On stability criteria for kinetic magnetohydrodynamics

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The existence of a potential energy functional in the zero-Larmor-radius collisionless plasma theory of Kruskal & Oberman (Phys. Fluids, vol. 1, 1958 p. 275), Rosenbluth & Rostoker (Phys. Fluids, vol. 2, 1959, p. 23) allows us to derive easily sufficient conditions for linear stability. However, this kinetic magnetohydrodynamics (KMHD) theory does not have a self-adjointness property, making it difficult to derive necessary conditions. In particular, the standard methods to prove that an instability follows if some trial perturbation makes the incremental potential energy negative, which rely on the self-adjointness of the force operator or on the existence of a complete basis of normal modes, are not applicable to KMHD. This paper investigates KMHD linear stability criteria based on the time evolution of initial-value solutions, without recourse to the classic bounds or comparison theorems of Kruskal-Oberman and Rosenbluth-Rostoker for the KMHD potential energy. The adopted approach does not solve the kinetic equations by integration along characteristics and does not require that the particle orbits be periodic or nearly periodic. Most importantly, the investigation of a necessary condition for stability does not require the self-adjointness of the force operator or the existence of a complete basis of normal modes. It is thereby shown that stability in isothermal ideal-MHD is a sufficient condition for stability in KMHD and that, with a proviso on the long-time behaviour of oscillations about stable equilibria, stability in the double-adiabatic fluid theory, including the variation of the parallel fluid displacement, would be a necessary condition for stability in KMHD.

Key words: plasma dynamics, plasma instabilities

1. Introduction

Energy principles provide a powerful tool to assess the linear stability of plasmas within different theoretical frameworks. In particular, the energy principles for the fluid models of ideal magnetohydrodynamics (MHD) and the double-adiabatic theory of Chew, Goldberger & Low (1956) yield a necessary and sufficient condition for stability (Bernstein *et al.* 1958; Laval, Mercier & Pellat 1965). The original work that formulated the hybrid fluid–kinetic theory of a zero-Larmor-radius collisionless plasma with one ion species, known as kinetic magnetohydrodynamics (KMHD) (Kruskal & Oberman 1958; Rosenbluth & Rostoker 1959), showed that, like in the

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other conservative theories, a potential energy functional which depends only on the state of the system exists also in KMHD. In this case, the state of a linear perturbation about a static equilibrium is specified by the fluid displacement vector $\boldsymbol{\xi}$ and the convection-subtracted (Lagrangian) perturbations of the ion and electron distribution functions, to be denoted by \hat{f}_s with s the species index. The incremental potential energy functional is the sum of fluid plus kinetic terms,

$$\delta W[\boldsymbol{\xi}, \hat{f}_{s}] = \delta W_{\perp}^{F}[\boldsymbol{\xi}_{\perp}] + \delta W^{K}[\hat{f}_{s}] = \delta W_{\perp}^{F}[\boldsymbol{\xi}_{\perp}] - \frac{1}{2} \sum_{s=i,e} \int d^{3}\boldsymbol{x} \int d^{3}\boldsymbol{v} \frac{\hat{f}_{s}^{2}}{\partial f_{s0}/\partial\varepsilon}.$$
 (1.1)

Here, $\delta W_{\perp}^{F}[\xi_{\perp}]$ is the incremental potential energy in 'perpendicular ideal MHD', namely the ideal-MHD model closed with the 'convection only' pressure evolution equation $dp/dt = \partial p/\partial t + \boldsymbol{u} \cdot \nabla p = 0$, which depends only on the component of the fluid displacement perpendicular to the equilibrium magnetic field ξ_{\perp} . The Lagrangian distribution function perturbations \hat{f}_s are related to the fixed-point (Eulerian) perturbations f_{s1} through $\hat{f}_s = f_{s1} + \boldsymbol{\xi} \cdot \partial f_{s0}/\partial \boldsymbol{x}$ and f_{s0} stands for the equilibrium distribution functions, which are uniform in the direction of the equilibrium magnetic field and monotonically decreasing with the phase-space energy ε , so $\delta W^{K}[\hat{f}_s]$ is positive definite. In (1.1) and throughout the present work, the equilibrium distribution functions are also assumed to be isotropic in velocity space, so the equilibrium pressures p_{s0} are scalars.

The existence of a potential energy functional allows us immediately to establish sufficient conditions for stability in KMHD. Clearly, if δW is a positive definite functional of $(\boldsymbol{\xi}, \hat{f}_s)$, energy conservation implies that the kinetic energy must remain bounded in time for any possible dynamical evolution, hence the system is stable. Since $\delta W^K[\hat{f}_s]$ is positive definite, the most obvious sufficient condition for KMHD stability is that $\delta W^F_{\perp}[\boldsymbol{\xi}_{\perp}]$ be positive definite, or equivalently that the system be stable according to 'perpendicular ideal MHD'. Tighter sufficient conditions for stability can be obtained by imposing physical constraints on \hat{f}_s instead of just using $\hat{f}_s^2 \ge 0$. The perturbed distribution functions must be such that their density moments are equal to the fluid perturbed density, which (assuming ions of unit electric charge) must be the same for the two species in order to satisfy charge neutrality and must fulfil the linearized fluid continuity equation, $\int d^3 \boldsymbol{v} f_{s1} = -\boldsymbol{\xi} \cdot \nabla n_0 - n_0 \nabla \cdot \boldsymbol{\xi}$, or equivalently $\int d^3 \boldsymbol{v} f_s = -n_0 \nabla \cdot \boldsymbol{\xi}$, where n_0 is the equilibrium particle density. Now, minimizing δW subject to the constraint $\int d^3 \boldsymbol{v} f_s = -n_0 \nabla \cdot \boldsymbol{\xi}$ yields

$$\delta W[\boldsymbol{\xi}, \hat{f}_{s}] \ge \delta W_{\perp}^{F}[\boldsymbol{\xi}_{\perp}] + \frac{1}{2} \int d^{3}\boldsymbol{x} \quad (p_{i0} + p_{e0})(\boldsymbol{\nabla} \cdot \boldsymbol{\xi})^{2}, \tag{1.2}$$

so $\delta W[\boldsymbol{\xi}, \hat{f}_s]$ is bounded from below by the incremental potential energy in the isothermal ideal-MHD model closed with the pressure evolution equation $d(pn^{-1})/dt = 0$, and stability according to isothermal ideal MHD is a sufficient condition for KMHD stability. Yet another sufficient condition for stability may be obtained by considering the Rosenbluth–Rostoker form of the KMHD potential energy, which results from specializing $\delta W^K[\hat{f}_s]$ to the distribution functions of a zero-frequency normal mode, defined as an unstable normal mode with zero real frequency and infinitesimally small growth rate. The solution for these zero-frequency normal modes, to be denoted by $\hat{f}_s^{\omega=0}$, was derived in Rosenbluth & Rostoker (1959)

and was expressed in terms of ξ_{\perp} and equilibrium quantities only, hence the following form of KMHD potential energy could be defined as a functional of ξ_{\perp}

$$\delta W^{RR}[\boldsymbol{\xi}_{\perp}] = \delta W^{F}_{\perp}[\boldsymbol{\xi}_{\perp}] - \frac{1}{2} \sum_{s=i,e} \int d^{3}\boldsymbol{x} \int d^{3}\boldsymbol{v} \frac{(\hat{f}^{\omega=0}_{s})^{2}}{\partial f_{s0}/\partial \varepsilon}.$$
 (1.3)

With the condition that the particle orbits be periodic or nearly periodic, upper and lower bounds for $\delta W^{RR}[\xi_{\perp}]$, known as comparison theorems, were also derived (Kruskal & Oberman 1958; Rosenbluth & Rostoker 1959). The lower bound is

$$\delta W^{RR}[\boldsymbol{\xi}_{\perp}] \ge \delta W^{F}_{\perp}[\boldsymbol{\xi}_{\perp}] + \frac{5}{6} \int \mathrm{d}^{3} \boldsymbol{x}(p_{i0} + p_{e0}) \langle \boldsymbol{\nabla} \cdot \boldsymbol{\xi}_{\perp} \rangle^{2}, \qquad (1.4)$$

where $\langle \cdots \rangle = \int dl (\cdots) B^{-1} / \int dl B^{-1}$ is the magnetic flux tube average, so $\delta W^{RR}[\xi_{\perp}]$ is bounded from below by the incremental potential energy in the adiabatic ideal-MHD model closed with the pressure evolution equation $d(pn^{-5/3})/dt = 0$, after minimization with respect to ξ_{\parallel} . This is usually accepted as proof that stability according to adiabatic ideal MHD is a sufficient condition for stability in KMHD although, strictly speaking, equations (1.3) and (1.4) mean only that, if an equilibrium admits a KMHD zero-frequency normal mode, it is either marginal or unstable in adiabatic ideal MHD. In any case, even if these two statements happened not to be equivalent, one always has the result that stability in isothermal ideal MHD is sufficient for stability in KMHD, a result that is slightly more pessimistic but is rigorous and has the advantage of not requiring the periodic orbit assumption.

The situation is different when it comes to proving necessary conditions for KMHD stability, and rigorous results regarding this more difficult problem have turned out to be elusive. The upper bound for the Rosenbluth–Rostoker potential energy is

$$\delta W^{RR}[\boldsymbol{\xi}_{\perp}] \leq \delta W^{F}_{\perp}[\boldsymbol{\xi}_{\perp}] + \frac{1}{6} \int \mathrm{d}^{3}\boldsymbol{x} \left(p_{i0} + p_{e0}\right) \left[5(\boldsymbol{\nabla} \cdot \boldsymbol{\xi}_{\perp})^{2} + (\boldsymbol{\nabla} \cdot \boldsymbol{\xi}_{\perp} + 3\boldsymbol{\xi}_{\perp} \cdot \boldsymbol{\kappa}_{0})^{2}\right] = \delta W^{DA}[\boldsymbol{\xi}_{\perp}],$$
(1.5)

where δW^{DA} is the incremental potential energy in the Chew–Goldberger–Low, double-adiabatic fluid theory, with κ_0 the equilibrium magnetic curvature vector. This implies that, if an equilibrium is unstable according to the double-adiabatic theory to a fluid displacement perturbation with zero parallel component, then a KMHD trial perturbation can be constructed that makes the KMHD potential energy negative. One may be tempted to argue that, by analogy with the mechanical systems with finite degrees of freedom or the simpler ideal-MHD and double-adiabatic fluid theories, this also implies a KMHD instability. However, actually proving it is neither immediate nor easy due to the fact that, as shown explicitly in Ramos (2015b), KMHD does not have a self-adjointness property. The standard approaches to prove that an unstable growth follows when a trial perturbation that makes the potential energy negative is used as initial condition, do not work in KMHD because of its lack of self-adjointness. There are two such standard approaches. In the first one, the initial condition is expanded as a superposition of normal modes and it is argued that, in order to make the potential energy negative, at least one of the normal modes must have a positive growth rate which will cause an exponential growth of the perturbation. The validity of this method requires of course that a complete basis of normal modes exists and this has not been proved for KMHD (even allowing for a continuum of singular modes) because the KMHD normal modes are not

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eigenfunctions of a self-adjoint operator. The second approach, which does not rely on the expansion in normal modes, is the one put forward in the rigorous proof of the necessary condition for ideal-MHD stability of Laval *et al.* (1965). However, this method requires that the 'force-times-displacement' functional

$$U = -\frac{1}{2} \int d^3 \mathbf{x} \ \boldsymbol{\xi} \cdot \boldsymbol{F} = -\frac{1}{2} \int d^3 \mathbf{x} \ \rho_0 \ \boldsymbol{\xi} \cdot \frac{\partial^2 \boldsymbol{\xi}}{\partial t^2}$$
(1.6)

be equal to the incremental potential energy, which is defined as

$$\delta W = -\int^{t} dt' \int d^{3}x \frac{\partial \boldsymbol{\xi}(t')}{\partial t'} \cdot \boldsymbol{F}(t') = -\int^{t} dt' \int d^{3}x \,\rho_{0} \frac{\partial \boldsymbol{\xi}(t')}{\partial t'} \cdot \frac{\partial^{2} \boldsymbol{\xi}(t')}{\partial t'^{2}} = -\int^{t} dt' \frac{dK(t')}{dt'},$$
(1.7)

where ρ_0 is the equilibrium mass density and $K = 1/2 \int d^3 x \rho_0 |\partial \xi/\partial t|^2$ is the kinetic energy. The equality $U = \delta W$ holds when the force operator F is self-adjoint so that $d(\int d^3 x \ \xi \cdot F)/dt = 2 \int d^3 x (\partial \xi/\partial t) \cdot F$, but it does not hold in KMHD whose force operator does not have this property.

