{\nu}=\lambda^{2}$. Then $\boldsymbol{\nu}=\lambda \boldsymbol{\eta}$, where $\boldsymbol{\eta}^{\prime} \boldsymbol{\eta}=1$. We call $\lambda^{2}=$ $\operatorname{tr} \mathscr{E} \boldsymbol{Q} \mathscr{E} \boldsymbol{Q}^{\prime}=\operatorname{tr} \boldsymbol{\nu} \boldsymbol{\alpha}^{\prime} \boldsymbol{\alpha} \boldsymbol{\nu}^{\prime}=\operatorname{tr} \boldsymbol{\nu} \boldsymbol{\nu}^{\prime}=\boldsymbol{\nu}^{\prime} \boldsymbol{\nu}$ the noncentrality parameter.

The density of $\boldsymbol{Q}$ is

$$
\begin{align*}
\frac{1}{\left(2 \pi \sigma^{2}\right)^{K}} e^{-\frac{1}{2} \operatorname{tr} \boldsymbol{W}^{\prime} \boldsymbol{W} / \sigma^{2}} & =\frac{1}{\left(2 \pi \sigma^{2}\right)^{K}} e^{-\frac{1}{2} \operatorname{tr}\left(\boldsymbol{Q}-\boldsymbol{\nu} \boldsymbol{\alpha}^{\prime}\right)^{\prime}\left(\boldsymbol{Q}-\boldsymbol{\nu} \boldsymbol{\alpha}^{\prime}\right) / \sigma^{2}} \\
& =\frac{1}{\left(2 \pi \sigma^{2}\right)^{K}} e^{-\frac{1}{2} \operatorname{tr}\left(\boldsymbol{Q}-\lambda \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}\right)^{\prime}\left(\boldsymbol{Q}-\lambda \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}\right) / \sigma^{2}} \\
& =\frac{1}{\left(2 \pi \sigma^{2}\right)^{K}} e^{\left(-\frac{1}{2} \operatorname{tr} \boldsymbol{Q}^{\prime} \boldsymbol{Q}-\frac{1}{2} \lambda^{2}+\lambda \boldsymbol{\eta}^{\prime} \boldsymbol{Q} \boldsymbol{\alpha}\right) / \sigma^{2}} \tag{4.10}
\end{align*}
$$

since $\lambda^{2} \operatorname{tr}\left(\boldsymbol{\alpha} \boldsymbol{\eta}^{\prime} \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}\right)=\lambda^{2}$ and $\lambda \operatorname{tr}\left(\boldsymbol{\alpha} \boldsymbol{\eta}^{\prime} \boldsymbol{Q}\right)=\lambda \boldsymbol{\eta}^{\prime} \boldsymbol{Q} \alpha$.

## 5. THE LIKELIHOOD RATIO TEST

In this section we derive the likelihood ratio test of $H_{0}: \boldsymbol{\alpha}=\boldsymbol{\alpha}^{0}$ vs $H_{1}: \mathscr{E} \boldsymbol{Q}=\boldsymbol{\nu} \boldsymbol{\alpha}^{\prime}$ when $\boldsymbol{Q}$ has the likelihood defined by (4.10). The derivative of the logarithm of (4.10) with respect to $\boldsymbol{\nu}$ set equal to $\mathbf{0}$ gives
$Q \alpha=\nu$.
Then
$\nu^{\prime} Q \alpha=\nu^{\prime} \nu=\alpha^{\prime} Q^{\prime} Q \alpha=\alpha^{\prime} G \alpha$,
where $\boldsymbol{G}=\boldsymbol{Q}^{\prime} \boldsymbol{Q}$. The logarithm of the likelihood maximized with respect to $\boldsymbol{\nu}$ is $-K \log (2 \pi)$ plus
$-\frac{1}{2}\left[\operatorname{tr} \boldsymbol{G}-\boldsymbol{\alpha}^{\prime} \boldsymbol{G} \boldsymbol{\alpha}\right]=-\frac{1}{2} \operatorname{tr} \boldsymbol{G}+\frac{1}{2} \boldsymbol{\alpha}^{\prime} \boldsymbol{G} \boldsymbol{\alpha}$.
Let $\boldsymbol{G}=\boldsymbol{O}_{t} \boldsymbol{R} \boldsymbol{O}_{t}^{\prime}$, where
$\boldsymbol{R}=\left[\begin{array}{cc}r_{1} & 0 \\ 0 & r_{2}\end{array}\right], \quad \boldsymbol{O}_{t}=\left[\begin{array}{cc}\cos t & -\sin t \\ \sin t & \cos t\end{array}\right]=\left(\boldsymbol{\beta}_{t}, \boldsymbol{\alpha}_{t}\right) ;$
that is, $r_{1} \leq r_{2}$ are the eigenvalues of $\boldsymbol{G}$ and $(\cos t, \sin t)^{\prime}$ and $(-\sin t, \cos t)^{\prime}$ are the corresponding eigenvectors of $\boldsymbol{G}$. Under $H_{1}$ the likelihood is maximized by $\boldsymbol{\alpha}=(-\sin t, \cos t)^{\prime}$ and (5.3) is $-\frac{1}{2} r_{1}$. Under $H_{0}$ the likelihood is maximized by $\boldsymbol{\alpha}=\boldsymbol{\alpha}^{0}=\left(-\sin \theta_{0}, \cos \theta_{0}\right)^{\prime}$. Then

$$
\begin{align*}
\boldsymbol{\alpha}^{0^{\prime}} \boldsymbol{G} \boldsymbol{\alpha}^{0} & =\boldsymbol{\alpha}^{0^{\prime}} \boldsymbol{O}_{t} \boldsymbol{R} \boldsymbol{O}_{t}^{\prime} \boldsymbol{\alpha}^{0} \\
& =r_{1} \sin ^{2}\left(t-\theta_{0}\right)+r_{2} \cos ^{2}\left(t-\theta_{0}\right) \\
& =\left(r_{1}-r_{2}\right) \sin ^{2}\left(t-\theta_{0}\right)+r_{2} \tag{5.5}
\end{align*}
$$

