

Viscous flow under an elastic sheet

Gunnar G. Peng^{1,†} and John R. Lister¹

¹Department of Applied Mathematics and Theoretical Physics, University of Cambridge,
Wilberforce Road, Cambridge CB3 0WA, UK

(Received 25 March 2020; revised 17 August 2020; accepted 3 September 2020)

We study the spreading of viscous fluid injected under an elastic sheet, which is driven by gravity and by elastic bending and tension forces and resisted by viscous forces. The injected fluid forms a large blister and spreads outwards analogously to a viscous gravity current or a capillary droplet. The relative strengths of the three driving forces are determined by how the horizontal length scales of the system compare with three key transition length scales. Bending is dominant on small length scales, tension is dominant on intermediate length scales and gravity is dominant on large length scales. We show how to use the method of matched asymptotic expansions to predict the spreading rate and thickness profile of the blister of fluid in the seven possible asymptotic regimes, for both two-dimensional and axisymmetric geometries. Consideration of different physical effects at the fluid front increases the number of regimes yet further.

Key words: lubrication theory, flow–structure interactions, contact lines

1. Introduction

Flow of viscous liquid in a deformable gap bounded by an elastic plate or membrane is ubiquitous in nature and in the laboratory. Examples include laccolith formation where magma spreads under a deformable layer of rock (Pollard & Johnson 1973), flow in the cardiovascular or respiratory system in the body (Grotberg & Jensen 2004) and flow in elastic microfluidic devices (Christov *et al.* 2018).

In this paper, we study the case where the liquid is spreading in the narrow gap between a flat rigid base and an overlying elastic sheet (Hosoi & Mahadevan 2004), which is the elastic-lidded analogue of a spreading viscous gravity current or capillary droplet. For these spreading problems, it is natural to model the bulk of the liquid using the Navier–Stokes equations with a no-slip boundary condition on the rigid base (and free slip or no slip on the upper surface, depending on whether it is a free surface or covered by the elastic lid). However, at the front of the spreading liquid, the moving contact line poses a problem since the viscous dissipation diverges as the liquid height tends to zero (Huh & Scriven 1971), and hence other physical effects must come into play near the contact line to cut off the divergence.

† Email address for correspondence: G.G.Peng@damtp.cam.ac.uk

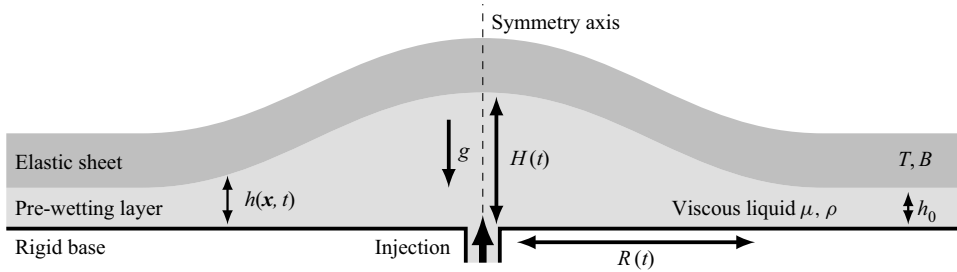


FIGURE 1. Schematic figure of fluid injected under an elastic sheet with either two-dimensional or axisymmetric geometry.

The spreading under an elastic sheet has been studied with various physical mechanisms at the moving front, including a pre-wetting film (e.g. Lister, Peng & Neufeld 2013; Hewitt, Balmforth & De Bruyn 2015), a fluid lag (e.g. Hewitt *et al.* 2015; Ball & Neufeld 2018; Wang & Detournay 2018) and elastic fracture (e.g. Bunger & Cruden 2011; Wang & Detournay 2018; Lister, Skinner & Large 2019), and sometimes with additional complications such as surface tension between two phases (e.g. Peng *et al.* 2015) or adhesive forces between the boundaries (e.g. Ball & Neufeld 2018). We focus on spreading over a pre-wetting layer of thickness h_0 , as shown in figure 1. This set-up can also be interpreted as injection in an elastic-walled Hele-Shaw cell, which has been studied by e.g. Pihler-Puzović *et al.* (2012) and Pihler-Puzović *et al.* (2018) in the context of controlling the Saffman–Taylor viscous-fingering instability.

Some aspects of this system have been studied theoretically (Flitton & King 2004; Lister *et al.* 2013; Hewitt *et al.* 2015) using the method of matched asymptotic expansions, exploiting the separation of length scales between the large central ‘blister’ of fluid, where viscous forces can be neglected, and the small ‘peeling region’ near the apparent contact line, where viscous forces are important. In the blister, the viscous pressure drop is asymptotically negligible, so the blister has a quasi-static shape analogous to the spherical-cap shape of a capillary droplet. The peeling region has a travelling-wave solution, moving outwards at some speed $\dot{R} = dR/dt$. If either bending stresses or tension forces alone are dominant, then the peeling speed depends on the apparent curvature $\kappa = d^2h/dx^2$ or slope $\alpha = -dh/dx$ at the edge of the blister solution according to the ‘peeling-by-bending’ or ‘peeling-by-pulling’ laws (see e.g. Lister *et al.* 2013)

$$\dot{R} = 0.472 \frac{Bh_0^{1/2} \kappa^{5/2}}{12\mu} \quad \text{or} \quad \dot{R} = \frac{T\alpha^3}{12\mu \ln[(R/\ell_p)^3]}, \quad (1.1a,b)$$

respectively, where μ is the dynamic viscosity of the fluid, B is the bending stiffness of the sheet, T is the tension in the sheet and ℓ_p is the length scale of the peeling region. (The peeling-by-pulling law (1.1b) is the elastic analogue of the Cox–Voinov law (Voinov 1976; Cox 1986) for capillary spreading.) Integration of the resulting differential equation then yields the spreading law $R(t)$ for the blister at late times when any initial transient behaviour has become irrelevant.

The aim of this paper is to unify and extend the work by Lister *et al.* (2013) and Hewitt *et al.* (2015). These studies considered various, but not all, combinations of bending, tension and gravitational forces and were restricted to the case of constant injection flux. We will, for both two-dimensional and axisymmetric geometries, systematically identify all the possible asymptotic combinations, revealing a rich variety of different behaviours. We calculate the asymptotic spreading laws $R(t)$ for each case, while allowing fluid to

		Viscous control with cut-off . . .			
		. . . height	. . . pressure	. . . length	Energy control
Two-dimensional	B	$(5\beta + 2)/17$	$(7\beta + 2)/23$	$(3\beta + 1)/10$	$\beta/3$
	BT	$(5\beta + 2)/12$	$(7\beta + 2)/16$	$(3\beta + 1)/7$	$\beta/2$
	T	$(3\beta + 1)/7^*$	$(3\beta + 1)/7^*$	$(3\beta + 1)/7^*$	
	BG	$(5\beta + 2)/7$	$(7\beta + 2)/9$	$(3\beta + 1)/4$	β
	BTG				
	TG	$(3\beta + 1)/4^*$	$(3\beta + 1)/4^*$	$(3\beta + 1)/4^*$	
	G	$(3\beta + 1)/5$	$(3\beta + 1)/5$	$(3\beta + 1)/5$	
Axisymmetric	B	$(5\beta + 2)/22$	$(7\beta + 2)/30$	$(3\beta + 1)/13$	$\beta/4$
	BT	$(5\beta + 2)/17$	$(7\beta + 2)/23$	$(3\beta + 1)/10$	$\beta/3$
	T	$(3\beta + 1)/10^*$	$(3\beta + 1)/10^*$	$(3\beta + 1)/10^*$	
	BG	$(5\beta + 2)/12$	$(5\beta + 2)/16$	$(3\beta + 1)/7$	$\beta/2$
	BTG				
	TG	$(3\beta + 1)/7^*$	$(3\beta + 1)/7^*$	$(3\beta + 1)/7^*$	
	G	$(3\beta + 1)/8$	$(3\beta + 1)/8$	$(3\beta + 1)/8$	

TABLE 1. Summary of results in this paper for various asymptotic limits, showing the exponent δ in $R(t) \propto t^\delta$ for various cases in two-dimensional and axisymmetric geometries with power-law injection rates (i.e. $V(t) \propto t^\beta$). See the discussion in § 8. The mechanism driving the spreading is either bending (B), tension (T), gravity (G) or a combination as seen in figure 2. For viscously controlled peeling by pulling, there is also a logarithmic factor (indicated by an asterisk). In each column, cases with the same exponent and numerical prefactor are grouped together.

be injected at an arbitrary power-law rate (which also includes the important case of constant-volume spreading).

A possible complicating factor is that the deflection of the elastic sheet also causes it to stretch and hence generates tension in the sheet, which is additional to the original constant tension imposed externally by the far-field boundary conditions. This additional tension is studied using the Föppl–von-Kármán equations in Peng & Lister (2020), so is assumed to be negligible here for simplicity. The condition for its neglect is discussed briefly in § 8.2.