This paper investigates the KMHD initial-value problem with the aim of establishing stability criteria whose derivation does not use the classic comparison theorems and does not require the self-adjointness of the force operator or the existence of a complete basis of normal modes. The analysis uses the KMHD formulation of Ramos (2015a,b) based on drift-kinetic equations in the reference frame of the complete macroscopic fluid velocity, in which the electric field is eliminated algebraically and the quasineutrality condition is satisfied automatically at all times if it is satisfied by the initial condition. This formulation does not rely on solutions of the kinetic equations by integration along particle orbits and does not require that such orbits be periodic or nearly periodic. Time-dependent solutions of the initial-value problem for the linear KMHD system are considered, hence all quantities are real and generally do not have a separable time dependence. For these physical solutions, the incremental potential energy δW and the 'force-times-displacement' U functionals are evaluated explicitly. They are shown to be different in general, which corroborates the claim that the KMHD force operator is not self-adjoint. A special class of such solutions of the KMHD initial-value problem makes the difference $\delta W - U$ particularly simple albeit not zero and, for these, the initial values of the KMHD potential energy $\delta W[\boldsymbol{\xi}(0), \hat{f}_s(0)]$ and the double-adiabatic potential energy $\delta W^{DA}[\xi(0)]$ are equal. Accounting for their still non-zero $\delta W - U$, these special KMHD perturbations are then used to obtain a condition under which they can be proved to grow in time without bound if the equilibrium is unstable in the double-adiabatic theory. That condition pertains a sufficiently regular behaviour of the oscillations about stable equilibria at long times (such that the squared amplitudes of the distribution function perturbations do not undergo short bursts with large deviations from their time averages) and its validity would guarantee that stability according to the double-adiabatic fluid theory is a necessary condition for KMHD stability.

2. The general KMHD system and its conservation laws

The KMHD theory describes a collisionless, quasineutral plasma with a single ion species (of unit charge for simplicity), in the strong magnetization limit of zero Larmor radii where particles are perfectly tied to the magnetic field lines. The kinetic pressures of each species are formally taken as comparable to the magnetic pressure (so the skin depths are of the order of the Larmor radii) and the macroscopic flow velocities are formally taken as comparable to the sound speed. Thus, the Hall and other two-fluid effects become negligible in the leading order as the Larmor radii tend to zero, in which limit the two species share a common, single-fluid macroscopic velocity u. The quasineutrality condition implies that they share also a common particle density n. The result is a hybrid model, whereby a system of single-fluid, dissipation-free, hydromagnetic equations is closed with a pressure tensor which is the sum of ion and electron contributions determined kinetically:

$$\frac{\partial \boldsymbol{B}}{\partial t} = \boldsymbol{\nabla} \times (\boldsymbol{u} \times \boldsymbol{B}) \tag{2.1}$$

$$\boldsymbol{j} = \boldsymbol{\nabla} \times \boldsymbol{B} \tag{2.2}$$

$$\frac{\partial n}{\partial t} + \nabla \cdot (n\boldsymbol{u}) = 0 \tag{2.3}$$

$$\rho \left[\frac{\partial \boldsymbol{u}}{\partial t} + (\boldsymbol{u} \cdot \boldsymbol{\nabla}) \boldsymbol{u} \right] - \boldsymbol{j} \times \boldsymbol{B} + \sum_{s=i,e} \boldsymbol{\nabla} \cdot \boldsymbol{P}_s = 0, \qquad (2.4)$$

where $\rho = (m_i + m_e)n$ denotes the mass density and the ion and electron pressure tensors have the zero-Larmor-radius collisionless form (Chew *et al.* 1956)

$$\boldsymbol{P}_{s} = \boldsymbol{p}_{s\perp} \boldsymbol{I} + (\boldsymbol{p}_{s\parallel} - \boldsymbol{p}_{s\perp}) \boldsymbol{b} \boldsymbol{b}, \qquad (2.5)$$

with b = B/B denoting the magnetic unit vector and I denoting the identity tensor. The parallel and perpendicular pressures are the corresponding moments of the distribution functions of each species,

$$p_{s\parallel} = m_s \int d^3 w \ w_{\parallel}^2 f_s, \quad p_{s\perp} = \frac{m_s}{2} \int d^3 w \ w_{\perp}^2 \ f_s$$
 (2.6*a*,*b*)

and the phase-space velocity variable w is the random velocity in the reference frame of the macroscopic flow, w = v - u. The distribution functions are independent of the gyrophase angle and satisfy a zero-Larmor-radius drift-kinetic equation. It is most advantageous to refer this drift-kinetic equation to the shifted velocity variable w so that its solution, $f_s = f_s(w_{\parallel}, w_{\perp}, x, t)$, can be used directly in the evaluation of the pressure moments (2.6), without having to subtract any components of the macroscopic velocity. The transformation to this reference frame of the macroscopic flow allows also to eliminate exactly the electric field from the drift-kinetic equation, which becomes (Ramos 2008)

$$\frac{\partial f_s}{\partial t} + \left(\boldsymbol{u} + w_{\parallel}\boldsymbol{b}\right) \cdot \frac{\partial f_s}{\partial \boldsymbol{x}} \bigg|_{w_{\parallel},w_{\perp}} + \frac{w_{\perp}}{2} \left[(\boldsymbol{b}\boldsymbol{b} - \boldsymbol{l}) : (\nabla \boldsymbol{u}) + w_{\parallel}\boldsymbol{b} \cdot \nabla \ln B \right] \frac{\partial f_s}{\partial w_{\perp}} \\ + \left[\frac{\boldsymbol{b} \cdot (\nabla \cdot \boldsymbol{P}_s)}{m_s n} - w_{\parallel} (\boldsymbol{b}\boldsymbol{b}) : (\nabla \boldsymbol{u}) - \frac{w_{\perp}^2}{2} \boldsymbol{b} \cdot \nabla \ln B \right] \frac{\partial f_s}{\partial w_{\parallel}} = 0.$$
(2.7)

The closed system of (2.1)–(2.7) (which has been written without any explicit reference to the electric field but has taken it properly into account) is the formulation of the KMHD theoretical model that will be investigated in this work. This general, nonlinear system has several exact conservation properties. The continuity

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equation (2.3) is in the form of conservation law for the number of particles and the equation of motion (2.4) combined with (2.3) can be expressed as the conservation law for momentum,

$$\frac{\partial(\rho \boldsymbol{u})}{\partial t} + \boldsymbol{\nabla} \cdot \left(\rho \boldsymbol{u} \boldsymbol{u} + \frac{1}{2} B^2 \boldsymbol{I} - \boldsymbol{B} \boldsymbol{B} + \sum_{s=i,e} \boldsymbol{P}_s\right) = 0.$$
(2.8)

The drift-kinetic equation (2.7) upholds these two conservation laws. For consistency with particle conservation and quasineutrality, the 'kinetically defined' particle densities $n_s^{kin} \equiv \int d^3 w f_s$ should always be the same for both species and equal to the solution *n* of the fluid continuity equation (2.3). Since the momentum conservation equation was subtracted from the kinetic equation when transforming it to the macroscopic flow frame and eliminating the electric field, the w_{\parallel} moment of (2.7) is not redundant with the parallel component of (2.4). Instead, the w_{\parallel} moment of f_s should by definition be always zero. Now, calling $c_{s\parallel} \equiv \int d^3 w w_{\parallel} f_s$, the 1 and w_{\parallel} moments of the drift-kinetic equation (2.7) combined with the continuity equation (2.3) yield

$$\frac{\partial (n_s^{kin} - n)}{\partial t} + \nabla \cdot \left[(n_s^{kin} - n)\boldsymbol{u} + c_{s\parallel} \boldsymbol{b} \right] = 0, \qquad (2.9)$$

$$\frac{\partial c_{s\parallel}}{\partial t} + \nabla \cdot (c_{s\parallel} \boldsymbol{u}) + c_{s\parallel} (\boldsymbol{b} \boldsymbol{b}) : (\nabla \boldsymbol{u}) - \frac{(n_s^{kin} - n)}{m_s n} \boldsymbol{b} \cdot (\nabla \cdot \boldsymbol{P}_s) = 0.$$
(2.10)

This is a homogeneous system for $(n_s^{kin} - n)$ and $c_{s\parallel}$, which guarantees that the required constraints $n_s^{kin} - n = 0$ and $c_{s\parallel} = 0$ are satisfied at all times provided they are satisfied by the initial condition. Finally, the KMHD system has an energy conservation law. Combining equation (2.1) dotted with **B**, equation (2.4) dotted with **u**, equation (2.3) and the w^2 moment of equation (2.7), one gets

$$\frac{\partial}{\partial t} \left[\frac{\rho u^2}{2} + \frac{B^2}{2} + \frac{1}{2} \sum_{s=i,e} \left(p_{s\parallel} + 2p_{s\perp} \right) \right] + \nabla \cdot \left\{ \frac{\rho u^2}{2} \boldsymbol{u} - (\boldsymbol{u} \times \boldsymbol{B}) \times \boldsymbol{B} + \sum_{s=i,e} \left[\frac{1}{2} \left(p_{s\parallel} + 2p_{s\perp} \right) \boldsymbol{u} + P_s \cdot \boldsymbol{u} + q_{s\parallel} \boldsymbol{b} \right] \right\} = 0,$$
(2.11)

where $q_{s\parallel} = m_s/2 \int d^3 w w_{\parallel} w^2 f_s$ is the parallel heat flux. In order to streamline the exposition, this paper will assume that the plasma domain is bounded by a rigid and perfectly conducting wall where the normal components of u and B vanish. As indicated by the normal-mode analysis of Ramos (2015b), the results can be generalized to the case where the plasma domain is surrounded by a vacuum region and the plasma–vacuum interface is a closed magnetic surface where the density drops continuously to zero, but the details of this generalization will be skipped here. Thus, for the purposes of the present paper, the global version of the energy conservation law is

$$\frac{\mathrm{d}}{\mathrm{d}t} \int \mathrm{d}^3 \mathbf{x} \left[\frac{\rho u^2}{2} + \frac{B^2}{2} + \frac{1}{2} \sum_{s=i,e} (p_{s\parallel} + 2p_{s\perp}) \right] = 0$$
(2.12)

and the space integral $\int d^3x$ extends over the plasma domain.