The likelihood ratio criterion for testing $\theta=\theta_{0}$ in the model (4.10) is
$e^{-\frac{1}{2}\left(r_{2}-r_{1}\right) \sin ^{2}\left(t-\theta_{0}\right)}$.
Note that the problem is invariant with respect to the group of transformations

$$
\begin{gather*}
\boldsymbol{\alpha} \longrightarrow \boldsymbol{O}_{a} \boldsymbol{\alpha}, \quad \boldsymbol{\alpha}^{0} \longrightarrow \boldsymbol{O}_{a} \boldsymbol{\alpha}^{0}, \quad \boldsymbol{\eta} \longrightarrow \boldsymbol{O}_{b} \boldsymbol{\eta},  \tag{5.7}\\
\theta \longrightarrow \theta+a, \quad \theta_{0} \longrightarrow \theta_{0}+a .
\end{gather*}
$$

The parameters that are invariant are the noncentrality parameter $\lambda^{2}$ and the difference in angles $\theta-\theta_{0}$. We shall consider testing $H_{0}: \theta=\theta_{0}$ for each fixed $\lambda$. We want to separate the effect of the testing procedure from the effect of the noncentrality parameter.

## 6. DEFINITION OF ADMISSIBILITY OF TESTS

Consider a family of densities $f(\boldsymbol{y} \mid \omega)$ defined over a sample space $\mathscr{Y}$ and a parameter space $\boldsymbol{\Omega}$. The parameter space is partitioned into two disjoint sets $\boldsymbol{\Omega}_{0}$ representing the null hypothesis and $\Omega_{1}$ representing the alternative. A set $\mathscr{A}$ in the sample space represents the acceptance of the null hypothesis.

DEFINITION 6.1. A test $A$ is as good as $B$ if
$\operatorname{Pr}(\mathscr{A} \mid \omega) \geq \operatorname{Pr}(\mathscr{B} \mid \omega), \quad \omega \in \Omega_{0}$,
$\operatorname{Pr}(\mathscr{A} \mid \omega) \leq \operatorname{Pr}(\mathscr{B} \mid \omega), \omega \in \boldsymbol{\Omega}_{1}$.

DEFINITION 6.2. $A$ is better than $B$ if the equations above hold with strict inequality for at least one $\omega$.

DEFINITION 6.3. $A$ is admissible if there is no $B$ better than $A$.
See, for example, Anderson (2003, Def. 5.6.3) or Lehmann (1986, Sect. 1.8).
Admissibility of a likelihood ratio test asserts that

$$
\begin{align*}
\operatorname{Pr}\left\{\text { Accept } H_{0} \mid H_{0}, \mathrm{LR}\right\} & \geq \operatorname{Pr}\left\{\text { Accept } H_{0} \mid H_{0} \text {, competing test }\right\}  \tag{6.3}\\
\operatorname{Pr}\left\{\text { Accept } H_{0} \mid H_{1}, \mathrm{LR}, \lambda\right\} & \leq \operatorname{Pr}\left\{\text { Accept } H_{0} \mid H_{1} \text {, competing test, } \lambda\right\}
\end{align*}
$$

In the terminology of economics the LR test is Pareto-optimal.
The inequality (6.3) says that LR is at least as good as the competitor with respect to significance level, that is, probability of acceptance of the null hypothesis, at each parameter point $\omega$ in the null hypothesis. The inequality (6.4) says that LR is at least as good as the competitor with respect to power. Note that the comparison of the two tests is made for each parameter point $\omega$. In the testing problem considered in Sections 6 and $7, \boldsymbol{Q}=\lambda \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}+\boldsymbol{W}$, the invariant parameters are essentially the noncentrality parameter $\lambda$ and the difference between the null hypothesis angle $\theta_{0}$ and the model value of $\theta$. Thus $\omega=\left(\lambda, \theta-\theta_{0}\right)$. The model is invariant with respect to transformations (5.7).

## 7. DENSITY OF G

The matrix $\boldsymbol{G}=\boldsymbol{Q}^{\prime} \boldsymbol{Q}$ has the noncentral Wishart distribution with $K$ degrees of freedom, covariance $\sigma^{2} \boldsymbol{I}_{2}$, and noncentrality matrix
$\left(\lambda \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}\right)^{\prime}\left(\lambda \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}\right)=\lambda^{2} \boldsymbol{\alpha} \boldsymbol{\alpha}^{\prime}$.
See Anderson and Girshick (1944). The density or likelihood of $\boldsymbol{G}$ is

$$
\begin{equation*}
\frac{e^{-\frac{1}{2} \lambda^{2}-\frac{1}{2} \operatorname{tr} \boldsymbol{G}}|\boldsymbol{G}|^{\frac{1}{2}(K-3)}}{2^{\frac{1}{2} K+1} \pi^{\frac{1}{2}} \Gamma\left[\frac{1}{2}(K-1)\right]}\left(\lambda^{2} \boldsymbol{\alpha}^{\prime} \boldsymbol{G} \boldsymbol{\alpha}\right)^{-(K-2) / 4} \mathrm{I}_{\frac{1}{2}(K-2)}\left(\lambda \sqrt{\boldsymbol{\alpha}^{\prime} \boldsymbol{G} \boldsymbol{\alpha}}\right) \tag{7.2}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathrm{I}_{\frac{1}{2}(K-2)}(z)=\left(\frac{1}{2} z\right)^{\frac{1}{2}(K-2)} \sum_{j=0}^{\infty}\left(\frac{z^{2}}{4}\right)^{j} \frac{1}{j!\Gamma\left(\frac{1}{2} K+j\right)} \tag{7.3}
\end{equation*}
$$

is the modified Bessel function of order $(K-2) / 2$ (Abramowitz and Stegun, 1972, (9.6.10) on p. 375); see also Appendix B. The first factor in (7.2) is a constant times the central Wishart density.