This paper is laid out as follows. We present the governing equations in § 2. The pressure driving the flow is coupled to the liquid height by bending, tension and gravitational forces. We identify three key transition length scales that determine which combination of forces is dominant and determine the full regime diagram in § 3. We then investigate the key travelling-wave peeling solutions (§ 4), and combine them with quasi-static blister solutions to obtain asymptotic predictions for each possible combination of dominant driving forces (§ 5). The asymptotic results are verified against numerical results in § 6, and some further regimes are identified in § 7. The main points are summarized in § 8, and several generalizations of the asymptotic analysis, including to different physical controls of the peeling front, are discussed. The extraordinary variety of asymptotic results is shown in table 1, and the different regimes are shown schematically in figures 2 and 5.

2. Governing equations

We consider the situation shown in figure 1. Viscous liquid fills the narrow gap, of initial height h_0 , between a horizontal rigid lower boundary and a thin overlying elastic sheet. The liquid has dynamic viscosity μ and density ρ , and is acted on by gravity (acceleration g). The sheet has bending stiffness $B = Ed^3/12(1 - \nu^2)$, where E is the

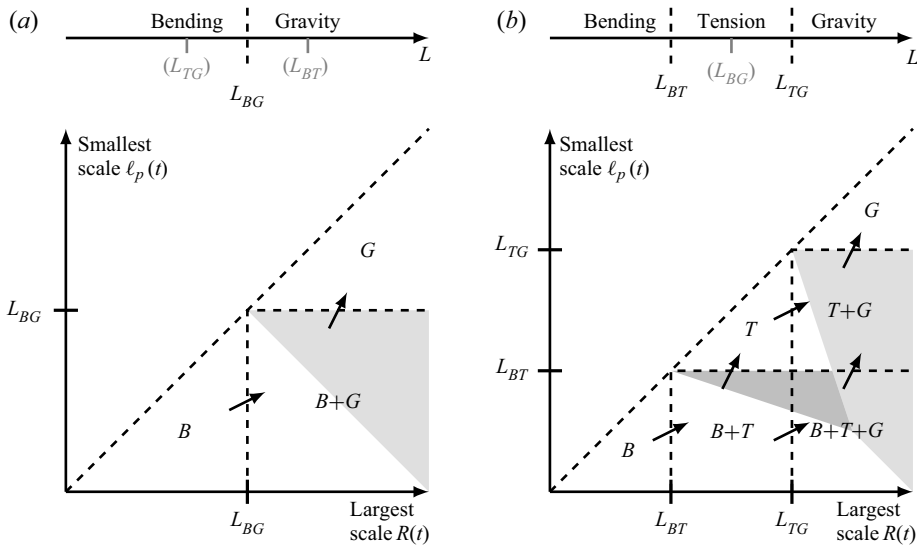


FIGURE 2. Schematic regime diagrams showing the succession of dominant terms in (2.3) (on logarithmic axes) for the cases (a) $L_{TG} \ll L_{BT}$ and (b) $L_{BT} \ll L_{TG}$, with $L_{BG} = (L_{BT}L_{TG})^{1/2}$. Main panels show which regime (combination of dominant terms) the system is in for different values of the largest scale R and the smallest scale ℓ_p of the system. The arrows show possible transitions between regimes as $R(t)$ increases (moving to the right) for the case that $\ell_p(t)$ increases (moving upwards). The main discussion in this paper covers the unshaded areas, while the shaded areas are discussed in § 7.1. Arrows above main panels show the transition lengths (3.2) and which term dominates on a length scale L .

Young’s modulus, ν is the Poisson’s ratio and d is the thickness of the sheet, and is also under an imposed tension T . We assume that these quantities are all constant.

The vertical length scales of the system are assumed to be small compared with the horizontal length scales, so that vertically integrated or averaged quantities can be employed, which are functions of the horizontal position vector $\mathbf{x} = (x, y)$ and time t . (All vectors and tensors here have only horizontal components.) We consider both two-dimensional (2-D) and axisymmetric (axi) geometries. For the two-dimensional geometry, we assume that fluid is injected along a line source $x = 0$ and spreads symmetrically in the x -direction. For the axisymmetric geometry, we define the radial coordinate $r = |\mathbf{x}|$ and assume that fluid is injected at the origin $r = 0$ and spreads axisymmetrically in the r -direction. We use ∇ to denote the horizontal gradient operator, primes to denote differentiation with respect to the main horizontal coordinate x or r , and overdots to denote differentiation with respect to time.

We seek to predict the evolution of the cell height profile $h(\mathbf{x}, t)$ (i.e. the thickness of the fluid layer), which for simplicity we often write as $h(x)$ or $h(r)$, leaving the dependence on t understood. We focus in particular on the height and radius of the blister of injected fluid, defined by

$$H(t) = h(\mathbf{0}, t), \quad R(t) = \min\{|\mathbf{x}| : h(\mathbf{x}, t) = h_0\}. \tag{2.1a,b}$$

(In (2.1b) we have chosen to define the blister radius as the distance from the origin to the closest point at which $h = h_0$. The deflection $h - h_0$ typically has decaying oscillations in $|\mathbf{x}| > R$ and there are other reasonable choices, for example the distance to the closest minimum of h , but the difference is negligible at late times.)

The net upward pressure p_e on the sheet and the deflection $h - h_0$ of the sheet are coupled by the Föppl–von-Kármán equations (e.g. Landau & Lifshitz 1986), which for constant imposed tension T simplify to

$$p_e = B\nabla^4 h - T\nabla^2 h. \quad (2.2)$$

The two terms describe, respectively, the effects of induced bending stresses (cf. the Euler beam equation) and imposed tension (cf. the Young–Laplace equation) in the sheet.

We model the viscous flow using lubrication theory (Reynolds 1886). The lubrication flow is driven by horizontal gradients in the pressure field, so we can leave out pressure contributions that have no horizontal gradient, such as the atmospheric pressure, the weight of the sheet, and the vertical hydrostatic variation. The resulting effective pressure $p(\mathbf{x}, t)$, hereafter referred to as just ‘the pressure’, is due both to the elastic forces in the sheet and to the net hydrostatic pressure

$$p = p_e + \rho gh = B\nabla^4 h - T\nabla^2 h + \rho gh. \quad (2.3)$$

We neglect any horizontal motion of the overlying sheet, and obtain a parabolic Poiseuille-flow profile. This yields the depth-integrated flux $\mathbf{q}(\mathbf{x}, t)$, from which the evolution of the height profile is found by mass conservation,

$$\mathbf{q} = -\frac{h^3}{12\mu}\nabla p, \quad \dot{h} = -\nabla \cdot \mathbf{q} = \nabla \cdot \left(\frac{h^3}{12\mu}\nabla p \right). \quad (2.4a,b)$$

Equations (2.3) and (2.4) are supplemented by far-field conditions for decay to the undisturbed pre-wetting film and symmetry conditions at the origin

$$h \rightarrow h_0, \quad p \rightarrow \rho gh_0 \text{ as } x \text{ or } r \rightarrow \infty, \quad h'(0) = h'''(0) = 0. \quad (2.5a,b)$$

The volume $V(t)$ of injected fluid is assumed to follow a power law,

$$\text{2-D: } \int_0^\infty (h - h_0) dx = V(t) = Qt^\beta, \quad \text{Axi: } \int_0^\infty (h - h_0) 2\pi r dr = V(t) = Qt^\beta, \quad (2.6a,b)$$

with an injection exponent $\beta \geq 0$. (In the two-dimensional case, $V(t)$ denotes the volume per unit width in the third dimension in the region $x \geq 0$, which is half the total amount by symmetry.) The injection flux at the origin is thus given by

$$\text{2-D: } q_x = -\frac{h^3}{12\mu}p' = \dot{V} \text{ at } x = 0, \quad \text{Axi: } q_r = -\frac{h^3}{12\mu}p' \sim \frac{\dot{V}}{2\pi r} \text{ as } r \rightarrow 0. \quad (2.7a,b)$$

We use the initial condition $h = h_0$ at $t = 0$, except that for $\beta = 0$ (constant volume) the injected volume is initially localized to a very small region near the origin.

3. Scaling analysis and transition lengths

We first need to determine which of bending, tension and gravity are dominant, and which can be neglected. In a region with height scale H and length scale L , the scales for the bending, tension and gravitational pressure terms in (2.3) are

$$p \sim \frac{BH}{L^4}, \quad \frac{TH}{L^2} \quad \text{and} \quad \rho gH, \quad (3.1)$$

respectively. Balancing these pairwise reveals three key length scales which we term the bending–tension length, the bending–gravity length and the tension–gravity length,

respectively,

$$L_{BT} = (B/T)^{1/2}, \quad L_{BG} = (B/\rho g)^{1/4}, \quad L_{TG} = (T/\rho g)^{1/2}. \quad (3.2a-c)$$

These length scales are analogous to the capillary length $(\gamma/\rho g)^{1/2}$ for capillary spreading. The bending term dominates on small length scales ($L \ll L_{BT}, L_{BG}$), the gravity term dominates on large length scales ($L \gg L_{BG}, L_{TG}$) and the tension term dominates on medium length scales ($L_{BT} \ll L \ll L_{TG}$, if this interval exists).