3. Linearized KMHD system and specification of initial conditions

The linear stability problem that this work will address concerns small-amplitude perturbations about a static equilibrium, and the subscripts 0 and 1 will be used to denote respectively equilibrium and first-order perturbation variables. The equilibrium distribution functions will be assumed here to be isotropic Maxwellians,

$$f_{Ms0} = \left(\frac{m_s}{2\pi}\right)^{3/2} \frac{n_0}{T_{s0}^{3/2}} \exp\left(-\frac{m_s w^2}{2T_{s0}}\right),$$
(3.1)

with density and temperatures that are uniform in the direction of the equilibrium magnetic field,

$$\boldsymbol{B}_0 \cdot \boldsymbol{\nabla} n_0 = 0, \quad \boldsymbol{B}_0 \cdot \boldsymbol{\nabla} T_{s0} = 0 \tag{3.2a,b}$$

and satisfy the force balance equation

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$$\boldsymbol{j}_0 \times \boldsymbol{B}_0 = (\boldsymbol{\nabla} \times \boldsymbol{B}_0) \times \boldsymbol{B}_0 = \boldsymbol{\nabla}[\boldsymbol{n}_0(\boldsymbol{T}_{i0} + \boldsymbol{T}_{e0})]$$
(3.3)

so that, with a vanishing macroscopic flow, $u_0 = 0$, this constitutes a time-independent solution of the KMHD system (2.1)–(2.7). The Maxwellian equilibrium distribution function is a preferred choice on physical grounds, but the analysis is equally applicable to other equilibrium distribution functions that are constant along the magnetic field, isotropic in velocity space and monotonically decreasing with w^2 .

The first-order perturbation satisfies the linearized KMHD system

$$\frac{\partial \boldsymbol{B}_1}{\partial t} = \boldsymbol{\nabla} \times (\boldsymbol{u}_1 \times \boldsymbol{B}_0), \qquad (3.4)$$

$$\boldsymbol{j}_1 = \boldsymbol{\nabla} \times \boldsymbol{B}_1, \tag{3.5}$$

$$\frac{\partial n_1}{\partial t} + \nabla \cdot (n_0 \boldsymbol{u}_1) = 0, \qquad (3.6)$$

$$\rho_0 \frac{\partial \boldsymbol{u}_1}{\partial t} - \boldsymbol{j}_0 \times \boldsymbol{B}_1 - \boldsymbol{j}_1 \times \boldsymbol{B}_0 + \sum_{s=i,e} \nabla \cdot \boldsymbol{P}_{s1} = 0, \qquad (3.7)$$

$$\boldsymbol{P}_{s1} = \boldsymbol{p}_{s\perp 1} \boldsymbol{I} + (\boldsymbol{p}_{s\parallel 1} - \boldsymbol{p}_{s\perp 1}) \boldsymbol{b}_0 \boldsymbol{b}_0, \qquad (3.8)$$

$$p_{s\parallel 1} = m_s \int d^3 w w_{\parallel}^2 f_{s1}, \quad p_{s\perp 1} = \frac{m_s}{2} \int d^3 w \ w_{\perp}^2 f_{s1}, \quad (3.9a,b)$$

$$\frac{\partial f_{s1}}{\partial t} + w_{\parallel} \boldsymbol{b}_{0} \cdot \frac{\partial f_{s1}}{\partial \boldsymbol{x}} \bigg|_{w_{\parallel},w_{\perp}} + \frac{w_{\perp}}{2} (\boldsymbol{b}_{0} \cdot \boldsymbol{\nabla} \ln B_{0}) \left(w_{\parallel} \frac{\partial f_{s1}}{\partial w_{\perp}} - w_{\perp} \frac{\partial f_{s1}}{\partial w_{\parallel}} \right) \\ + \left(\boldsymbol{u}_{1} + w_{\parallel} \boldsymbol{b}_{1} \right) \cdot \frac{\partial f_{Ms0}}{\partial \boldsymbol{x}} \bigg|_{w_{\parallel},w_{\perp}} + \frac{w_{\perp}}{2} [(\boldsymbol{b}_{0} \boldsymbol{b}_{0} - \boldsymbol{I}) : (\boldsymbol{\nabla} \boldsymbol{u}_{1})] \frac{\partial f_{Ms0}}{\partial w_{\perp}} \\ + \left[\frac{\boldsymbol{b}_{0} \cdot (\boldsymbol{\nabla} \cdot \boldsymbol{P}_{s1}) + \boldsymbol{b}_{1} \cdot (\boldsymbol{\nabla} \cdot \boldsymbol{P}_{s0})}{m_{s} n_{0}} - w_{\parallel} (\boldsymbol{b}_{0} \boldsymbol{b}_{0}) : (\boldsymbol{\nabla} \boldsymbol{u}_{1}) \right] \frac{\partial f_{Ms0}}{\partial w_{\parallel}} = 0. \quad (3.10)$$

The initial-value solution of this system requires specification of the initial conditions $B_1(0)$, $n_1(0)$, $u_1(0)$ and $f_{s1}(0)$, subject to the constraints $\nabla \cdot B_1(0) = 0$, $\int d^3 w \ f_{s1}(0) = n_1(0)$ and $\int d^3 w \ w_{\parallel} f_{s1}(0) = 0$. The zero-divergence constraint on $B_1(0)$ leaves it with only two independent components, so the initial conditions for B_1 and n_1 can be implemented in terms of a three-component vector $\boldsymbol{\xi}(0) = \xi_{\parallel}(0)\boldsymbol{b}_0 + \boldsymbol{\xi}_{\perp}(0)$, through

 $B_1(0) = \nabla \times [\xi_{\perp}(0) \times B_0]$ and $n_1(0) = -\xi_{\perp}(0) \cdot \nabla n_0 - n_0 \nabla \cdot \xi(0)$. Now, defining the time-dependent displacement vector

$$\boldsymbol{\xi}(t) = \boldsymbol{\xi}(0) + \int_0^t dt' \, \boldsymbol{u}_1(t'), \qquad (3.11)$$

equations (3.4) and (3.6) can be integrated to get the relationships

$$\boldsymbol{B}_1 = \boldsymbol{\nabla} \times (\boldsymbol{\xi}_\perp \times \boldsymbol{B}_0), \tag{3.12}$$

$$n_1 = -\boldsymbol{\xi}_\perp \cdot \boldsymbol{\nabla} n_0 - n_0 \ \boldsymbol{\nabla} \cdot \boldsymbol{\xi}, \qquad (3.13)$$

valid at all times, which allow us to eliminate B_1 , j_1 and n_1 in favour of ξ in the dynamical system. The dynamical displacement vector ξ also serves to define the convection-subtracted (Lagrangian) perturbations of the distribution functions,

$$\hat{f}_s = f_{s1} + \boldsymbol{\xi} \cdot \frac{\partial f_{Ms0}}{\partial \boldsymbol{x}}, \qquad (3.14)$$

so the pressure tensors become

$$\boldsymbol{P}_{s1} = -[\boldsymbol{\xi}_{\perp} \cdot \boldsymbol{\nabla}(n_0 T_{s0})]\boldsymbol{I} + \hat{\boldsymbol{P}}_s \tag{3.15}$$

with

$$\hat{\boldsymbol{P}}_{s} = \left(\frac{m_{s}}{2} \int \mathrm{d}^{3} \boldsymbol{w} \, w_{\perp}^{2} \, \hat{f}_{s}\right) \boldsymbol{I} + \left[m_{s} \int \mathrm{d}^{3} \boldsymbol{w} \left(w_{\parallel}^{2} - \frac{w_{\perp}^{2}}{2}\right) \hat{f}_{s}\right] \boldsymbol{b}_{0} \boldsymbol{b}_{0}, \qquad (3.16)$$

and the parallel and perpendicular components of $-\nabla \cdot \hat{P}_s$ are the following functionals of \hat{f}_s :

$$\hat{F}_{s\parallel}[\hat{f}_s] = -\boldsymbol{b}_0 \cdot \boldsymbol{\nabla} \left[m_s \int \mathrm{d}^3 \boldsymbol{w} \ w_{\parallel}^2 \hat{f}_s \right] + \left[m_s \int \mathrm{d}^3 \boldsymbol{w} \ \left(w_{\parallel}^2 - \frac{w_{\perp}^2}{2} \right) \hat{f}_s \right] (\boldsymbol{b}_0 \cdot \boldsymbol{\nabla} \ln B_0) \quad (3.17)$$

and

$$\hat{\boldsymbol{F}}_{s\perp}[\hat{f}_s] = -\boldsymbol{\nabla}_{\perp} \left[\frac{m_s}{2} \int d^3 \boldsymbol{w} \ w_{\perp}^2 \hat{f}_s \right] - \left[m_s \int d^3 \boldsymbol{w} \ \left(w_{\parallel}^2 - \frac{w_{\perp}^2}{2} \right) \hat{f}_s \right] \boldsymbol{\kappa}_0, \qquad (3.18)$$

where $\kappa_0 = (\boldsymbol{b}_0 \cdot \nabla) \boldsymbol{b}_0$ is the equilibrium magnetic curvature. Then, recalling that the force operator in 'perpendicular ideal MHD' is the functional of $\boldsymbol{\xi}_{\perp}$

$$\boldsymbol{F}_{\perp}^{F}[\boldsymbol{\xi}_{\perp}] = (\boldsymbol{j}_{0} \times \boldsymbol{B}_{1})_{\perp} + \boldsymbol{j}_{1} \times \boldsymbol{B}_{0} + \boldsymbol{\nabla}_{\perp}[\boldsymbol{\xi}_{\perp} \cdot \boldsymbol{\nabla}(n_{0}T_{i0} + n_{0}T_{e0})], \qquad (3.19)$$

with B_1 and j_1 given respectively by (3.12) and (3.5), and that, as a consequence of (3.3) and (3.12) the parallel component of $(j_0 \times B_1) + \nabla[\xi_{\perp} \cdot \nabla(n_0 T_{i0} + n_0 T_{e0})]$ vanishes, the linearized momentum equation (3.7) can be written as

$$\rho_0 \frac{\partial \boldsymbol{u}_1}{\partial t} = \rho_0 \frac{\partial^2 \boldsymbol{\xi}}{\partial t^2} = \boldsymbol{F}_{\perp}^F[\boldsymbol{\xi}_{\perp}] + \sum_{s=i,e} \left(\hat{F}_{s\parallel}[\hat{f}_s] \boldsymbol{b}_0 + \hat{\boldsymbol{F}}_{s\perp}[\hat{f}_s] \right).$$
(3.20)

