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The main objective of the Journal of Intelligent and Robotic Systems is to provide a forum for the fruitful interaction of ideas and techniques that combine systems and control science with artificial intelligence - and other related computer science - concepts. On the application side, the emphasis is given to industrial robotic systems, of course focusing on intelligent and sensory control problems. Papers on real applications of intelligent and robotic systems (mechatronics, manufacturing systems, biomedical systems, underwater and space applications, etc.) are most welcome. On the theoretical side, papers focusing on intelligent systems engineering, outlining new concepts and approaches in the field of intelligent systems and intelligent control are equally welcome. The journal bridges the gap between theory and practice, and stimulates interaction between workers carrying out theoretical and applied research.

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