Since $L_{BG} = (L_{BT}L_{TG})^{1/2}$ lies between L_{BT} and L_{TG} , the three transition lengths can only be ordered either as $L_{TG} \leq L_{BG} \leq L_{BT}$ or as $L_{BT} \leq L_{BG} \leq L_{TG}$. Thus, there are two asymptotic limits to consider: If $L_{TG} \ll L_{BG} \ll L_{BT}$ (or equivalently $T^2 \ll B\rho g$), then bending is dominant for $L \ll L_{BG}$ and gravity is dominant for $L_{BG} \ll L$, as shown in [figure 2\(a\)](#), while tension is always negligible. On the other hand, if $L_{BT} \ll L_{BG} \ll L_{TG}$ (or equivalently $T^2 \gg B\rho g$), then bending is dominant for $L \ll L_{BT}$, tension is dominant for $L_{BT} \ll L \ll L_{TG}$, and gravity is dominant for $L_{TG} \ll L$, as shown in [figure 2\(b\)](#).

At any given time, the horizontal length scales in the system span the range from the large blister radius $R(t)$ down to the small length scale $\ell_p(t)$ of the peeling region (see § 4), which can be represented as a point (R, ℓ_p) in a two-dimensional regime diagram ([figure 2](#)). The diagram can then be divided into regimes according to which forces are dominant, which is determined by how ℓ_p and R compare to the transition lengths L_{BT}, L_{BG} and L_{TG} .

In [figure 2\(a\)](#), for example, if both ℓ_p and R are smaller than L_{BG} , then all length scales in the system are too, so only bending forces are dominant. We refer to this regime as the ‘pure’ bending regime. Similarly, if both are larger than L_{BG} , then only gravity is dominant. However, if $\ell_p \ll L_{BG} \ll R$, then bending is dominant in the parts of the system where the length scale is $\ll L_{BG}$, while gravity is dominant in the parts where the length scale is $\gg L_{BG}$, so we have a ‘hybrid’ bending–gravity regime.

Since the fluid spreads and $R(t)$ increases with time, the system moves towards the right in the regime diagram ([figure 2](#)). For ease of discussion, we focus on the case where $\ell_p(t)$ also increases with time, so that the system also moves upwards in the diagram. We shall see that this case corresponds to a decreasing peeling speed \dot{R} and thus to a condition that the injection exponent β is not too large. (For sufficiently large β , \dot{R} increases and $\ell_p(t)$ decreases with time, and the system moves downwards in the diagram instead.) Moving rightwards and upwards in the diagram, the system generally evolves from being purely bending dominated at very early times to being purely gravity dominated at very late times, passing through a number of intervening hybrid, or possibly tension-dominated, regimes at intermediate times.

Since $R(t)$ and $\ell_p(t)$ are not known *a priori*, our approach is to solve for each regime first, before determining its temporal range of validity. In § 4 we analyse the peeling region on the scale ℓ_p , and in § 5 we analyse the blister shape and determine the spreading law $R(t)$ in the various regimes.

4. Travelling-wave peeling solutions

We consider the asymptotic limit $h_0 \ll H$ where the pre-wetting layer is very thin relative to the thickness of the fluid that has been injected. This results in different parts of the system having asymptotically different scales, as shown in [figure 3](#). The blister $x < R$ (or $r < R$) is the largest region, with height $H(t)$ and radius $R(t)$. Near its edge $x \approx R$ (or $r \approx R$) at the apparent contact line we expect to find a peeling region with height scale $h_0 \ll H$ and some length scale $\ell_p(t) \ll R$ to be determined.

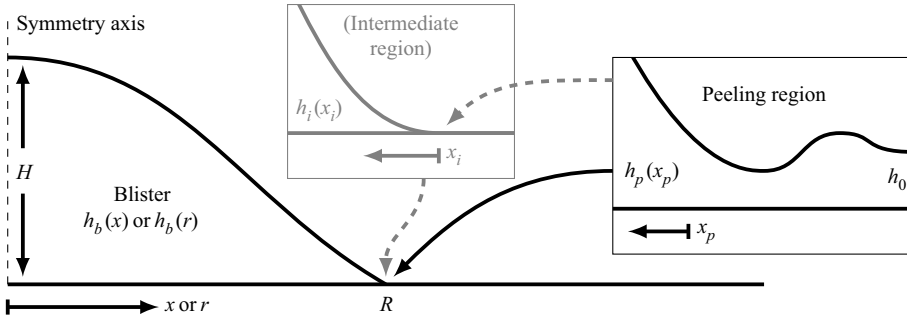


FIGURE 3. Schematic figure of the asymptotic structure. The large blister has a small peeling region at its edge $x = R$ or $r = R$. For the hybrid cases where multiple driving forces are dominant, the peeling region is nested inside an intermediate region (dashed arrows). The variables h_b , h_p and h_i and local coordinates x_p and x_i are used to describe the leading-order asymptotic solutions in each region.

In the peeling region, we define the leading-order solution $h = h_p(x_p)$, where $x_p = R(t) - x$ or $x_p = R(t) - r$ is an inward-pointing local coordinate. The scaling $x_p \sim \ell_p \ll R$ allows two approximations. Firstly, regardless of the global geometry (2-D or axi), the leading-order local peeling process is two-dimensional, with no variation in the horizontal direction transverse to the direction of motion. Secondly, in the time derivative $\partial h / \partial t = \partial h_p / \partial t + \dot{R} \partial h_p / \partial x_p$ the second term, due to the outward spreading motion, is dominant by a factor of order R / ℓ_p (assuming that $\dot{R} \sim R / t$). Neglecting the first term allows the governing equation (2.4b) to be integrated once, with far-field condition $h_p(-\infty) = h_0$, to yield the travelling-wave equation

$$\dot{R}(h_p - h_0) = \frac{h_p^3}{12\mu} (Bh_p'''' - Th_p''' + \rho gh_p'). \tag{4.1}$$

Given the value of \dot{R} , the peeling length scale ℓ_p is determined by balancing the terms on the left-hand side with the relevant term or terms on the right-hand side. If one of the three terms is dominant, then ℓ_p is given by one of the expressions

$$\ell_{pB} = \left(\frac{Bh_0^3}{12\mu\dot{R}} \right)^{1/5}, \quad \ell_{pT} = \left(\frac{Th_0^3}{12\mu\dot{R}} \right)^{1/3}, \quad \ell_{pG} = \frac{\rho gh_0^3}{12\mu\dot{R}}. \tag{4.2a-c}$$

Which of these expressions is the relevant one is determined by comparing them to the transition length scales (3.2). For example, if \dot{R} is very large, then all the options in (4.2) are smaller than L_{BG} and L_{BT} , so the only self-consistent possibility is that bending is dominant and $\ell_p = \ell_{pB}$. As \dot{R} decreases, the length scales all increase and either tension becomes dominant instead due to both ℓ_{pB} and ℓ_{pT} crossing L_{BT} , leading to $\ell_p = \ell_{pT}$, or gravity becomes dominant instead due to both ℓ_{pB} and ℓ_{pG} crossing L_{BG} , leading to $\ell_p = \ell_{pG}$.

When a single term on the right-hand side of (4.1) is dominant, we can introduce the non-dimensionalization $h_p = h_0 F(X \equiv x_p / \ell_p)$, which yields the travelling-wave equations

$$F - 1 = F^3 F''''', \quad F - 1 = -F^3 F''', \quad F - 1 = F^3 F', \tag{4.3a-c}$$

for bending, tension and gravity, respectively. These are supplemented by the far-field condition and a choice of origin

$$F \rightarrow 1 \text{ as } X \rightarrow -\infty, \quad 0 = \max\{X : F(X) = 1\}, \tag{4.4a,b}$$

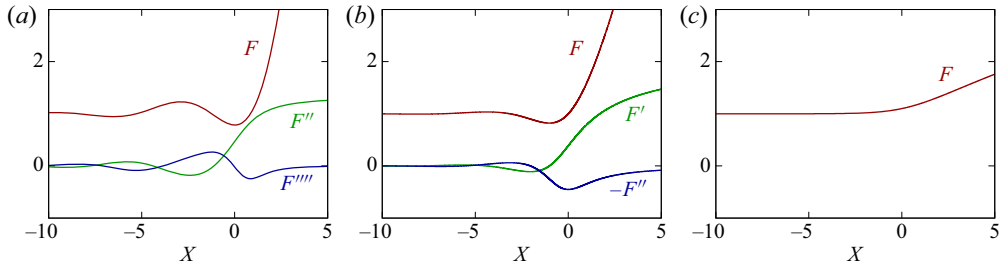


FIGURE 4. Asymptotic travelling-wave peeling solutions for (a) bending (showing the rescaled height F , curvature F'' and pressure F'''), (b) tension (showing the rescaled height F , slope F' and pressure $-F''$) and (c) gravity (showing the rescaled height or pressure F).

from (2.5a) and (2.1b), respectively, as well as suitable matching conditions to the blister as $X \rightarrow \infty$, as stated below.