Transform $\boldsymbol{G}(2 \times 2)$ to $\left(r_{1}, r_{2}, t\right)$. The Jacobian of the transformation is $r_{2}-r_{1}$; see Appendix A. The density of $r_{1}, r_{2}$ and $t(-\pi \leq t \leq \pi)$ is
$\frac{\left(r_{2}-r_{1}\right) e^{-\frac{1}{2} \lambda^{2}-\frac{1}{2}\left(r_{1}+r_{2}\right)}\left(r_{1} r_{2}\right)^{\frac{1}{2}(K-3)}}{2^{\frac{1}{2} K+1} \pi^{\frac{1}{2}} \Gamma\left[\frac{1}{2}(K-1)\right]} I_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} c^{2}\right)$,
where

$$
\begin{align*}
c^{2} & =\boldsymbol{\alpha}^{\prime} \boldsymbol{O}_{t} \boldsymbol{R} \boldsymbol{O}_{t}^{\prime} \boldsymbol{\alpha} \\
& =\boldsymbol{\alpha}_{\theta-t}^{\prime} \boldsymbol{R} \boldsymbol{\alpha}_{\theta-t} \\
& =r_{1} \sin ^{2}(t-\theta)+r_{2} \cos ^{2}(t-\theta) \\
& =r_{2}-\left(r_{2}-r_{1}\right) \sin ^{2}(t-\theta), \tag{7.5}
\end{align*}
$$

$$
\begin{align*}
\mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} c^{2}\right) & =\left(\frac{\lambda c}{2}\right)^{-\frac{1}{2}(K-2)} \mathrm{I}_{\frac{1}{2}(K-2)}(\lambda c) \\
& =\sum_{j=0}^{\infty}\left(\frac{\lambda^{2} c^{2}}{4}\right)^{j} \frac{1}{j!\Gamma\left(\frac{1}{2} K+j\right)} \tag{7.6}
\end{align*}
$$

Let
$n\left(r_{1}, r_{2}\right)=\frac{\left(r_{2}-r_{1}\right)\left(r_{1} r_{2}\right)^{\frac{1}{2}(K-3)} e^{-\left(r_{1}+r_{2}\right) / 2}}{2^{\frac{1}{2} K+1} \pi^{\frac{1}{2}} \Gamma\left[\frac{1}{2}(K-1)\right]}$.
Then the density of $r_{1}, r_{2}$, and $t$ is
$h\left(r_{1}, r_{2}, t \mid \theta, \lambda\right)=n\left(r_{1}, r_{2}\right) e^{-\frac{1}{2} \lambda^{2}} \mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} c^{2}\right)$.

## 8. LIKELIHOOD RATIO CRITERION IN TERMS OF G

The density (i.e., likelihood) of $r_{1}, r_{2}$, and $t$ given $\lambda$ and
$H_{0}: \theta=\theta_{0}$
is
$\max _{H_{0}} \operatorname{Lhd}=n\left(r_{1}, r_{2}\right) e^{-\lambda^{2} / 2} \mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} c_{0}^{2}\right)$,
where
$c_{0}^{2}=r_{1} \sin ^{2}\left(t-\theta_{0}\right)+r_{2} \cos ^{2}\left(t-\theta_{0}\right)=r_{2}-\left(r_{2}-r_{1}\right) \sin ^{2}\left(t-\theta_{0}\right)$.
The likelihood is maximized with respect to $\theta$ (given $\lambda$ ) for
$H_{1}:-\pi \leq \theta \leq \pi$
at $\hat{\theta}=t$. Then
$\max _{H_{1}} \operatorname{Lhd}=n\left(r_{1}, r_{2}\right) e^{-\lambda^{2} / 2} \mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} r_{2}\right)$.
The likelihood ratio criterion for testing $H_{0}: \theta=\theta_{0}$ against the alternative $H_{1}$ : $-\pi \leq \theta \leq \pi$ given $\lambda$ is

$$
\begin{align*}
\mathrm{LRC} & =\frac{\max _{H_{0}} \text { Lhd }}{\max _{H_{1}} \operatorname{Lhd}}=\frac{\mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} c_{0}^{2}\right)}{\mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} r_{2}\right)} \\
& =\frac{\mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left\{\lambda^{2}\left[r_{2}-\left(r_{2}-r_{1}\right) \sin ^{2}\left(t-\theta_{0}\right)\right]\right\}}{\mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} r_{2}\right)} \tag{8.6}
\end{align*}
$$

The function $I_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} c_{0}^{2}\right)$ is an increasing function of $\lambda^{2} c_{0}^{2}$, and $c_{0}^{2}$ is an increasing function of $\left(r_{2}-r_{1}\right) \sin ^{2}\left(t-\theta_{0}\right)$, hence $I_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} c_{0}^{2}\right)$ is decreasing in $\left(r_{2}-r_{1}\right) \sin ^{2}\left(t-\theta_{0}\right)$. The acceptance region of the likelihood ratio test of $H_{0}$ : $\theta=\theta_{0}$ given $\lambda$ can be written in terms of
$\left(r_{2}-r_{1}\right) \sin ^{2}\left(t-\theta_{0}\right) \leq$ function of $r_{1}, r_{2}$, and $\lambda$.
Note that the likelihood ratio criterion (the left side of (8.7)) does not depend on the parameter $\lambda$. However, the probability of acceptance does depend on $\lambda$. When the null hypothesis is true, the distribution of the LRC does not depend on $\theta_{0}$; that is, the distribution is invariant with respect to transformation (3.10). The maximum likelihood estimator of $\theta$ is $\hat{\theta}=t$; the maximum likelihood estimator of $\boldsymbol{\beta}$ is $\hat{\boldsymbol{\beta}}=\boldsymbol{\beta}_{\hat{\theta}}$.