The transformation of the linearized drift-kinetic equation (3.10) to the variable \hat{f}_s yields

$$\frac{\partial \hat{f}_s}{\partial t} + w_{\parallel} \boldsymbol{b}_0 \cdot \frac{\partial \hat{f}_s}{\partial \boldsymbol{x}} \Big|_{w_{\parallel},w_{\perp}} + \frac{w_{\perp}}{2} (\boldsymbol{b}_0 \cdot \boldsymbol{\nabla} \ln B_0) \left(w_{\parallel} \frac{\partial \hat{f}_s}{\partial w_{\perp}} - w_{\perp} \frac{\partial \hat{f}_s}{\partial w_{\parallel}} \right) \\ + \left[\frac{w_{\parallel} \hat{F}_{s\parallel}}{m_s n_0} + \frac{w_{\perp}^2}{2} \boldsymbol{\nabla} \cdot \boldsymbol{u}_1 + \left(w_{\parallel}^2 - \frac{w_{\perp}^2}{2} \right) (\boldsymbol{b}_0 \boldsymbol{b}_0) : (\boldsymbol{\nabla} \boldsymbol{u}_1) \right] \frac{m_s f_{Ms0}}{T_{s0}} = 0, \quad (3.21)$$

subject to the initial-value constraints $\int d^3 w \hat{f}_s(0) = -n_0 \nabla \cdot \boldsymbol{\xi}(0)$ and $\int d^3 w w_{\parallel} \hat{f}_s(0) = 0$. Now, equations (3.17)–(3.21) constitute the sought-after formulation of the linearized KMHD system that uses $(\boldsymbol{\xi}, \hat{f}_s)$ as the primary dynamical variables.

It is convenient to express \hat{f}_s as the sum $\hat{f}_s^{even} + \hat{f}_s^{odd}$ of its even and odd parts with respect to w_{\parallel} and split equation (3.21) into a system for \hat{f}_s^{even} and \hat{f}_s^{odd} . Also, it is useful to change the phase-space coordinates from $(w_{\parallel}, w_{\perp})$ to the coordinates $w = (w_{\parallel}^2 + w_{\perp}^2)^{1/2}$ and $\lambda = w_{\perp}^2/(w^2B_0)$ related to the kinetic energy and the magnetic moment. Denoting the phase-space parallel derivative at constant w and λ simply by $b_0 \cdot \partial/\partial x$ and defining the Q operator

$$Q[\boldsymbol{\eta}] \equiv \frac{1}{w^2} \left[\frac{w_{\perp}^2}{2} \boldsymbol{\nabla} \cdot \boldsymbol{\eta} + \left(w_{\parallel}^2 - \frac{w_{\perp}^2}{2} \right) (\boldsymbol{b}_0 \boldsymbol{b}_0) : (\boldsymbol{\nabla} \boldsymbol{\eta}) \right], \qquad (3.22)$$

one obtains

$$\frac{\partial \hat{f}_s^{even}}{\partial t} + w_{\parallel} \boldsymbol{b}_0 \cdot \frac{\partial \hat{f}_s^{odd}}{\partial \boldsymbol{x}} + Q[\boldsymbol{u}_1] \ \frac{m_s w^2 f_{Ms0}}{T_{s0}} = 0, \tag{3.23}$$

$$\frac{\partial \hat{f}_s^{odd}}{\partial t} + w_{\parallel} \boldsymbol{b}_0 \cdot \frac{\partial \hat{f}_s^{even}}{\partial \boldsymbol{x}} + w_{\parallel} \hat{F}_{s\parallel} \quad \frac{f_{Ms0}}{n_0 T_{s0}} = 0.$$
(3.24)

Several useful identities involving the parallel derivative $\mathbf{b}_0 \cdot \partial/\partial \mathbf{x}$ at constant w and λ are listed in appendix A. By virtue of (A4), the functional $\hat{F}_{s\parallel}[\hat{f}_s]$ (3.17) reduces to

$$\hat{F}_{s\parallel}[\hat{f}_s] = -m_s \int \mathrm{d}^3 \boldsymbol{w} w_{\parallel}^2 \boldsymbol{b}_0 \cdot \frac{\partial \hat{f}_s^{even}}{\partial \boldsymbol{x}}.$$
(3.25)

Then, the w_{\parallel} moment of (3.24) yields

$$\frac{\partial}{\partial t} \left(\int d^3 \boldsymbol{w} \ w_{\parallel} \hat{f}_s^{odd} \right) = 0 \tag{3.26}$$

and, using (A3), the 1 moment of (3.23) yields

$$\frac{\partial}{\partial t} \left[\left(\int d^3 \boldsymbol{w} \, \hat{f}_s^{even} \right) + n_0 \boldsymbol{\nabla} \cdot \boldsymbol{\xi} \right] + \boldsymbol{\nabla} \cdot \left[\left(\int d^3 \boldsymbol{w} \, w_{\parallel} \hat{f}_s^{odd} \right) \boldsymbol{b}_0 \right] = 0.$$
(3.27)

Thus, as expected from the general nonlinear result (2.9) and (2.10), the linearized drift-kinetic equation (3.21) also preserves the constraints $\int d^3 \mathbf{w} \ \hat{f}_s = -n_0 \nabla \cdot \boldsymbol{\xi}$ and $\int d^3 \mathbf{w} \ w_{\parallel} \hat{f}_s = 0$ at all times, once they are imposed on the initial condition.

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4. The potential energy functional

The first term of the nonlinearly conserved energy (2.12) is the kinetic energy of the macroscopic flow, $K = \int d^3x \rho u^2/2$. One may call the remainder a 'potential energy W' and state the energy conservation law as d(K + W)/dt = 0. Within the context of small-amplitude perturbations about a static equilibrium, it can be shown that such W agrees with the physical definition of potential energy as the integral along a dynamic trajectory of the force times the infinitesimal displacement, the result of which is a functional of the final state independent of the details of the trajectory leading to it. For the considered small-amplitude perturbations about a static equilibrium, the kinetic energy is quadratic in the perturbation. Therefore, retaining quantities to the second perturbative order, one has

$$K = K_2 = \int d^3 \boldsymbol{x} \; \frac{\rho_0 u_1^2}{2} = \int d^3 \boldsymbol{x} \; \frac{\rho_0}{2} \; \left| \frac{\partial \boldsymbol{\xi}}{\partial t} \right|^2 \tag{4.1}$$

and $W = W_0 + W_1 + W_2$, where

$$W_0 = \int d^3 \mathbf{x} \left(\frac{B_0^2}{2} + \frac{3}{2} \sum_{s=i,e} n_0 T_{s0} \right), \qquad (4.2)$$

$$W_{1} = \int d^{3}\boldsymbol{x} \left[\boldsymbol{B}_{0} \cdot \boldsymbol{B}_{1} + \frac{1}{2} \sum_{s=i,e} (p_{s\parallel 1} + 2p_{s\perp 1}) \right], \qquad (4.3)$$

$$W_2 = \int d^3 \mathbf{x} \left[\frac{B_1^2}{2} + \mathbf{B}_0 \cdot \mathbf{B}_2 + \frac{1}{2} \sum_{s=i,e} (p_{s\parallel 2} + 2p_{s\perp 2}) \right].$$
(4.4)

Since K is a second-order quantity, energy conservation implies that W_1 must be independent of time like W_0 . This is also a consequence of the equilibrium condition (3.3), as shown in appendix B. Moreover, instead of using (4.4) that involves the second-order perturbation of the magnetic field and the pressures, W_2 can be inferred from the energy conservation law. Thus, up to a constant C independent of time, one can write $W(t) = W_0 + W_1 + W_2(t) = C + \delta W(t)$, with

$$\frac{\mathrm{d}\delta W}{\mathrm{d}t} = -\frac{\mathrm{d}K}{\mathrm{d}t} = -\int \mathrm{d}^3 \boldsymbol{x} \ \rho_0 \boldsymbol{u}_1 \cdot \frac{\partial \boldsymbol{u}_1}{\partial t}.$$
(4.5)

The linearized momentum equation (3.20) implies that δW is the sum of a fluid term plus a kinetic term, $\delta W = \delta W_{\perp}^F + \delta W^K$, given by

$$\frac{\mathrm{d}\delta W_{\perp}^{F}}{\mathrm{d}t} = -\int \mathrm{d}^{3}\boldsymbol{x} \,\boldsymbol{u}_{1\perp} \cdot \boldsymbol{F}_{\perp}^{F}[\boldsymbol{\xi}_{\perp}] \tag{4.6}$$

and

$$\frac{\mathrm{d}\delta W^{K}}{\mathrm{d}t} = -\sum_{s=i,e} \int \mathrm{d}^{3}\boldsymbol{x} \left(u_{1\parallel} \hat{F}_{s\parallel} [\hat{f}_{s}] + \boldsymbol{u}_{1\perp} \cdot \hat{F}_{s\perp} [\hat{f}_{s}] \right).$$
(4.7)

The 'perpendicular ideal-MHD' force operator $F_{\perp}^{F}[\xi_{\perp}]$ is known to be self-adjoint (Bernstein *et al.* 1957, 1958), therefore

$$\int d^3 \boldsymbol{x} \boldsymbol{u}_{1\perp} \cdot \boldsymbol{F}_{\perp}^F[\boldsymbol{\xi}_{\perp}] = \int d^3 \boldsymbol{x} \; \frac{\partial \boldsymbol{\xi}_{\perp}}{\partial t} \cdot \boldsymbol{F}_{\perp}^F[\boldsymbol{\xi}_{\perp}] = \frac{d}{dt} \left(\frac{1}{2} \int d^3 \boldsymbol{x} \; \boldsymbol{\xi}_{\perp} \cdot \boldsymbol{F}_{\perp}^F[\boldsymbol{\xi}_{\perp}] \right)$$
(4.8)

and (4.6) can be integrated to express δW^F_{\perp} as the functional of $\pmb{\xi}_{\perp}$

$$\delta W_{\perp}^{F}[\boldsymbol{\xi}_{\perp}] = -\frac{1}{2} \int \mathrm{d}^{3}\boldsymbol{x} \, \boldsymbol{\xi}_{\perp} \cdot \boldsymbol{F}_{\perp}^{F}[\boldsymbol{\xi}_{\perp}]. \tag{4.9}$$

It will be shown next that, for physical trajectories that are solutions of the linearized KMHD system, equation (4.7) can also be integrated to get an expression of δW^K as a functional of \hat{f}_s only. Substituting (3.25) and (3.18) for $\hat{F}_{s\parallel}$ and $\hat{F}_{s\perp}$, integrating by parts and using the identity (A 3), one obtains

$$\frac{\mathrm{d}\delta W^{K}}{\mathrm{d}t} = \sum_{s=i,e} m_{s} \int \mathrm{d}^{3}\boldsymbol{x} \, \boldsymbol{\nabla} \cdot \left[\int \mathrm{d}^{3}\boldsymbol{w} \, \hat{f}_{s}^{even} \left(w_{\parallel}^{2}\boldsymbol{u}_{\parallel}\boldsymbol{b}_{0} + \frac{w_{\perp}^{2}}{2}\boldsymbol{u}_{\perp} \right) \right]
- \sum_{s=i,e} m_{s} \int \mathrm{d}^{3}\boldsymbol{x} \int \mathrm{d}^{3}\boldsymbol{w} \hat{f}_{s}^{even} \left[w_{\parallel}\boldsymbol{b}_{0} \cdot \frac{\partial (w_{\parallel}\boldsymbol{u}_{\parallel})}{\partial \boldsymbol{x}} + \frac{w_{\perp}^{2}}{2} \boldsymbol{\nabla} \cdot \boldsymbol{u}_{\perp} - \left(w_{\parallel}^{2} - \frac{w_{\perp}^{2}}{2} \right) \boldsymbol{u}_{\perp} \cdot \boldsymbol{\kappa}_{0} \right].$$
(4.10)