4.1. Peeling by bending

For the fifth-order peeling-by-bending equation (4.3a), the condition (4.4a) excludes two growing solutions and (4.4b) is a third condition, so we can further impose the two far-field conditions

$$F'''' , F''' \rightarrow 0 \text{ as } X \rightarrow \infty, \tag{4.5}$$

which excludes the generic quartic growth of solutions to (4.3a) in favour of a slower quadratic growth. This yields a unique solution, which can be calculated numerically (Lister *et al.* 2013) and is shown in figure 4(a). The solution has a quadratic far-field behaviour $F'' \rightarrow C_p$ as $X \rightarrow \infty$, with $C_p \approx 1.350507$. In order to match, the leading-order blister solution $h = h_b$ must also have a quadratic behaviour near the apparent contact line, i.e. satisfy clamped conditions and have a non-zero curvature κ ,

$$h_b(R) = h'_b(R) = 0, \quad \kappa = h''_b(R). \tag{4.6a,b}$$

(These conditions are seen in § 5 to yield a unique solution for the blister, and matching to a different peeling solution with quartic or cubic far-field behaviour would not be possible.) Matching the curvature at the edge of the blister to that of the peeling solution yields

$$\kappa = C_p \frac{h_0}{\ell_{pB}^2} \Rightarrow \dot{R} = 0.471800 \frac{Bh_0^{1/2}}{12\mu} \kappa^{5/2}, \tag{4.7}$$

from (4.2a), as stated in (1.1a).

4.2. Peeling by pulling

For the third-order peeling-by-pulling equation (4.3b), the condition (4.4a) excludes one growing solution and (4.4b) is a second condition, so we can further impose (in analogy with (4.5)) the one condition that

$$F'' \rightarrow 0 \text{ as } X \rightarrow \infty. \tag{4.8}$$

This yields a unique solution, which can be calculated numerically and is shown in figure 4(b). The leading-order far-field behaviour can be determined analytically from the

large- F approximation of (4.3b), $1 \approx -F^2 F'''$, as

$$F \sim X(3 \ln X)^{1/3}, \quad F' \sim (3 \ln X)^{1/3} \quad \text{as } X \rightarrow \infty. \quad (4.9)$$

The far-field slope F' varies with X , but logarithmically slowly, so, in matching with the blister region with length scale R , we can use the value of F' evaluated at $X = R/\ell_{pT}$.

In order for the blister solution to match the approximately linear behaviour (4.9), we require zero height and a non-zero slope α near the contact line,

$$h_b(R) = 0, \quad \alpha = -h'_b(R). \quad (4.10a,b)$$

Comparison with (4.9) evaluated at $X = R/\ell_{pT}$ yields

$$\alpha = \left(3 \ln \frac{R}{\ell_{pT}}\right)^{1/3} \frac{h_0}{\ell_{pT}} \Rightarrow \dot{R} = \frac{T\alpha^3}{12\mu \ln[(R/\ell_{pT})^3]}, \quad (4.11)$$

as given in (1.1b). This expression has a weak logarithmic dependence on ℓ_{pT} and hence on \dot{R} . In order to solve for \dot{R} explicitly, we can make use of the Lambert W -function, which we denote by $\ln_*(x)$ due to its similarity with $\ln(x)$. This is defined by

$$\ln_*(x)e^{\ln_*(x)} = x, \quad \ln_*(x) = \ln x + O(\ln \ln x) \quad \text{as } x \rightarrow \infty. \quad (4.12)$$

We then obtain, from (4.11) and (4.2b),

$$\dot{R} = \frac{T\alpha^3}{12\mu \ln_*[(R\alpha/h_0)^3]}. \quad (4.13)$$

4.3. Peeling by gravitational spreading

For the first-order gravity-current equation (4.3c), the peeling process is simply gravitational spreading of the fluid under the sheet. The general solution is given implicitly by

$$X - X_0 = \ln(F - 1) + F + \frac{F^2}{2} + \frac{F^3}{3}, \quad (4.14)$$

which automatically satisfies the condition (4.4a) leaving only the choice of origin X_0 . In this case, the origin cannot be chosen using (4.4b) since $F > 1$ everywhere (the solution approaches $F = 1$ monotonically rather than in an oscillatory manner as $X \rightarrow -\infty$), but we can instead choose, for example, $F(0) = 1.1$, which corresponds to $X_0 \approx 0.154$. This solution is shown in figure 4(c).

For matching with the blister solution, we would expect, by analogy with the bending and tension cases, to use just the height F . Requiring h_b to match the cube-root behaviour $F \sim (3X)^{1/3}$ as $X \rightarrow \infty$ yields

$$\dot{R} = -\frac{\rho g}{12\mu} h_b^2(R) h'_b(R), \quad (4.15)$$

which describes conservation of flux at the apparent contact line.

5. Quasi-static blister solutions and resulting spreading rates

For peeling by bending (4.7) and peeling by pulling (4.13), the peeling speed \dot{R} decreases as h_0 decreases, and *a posteriori* scaling analyses (see § 7) show that if $h_0 \ll H$ then the spreading is sufficiently slow that the pressure drop in the bulk of the large blister is asymptotically negligible. The large blister region then evolves quasi-statically and its shape can be determined analytically. In this section, we perform these calculations and use (4.7) and (4.13) to obtain the spreading rate $R(t)$ in the various regimes shown in the regime diagrams in figure 2 (but restricted to the unshaded areas). We also discuss the non-quasi-static gravity-dominated case in § 5.8.

5.1. The general blister solution

We assume that the viscous pressure drop in the bulk of the blister is asymptotically negligible, and hence the pressure in the blister is spatially uniform, $p = p_b(t)$, to leading order. Equivalently, pressure variations in the blister region are quickly equilibrated, owing to the large mobility $h^3/12\mu$ in the blister, and hence on the much slower time scale of spreading the pressure is approximately uniform.

The asymptotic leading-order blister solution $h = h_b$ is thus obtained by solving the equation

$$p_b(t) = B\nabla^4 h_b - T\nabla^2 h_b + \rho gh_b, \tag{5.1}$$

(where some of the terms on the right-hand side may be negligible) with a simplified volume constraint (2.6),

$$\text{2-D: } \int_0^R h_b \, dx = V(t) = Qt^\beta, \quad \text{Axi: } \int_0^R h_b 2\pi r \, dr = V(t) = Qt^\beta, \tag{5.2a,b}$$

symmetry conditions (2.5b),

$$h'_b(0) = h'''_b(0) = 0, \tag{5.3}$$

and suitable matching conditions to the peeling solution at the apparent contact line $x = R$ or $r = R$ as follows.

For peeling by bending (§ 4.1), where the fourth-order bending term in (5.1) is dominant near the contact line, we use the conditions $h_b(R) = h'_b(R) = 0$ from (4.6). For peeling by pulling (§ 4.2), where the second-order tension term in (5.1) is dominant near the contact line (and hence the fourth-order term is negligible everywhere), we use the condition $h_b(R) = 0$ from (4.10). Finally, if gravity is dominant near the contact line (§ 4.3), then it turns out that the blister is not quasi-static (see § 5.8).

The general solutions of the blister equations (5.1)–(5.3) with these boundary conditions involve hyperbolic or Bessel functions. The expressions are given in appendix B and some representative results are shown in figure 5. The solutions yield the curvature κ or slope α at the edge of the blister in terms of R , t and the parameters of the system, which when combined with the peeling-by-bending (4.7) or peeling-by-pulling (4.13) law for \dot{R} can be integrated to yield $R(t)$. However, in order to understand the physics better, we solve the blister equations here using asymptotic methods in each of the regimes indicated in figure 2 to obtain the relevant values of κ or α as well as power-law expressions for $R(t)$ in each regime.