The likelihood ratio criterion when $\lambda$ is considered as a parameter could be derived from the model (4.10); that is equivalent to the hypothesis $\boldsymbol{\beta}=\boldsymbol{\beta}_{\theta_{0}}$, when $\boldsymbol{\beta}^{\prime} \boldsymbol{\beta}=1$. The likelihood of (4.10) is maximized with respect to $\boldsymbol{\nu}$ for fixed $\theta$ at $\hat{\boldsymbol{\nu}}=\boldsymbol{Q} \boldsymbol{\alpha}$ yielding a maximized likelihood of

$$
\begin{align*}
\frac{1}{(2 \pi)^{K}} e^{-\frac{1}{2} \operatorname{tr} \boldsymbol{Q}^{\prime} \boldsymbol{Q}+\frac{1}{2} \alpha^{\prime} \boldsymbol{Q}^{\prime} \boldsymbol{Q} \boldsymbol{\alpha}} & =\frac{1}{(2 \pi)^{K}} e^{-\frac{1}{2}\left(\operatorname{tr} \boldsymbol{G}-\boldsymbol{\alpha}^{\prime} \boldsymbol{G} \boldsymbol{\alpha}\right)} \\
& =\frac{1}{(2 \pi)^{K}} e^{-\frac{1}{2} \operatorname{tr} \boldsymbol{R}+\frac{1}{2} c^{2}} \tag{8.8}
\end{align*}
$$

Under the null hypothesis $c^{2}$ is
$c_{0}^{2}=r_{2}-\left(r_{2}-r_{1}\right) \sin ^{2}\left(t-\theta_{0}\right)$.
Under the alternative $H_{1}$ the maximum of the likelihood (8.8) occurs at $\theta=0$ and $c^{2}=r_{2}$. Then the likelihood ratio criterion for testing $H_{0}$ vs $H_{1}$ is
$e^{-\frac{1}{2}\left(r_{2}-r_{1}\right) \sin ^{2}\left(t-\theta_{0}\right)}$.
However, to carry out the admissibility argument requires explicit treatment for each value of $\lambda$. See Anderson and Kunitomo (2009).

## 9. BAYES TEST

We now formulate the testing problem as a 2-decision problem: $\theta=\theta_{0}$ vs $\theta \neq \theta_{0}$ with the loss function $L(\theta, a)$, where the action $a$ is accept $H_{0}$ or reject $H_{0}$.

|  | Action |  |
| ---: | :---: | :---: |
| $L(\theta, a)$ | Accept $H_{0}$ | Reject $H_{0}$ |
| Parameter $\theta=\theta_{0}$ | 0 | 1 |
| $\theta \neq \theta_{0}$ | 1 | 0 |

A test (or decision rule) is a function $d\left(r_{1}, r_{2}, t\right)$ taking values $a=$ accept $H_{0}$ and $a=$ reject $H_{0}$. The risk of a test is the expected loss
$R(\theta, \lambda, d)=\int_{0}^{\infty} \int_{0}^{r_{2}} \int_{-\pi}^{\pi} L\left[\theta, d\left(r_{1}, r_{2}, t\right)\right] h\left(r_{1}, r_{2}, t \mid \theta, \lambda\right) d t d r_{1} d r_{2}$
as a function of $\theta$ and $\lambda$. The average risk of a procedure with prior distribution $P(\theta)$ is
$R^{*}[P(\cdot), \lambda, d]=\int_{-\pi}^{\pi} R(\theta, \lambda, d) d P(\theta)$.
We suppose the distribution $P(\theta)$ has a jump of $\operatorname{Pr}\left\{\theta=\theta_{0}\right\}$ at $\theta_{0}$ and a density $\left[1-\operatorname{Pr}\left\{\theta=\theta_{0}\right\}\right] p(\theta)$ for $\theta \neq \theta_{0}$. Then $R^{*}[P(\cdot), \lambda, d]=\operatorname{Pr}\left\{\theta=\theta_{0}\right\} \operatorname{Pr}\left\{\right.$ reject $\left.H_{0} \mid \theta_{0}, \lambda\right\}$ $+\left[1-\operatorname{Pr}\left\{\theta=\theta_{0}\right\}\right] \int_{-\pi}^{\pi} \operatorname{Pr}\left\{\right.$ accept $\left.H_{0} \mid \theta, \lambda\right\} p(\theta) d \theta$ $=\operatorname{Pr}\left\{\theta=\theta_{0}\right\} \int_{R} h\left(r_{1}, r_{2}, t \mid \theta_{0}, \lambda\right) d r_{1} d r_{2} d t$
$+\left[1-\operatorname{Pr}\left\{\theta=\theta_{0}\right\}\right] \int_{A} \bar{h}\left(r_{1}, r_{2}, t \mid \lambda\right) d r_{1} d r_{2} d t$,
where $R$ is the rejection set of $r_{1}, r_{2}, t$ and $A$ is the corresponding acceptance set, and
$\bar{h}\left(r_{1}, r_{2}, t \mid \lambda\right)=\int_{-\pi}^{\pi} h\left(r_{1}, r_{2}, t \mid \theta, \lambda\right) p(\theta) d \theta$
is a density. The average risk can be written as

$$
\begin{align*}
R^{*}[P(\cdot), \lambda, d]= & \operatorname{Pr}\left\{\theta=\theta_{0}\right\}+\int_{A}\left\{\left[1-\operatorname{Pr}\left\{\theta=\theta_{0}\right\}\right] \bar{h}\left(r_{1}, r_{2}, t \mid \lambda\right)\right. \\
& \left.-\operatorname{Pr}\left\{\theta=\theta_{0}\right\} h\left(r_{1}, r_{2}, t \mid \theta_{0}, \lambda\right)\right\} d r_{1} d r_{2} d t \tag{9.5}
\end{align*}
$$