The first term of this expression vanishes by virtue of Green's divergence theorem and the ideal wall boundary conditions, and the second term can be rewritten using the identity (A 5) and the definition (3.22). The result is

$$\frac{\mathrm{d}\delta W^{K}}{\mathrm{d}t} = -\sum_{s=i,e} m_{s} \int \mathrm{d}^{3}\boldsymbol{x} \int \mathrm{d}^{3}\boldsymbol{w} \hat{f}_{s}^{even} w^{2} Q[\boldsymbol{u}_{1}]$$
(4.11)

and, substituting the drift-kinetic evolution equation for \hat{f}_s^{even} (3.23),

$$\frac{\mathrm{d}\delta W^{K}}{\mathrm{d}t} = \sum_{s=i,e} \int \mathrm{d}^{3}\boldsymbol{x} \int \mathrm{d}^{3}\boldsymbol{w} \frac{T_{s0}}{f_{Ms0}} \hat{f}_{s}^{even} \left[\frac{\partial \hat{f}_{s}^{even}}{\partial t} + w_{\parallel} \boldsymbol{b}_{0} \cdot \frac{\partial \hat{f}_{s}^{odd}}{\partial \boldsymbol{x}} \right].$$
(4.12)

Further integration by parts with a vanishing boundary term yields

$$\frac{\mathrm{d}\delta W^{K}}{\mathrm{d}t} = \sum_{s=i,e} \int \mathrm{d}^{3}\boldsymbol{x} \int \mathrm{d}^{3}\boldsymbol{w} \frac{T_{s0}}{f_{Ms0}} \left[\frac{1}{2} \frac{\partial (\hat{f}_{s}^{even})^{2}}{\partial t} - w_{\parallel} \hat{f}_{s}^{odd} \boldsymbol{b}_{0} \cdot \frac{\partial \hat{f}_{s}^{even}}{\partial \boldsymbol{x}} \right]$$
(4.13)

and, substituting the drift-kinetic equation for \hat{f}_s^{odd} (3.24),

$$\frac{\mathrm{d}\delta W^{K}}{\mathrm{d}t} = \sum_{s=i,e} \int \mathrm{d}^{3}\mathbf{x} \int \mathrm{d}^{3}\mathbf{w} \left\{ \frac{T_{s0}}{2f_{Ms0}} \left[\frac{\partial (\hat{f}_{s}^{even})^{2}}{\partial t} + \frac{\partial (\hat{f}_{s}^{odd})^{2}}{\partial t} \right] + \frac{\hat{F}_{s\parallel} w_{\parallel} \hat{f}_{s}^{odd}}{n_{0}} \right\}.$$
(4.14)

Finally, recalling $\int d^3 w \ w_{\parallel} \hat{f}_s^{odd} = 0$, this becomes

$$\frac{d\delta W^{K}}{dt} = \frac{d}{dt} \left\{ \sum_{s=i,e} \int d^{3}x \int d^{3}w \frac{T_{s0}}{2f_{Ms0}} \left[(\hat{f}_{s}^{even})^{2} + (\hat{f}_{s}^{odd})^{2} \right] \right\},$$
(4.15)

which can be integrated to arrive at the desired result

$$\delta W^{K}[\hat{f}_{s}] = \sum_{s=i,e} \int d^{3}x \int d^{3}w \frac{T_{s0}}{2f_{Ms0}} \left[(\hat{f}_{s}^{even})^{2} + (\hat{f}_{s}^{odd})^{2} \right] = \sum_{s=i,e} \int d^{3}x \int d^{3}w \frac{T_{s0}}{2f_{Ms0}} \hat{f}_{s}^{2}. \quad (4.16)$$

In summary, adding its fluid and kinetic terms, the KMHD incremental potential energy functional is

$$\delta W[\boldsymbol{\xi}, \hat{f}_{s}] = \delta W_{\perp}^{F}[\boldsymbol{\xi}_{\perp}] + \delta W^{K}[\hat{f}_{s}] = -\frac{1}{2} \int d^{3}\boldsymbol{x} \, \boldsymbol{\xi}_{\perp} \cdot \boldsymbol{F}_{\perp}^{F}[\boldsymbol{\xi}_{\perp}] + \frac{1}{2} \sum_{s=i,e} \int d^{3}\boldsymbol{x} \int d^{3}\boldsymbol{w} \, \frac{T_{s0}}{f_{Ms0}} \hat{f}_{s}^{2},$$
(4.17)

which is equivalent to the expression advanced in (1.1) since, for the equilibrium Maxwellian distribution functions, $\partial f_{Ms0}/\partial \varepsilon = -f_{Ms0}/T_{s0}$. The second-order energy conservation law becomes

$$\frac{\mathrm{d}}{\mathrm{d}t}(K[\partial \boldsymbol{\xi}/\partial t] + \delta W[\boldsymbol{\xi}, \hat{f}_s]) = 0, \qquad (4.18)$$

with the K and δW functionals given respectively by (4.1) and (4.17). The relationship between this energy conservation law and the quadratic form for normal modes derived in Ramos (2015b) is discussed in appendix C.

The criterion that a positive definite $\delta W[\boldsymbol{\xi}, \hat{f}_s]$ is sufficient for KMHD stability is an immediate consequence of the second-order energy conservation law because then, for any dynamical evolution,

$$K(t) = K(0) + \delta W(0) - \delta W(t) \leqslant K(0) + \delta W(0)$$
(4.19)

and K(t) would be a bounded function of time. The Cauchy–Schwarz inequality and the particle conservation constraint yield

$$\int d^3 w \ \frac{T_{s0}}{f_{Ms0}} \hat{f}_s^2 \ge \left(\int d^3 w \ \frac{f_{Ms0}}{T_{s0}} \right)^{-1} \left(\int d^3 w \ \hat{f}_s \right)^2 = n_0 T_{s0} (\nabla \cdot \boldsymbol{\xi})^2, \tag{4.20}$$

which implies the lower bound (1.2) for the KMHD incremental potential energy, hence the result that stability in isothermal ideal MHD is a sufficient condition for stability in KMHD.

5. The 'force-times-displacement' functional

The search for a necessary condition for KMHD stability will involve the 'force-times-displacement' functional U defined in (1.6). From the linearized momentum equation (3.20) and the expression for the 'perpendicular ideal-MHD' potential energy (4.9), this functional is $U = \delta W_{\perp}^F + U^K$ with

$$U^{K} = -\frac{1}{2} \sum_{s=i,e} \int d^{3} \boldsymbol{x} (\xi_{\parallel} \hat{F}_{s\parallel} [\hat{f}_{s}] + \boldsymbol{\xi}_{\perp} \cdot \hat{F}_{s\perp} [\hat{f}_{s}]).$$
(5.1)

Unlike the fluid part of U that equals δW_{\perp}^{F} , and as a consequence of the lack of selfadjointness in the kinetic part of the force operator, U^{K} is in general different from δW^{K} and an explicit evaluation of U^{K} is necessary. This can be carried out along the lines of the evaluation of δW^{K} in the previous section. In complete analogy with the procedure followed to arrive at (4.11), one obtains

$$U^{K} = -\frac{1}{2} \sum_{s=i,e} m_{s} \int \mathrm{d}^{3} \boldsymbol{x} \int \mathrm{d}^{3} \boldsymbol{w} \hat{f}_{s}^{even} w^{2} Q[\boldsymbol{\xi}].$$
 (5.2)

The next step is to substitute the drift-kinetic evolution equation for \hat{f}_s^{even} . However, what is needed here is not (3.23) but its integrated form with respect to time,

$$\hat{f}_{s}^{even} - \hat{f}_{s}^{even}(0) + w_{\parallel} \boldsymbol{b}_{0} \cdot \frac{\partial}{\partial \boldsymbol{x}} \int_{0}^{t} dt' \hat{f}_{s}^{odd}(t') + Q[\boldsymbol{\xi} - \boldsymbol{\xi}(0)] \ \frac{m_{s} w^{2} f_{Ms0}}{T_{s0}} = 0.$$
(5.3)

After substituting this time-integrated form, (5.2) becomes

$$U^{K} = \frac{1}{2} \sum_{s=i,e} \int d^{3}\boldsymbol{x} \int d^{3}\boldsymbol{w} \frac{T_{s0}}{f_{Ms0}} \hat{f}_{s}^{even} \left[\hat{f}_{s}^{even} - \hat{f}_{s}^{even}(0) + w_{\parallel} \boldsymbol{b}_{0} \cdot \frac{\partial}{\partial \boldsymbol{x}} \int_{0}^{t} dt' \hat{f}_{s}^{odd}(t') \right] - \frac{1}{2} \sum_{s=i,e} m_{s} \int d^{3}\boldsymbol{x} \int d^{3}\boldsymbol{w} \hat{f}_{s}^{even} w^{2} Q[\boldsymbol{\xi}(0)]$$
(5.4)

and, after integration by parts with a vanishing boundary term,

$$U^{K} = \frac{1}{2} \sum_{s=i,e} \int d^{3}\boldsymbol{x} \int d^{3}\boldsymbol{w} \, \frac{T_{s0}}{f_{Ms0}} \left[(\hat{f}_{s}^{even})^{2} - \left(w_{\parallel} \boldsymbol{b}_{0} \cdot \frac{\partial \hat{f}_{s}^{even}}{\partial \boldsymbol{x}} \right) \int_{0}^{t} dt' \hat{f}_{s}^{odd}(t') \right] \\ - \frac{1}{2} \sum_{s=i,e} m_{s} \int d^{3}\boldsymbol{x} \int d^{3}\boldsymbol{w} \, \hat{f}_{s}^{even} \left\{ \frac{T_{s0}}{m_{s} f_{Ms0}} \hat{f}_{s}^{even}(0) + w^{2} Q[\boldsymbol{\xi}(0)] \right\}.$$
(5.5)

Finally, substituting the drift-kinetic equation for \hat{f}_s^{odd} (3.24) and using again $\int d^3 w \, w_{\parallel} \hat{f}_s^{odd} = 0$,

$$U^{K} = \frac{1}{2} \sum_{s=i,e} \int d^{3}x \int d^{3}w \frac{T_{s0}}{f_{Ms0}} \left[(\hat{f}_{s}^{even})^{2} + \frac{\partial \hat{f}_{s}^{odd}}{\partial t} \int_{0}^{t} dt' \hat{f}_{s}^{odd}(t') \right] - \frac{1}{2} \sum_{s=i,e} m_{s} \int d^{3}x \int d^{3}w \ \hat{f}_{s}^{even} \left\{ \frac{T_{s0}}{m_{s} f_{Ms0}} \hat{f}_{s}^{even}(0) + w^{2} \mathcal{Q}[\boldsymbol{\xi}(0)] \right\}, \quad (5.6)$$

hence

$$U^{K} = \delta W^{K} - \frac{1}{2} \sum_{s=i,e} \int d^{3}x \int d^{3}w \frac{T_{s0}}{f_{Ms0}} \left[(\hat{f}_{s}^{odd})^{2} - \frac{\partial \hat{f}_{s}^{odd}}{\partial t} \int_{0}^{t} dt' \hat{f}_{s}^{odd}(t') \right] - \frac{1}{2} \sum_{s=i,e} m_{s} \int d^{3}x \int d^{3}w \, \hat{f}_{s}^{even} \left\{ \frac{T_{s0}}{m_{s} f_{Ms0}} \hat{f}_{s}^{even}(0) + w^{2} \mathcal{Q}[\boldsymbol{\xi}(0)] \right\}.$$
(5.7)

This result provides an explicit formula for the difference $\delta W - U$ which, due to the lack of KMHD self-adjointness, is not zero in general, as anticipated.