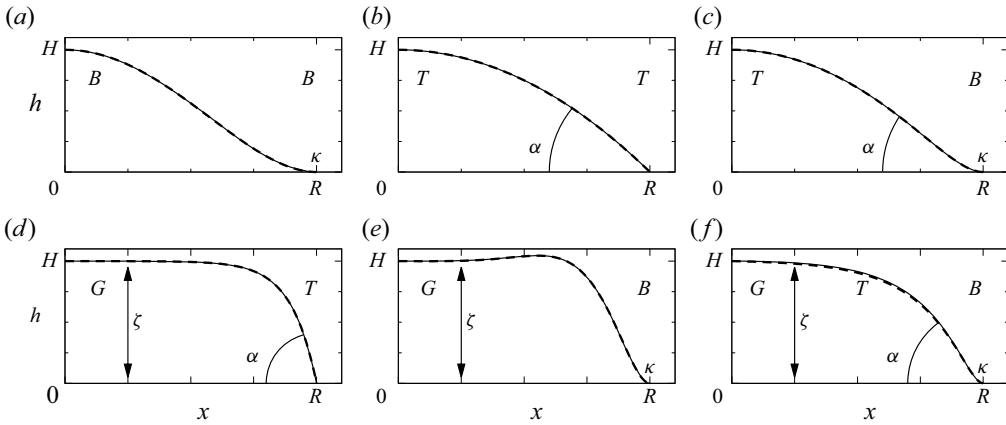


FIGURE 5. Representative two-dimensional quasi-static blister height profiles, comparing the full solutions (B 1) and (B 2) (solid curves) and the asymptotic solutions (dashed curves). The regime name, subsection and values of $(L_{BT}/R, L_{BG}/R, L_{TG}/R)$ for each case are (a) ‘B’, § 5.2, (5,5,5); (b) ‘T’, § 5.3, (0,0,5); (c) ‘B + T’, § 5.4, (0.1,1,10); (d) ‘T + G’, § 5.5, (0,0,0.1); (e) ‘B + G’, § 5.6, (0.01,0.1,1); (f) ‘B + T + G’, § 5.7, (0.04,0.2^{3/2},0.2). The asymptotic solutions are given by the main blister solutions (5.4), (5.6) and composites (5.11), (5.14), (5.16) and (5.18). The letters indicate which term dominates in the bulk of the blister, in the peeling region, and in an intermediate region (if present). The key quantities – curvature $\kappa = h''$ (associated with bending), slope $\alpha = -h'$ (associated with tension) and height $\zeta = h$ (associated with gravity) – are labelled.

5.2. Bending only (regime ‘B’)

First, if $R \ll L_{BG}, L_{BT}$ then bending is dominant everywhere and (5.1) reduces to $p_b = B\nabla^4 h_b$. Together with (5.2), (5.3) and (4.6), this yields the blister profile h_b , pressure p_b and peeling curvature $\kappa = h''_b(R)$ as

$$2\text{-D: } h_b = \frac{15}{8} \frac{V}{R} \left(1 - \frac{x^2}{R^2}\right)^2, \quad \frac{p_b}{B} = 45 \frac{V}{R^5}, \quad \kappa = 15 \frac{V}{R^3}, \tag{5.4a}$$

$$\text{Axi: } h_b = \frac{3}{\pi} \frac{V}{R^2} \left(1 - \frac{r^2}{R^2}\right)^2, \quad \frac{p_b}{B} = \frac{192}{\pi} \frac{V}{R^6}, \quad \kappa = \frac{24}{\pi} \frac{V}{R^4}, \tag{5.4b}$$

in agreement with the sample solution of (B 1) shown in figure 5(a).

We substitute the curvature κ into the peeling-by-bending law (4.7) and integrate the differential equation to find the spreading rate

$$2\text{-D: } \dot{R} = 411 \frac{Bh_0^{1/2} Q^{5/2} t^{5\beta/2}}{12\mu R^{15/2}} \Rightarrow R(t) = 2.83 \left(\frac{B^2 h_0 Q^5 t^{5\beta+2}}{(5\beta+2)^2 (12\mu)^2} \right)^{1/17}, \tag{5.5a}$$

$$\text{Axi: } \dot{R} = 76.1 \frac{Bh_0^{1/2} Q^{5/2} t^{5\beta/2}}{12\mu R^{10}} \Rightarrow R(t) = 1.96 \left(\frac{B^2 h_0 Q^5 t^{5\beta+2}}{(5\beta+2)^2 (12\mu)^2} \right)^{1/22}. \tag{5.5b}$$

In this case and the following ones, once the spreading rate $R(t)$ is known, the blister height $H(t)$ and pressure $p_b(t)$ can be calculated from the appropriate blister solution if required.

5.3. Tension only (regime ‘T’)

If $L_{BT} \ll (R, \ell_p) \ll L_{TG}$, then tension is dominant everywhere. Equation (5.1) reduces to $p_b = -T\nabla^2 h_b$, which is of lower order than (5.1), so we can only impose a single symmetry condition $h'_b(0) = 0$, together with $h_b(R) = 0$. The solution, which has a slope $\alpha = -h'_b(R)$ at the edge, is

$$2\text{-D: } h_b = \frac{3}{2} \frac{V}{R} \left(1 - \frac{x^2}{R^2}\right), \quad \frac{p_b}{T} = 3 \frac{V}{R^3}, \quad \alpha = 3 \frac{V}{R^2}, \tag{5.6a}$$

$$\text{Axi: } h_b = \frac{2}{\pi} \frac{V}{R^2} \left(1 - \frac{r^2}{R^2}\right), \quad \frac{p_b}{T} = \frac{8}{\pi} \frac{V}{R^4}, \quad \alpha = \frac{4}{\pi} \frac{V}{R^3}, \tag{5.6b}$$

in agreement with figure 5(b).

Substitution of α into the peeling-by-pulling law (4.13) yields a differential equation for $R(t)$, which can be integrated at leading order by approximating the logarithmic factor \ln_* in (4.13) as a constant. The leading-order result is

$$2\text{-D: } R(t) = 2.29 \left(\frac{TQ^3 t^{3\beta+1}}{(3\beta + 1)12\mu \ln_*[(12\mu Q^4 t^{4\beta-1}/Th_0^7)^{3/4}]} \right)^{1/7}, \tag{5.7a}$$

$$\text{Axi: } R(t) = 1.48 \left(\frac{TQ^3 t^{3\beta+1}}{(3\beta + 1)12\mu \ln_*[(12\mu Q^2 t^{2\beta-1}/Th_0^5)^{3/2}]} \right)^{1/10}. \tag{5.7b}$$

We have neglected an $O(1)$ numerical factor inside the argument of each \ln_* in (5.7) as it represents only a higher-order correction. Determining the values of these $O(1)$ factors requires not only more careful integration of the differential equation, but also evaluation of corrections to the blister solution (due to the viscous pressure drop in the blister) and to the far-field behaviour of the peeling solution; the details are somewhat complicated and are given in appendix C.

5.4. Bending and tension (regime ‘B + T’)

When $\ell_p \ll L_{BT} \ll R \ll L_{TG}$, bending is dominant on the peeling length scale $\ell_p = \ell_{pB}$, while tension is dominant on main scale R of the blister. Hence, the peeling-by-bending solution (4.7) and the tension-dominated blister solution (5.6) apply. Since this blister solution has a non-zero slope $\alpha = -h'(R)$, it does not satisfy the clamping condition $h'(R) = 0$ required for direct matching, so there must be an intermediate region near the apparent contact line, on the length scale L_{BT} where tension and bending balance.

For the intermediate solution, we define the leading-order solution h_i and local coordinate x_i (which is equal to x_p) by

$$h = h_i(x_i), \quad x_i = R(t) - x \text{ (2-D)} \quad \text{or} \quad x_i = R(t) - r \text{ (axi)}. \tag{5.8}$$

In the blister equation (5.1), the constant pressure $p_b \sim T\alpha/R$ is set by the main solution (5.6). This pressure is negligible on the intermediate scale, where the bending and tension terms are much larger, scaling like $T\alpha/L_{BT}$ (from $x_i \sim L_{BT} \ll R$ and $h_i \sim \alpha x_i$). Thus, the leading-order problem on the intermediate scale is

$$Bh_i'''' - Th_i'' = 0, \quad h_i(0) = h'_i(0) = 0, \quad h'_i(\infty) = \alpha, \tag{5.9}$$

representing the role of bending in effecting the transition from clamped conditions at $x_i = 0$ to a non-zero slope α as $x_i \rightarrow \infty$. The unique solution of (5.9) is

(e.g. Lister *et al.* 2013)

$$h_i(x_i) = \alpha L_{BT} \left[\frac{x_i}{L_{BT}} + (e^{-x_i/L_{BT}} - 1) \right], \quad \kappa = h_i''(0) = \frac{\alpha}{L_{BT}}. \quad (5.10a,b)$$

For comparison with the full solution (B 1), we can form composite solutions of (5.6) and (5.10). For the two-dimensional case, after rescaling by the blister height, the additive composite is given by

$$h = H \frac{1 - (x/R)^2 + 2(L_{BT}/R)(e^{-(R-x)/L_{BT}} - 1)}{1 + 2(L_{BT}/R)(e^{-R/L_{BT}} - 1)}, \quad (5.11)$$

and is in good agreement with the full solution, as shown in figure 5(c). The axisymmetric case can be treated similarly.

The effect of the bending–tension intermediate solution is to convert the slope α given by the main blister solution (5.6) to a curvature $\kappa = \alpha/L_{BT}$ that matches with the peeling region. Substitution into the peeling-by-bending law (4.7) yields, after integration,

$$\text{2-D: } R(t) = 2.11 \left(\frac{T^5 h_0^2 Q^{10} t^{10\beta+4}}{(5\beta+2)^4 (12\mu)^4 B} \right)^{1/24}, \quad (5.12a)$$

$$\text{Axi: } R(t) = 1.37 \left(\frac{T^5 h_0^2 Q^{10} t^{10\beta+4}}{(5\beta+2)^4 (12\mu)^4 B} \right)^{1/34}. \quad (5.12b)$$

For this and the other hybrid solutions calculated below in § 5, the results only apply in the unshaded areas of the regime diagram (figure 2), as the assumption that the pressure is approximately uniform throughout the blister fails in the shaded areas. We discuss this issue further in § 7.