The average risk $R^{*}[P(\cdot), \lambda, d]$ is minimized by the largest acceptance set $A$ for which
$\left[1-\operatorname{Pr}\left\{\theta=\theta_{0}\right\}\right] \bar{h}\left(r_{1}, r_{2}, t \mid \lambda\right)-\operatorname{Pr}\left\{\theta=\theta_{0}\right\} h\left(r_{1}, r_{2}, t \mid \theta_{0}, \lambda\right) \leq 0$,
that is, the largest set $A$ for which
$A: \frac{h\left(r_{1}, r_{2}, t \mid \theta_{0}, \lambda\right)}{\bar{h}\left(r_{1}, r_{2}, t \mid \lambda\right)} \geq \frac{1-\operatorname{Pr}\left\{\theta=\theta_{0}\right\}}{\operatorname{Pr}\left\{\theta=\theta_{0}\right\}}$.

THEOREM 9.1. For each $\lambda$ the Bayes test of $H_{0}: \theta=\theta_{0}$ vs $H_{1}: \theta \neq \theta_{0}$ when $H_{0}$ has the prior probability $\left[1-\operatorname{Pr}\left\{\theta=\theta_{0}\right\}\right]$ and $H_{1}$ has the prior probability $\operatorname{Pr}\left\{\theta=\theta_{0}\right\}$ with density $p(\theta)\left(\theta \neq \theta_{0}\right)$, has the acceptance set (9.7).

The Bayes test is essentially obtained by applying the Neyman-Pearson Fundamental Lemma to $h\left(r_{1}, r_{2}, t \mid \theta_{0}, \lambda\right)$ and $\bar{h}\left(r_{1}, r_{2}, t \mid \lambda\right)$.

When
$p(\theta)=\frac{1}{2 \pi}, \quad-\pi \leq \theta \leq \pi$,
the denominator of the left-hand side of (9.7) is

$$
\begin{align*}
\bar{h} & \left(r_{1}, r_{2}, \lambda\right) \\
& =n\left(r_{1}, r_{2}\right) e^{-\frac{1}{2} \lambda^{2}} \frac{1}{2 \pi} \int_{-\pi}^{\pi} \sum_{j=0}^{\infty}\left(\frac{\lambda^{2}}{4}\right)^{j} \frac{1}{j!\Gamma\left[\frac{1}{2} K+j\right]}\left[r_{2}-\left(r_{2}-r_{1}\right) \sin ^{2}(t-\theta)\right]^{j} d \theta \\
& =n\left(r_{1}, r_{2}\right) e^{-\frac{1}{2} \lambda^{2}} \sum_{j=0}^{\infty}\left(\frac{\lambda^{2}}{4}\right)^{j} \frac{1}{j!\Gamma\left[\frac{1}{2} K+j\right]} \frac{1}{2 \pi} \int_{t-\pi}^{t+\pi}\left[r_{2}-\left(r_{2}-r_{1}\right) \sin ^{2} x\right]^{j} d x \\
& =n\left(r_{1}, r_{2}\right) e^{-\frac{1}{2} \lambda^{2}} f_{K}\left(r_{1}, r_{2}, \lambda\right), \tag{9.9}
\end{align*}
$$

where
$f_{K}\left(r_{1}, r_{2}, \lambda\right)=\sum_{j=0}^{\infty}\left(\frac{\lambda^{2}}{4}\right)^{j} \frac{1}{j!\Gamma\left[\frac{1}{2} K+j\right]} \frac{1}{2 \pi} \int_{-\pi}^{\pi}\left[r_{2}-\left(r_{2}-r_{1}\right) \sin ^{2} x\right]^{j} d x$.
The integrand in (9.10) is nonnegative and less than $r_{2}^{j}$; hence, the sum converges and $f_{K}\left(r_{1}, r_{2}, \lambda\right)$ is well-defined. Then the left-hand side of (9.7) is
$\frac{h\left(r_{1}, r_{2}, t \mid \theta_{0}, \lambda\right)}{\bar{h}\left(r_{1}, r_{2}, t \mid \lambda\right)}=\frac{\mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} c^{2}\right)}{f_{K}\left(r_{1}, r_{2}, \lambda\right)}$.
The numerator of the LRC and the left-hand side of (9.7) are the same.
The conclusion is that a LR test can be expressed as a Bayes test for a prior of the uniform distribution for the parameter $\theta$.

THEOREM 9.2. The likelihood ratio test for $H_{0}: \theta=\theta_{0}$ vs $H_{1}: \theta \neq \theta_{0}$ is a Bayes test for a prior density $1 /(2 \pi)$.

## 10. ADMISSIBILITY OF INVARIANT TESTS

See Section 5.6.2 of Anderson (2003), for example. If the sets $\mathscr{A}$ and $\mathscr{B}$ are invariant with respect to a group of transformations, the test with acceptance set $\mathscr{A}$ is known as an admissible invariant test.

THEOREM 10.1. The Bayes test with acceptance region (9.7) is an admissible invariant test of $H_{0}$ vs $H_{1}$.