A special class of perturbations make the difference $\delta W - U$ particularly simple, albeit not zero. They are those for which the initial value of the distribution functions is

$$\hat{f}_s(0) = \hat{f}_s^{even}(0) = -Q[\boldsymbol{\xi}(0)] \frac{m_s w^2 f_{Ms0}}{T_{s0}},$$
(5.8)

that satisfies the constraints $\int d^3 w \hat{f}_s(0) = -n_0 \nabla \cdot \boldsymbol{\xi}(0)$ and $\int d^3 w w_{\parallel} \hat{f}_s(0) = 0$, and makes the last term of (5.7) vanish. For this special class, the 'force-timesdisplacement' functional reduces to $U = \delta W - R/2$, with

$$R = \sum_{s=i,e} \int d^3 \mathbf{x} \int d^3 \mathbf{w} \; \frac{T_{s0}}{f_{Ms0}} \left[(\hat{f}_s^{odd})^2 - \frac{\partial \hat{f}_s^{odd}}{\partial t} \int_0^t dt' \hat{f}_s^{odd}(t') \right], \tag{5.9}$$

and the initial value of the kinetic term of the potential energy functional is

$$\delta W^{K}[\hat{f}_{s}(0)] = \frac{1}{2} \sum_{s=i,e} \int d^{3}x \int d^{3}w \, Q[\boldsymbol{\xi}(0)]^{2} \frac{m_{s}^{2} w^{4} f_{Ms0}}{T_{s0}} = \frac{1}{6} \sum_{s=i,e} \int d^{3}x \, n_{0} T_{s0} \left\{ 5 [\boldsymbol{\nabla} \cdot \boldsymbol{\xi}(0)]^{2} + [\boldsymbol{\nabla} \cdot \boldsymbol{\xi}(0) - 3(\boldsymbol{b}_{0}\boldsymbol{b}_{0}) : (\boldsymbol{\nabla}\boldsymbol{\xi}(0))]^{2} \right\}.$$
(5.10)

Thus, for this class of perturbations, the initial value of the KMHD incremental potential energy is equal to that of the double-adiabatic fluid theory (Chew *et al.* 1956; Bernstein *et al.* 1958),

$$\delta W[\boldsymbol{\xi}(0), \hat{f}_{s}(0)] = \delta W_{\perp}^{F}[\boldsymbol{\xi}_{\perp}(0)] + \delta W^{K}[\hat{f}_{s}(0)] = \delta W^{DA}[\boldsymbol{\xi}(0)], \qquad (5.11)$$

where $\delta W^{DA}[\boldsymbol{\xi}(0)]$ includes the contribution of the parallel displacement $\boldsymbol{\xi}_{\parallel}(0)$. This choice of initial condition will be used next in the investigation of a necessary condition for KMHD stability.

6. Necessary condition for KMHD stability

The energy principle provides a necessary and sufficient condition for stability in the double-adiabatic fluid theory (Bernstein *et al.* 1958; Laval *et al.* 1965). This means that, if an equilibrium is unstable in the double-adiabatic theory, a trial fluid displacement $\boldsymbol{\xi}^{tr}$ exists such that $\delta W^{DA}[\boldsymbol{\xi}^{tr}] < 0$. Such a trial fluid displacement may have a non-zero parallel component. Consider then the following initial condition for the KMHD system:

$$\boldsymbol{\xi}(0) = \boldsymbol{\xi}^{tr}, \quad \boldsymbol{u}_1(0) = \partial \boldsymbol{\xi}(0) / \partial t = 0, \tag{6.1a,b}$$

$$\hat{f}_s(0) = \hat{f}_s^{even}(0) = -Q[\boldsymbol{\xi}^{tr}] \frac{m_s w^2 f_{Ms0}}{T_{s0}}.$$
(6.2)

This perturbation belongs to the special class discussed in the previous section, therefore the initial value of the KMHD incremental potential energy is

$$\delta W(0) = \delta W_{\perp}^{F}[\boldsymbol{\xi}_{\perp}(0)] + \delta W^{K}[\hat{f}_{s}(0)] = \delta W^{DA}[\boldsymbol{\xi}^{tr}] < 0$$
(6.3)

and the initial value of the kinetic energy is K(0) = 0. Defining the time-dependent fluid displacement norm,

$$N(t) \equiv \frac{1}{2} \int d^3 x \, \rho_0 |\boldsymbol{\xi}(t)|^2, \tag{6.4}$$

its time derivatives are

$$\frac{\mathrm{d}N\left(t\right)}{\mathrm{d}t} = \int \mathrm{d}^{3}\boldsymbol{x}\,\rho_{0}\,\,\boldsymbol{\xi}\cdot\frac{\partial\boldsymbol{\xi}}{\partial t},\tag{6.5}$$

$$\frac{\mathrm{d}^2 N(t)}{\mathrm{d}t^2} = \int \mathrm{d}^3 \boldsymbol{x} \,\rho_0 \left[\left| \frac{\partial \boldsymbol{\xi}}{\partial t} \right|^2 + \boldsymbol{\xi} \cdot \frac{\partial^2 \boldsymbol{\xi}}{\partial t^2} \right] = 2K(t) - 2U(t). \tag{6.6}$$

The considered perturbation belongs to the class for which $U(t) = \delta W(t) - R(t)/2$ and energy conservation implies $\delta W(t) + K(t) = \delta W(0) + K(0) = \delta W(0)$, hence

$$\frac{\mathrm{d}^2 N(t)}{\mathrm{d}t^2} = 4K(t) - 2\delta W(0) + R(t)$$
(6.7)

with R(t) as defined in (5.9). The initial condition $\partial \xi(0)/\partial t = 0$ implies dN(0)/dt = 0. Then, after time integration,

$$N(t) = N(0) - \delta W(0) t^{2} + N_{R}(t) + 4 \int_{0}^{t} dt' \int_{0}^{t'} dt'' K(t''), \qquad (6.8)$$

with

$$N_R(t) = \int_0^t dt' \int_0^{t'} dt'' R(t'').$$
(6.9)

A general lower bound for $N_R(t)$ can be derived. Calling

$$g_s \equiv (\hat{f}_s^{odd})^2 - \frac{\partial \hat{f}_s^{odd}}{\partial t} \int_0^t dt' \hat{f}_s^{odd}(t'), \qquad (6.10)$$

one has

$$N_R(t) = \sum_{s=i,e} \int d^3 \mathbf{x} \int d^3 \mathbf{w} \; \frac{T_{s0}}{f_{Ms0}} \int_0^t dt' \int_0^{t'} dt'' g_s(t''). \tag{6.11}$$

Simple integration by parts yields

$$\int_{0}^{t} dt' \int_{0}^{t'} dt'' g_{s}(t'') = 2 \int_{0}^{t} dt' \int_{0}^{t'} dt'' [\hat{f}_{s}^{odd}(t'')]^{2} - \int_{0}^{t} dt' \hat{f}_{s}^{odd}(t') \int_{0}^{t'} dt'' \hat{f}_{s}^{odd}(t'')$$
$$= 2 \int_{0}^{t} dt' (t - t') [\hat{f}_{s}^{odd}(t')]^{2} - \frac{1}{2} \left[\int_{0}^{t} dt' \hat{f}_{s}^{odd}(t') \right]^{2}$$
(6.12)

and, by virtue of the Cauchy-Schwarz inequality

$$0 \leqslant \left[\int_{0}^{t} dt' \hat{f}_{s}^{odd}(t')\right]^{2} \leqslant t \int_{0}^{t} dt' [\hat{f}_{s}^{odd}(t')]^{2},$$
(6.13)

one obtains

$$\int_{0}^{t} dt' \int_{0}^{t'} dt'' g_{s}(t'') \geq \frac{1}{2} \int_{0}^{t} dt' (3t - 4t') [\hat{f}_{s}^{odd}(t')]^{2}.$$
(6.14)

This yields the lower bound for $N_R(t)$

$$N_{R}(t) \ge \frac{t^{2}}{2} \sum_{s=i,e} \int d^{3}x \int d^{3}w \, \frac{T_{s0}}{f_{Ms0}} \Phi_{s}(t), \qquad (6.15)$$

where

$$\Phi_s(t) = \int_0^1 d\nu (3 - 4\nu) [\hat{f}_s^{odd}(\nu t)]^2.$$
 (6.16)

Since $K(t) \ge 0$, this implies also the lower bound for N(t)

$$N(t) \ge N(0) - \delta W(0)t^2 + \frac{t^2}{2} \sum_{s=i,e} \int d^3 \mathbf{x} \int d^3 \mathbf{w} \, \frac{T_{s0}}{f_{Ms0}} \Phi_s(t).$$
(6.17)

The considered perturbation has $\delta W(0) = \delta W^{DA}(0) < 0$, so $-\delta W(0)t^2$ grows in time without bound. If the equilibrium under consideration is KMHD stable, the norm N(t) must be a bounded function of time and (6.17) implies that this can only happen if $\Phi_s(t)$ becomes negative and not negligible as $t \to \infty$. Therefore, if it were possible to prove that for any KMHD-stable equilibrium the long-time behaviour of $\hat{f}_s^{odd}(t)$ is such that, as $t \to \infty$, $\Phi_s(t)$ either stays non-negative or tends to zero, the double-adiabatic unstable equilibrium under consideration must be KMHD unstable and that would complete the proof that stability according to the double-adiabatic fluid theory is a necessary condition for KMHD stability. The KMHD theory is time reversible and dissipationless, but includes the possible Landau damping of initial-value solutions as a consequence of the mixing of the phases of different spectral components. It would then seem reasonable to expect that, for perturbations about a KMHD-stable equilibrium, the long-time behaviour of $[\hat{f}_s^{odd}(t)]^2$ is such that it either tends to a time-independent limit or oscillates about some time-independent average, with deviations of finite amplitude evenly distributed above and below the average. If one characterizes such a behaviour by the condition that the limit

$$(\hat{f}_{\infty s}^{odd})^2 = \lim_{t \to \infty} \frac{1}{t} \int_0^t dt' [\hat{f}_s^{odd}(t')]^2$$
(6.18)

exists and $0 \leq [\hat{f}_s^{odd}(t \to \infty)]^2 \leq 2(\hat{f}_{\infty s}^{odd})^2$, then the lemma given in appendix D guarantees that, as $t \to \infty$, $\Phi_s(t)$ either stays non-negative or tends to zero. Actually, appendix D shows that this is guaranteed by the weaker condition that $\hat{f}_s^{odd}(t)$ be bounded and, for sufficiently large values of t,

$$[\hat{f}_{s}^{odd}(t)]^{2} \leqslant \frac{3}{t} \int_{0}^{t} \mathrm{d}t' [\hat{f}_{s}^{odd}(t')]^{2}$$
(6.19)

regardless of the existence of the limit (6.18). The validity of this condition means that linear KMHD would not allow the possibility that, after a sufficiently long time has elapsed, $[\hat{f}_s^{odd}(t)]^2$ underwent short bursts during which it would reach large values relative to the prevalent, time-averaged ones. Such bursty time variation, reminiscent of the so-called 'rogue wave' phenomenon, is precluded by the condition (6.19). In conclusion, if the long-time behaviour of oscillations about a KMHD-stable equilibrium satisfies the condition (6.19), it has been demonstrated that stability in the double-adiabatic fluid theory would be a necessary condition for stability in KMHD.