5.5. Tension and gravity (regime ‘T + G’)

Gravity is dominant on the main scale R of the blister if $R \gg L_{BG}, L_{TG}$. This reduces (5.1) to the trivial equation $p_b = \rho g h_b$, resulting in a flat-topped profile with constant height ζ ,

$$\text{2-D: } h_b(x) = \frac{p_b}{\rho g} = \zeta = \frac{V}{R}, \quad \text{Axi: } h_b(r) = \frac{p_b}{\rho g} = \zeta = \frac{1}{\pi} \frac{V}{R^2}, \quad (5.13a,b)$$

which again agrees with (B 1) and figure 5(d–f). However, this solution cannot match (4.6) or (4.10) directly.

If $L_{BT} \ll \ell_p \ll L_{TG} \ll R$, then tension dominates in the peeling region (while bending is negligible everywhere). At the edge of the gravity-dominated blister (5.13), there is need for a tension–gravity intermediate solution $h_i(x_i)$ on the scale L_{TG} , which satisfies $-Th_i'' + \rho g h_i = p_b = \rho g \zeta$ with the condition $h_i(0) = 0$ and the matching condition $h_i(\infty) = \zeta$ to (5.13). The solution is

$$h_i(x_i) = \zeta [1 - e^{-x_i/L_{TG}}], \quad \alpha = h_i'(0) = \frac{\zeta}{L_{TG}}, \quad (5.14a,b)$$

which converts the height ζ into the slope α , as illustrated in figure 5(d) (where (5.14) is used as asymptotic composite of (5.14) and (5.13), with a rescaling). Substitution of α into

the peeling-by-pulling law (4.13) with the length scale L_{TG} instead of R in the argument of \ln_* yields, after integration,

$$2\text{-D: } R(t) = 2.00 \left(\frac{(\rho g)^{3/2} T^{-1/2} Q^3 t^{3\beta+1}}{(3\beta + 1) 12\mu \ln_*[(12\mu)^3 T^{3/2} Q^3 t^{3\beta-3} / (\rho g)^9 h_0^{12}]} \right)^{1/4}, \quad (5.15a)$$

$$\text{Axi: } R(t) = 1.07 \left(\frac{(\rho g)^{3/2} T^{-1/2} Q^3 t^{3\beta+1}}{(3\beta + 1) 12\mu \ln_*[(12\mu)^6 T^3 Q^3 t^{3\beta-6} / (\rho g)^9 h_0^{21}]} \right)^{1/7}. \quad (5.15b)$$

(In this case, the next-order corrections due to the viscous pressure drop in the flat-topped part of the blister are of relative order $O(12\mu R^3 / H^3 t)$, which turns out to be much greater than the effect of changing the argument of \ln_* by a $O(1)$ constant or indeed replacing $\ln_*(\cdot)$ with $\ln(\cdot)$. Due to the effect to be discussed in § 7.1, this regime has a rather small range of validity, so we do not calculate the corrections in more detail.)

5.6. Bending and gravity (regime ‘B + G’)

If $\ell_p \ll L_{BG} \ll R$ and $T^2 \ll \rho g B$ (figure 2a), then gravity dominates in the blister and bending dominates in the peeling region (while tension is negligible everywhere). This leads to a bending–gravity intermediate solution $h_i(x_i)$ on the scale $x_i \sim L_{BG}$, satisfying $Bh_i'''' + \rho g h_i = p_b = \rho g \zeta$ with the clamped conditions $h_i(0) = h_i'(0) = 0$ and the matching condition $h_i(\infty) = \zeta$. The unique solution is (e.g. Bungler & Cruden 2011)

$$h_i = \zeta \left[1 - e^{-x_i/\sqrt{2}L_{BG}} \left(\cos \frac{x_i}{\sqrt{2}L_{BG}} + \sin \frac{x_i}{\sqrt{2}L_{BG}} \right) \right], \quad \kappa = h_i''(0) = \frac{\zeta}{L_{BG}^2}, \quad (5.16a,b)$$

which converts the height ζ of the gravity-dominated blister solution (5.13) into a curvature κ at the edge as shown in figure 5(e) (where (5.16) is used as asymptotic composite of (5.16) and (5.13), with a rescaling).

Substitution of (5.13) and (5.16) into the peeling-by-bending law (4.7) yields, after integration,

$$2\text{-D: } R(t) = 1.41 \left(\frac{(\rho g)^5 h_0^2 Q^{10} t^{10\beta+4}}{(5\beta + 2)^4 (12\mu)^4 B} \right)^{1/14}, \quad (5.17a)$$

$$\text{Axi: } R(t) = 0.829 \left(\frac{(\rho g)^5 h_0^2 Q^{10} t^{10\beta+4}}{(5\beta + 2)^4 (12\mu)^4 B} \right)^{1/24}. \quad (5.17b)$$

5.7. Bending, tension and gravity (regime ‘B + T + G’)

If instead $T^2 \gg \rho g B$ (figure 2b), so that $\ell_p \ll L_{BT} \ll L_{TG} \ll R$, then we obtain a nested hierarchy of intermediate solutions as shown in figure 5(f). The gravity-dominated blister (5.13) has a constant height ζ , a tension–gravity intermediate solution (5.14) converts ζ into the slope $\alpha = \zeta / L_{TG}$, and a bending–tension intermediate solution (5.10) converts α into the curvature $\kappa = \alpha / L_{BT}$, which then feeds into the peeling-by-bending law (4.7). The two-dimensional asymptotic composite of (5.13), (5.14) and (5.10) shown in figure 5(f) is

$$h = H \frac{1 - e^{-(R-x)/L_{TG}} + (L_{BT}/L_{TG})(e^{-(R-x)/L_{BT}} - 1)}{1 - e^{-R/L_{TG}} + (L_{BT}/L_{TG})(e^{-R/L_{BT}} - 1)}. \quad (5.18)$$

The relationship between κ and ζ is given by $\kappa = \zeta / (L_{BT} L_{TG}) = \zeta / L_{BG}^2$, which is the same as the bending–gravity result (5.16) without the intermediate tension. Hence, the spreading rate is again given by (5.17).

5.8. Gravity only (regime 'G')

If gravity dominates everywhere, then the quasi-static solution (5.13) does not apply: It clearly does not match the cube-root behaviour (4.15), and a scaling analysis reveals that the pressure gradient is not, in fact, negligible in the blister. Instead, there is a full leading-order balance in the lubrication equation (2.4) on the blister scale, with the condition that $h_b \rightarrow 0$ with conservation of flux (4.15) at the apparent contact line. At leading order, this yields the self-similar gravity-current solutions calculated by Huppert (1982),

$$\text{2-D: } h_b(x) = H(t) \phi_1(x/R(t)), \quad \text{Axi: } h_b(r) = H(t) \phi_2(r/R(t)), \quad (5.19a,b)$$

with the blister radius and height given by the power laws

$$\text{2-D: } R(t) = A_1 \left(\frac{\rho g Q^3 t^{3\beta+1}}{12\mu} \right)^{1/5}, \quad H(t) = A_2 \left(\frac{12\mu Q^2 t^{2\beta-1}}{\rho g} \right)^{1/5}, \quad (5.20a)$$

$$\text{Axi: } R(t) = A_3 \left(\frac{\rho g Q^3 t^{3\beta+1}}{12\mu} \right)^{1/8}, \quad H(t) = A_4 \left(\frac{12\mu Q t^{\beta-1}}{\rho g} \right)^{1/4}. \quad (5.20b)$$

The profiles $\phi_{1,2}$ and the coefficients $A_{1,2,3,4}$ depend on β and are calculated numerically. At the apparent contact line, the nose of the gravity current (5.19) connects smoothly to the pre-wetting layer via the peeling solution (4.14).

6. Comparison with numerical results

We solved the governing equations (2.3)–(2.7) numerically using a finite-difference method; see appendix A for details. For the numerical calculations, we non-dimensionalized the equations using the scale h_0 for h and the bending scales

$$\text{2-D: } x_B = \left(\frac{B^\beta h_0^{3\beta+1}}{(12\mu)^\beta Q} \right)^{1/(6\beta-1)}, \quad t_B = \left(\frac{B h_0^9}{12\mu Q^6} \right)^{1/(6\beta-1)}, \quad (6.1a)$$

$$\text{Axi: } x_B = \left(\frac{B^\beta h_0^{3\beta+1}}{(12\mu)^\beta Q} \right)^{1/(6\beta-2)}, \quad t_B = \left(\frac{B^2 h_0^{12}}{(12\mu)^2 Q^6} \right)^{1/(6\beta-2)}, \quad (6.1b)$$

for x or r and t , respectively. These are obtained by balancing the pressure with the bending term in (2.3), i.e. $p \sim Bh/x^4$, and then balancing all the other terms in the remaining equations (2.4)–(2.7). The resulting non-dimensionalization is equivalent to setting $B = 12\mu = Q = h_0 = 1$ and replacing the tension and gravity coefficients T and ρg with non-dimensional versions

$$T_B = \frac{T x_B^2}{B} = \left(\frac{x_B}{L_{BT}} \right)^2, \quad G_B = \frac{\rho g x_B^4}{B} = \left(\frac{x_B}{L_{BG}} \right)^4, \quad (6.2a,b)$$

both in the governing equations (2.3)–(2.7) and in the asymptotic results (§ 5). The coefficients T_B and G_B and the injection exponent β form a complete set of three independent parameters for this system.