Proof. Let the Bayes test for $\operatorname{Pr}\left\{\theta=\theta_{0}\right\}$ and the density $p(\cdot)$ be given by (9.7), resulting in the average risk $\mathrm{R}^{*}\left[p(\cdot), \lambda, d_{B}\right]$. If this test is not admissible, then there is a test $d^{*}$ that is better than $d_{B}$, that is,
$\mathrm{R}^{*}\left[p(\cdot), \lambda, d^{*}\right] \leq \mathrm{R}^{*}\left[p(\cdot), \lambda, d_{B}\right]$
for all $\theta$ and $\lambda$ with strict inequality for some $\theta$ and $\lambda$. However, this assertion contradicts the construction of the Bayes test $d_{B}$.

The conclusion is that the LR test is an admissible invariant test.
The invariance involved here is with respect to certain linear transformations. This consideration is a generalization of the notion that the questions at issue do not depend on the unit of measurement; for example, inches vs feet vs meters or pounds vs kilograms or radians vs degrees. The linear transformations do not affect the inference problems for which the model is used.

## 11. ADMISSIBILITY OVER ALL TESTS

### 11.1. General Theorem

Now we consider admissibility with respect to all tests. We assert that the best invariant test of $\theta=\theta_{0}$ is admissible within the class of all tests; in particular, a LR test is admissible within the class of all tests. The idea is that a family of tests invariant or not - can be transformed to a family of randomized invariant tests; if the original family of invariant tests is admissible within the class of invariant tests, the transformed family is admissible within the class of all tests.

We apply the so-called "Hunt-Stein theorem" to the effect that the best invariant test is admissible in the class of all tests if the group of transformations defining invariance is finite or compact. See Zaman (1996, Sect. 7.9) or Lehmann (1986, Thm. 7 of Chap. 3). The proofs of such theorems are based on the argument that the randomization of the noninvariant tests yields an invariant test that is as good as the noninvariant test.

In the model
$Q=\lambda \eta \alpha^{\prime}+W$
for fixed $\boldsymbol{\lambda}$, each parameter vector $\boldsymbol{\eta}$ and $\boldsymbol{\alpha}$ take values in closed sets $\boldsymbol{\eta}^{\prime} \boldsymbol{\eta}=1$ and $\boldsymbol{\alpha}^{\prime} \boldsymbol{\alpha}=1$, which are therefore compact and satisfy the Hunt-Stein conditions.

THEOREM 11.1. The $L R$ test of $\theta=\theta_{0}$ is admissible in the set of all tests.

### 11.2. An Example

To illustrate the Hunt-Stein theory, consider the model in which $\theta$ can take on a finite number of values, say
$\theta=0, \frac{1}{N} 2 \pi, \frac{2}{N} 2 \pi, \ldots, \frac{N-1}{N} 2 \pi$.
Note that $\boldsymbol{\alpha}^{\prime}=(-\sin \theta, \cos \theta)$. Consider the group of transformations
$\theta \longrightarrow \theta+\frac{j}{N} 2 \pi, \quad t \longrightarrow t+\frac{j}{N} 2 \pi, \quad j=0,1, \ldots, N-1$.
Let these values of $\theta$ be labeled as $\theta_{0}^{*}, \theta_{1}^{*}, \ldots, \theta_{N-1}^{*}$. Each of them corresponds to a null hypothesis. Define a test of the hypothesis $\theta=\theta_{k}^{*}$ by the acceptance region $A_{k}^{*}=A_{k}^{*}\left(t, r_{1}, r_{2}\right)$ in the space of $t, r_{1}, r_{2}$. The set of tests is an invariant set if
$A_{k}^{*}\left(t-\theta_{k}^{*}, r_{1}, r_{2}\right)=A_{j}^{*}\left(t-\theta_{j}^{*}, r_{1}, r_{2}\right)$
for $k, j=0,1, \ldots, N-1$.
The LR test of the hypothesis $\theta=\theta_{i}^{*}$ against the alternative $\theta=\theta_{j}^{*}$ for some $j=0,1, \ldots, N-1$ is the Bayes solution for the hypothesis $\theta=\theta_{i}^{*}$ for prior probabilities
$\operatorname{Pr}\left\{\theta=\theta_{j}^{*}\right\}=\frac{1}{N}, \quad j=0,1, \ldots, N-1$.
Suppose the set of tests are not necessarily invariant; that is, (11.4) does not necessarily hold. We can randomize these $N$ tests by defining an invariant randomized test.

The acceptance region $A_{k}^{*}\left(t, r_{1}, r_{2}\right)$ can be adapted to test $\theta=\theta_{i}^{*}$ by subtracting $\theta_{k}^{*}$ from $A_{k}^{*}\left(t, r_{1}, r_{2}\right)$ and adding $\theta_{i}^{*}$, which is the region $A_{k}^{*}\left(t-\theta_{k}^{*}+\theta_{i}^{*}, r_{1}, r_{2}\right)$. A randomized test for the null hypothesis $\theta=\theta_{i}^{*}$ has acceptance region
$\frac{1}{N} \sum_{k=0}^{N-1} A_{k}^{*}\left(t-\theta_{k}^{*}+\theta_{i}^{*}, r_{1}, r_{2}\right)$.
The set of such tests for $\theta_{i}^{*}, i=0,1, \ldots, N-1$, is an invariant set.
LEMMA 11.1. If a test with an invariant family of acceptance regions $A_{0}, A_{1}, \ldots, A_{N-1}$ is admissible in the set of invariant tests, it is admissible in the set of all tests.

Proof by Contradiction. Suppose $\bar{A}_{0}, \ldots, \bar{A}_{N-1}$ is a family of better tests (not necessarily invariant). Then the invariant randomized tests based on $\bar{A}_{0}, \ldots, \bar{A}_{N-1}$ is better than the family of $A_{0}, \ldots, A_{N-1}$. But this contradicts the assumption that $A_{0}, \ldots, A_{N-1}$ is admissible in the set of invariant tests.