The form of the initial condition for the distribution functions (6.2) used here is related to that of the zero-frequency normal modes, although it is not the same. The distribution functions of the zero-frequency normal mode solution of Rosenbluth & Rostoker (1959) are given in terms of the corresponding fluid displacement eigenvector $\boldsymbol{\xi}$ by

$$\hat{f}_{s}^{\omega=0} = -\langle Q[\boldsymbol{\xi}] \rangle_{\tau} \frac{m_{s} w^{2} f_{Ms0}}{T_{s0}}, \qquad (6.20)$$

where $\langle \cdots \rangle_{\tau}$ is the transit-bounce average

$$\langle Q \rangle_{\tau} = \frac{\oint \mathrm{d}l \, w_{\parallel}^{-1} Q}{\oint \mathrm{d}l \, w_{\parallel}^{-1}}.\tag{6.21}$$

These contour integrals are taken along one period of the particle phase-space trajectories that follow the magnetic field lines at constant w and λ , under the assumption that such orbits are periodic (trapped particles or passing particles on closed magnetic loops) or nearly periodic (passing particles on ergodic magnetic lines, with the argument that such lines approximately close on themselves). As a consequence of the identity (A 5), the contribution of ξ_{\parallel} to $\langle Q[\xi] \rangle_{\tau}$ vanishes, so the zero-frequency normal-mode distribution functions depend only on the perpendicular displacement, $\langle Q[\xi] \rangle_{\tau} = \langle Q[\xi_{\perp}] \rangle_{\tau}$. The classic comparison theorem (1.5) (Kruskal & Oberman 1958; Rosenbluth & Rostoker 1959) applies to a generic perpendicular displacement ξ_{\perp} and can be stated as

$$\delta W^{RR}[\boldsymbol{\xi}_{\perp}] = \delta W \left[\boldsymbol{\xi}_{\perp}, -\langle Q[\boldsymbol{\xi}_{\perp}] \rangle_{\tau} \frac{m_s w^2 f_{Ms0}}{T_{s0}} \right] \leqslant \delta W \left[\boldsymbol{\xi}_{\perp}, -Q[\boldsymbol{\xi}_{\perp}] \frac{m_s w^2 f_{Ms0}}{T_{s0}} \right] = \delta W^{DA}[\boldsymbol{\xi}_{\perp}]$$
(6.22)

but, in order to prove the inequality, one needs the periodic or nearly periodic orbit assumption. The present study uses the initial distribution functions $\hat{f}_s(0) = -Q[\boldsymbol{\xi}(0)] m_s w^2 T_{s0}^{-1} f_{Ms0}$ with an initial $\boldsymbol{\xi}(0)$ that can have a non-zero parallel component and makes $\delta W^{DA}[\boldsymbol{\xi}(0)]$ negative. Therefore, the initial KMHD incremental potential energy is known to be negative irrespective of orbit periodicity considerations and the analysis is equally valid for non-periodic passing particles. The argument of near periodicity on ergodic magnetic lines is not needed here. Besides, the present study looked for a proof of instability by actually demonstrating that the chosen initial condition would result in an unbounded growth of the perturbation, not just that the incremental potential energy would become negative.

7. Summary

This work has investigated the linear stability properties of KMHD from the initial-value point of view. The analysis has been based on the formulation introduced in Ramos (2015a,b) to study the KMHD normal modes. This formulation uses drift-kinetic equations in the reference frame of the complete macroscopic fluid velocity, eliminates the electric field and guarantees that the quasineutrality condition is satisfied automatically at all times if it is satisfied by the initial condition. Moreover, it does not solve the kinetic equations by integration along characteristics and does not require that the particle orbits be periodic or nearly periodic. Such a formulation is unconventional compared with more traditional approaches, so the article was written as a self-contained presentation and §§ 2 and 3 were devoted to the detailed introduction of the adopted KMHD description, both in its nonlinear and linearized versions. The derivation of the KMHD potential energy functional within this framework was then given in §4. The main new results are in §§5 and 6. Section 5 evaluated explicitly the 'force-times-displacement' functional, emphasizing the fact that it is different from the potential energy in KMHD, a result that can be taken as an independent proof that the KMHD force operator is not self-adjoint. Finally, §6 looked for a proof that stability according to the double-adiabatic fluid theory is a necessary condition for KMHD stability by studying the possibility

that, if an isotropic-pressure static equilibrium is double-adiabatic unstable, an appropriately chosen KMHD initial condition would grow in time without bound. This was demonstrated with the proviso that the long-time behaviour of oscillations about KMHD-stable equilibria satisfies the condition (6.19).

The two results regarding KMHD stability that this work has arrived at, namely that stability in isothermal ideal MHD is sufficient for stability in KMHD and that, provided the condition (6.19) holds, stability in the Chew–Goldberger–Low double-adiabatic theory including the variation of the parallel fluid displacement would be necessary for stability in KMHD, do not rely on the classic comparison theorems of Kruskal & Oberman (1958), Rosenbluth & Rostoker (1959). They do not require the periodicity or near periodicity of particle orbits and are equally valid for non-periodic passing particles. In addition, the necessary condition analysis does not require the self-adjointness of the force operator or the existence of a complete basis of normal modes, which are properties that have not been proved for KMHD. However, the necessary condition result hinges on the validity of the hypothesis (6.19) on the long-time behaviour of oscillations about KMHD-stable equilibria. This is a reasonable assumption but remains a yet to be proved mathematical conjecture, which underscores the difficulty of finding a completely rigorous proof of a necessary condition for KMHD stability.

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Appendix A. Some identities involving the phase-space parallel derivative at constant magnetic moment

When taking the phase-space parallel derivative $b_0 \cdot \partial/\partial x$ at constant w and λ , w_{\perp} and w_{\parallel} must be considered as the functions

$$w_{\perp}(w,\lambda,\mathbf{x}) = w[\lambda B_0(\mathbf{x})]^{1/2}, \quad w_{\parallel}(w,\lambda,\mathbf{x}) = \pm w[1-\lambda B_0(\mathbf{x})]^{1/2}.$$
(A 1*a*,*b*)

Also, the Jacobian of the coordinate transformation from $(w_{\perp}, w_{\parallel})$ to (w, λ) is

$$\left|\frac{\partial(w_{\perp}, w_{\parallel})}{\partial(w, \lambda)}\right| = \frac{B_0 w^3}{w_{\perp} |w_{\parallel}|}.$$
 (A 2)

Then, it is a simple exercise to verify the following identities: If f^{odd} is a continuous function of phase space that is odd with respect to w_{\parallel} and therefore vanishes at $w_{\parallel} = 0$,

$$\int d^3 \boldsymbol{w} \ \boldsymbol{w}_{\parallel} \ \boldsymbol{b}_0 \cdot \frac{\partial f^{odd}}{\partial \boldsymbol{x}} = \boldsymbol{B}_0 \cdot \boldsymbol{\nabla} \left(\frac{1}{B_0} \int d^3 \boldsymbol{w} \ \boldsymbol{w}_{\parallel} \ f^{odd} \right) = \boldsymbol{\nabla} \cdot \left[\left(\int d^3 \boldsymbol{w} \ \boldsymbol{w}_{\parallel} f^{odd} \right) \boldsymbol{b}_0 \right].$$
(A 3)

If f^{even} is a function of phase space that is even with respect to w_{\parallel} ,

$$\int d^3 \boldsymbol{w} \, w_{\parallel}^2 \boldsymbol{b}_0 \cdot \frac{\partial f^{even}}{\partial \boldsymbol{x}} = \boldsymbol{b}_0 \cdot \boldsymbol{\nabla} \left(\int d^3 \boldsymbol{w} \, w_{\parallel}^2 f^{even} \right) - \left[\int d^3 \boldsymbol{w} \left(w_{\parallel}^2 - \frac{w_{\perp}^2}{2} \right) f^{even} \right] (\boldsymbol{b}_0 \cdot \boldsymbol{\nabla} \ln B_0).$$
(A4)

If $\eta_{\parallel} \boldsymbol{b}_0$ is a parallel vector function of \boldsymbol{x} ,

$$w_{\parallel}\boldsymbol{b}_{0} \cdot \frac{\partial(w_{\parallel}\eta_{\parallel})}{\partial \boldsymbol{x}} = \frac{w_{\perp}^{2}}{2} \boldsymbol{\nabla} \cdot (\eta_{\parallel}\boldsymbol{b}_{0}) + \left(w_{\parallel}^{2} - \frac{w_{\perp}^{2}}{2}\right) (\boldsymbol{b}_{0}\boldsymbol{b}_{0}) : [\boldsymbol{\nabla}(\eta_{\parallel}\boldsymbol{b}_{0})].$$
(A5)

Appendix B. The first-order potential energy

Energy conservation implies that the first-order potential energy W_1 must be independent of time. Here it is shown how this is also a consequence of the equilibrium force balance condition. Substituting (3.12) for B_1 in (4.3) and differentiating with respect to time,

$$\frac{\mathrm{d}W_1}{\mathrm{d}t} = \int \mathrm{d}^3 \boldsymbol{x} \left\{ \boldsymbol{B}_0 \cdot [\boldsymbol{\nabla} \times (\boldsymbol{u}_1 \times \boldsymbol{B}_0)] + \frac{1}{2} \sum_{s=i,e} \frac{\partial}{\partial t} (p_{s\parallel 1} + 2p_{s\perp 1}) \right\}$$
(B1)

and, using vector identities along with (3.9), (3.14),

$$\frac{\mathrm{d}W_1}{\mathrm{d}t} = -\int \mathrm{d}^3 \mathbf{x} \left\{ \mathbf{u}_1 \cdot \left[\mathbf{j}_0 \times \mathbf{B}_0 + \frac{3}{2} \nabla \left(n_0 \sum_{s=i,e} T_{s0} \right) \right] - \frac{1}{2} \sum_{s=i,e} m_s \int \mathrm{d}^3 \mathbf{w} \, w^2 \frac{\partial \hat{f}_s^{even}}{\partial t} \right\}.$$
(B 2)