We compare the asymptotic predictions for $R(t)$ from § 5 with the corresponding numerical results in figure 6 using a compensated log–log plot where $R(t)$ is divided by a suitable power of t in order to highlight the difference between regimes. We focus on the

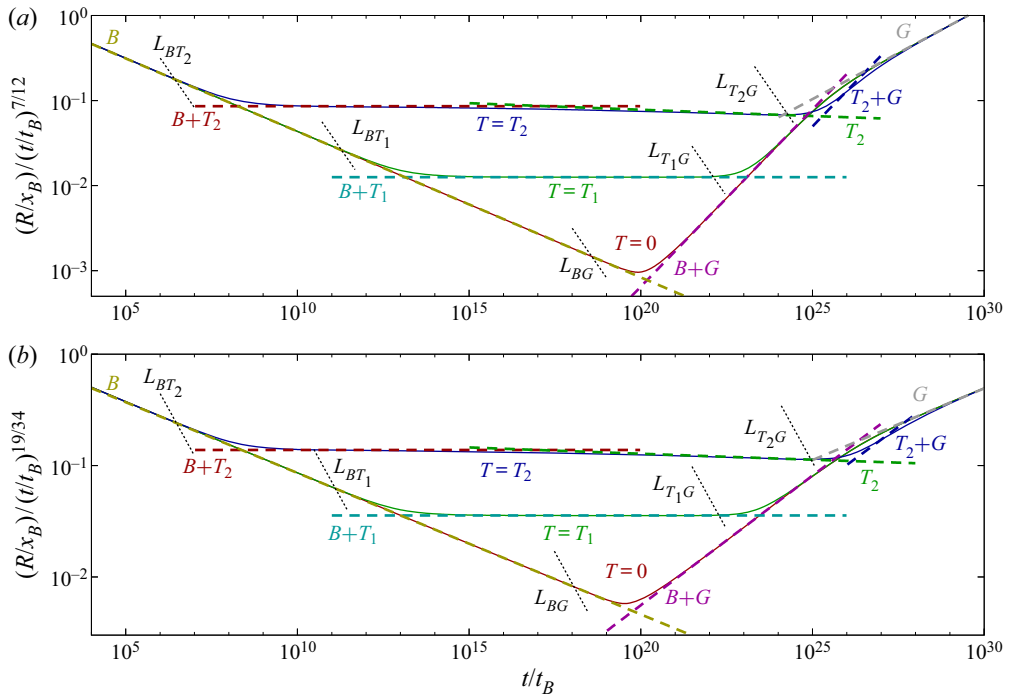


FIGURE 6. Numerical results (solid curves) and asymptotic solutions (dashed curves) for (a) two-dimensional spreading with injection exponent $\beta = 1$ and (b) axisymmetric spreading with injection exponent $\beta = 1.5$. We use the bending scales (6.1) and fix $\rho g = 10^{-32}B/x_B^4$, while considering three values for tension, $T = 0, T_1 = 10^{-10}B/x_B^2$ and $T_2 = 10^{-6}B/x_B^2$. The asymptotic results are labelled as in figures 2 and 5, with the subscripts indicating the value of T . The radius $R(t)$ has been divided by the power of t from the bending–tension hybrid regime (5.12) in order to show more clearly the differences between the regimes. The dotted lines indicate where R is equal to one of the transition lengths (3.2).

fixed value $G_B = 10^{-32}$ for the non-dimensional gravity, and consider three different values $T_B = 0, 10^{-10}, 10^{-6}$ for the non-dimensional tension. These values have been chosen to be rather extreme, in order to allow the system to display clear transitions between the various regimes. We find that the transitions are very similar for the two-dimensional and axisymmetric cases, albeit with different exponents. The following discussion applies to both cases, and more generally to cases where the injection exponent β is sufficiently small that ℓ_p increases with time.

Initially, since $T_B \ll 1$ and $G_B \ll 1$ the system is bending dominated and follows the pure-bending spreading law (5.5), labelled ‘B’.

For the case $T_B = 0$ (which corresponds to figure 2a), the bending-dominated regime lasts until the radius crosses $L_{BG} = 10^{-8}x_B$ (indicated by the dotted line). Then, gravitational forces become important and the system follows the bending–gravity hybrid solution (5.17), labelled ‘B + G’. Finally, the system transitions to the gravity-current spreading law (5.20), labelled ‘G’.

For the cases $T_B = 10^{-10}$ and 10^{-6} (which correspond to figure 2b), the system transitions from the pure-bending regime to the bending–tension hybrid regime (5.12), labelled ‘B + $T_{1,2}$ ’, as R crosses L_{BT} . For $T_B = 10^{-10}$, when R subsequently crosses L_{TG}

the system transitions to the bending–tension–gravity regime, whose spreading rate is the same as the bending–gravity regime ($B + G$), and eventually into the gravity regime (G). For $T_B = 10^{-6}$, the bending–tension regime gives way to the pure-tension regime (5.7), labelled T_2 . The system then follows the tension–gravity regime (5.15), labelled $T_2 + G$, briefly before transitioning to the gravity regime (G).

We have thus exhibited all possible transitions shown in the regime diagrams in figure 2, and found excellent agreement between the numerical results and our asymptotic predictions. For less extreme, but still small, values of T_B and G_B , the same transitions will happen but less clearly, while if one or both of T_B and G_B is large then some of the earlier regimes involving bending might not occur. Also, for larger values of β other paths through the regime diagram might be taken.

However, a more careful investigation reveals that there are a few additional transitional regimes, indicated by the shaded areas in the regime diagrams in figure 2. We identify these by examining the validity of some of the asymptotic assumptions made.

7. Validity of assumptions

The asymptotic results presented in this paper thus far rely on several assumptions, which we shall now check *a posteriori*, making use of the bending scales x_B and t_B (6.1) to keep the expressions simple.

Firstly, the governing elastic and lubrication equations (2.2) and (2.4) require the slope of the sheet to be small, $h' \ll 1$, in order to be valid. Thus, the validity of the results shown in figure 6 depends on the aspect ratio x_B/h_0 of the non-dimensionalization (6.1), since the true slope h' is related to the non-dimensional slope h^* by $h' = (h_0/x_B)h^*$. In general, any non-dimensional results in a finite time range have a maximum slope h^* and hence are valid provided that $x_B/h_0 \gg h^*$. More specific bounds can be obtained for each asymptotic regime. For example, for the two-dimensional pure-bending case (5.5a), the slope is largest in the blister, with $h' \sim H/R \sim (h_0/x_B)(t/t_B)^{(7\beta-4)/17}$. Thus, for $\beta < 4/7$ the slope decreases with time and the equations are valid for $t \gg t_B(h_0/x_B)^{17/(4-7\beta)}$, while for $\beta > 4/7$ the criterion is $t \ll t_B(x_B/h_0)^{17/(7\beta-4)}$.

Secondly, the height $H(t)$ of the blister must satisfy $H \gg h_0$. Using (5.5a) as an example again, we have $H \sim h_0(t/t_B)^{(12\beta-2)/17}$, so for $\beta > 1/6$ the result is valid at late times $t \gg t_B$, while for $\beta < 1/6$ the result is valid at early times $t \ll t_B$. As long as this height condition $H \gg h_0$ is satisfied, the separation of length scales between the large two-dimensional or axisymmetric blister and the small two-dimensional travelling-wave peeling region ($R \gg \ell_p$) is also guaranteed.

Thirdly, the horizontal length scales ℓ_p and R must lie in the predicted range according to the regime diagram in figure 2. For the radius $R(t)$, the situation is straightforward. For example, in the absence of tension, the pure-bending solution (5.5) transitions to the gravity–bending solution (5.17) when gravity becomes important due to $R(t)$ crossing L_{BG} as expected (figure 6), and this transition can also be identified by simply equating the results (5.5) and (5.17).

