

## CORRIGENDUM

### **Robust Bipedal Locomotion Based on a Hierarchical Control Structure – CORRIGENDUM**

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In the aforementioned article, the affiliation for Chenglong Fu and contact emails for Chenglong Fu and Jianwen Luo are incorrect:

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The authors apologise for this error.

#### **Reference**

1. Luo, J., Su, Y., Ruan, L., Zhao, Y., Kim, D., Sentis, L. and Fu, C. (2019). Robust bipedal locomotion based on a hierarchical control structure. *Robotica*, 1–18. doi:[10.1017/S0263574719000237](https://doi.org/10.1017/S0263574719000237)