From the drift-kinetic equation for \hat{f}_s^{even} (3.23) and the identity (A 3), one gets

$$-\frac{m_s}{2} \int \mathrm{d}^3 \boldsymbol{w} \, w^2 \frac{\partial \hat{f}_s^{even}}{\partial t} = \frac{m_s}{2} \boldsymbol{\nabla} \cdot \left[\left(\int \mathrm{d}^3 \boldsymbol{w} \, w_{\parallel} w^2 \hat{f}_s^{odd} \right) \boldsymbol{b}_0 \right] + \frac{m_s^2}{2} \int \mathrm{d}^3 \boldsymbol{w} \, \frac{w^4 f_{Ms0}}{T_{s0}} \mathcal{Q}[\boldsymbol{u}_1]$$
$$= \boldsymbol{\nabla} \cdot (q_{s\parallel 1} \boldsymbol{b}_0) + \frac{5n_0 T_{s0}}{2} \boldsymbol{\nabla} \cdot \boldsymbol{u}_1$$
(B 3)

so, bringing this result to (B 2), integrating by parts and using Green's divergence theorem with a vanishing boundary term,

$$\frac{\mathrm{d}W_1}{\mathrm{d}t} = -\int \mathrm{d}^3 \boldsymbol{x} \, \boldsymbol{u}_1 \cdot \left[\boldsymbol{j}_0 \times \boldsymbol{B}_0 - \boldsymbol{\nabla} (n_0 \sum_{s=i,e} T_{s0}) \right], \tag{B4}$$

which is equal to zero by virtue of the equilibrium relation (3.3).

Appendix C. Relationship between the second-order energy conservation law and the normal-mode quadratic form

KMHD normal modes are $(\boldsymbol{\xi}, \hat{f}_s)$ solutions of the linearized KMHD system that can be factorized as the product of a time-dependent exponential, $\exp(-i\omega t)$, and a timeindependent eigenfunction which may now be complex. For the proper normal modes that are square-integrable functions of $(\boldsymbol{x}, \boldsymbol{w})$, the following quadratic form was derived in Ramos (2015*b*):

$$\omega^{2} \left(-\int \mathrm{d}^{3}\boldsymbol{x} \; \boldsymbol{\xi}_{\perp} \cdot \boldsymbol{F}_{\perp}^{F}[\boldsymbol{\xi}_{\perp}^{*}] + \sum_{s=i,e} \int \mathrm{d}^{3}\boldsymbol{x} \int \mathrm{d}^{3}\boldsymbol{w} \frac{T_{s0}|\hat{f}_{s}^{even}|^{2}}{f_{Ms0}} \right) = |\boldsymbol{\omega}|^{4} \int \mathrm{d}^{3}\boldsymbol{x} \; \rho_{0} \; \boldsymbol{\xi} \cdot \boldsymbol{\xi}^{*} + \mathcal{P},$$
(C 1)

where

$$\mathcal{P} = \sum_{s=i,e} \int \mathrm{d}^{3} \boldsymbol{x} \left(\int \mathrm{d}^{3} \boldsymbol{w} \; \frac{T_{s0} w_{\parallel}^{2}}{f_{Ms0}} \; \left| \boldsymbol{b}_{0} \cdot \frac{\partial \hat{f}_{s}^{even}}{\partial \boldsymbol{x}} \right|^{2} - \frac{m_{s}}{n_{0}} \; \left| \int \mathrm{d}^{3} \boldsymbol{w} \; w_{\parallel}^{2} \; \boldsymbol{b}_{0} \cdot \frac{\partial \hat{f}_{s}^{even}}{\partial \boldsymbol{x}} \right|^{2} \right).$$
(C2)

The notation used in Ramos (2015*a*,*b*) defined the forces F_{\perp}^{F} , $\hat{F}_{s\parallel}$ and $\hat{F}_{s\perp}$ with a sign opposite to the definitions used here, but (C 1) has been written following the standard sign convention adopted in the present paper. This quadratic form, together with the self-adjointness of F_{\perp}^{F} , implies that the squared KMHD eigenfrequencies ω^{2} are real. The term \mathcal{P} is positive because of the Cauchy–Schwarz inequality and, recalling (3.25), it can also be written as

$$\mathcal{P} = \sum_{s=i,e} \int d^3 \mathbf{x} \left(\int d^3 \mathbf{w} \left(\frac{T_{s0}}{f_{Ms0}} \right) \left| w_{\parallel} \mathbf{b}_0 \cdot \frac{\partial \hat{f}_s^{even}}{\partial \mathbf{x}} \right|^2 - \frac{|\hat{F}_{s\parallel}|^2}{m_s n_0} \right).$$
(C3)

The normal-mode drift-kinetic equation for \hat{f}_s^{odd} (3.24) yields

$$w_{\parallel} \boldsymbol{b}_{0} \cdot \frac{\partial \hat{f}_{s}^{even}}{\partial \boldsymbol{x}} = i\omega \hat{f}_{s}^{odd} - w_{\parallel} \hat{F}_{s\parallel} \quad \frac{f_{Ms0}}{n_{0} T_{s0}}$$
(C4)

and, using the property $\int d^3 w \, w_{\parallel} \, \hat{f}_s^{odd} = 0$,

$$\int \mathrm{d}^3 \boldsymbol{w} \, \frac{T_{s0}}{f_{Ms0}} \, \left| \boldsymbol{w}_{\parallel} \boldsymbol{b}_0 \cdot \frac{\partial \hat{f}_s^{even}}{\partial \boldsymbol{x}} \right|^2 = |\boldsymbol{\omega}|^2 \int \mathrm{d}^3 \boldsymbol{w} \, \frac{T_{s0} |\hat{f}_s^{odd}|^2}{f_{Ms0}} + \frac{|\hat{F}_{s\parallel}|^2}{m_s n_0}, \tag{C5}$$

therefore

$$\mathcal{P} = |\omega|^2 \sum_{s=i,e} \int d^3 x \int d^3 w \, \frac{T_{s0} |\hat{f}_s^{odd}|^2}{f_{Ms0}}.$$
 (C6)

Since ω^2 is real, $|\omega|^4 = \omega^4$. Then, substituting (C 6) in (C 1) and dividing by ω^2 , one obtains the following equivalent version of the normal-mode quadratic form

$$-\int \mathrm{d}^{3}\boldsymbol{x} \ \boldsymbol{\xi}_{\perp} \cdot \boldsymbol{F}_{\perp}^{F}[\boldsymbol{\xi}_{\perp}^{*}] + \sum_{s=i,e} \int \mathrm{d}^{3}\boldsymbol{x} \int \mathrm{d}^{3}\boldsymbol{w} \frac{T_{s0}}{f_{Ms0}} \left(|\hat{f}_{s}^{even}|^{2} - \frac{|\omega|^{2}}{\omega^{2}} |\hat{f}_{s}^{odd}|^{2} \right)$$
$$= \omega^{2} \int \mathrm{d}^{3}\boldsymbol{x} \ \rho_{0} \ \boldsymbol{\xi} \cdot \boldsymbol{\xi}^{*}. \tag{C7}$$

A single normal mode can also be a real solution of the initial-value problem (of the kind considered in the main body of this paper) if it is a growing or damped mode, so that its time dependence is $\exp(\gamma t)$ with a real $\gamma = -i\omega$ and a real eigenfunction. In this case $\xi = \xi^*$, $\hat{f}_s = \hat{f}_s^*$ and $\omega^2 = -|\omega|^2$, besides $\omega \xi = i\partial \xi/\partial t$, so the quadratic form (C 7) becomes

$$-\int \mathrm{d}^{3}\boldsymbol{x} \,\,\boldsymbol{\xi}_{\perp} \cdot \boldsymbol{F}_{\perp}^{F}[\boldsymbol{\xi}_{\perp}] + \sum_{s=i,e} \int \mathrm{d}^{3}\boldsymbol{x} \int \mathrm{d}^{3}\boldsymbol{w} \frac{T_{s0}}{f_{Ms0}} \left[(\hat{f}_{s}^{even})^{2} + (\hat{f}_{s}^{odd})^{2} \right] = -\int \mathrm{d}^{3}\boldsymbol{x} \,\,\rho_{0} \left| \frac{\partial \boldsymbol{\xi}}{\partial t} \right|^{2},$$
(C.8)

which, divided by 2, is the second-order energy conservation law (4.18)

$$\delta W[\boldsymbol{\xi}, \hat{f}_s] = -K[\partial \boldsymbol{\xi}/\partial t]. \tag{C9}$$

Appendix D. An auxiliary lemma

Let $\phi(t)$ be a differentiable real function of the real variable *t*, bounded by $0 \le \phi(t) \le \phi_{max}$ that, for $t \ge t_c \ge 0$, satisfies

$$\phi(t) \leqslant \frac{3}{t} \int_0^t dt' \,\phi(t'). \tag{D1}$$

It is to be proved next, that the behaviour as $t \to \infty$ of the function

$$\Phi(t) = \int_0^1 d\nu (3 - 4\nu)\phi(\nu t)$$
 (D 2)

is such that it either stays non-negative or tends to zero.

Differentiating with respect to t,

$$\frac{\mathrm{d}\Phi(t)}{\mathrm{d}t} = \int_0^1 \mathrm{d}\nu(3-4\nu)\frac{\partial\phi(\nu t)}{\partial t} = \int_0^1 \mathrm{d}\nu(3-4\nu)\frac{\nu}{t}\frac{\partial\phi(\nu t)}{\partial\nu} \tag{D3}$$

and, integrating by parts with respect to v,

$$\frac{d\Phi(t)}{dt} = \frac{1}{t} \left[-\phi(t) - \int_0^1 d\nu (3 - 8\nu)\phi(\nu t) \right]$$
(D4)

hence

$$t\frac{d\Phi(t)}{dt} = -\phi(t) - 2\Phi(t) + \frac{3}{t} \int_0^t dt' \,\phi(t').$$
 (D 5)

The condition (D1) implies that, for $t \ge t_c$,

$$t\frac{\mathrm{d}\Phi(t)}{\mathrm{d}t} + 2\Phi(t) \ge 0 \tag{D6}$$

and the bound $0 \le \phi(t) \le \phi_{max}$ implies that $\Phi(t)$ is bounded by $-\phi_{max}/8 \le \Phi(t) \le 9\phi_{max}/8$. Since $\Phi(t)$ is bounded, it either oscillates or tends to a limit as $t \to \infty$. If it oscillates, it must stay non-negative because otherwise there would be intervals at arbitrarily large values of t where $\Phi(t) < 0$ and $d\Phi(t)/dt < 0$, contradicting (D 6). If it tends to a limit, such limit must be positive or zero because otherwise $\lim_{t\to\infty} \Phi(t) < 0$ and $\lim_{t\to\infty} t d\Phi(t)/dt = 0$, contradicting again (D 6).

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