## 12. COMMENTS

### 12.1. Invariance with Respect to Linear Transformations of Exogenous Variables

In the model (2.1) $\boldsymbol{Y}=\boldsymbol{Z} \boldsymbol{\Pi}+\boldsymbol{V}$ a linear transformation of $\boldsymbol{Z}$ and $\boldsymbol{\Pi}\left(\boldsymbol{Z}^{+}=\boldsymbol{Z} \boldsymbol{C}\right.$ and $\boldsymbol{\Pi}^{+}=\boldsymbol{C}^{-1} \boldsymbol{\Pi}$ ) leaves $\boldsymbol{Z} \boldsymbol{\Pi}$ invariant and hence does not affect the model.

Similarly, the transformation does not affect the equation $\boldsymbol{\Pi} \boldsymbol{\beta}=\mathbf{0}$, in particular the null hypothesis $\boldsymbol{\Pi} \boldsymbol{\beta}^{0}=\mathbf{0}$. This property is a generalization of the idea that the model and the problem do not depend on the units of measurement. This property implies that a test can be based on $\boldsymbol{G}=\boldsymbol{P}^{\prime} \boldsymbol{A} \boldsymbol{P}$.

### 12.2. Invariance with Respect to Orthogonal Transformations of Endogenous Variables

When $\Omega=\boldsymbol{I}$ is assumed, an orthogonal transformation of the disturbance $\boldsymbol{V} \rightarrow \boldsymbol{V} \boldsymbol{O}$ and a corresponding transformation of $\boldsymbol{\beta}, \boldsymbol{\beta} \rightarrow \boldsymbol{O}^{\prime} \boldsymbol{\beta}$ and of the null hypothesis $\boldsymbol{\beta}^{0} \rightarrow \boldsymbol{O}^{\prime} \boldsymbol{\beta}^{0}$ do not affect the equations, $\boldsymbol{\beta}=\boldsymbol{\beta}^{0}$ and $\boldsymbol{\beta}^{\prime} \boldsymbol{\beta}=1$. In the $G$-space this transformation is a rotation of coordinates.

### 12.3. Conclusions

Theorem 11.1 states that the LR test of $H_{0}: \boldsymbol{\alpha}=\boldsymbol{\alpha}^{0}$ vs $H_{1}: \mathscr{E} \boldsymbol{Q}=\lambda \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}\left(\boldsymbol{\eta}^{\prime} \boldsymbol{\eta}=1\right.$, $\boldsymbol{\alpha}^{\prime} \boldsymbol{\alpha}=1$ ) is admissible in the class of all (randomized) tests. This implies that given any test of $H_{0}$ vs $H_{1}$ in the model $\mathscr{E} \boldsymbol{Q}=\lambda \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}$ there is an LR test that is better than that test. Thus the statistician need only consider (randomized) LR tests.

Note that the comparison of a given test with respect to $\alpha$ holds for each specified $\lambda$. The theorem does not indicate how to establish the significance level for a specific $\lambda$. The analysis assumes that the system is in equilibrium; that is, that (4.8) holds for all $T$.

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## APPENDIX A: Jacobian

The representation of $\boldsymbol{G}=\boldsymbol{O}_{t} \boldsymbol{R} \boldsymbol{O}_{t}^{\prime}$ in components is

$$
\left[\begin{array}{ll}
g_{11} & g_{12}  \tag{A.1}\\
g_{21} & g_{22}
\end{array}\right]=\left[\begin{array}{ll}
r_{1} \cos ^{2} t+r_{2} \sin ^{2} t & \left(r_{1}-r_{2}\right) \cos t \sin t \\
\left(r_{1}-r_{2}\right) \cos t \sin t & r_{1} \sin ^{2} t+r_{2} \cos ^{2} t
\end{array}\right] .
$$

The matrix of partial derivatives of $g_{11}, g_{22}, g_{12}$ with respect to $r_{1}, r_{2}$ and $t$ is

$$
\left[\begin{array}{ccc}
\cos ^{2} t & \sin ^{2} t & -2\left(r_{1}-r_{2}\right) \cos t \sin t  \tag{A.2}\\
\sin ^{2} t & \cos ^{2} t & 2\left(r_{1}-r_{2}\right) \cos t \sin t \\
\cos t \sin t & -\cos t \sin t & \left(r_{1}-r_{2}\right)\left(\cos ^{2} t-\sin ^{2} t\right)
\end{array}\right]
$$

The Jacobian of the transformation is the absolute value of the determinant of (A.2) which is $r_{2}-r_{1}$.

## APPENDIX B: The Noncentral Wishart Distribution

Let $\boldsymbol{Q}=\lambda \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}+\boldsymbol{W}$, and
$\boldsymbol{Q}=\left[\begin{array}{l}\boldsymbol{Q}_{1}^{\prime} \\ \boldsymbol{Q}_{2}\end{array}\right], \quad \boldsymbol{\eta}=\left[\begin{array}{l}1 \\ \mathbf{0}\end{array}\right], \quad \boldsymbol{\alpha}=\left[\begin{array}{l}1 \\ \mathbf{0}\end{array}\right], \quad \boldsymbol{W}=\left[\begin{array}{l}\boldsymbol{w}_{1}^{\prime} \\ \boldsymbol{W}_{2}\end{array}\right]$,
where $\boldsymbol{Q}_{2}$ and $\boldsymbol{W}_{2}$ are $(K-1) \times G, \boldsymbol{Q}_{1}$ and $\boldsymbol{w}_{1}$ are $G \times 1, \boldsymbol{\eta}$ is $K \times 1$ and $\boldsymbol{\alpha}$ is $G \times 1$. Note that $\boldsymbol{\eta}^{\prime} \boldsymbol{\eta}=1=\boldsymbol{\alpha}^{\prime} \boldsymbol{\alpha}$. The rows of $\boldsymbol{W}$ are independently normally distributed with means $\mathbf{0}$ and covariance matrix $\boldsymbol{I}_{G}$. Then $\boldsymbol{Q}_{2}^{\prime} \boldsymbol{Q}_{2}=\boldsymbol{G}_{2}$ has a (central) Wishart distribution $W\left(\boldsymbol{I}_{G}, K-1\right)$ with density
$\frac{\left|\boldsymbol{G}_{2}\right|^{\frac{1}{2}(K-G-2)} e^{-\frac{1}{2} \operatorname{tr} \boldsymbol{G}_{2}}}{2^{\frac{1}{2}(K-1) G} \pi^{G(G-1) / 4} \prod_{i=1}^{G} \Gamma\left[\frac{1}{2}(K-i)\right]}$
(Anderson, 2003, Thm. 7.2.2). The vector $\boldsymbol{q}_{1}^{\prime}=\left(q_{11}, \boldsymbol{q}_{12}^{\prime}\right)$ has the density

$$
\begin{equation*}
\frac{1}{(2 \pi)^{\frac{1}{2} G}} e^{-\frac{1}{2}\left(q_{11}-\lambda\right)^{2}-\frac{1}{2} q_{12}^{\prime} q_{12}} \tag{B.3}
\end{equation*}
$$

The joint density of the matrix $\boldsymbol{G}_{2}$ and the vector $\boldsymbol{q}_{1}^{\prime}$ is the product of (B.2) and (B.3). The joint density of $\boldsymbol{G}=\boldsymbol{q}_{1} \boldsymbol{q}_{1}^{\prime}+\boldsymbol{G}_{2}$ and $\boldsymbol{q}_{1}$ is

$$
\begin{align*}
& \frac{\left|\boldsymbol{G}-\boldsymbol{q}_{1} \boldsymbol{q}_{1}^{\prime}\right|^{\frac{1}{2}(K-G-2)} e^{-\frac{1}{2} \operatorname{tr} \boldsymbol{G}+\lambda q_{11}-\lambda^{2} / 2}}{2^{\frac{1}{2} K G} \pi^{G(G+1) / 4} \prod_{i=1}^{G} \Gamma\left[\frac{1}{2}(K-i)\right]} \\
&=\frac{|\boldsymbol{G}|^{\frac{1}{2}(K-G-2)}\left(1-\boldsymbol{q}_{1}^{\prime} \boldsymbol{G}^{-1} \boldsymbol{q}_{1}\right)^{\frac{1}{2}(K-G-2)} e^{-\frac{1}{2} \operatorname{tr} \boldsymbol{G}+\lambda q_{11}-\lambda^{2} / 2}}{2^{\frac{1}{2} K G} \pi^{G(G+1) / 4} \prod_{i=1}^{G} \Gamma\left[\frac{1}{2}(K-i)\right]} . \tag{B.4}
\end{align*}
$$

See Corollary A.3.1 of Anderson (2003), for example.

The noncentral Wishart density of $\boldsymbol{G}$ is the integral of (B.4) with respect to the vector $\boldsymbol{q}_{1}^{\prime}=\left(q_{11}, \boldsymbol{q}_{12}^{\prime}\right)$ over the range for which $1-\boldsymbol{q}_{1}^{\prime} \boldsymbol{G}^{-1} \boldsymbol{q}_{1}$ is positive. Anderson and Girshick (1944) carried out the algebraic details of this integration.

THEOREM B.1. The density of $\boldsymbol{G}=\boldsymbol{Q}^{\prime} \boldsymbol{Q}$, where $\boldsymbol{Q}=\lambda \boldsymbol{\eta} \boldsymbol{\alpha}^{\prime}+\boldsymbol{W}, \boldsymbol{\eta}=(1, \mathbf{0})^{\prime}$, and $\boldsymbol{\alpha}=(1, \mathbf{0})^{\prime}$, is

$$
\begin{equation*}
\frac{e^{-(1 / 2) \lambda^{2}-(1 / 2) \operatorname{tr} \boldsymbol{G}}}{2^{(1 / 2) K G-(1 / 2)(K-2)} \pi^{G(G-1) / 4} \prod_{i=1}^{G-1} \Gamma\left[\frac{1}{2}(K-i)\right]}|\boldsymbol{G}|^{\frac{1}{2}(K-G-1)} \mathbf{I}_{\frac{1}{2}(K-2)}^{*}\left(\lambda^{2} g_{11}\right) \tag{B.5}
\end{equation*}
$$

where
$\mathrm{I}_{\frac{1}{2}(K-2)}^{*}\left(z^{2}\right)=\sum_{j=0}^{\infty}\left(\frac{z^{2}}{4}\right)^{j} \frac{1}{j!\Gamma\left(\frac{K}{2}+j\right)}$.

## APPENDIX C: Neyman-Pearson Fundamental Lemma

Let $p_{0}(x)$ and $p_{1}(x)$ be two densities defined for $x$ in some (finite) Euclidean space. Consider testing the null hypothesis that the density of $x$ is $p_{0}(x)$ against the alternative that the density is $p_{1}(x)$. The significance level of the test is defined as
$\alpha=\operatorname{Pr}\left\{\right.$ rejecting $H_{0} \mid$ sampling $\left.p_{0}(x)\right\}$.
The power of the test is defined as
$\operatorname{Pr}\left\{\right.$ rejecting $H_{0} \mid$ sampling $\left.p_{1}(x)\right\}$.
The most powerful test of $H_{0}$ given the significance level $\alpha$ is defined by the rejection region

$$
\frac{p_{0}(x)}{p_{1}(x)} \leq k
$$

for the minimum $k$. See Problem 6.4 of Anderson (2003), for example.


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