However, for the peeling length $\ell_p(t)$ things are more complicated. For example, consider the transition from the bending–gravity regime (5.17) towards the gravity-current regime (5.20). The two-dimensional result (5.17a) yields the prediction $\ell_{pB}(t) \sim G_B^{-1/14}(t/t_B)^{(1-\beta)/7}x_B$ for the peeling-by-bending length scale, which crosses $L_{BG} = G_B^{-1/4}x_B$ at the time $t \sim t_B G_B^{5/(4\beta-4)}$. However, the transition actually occurs at the time found from equating (5.17) and (5.20) as seen in figure 6,

$$G_B^{5/14}(t/t_B)^{(5\beta+2)/7} \sim G_B^{1/5}(t/t_B)^{(3\beta+1)/5} \Rightarrow t \sim G_B^{-11/(8\beta+6)}t_B. \quad (7.1)$$

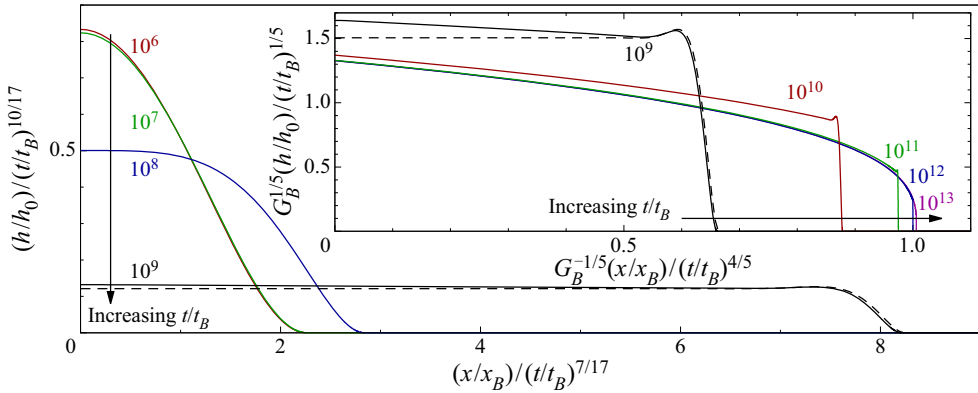


FIGURE 7. Numerical results (height profiles) for two-dimensional bending- and gravity-driven spreading with $\beta = 1$ and $x_B/L_{BG} = G_B^{1/4} = 10^{-3}$ (see (6.1a)). The initial evolution $t/t_B \leq 10^9$ (main figure) is rescaled using the pure-bending asymptotic result (5.5) and the subsequent evolution $t/t_B \geq 10^9$ (inset) is rescaled using the pure-gravity asymptotic result (5.20). The asymptotic result (5.16) is overlaid for $t/t_B = 10^9$ (dashed curve).

Past this transition, although the peeling length is $\ell_p = \ell_{pB} \ll L_{BG}$ and bending forces are present, the spreading rate $R(t)$ is given by the gravity-current solution (5.20).

This is because, fourthly, the asymptotic method requires viscous dissipation in the blister to be small compared with the viscous dissipation in the peeling region, so that the spreading is controlled by the peeling process. In the blister, the dissipation is due to the (slow) evolution represented by h in (2.4), and results in a pressure drop that scales like $\Delta p = 12\mu R\dot{R}/H^2$, which needs to be small compared with the blister pressure $p_b \sim BH/R^4$ in order to be negligible. For the pure-bending regime (5.5), we obtain $\Delta p/p_b \sim (h_0/H)^{1/2}$, so this condition is satisfied provided $H \gg h_0$. However, for the bending–gravity regime (5.17), we have $p_b \sim \rho gH$ and find that $\Delta p/p_b \sim \ell_{pB}R/L_{BG}^2$. Thus, the condition $\ell_{pB} \ll L_{BG}$ is not sufficient, and instead we have the stricter condition $\ell_{pB}R \ll L_{BG}^2$, which agrees with the transition (7.1) above.

7.1. Additional regimes

We have thus found that when $\ell_{pB} \ll L_{BG} \ll R$, so that bending and gravity dominate in the peeling and blister regions, respectively, if also $\ell_{pB}R \gg L_{BG}^2$ then the spreading is controlled by viscous dissipation in the bulk of the blister rather than by peeling. Hence we recover the gravity-current solution (5.20) for the blister, with a peeling-by-bending tip that has a negligible effect on the spreading rate, but which persists until $\ell_p \gg L_{BG}$.

We illustrate the relevant transitions in figure 7 with some snapshots from a two-dimensional numerical simulation with no tension ($T_B = 0$) and weak gravity $G_B = 10^{-12}$, leading to a bending–gravity length scale $L_{BG} = 10^3 x_B$. (This case has been studied in more detail by Hewitt *et al.* (2015).) Initially, when $x_B \ll R(t) \ll L_{BG}$, the system follows the pure-bending solution (5.5), and the profiles collapse onto the blister prediction (5.4) when rescaled by the predicted time dependence. As R crosses L_{BG} , gravity becomes important and the blister becomes flatter. At $t = 10^9 t_B$ the profile matches the asymptotic bending–gravity solution (5.16), and then tends towards the gravity-current profile (inset of figure 7).

The peeling-by-bending solution (4.7) and the bending–gravity intermediate solution (5.16) are still present near the apparent contact line, as predicted by the regime diagram (figure 2), but they do not control the spreading. Rather, the causality can be thought of as being reversed: the spreading rate \dot{R} set by the gravity current (5.20) determines the peeling curvature κ (4.7), which sets the cut-off height ζ (5.16) at the front of the gravity-current solution as seen in the inset of figure 7.

This regime, where bending and gravitational forces are dominant in different regions but $R(t)$ is given by the gravity-current result (5.20) instead of the bending–gravity hybrid result (5.17), is indicated schematically by the shaded area in figure 2(a). Similarly, in the analogous light shaded areas in figure 2(b), elastic forces are present but the leading-order solution is the gravity current (5.20). The results labelled ‘G’ in figure 6 are in fact in these shaded regimes, rather than in the pure-gravity regime.

The only remaining additional regime is for the combination of bending and tension, and corresponds to the dark shaded area in figure 2(b). In the transition between peeling by bending and peeling by pulling, there is an intermediate regime that is very similar to the pure-tension regime (§ 5.3), but with the bending–tension intermediate solution (5.10) and peeling-by-bending region (4.7) providing a cutoff. In this case, the bending–tension length L_{BT} takes the place of the peeling-by-pulling length ℓ_{pT} in the logarithm in (4.11), resulting in a spreading rate that has the same main power-law behaviour as for pure tension (5.7) but with a different logarithmic factor. A scaling analysis shows that this regime has a very narrow range of validity,

$$\frac{R}{L_{BT}} \left(\ln \frac{R}{L_{BT}} \right)^{1/3} \ll \frac{H}{h_0} \ll \frac{R}{L_{BT}} \left(\ln \frac{R}{L_{BT}} \right)^2, \quad \frac{R}{L_{BT}} \gg 1, \quad (7.2)$$

so we do not study it further.

8. Summary and generalizations

We have investigated spreading of a large two-dimensional or axisymmetric blister of fluid in the narrow gap between a horizontal rigid base and an overlying elastic sheet, with a pre-wetting film extending ahead of the blister. The spreading is driven by various combinations of bending, tension and gravitational forces depending on the horizontal length scales of the system as shown in figure 2, and is typically controlled by viscous forces in a travelling-wave peeling region at the apparent contact line at the edge of the blister (§ 4). The blister is then described by a quasi-static solution, as shown in figure 5, which depends on which of the driving forces play a role (§ 5).

If $R(t) \ll L_{BG}, L_{BT}$, then the blister is bending dominated and has the profile (5.4) with given curvature κ at its edge. The peeling speed is then given in terms of κ by the peeling-by-bending law (4.7).

If $L_{BT} \ll R(t) \ll L_{TG}$, then the main part of the blister is tension dominated and has the parabolic profile (5.6), with given slope α at its edge. If the peeling length $\ell_p(t)$ is also in the same range, then the peeling speed is given in terms of α by the peeling-by-pulling law (4.13). If, on the other hand, the peeling length is much shorter, then the slope α is converted into a curvature κ by a bending–tension intermediate solution (5.10), and the peeling speed is given by the peeling-by-bending law (4.7).

If $R(t) \gg L_{BG}, L_{TG}$, then the bulk of the blister is gravity dominated and has the profile (5.13) with a constant height ζ (provided the spreading is sufficiently slow). Intermediate solutions convert the height ζ into either the curvature κ of (5.16) for peeling by bending (4.7) or the slope α of (5.14) for peeling by pulling (4.13). (However, if the viscous

dissipation of the elastic peeling solutions is too small, then the dissipation in the blister dominates instead, and the blister spreads like a classical viscous gravity current (5.20) despite the presence of elastic forces at the apparent contact line.)

In all the above cases, except for the gravity-current regimes, we obtain a differential equation for $R(t)$ which is readily solved. A summary of the power laws obtained in the various cases is given in table 1, which also contains some extensions to our work as described below.

8.1. Alternative physics at the peeling front

As mentioned in § 1, the problem that a no-slip contact line cannot advance (Huh & Scriven 1971) can be resolved by other physical mechanisms than a pre-wetting layer. If these mechanisms are also ‘microscopic’, i.e. only have an effect on a scale much smaller than the blister, then the spreading remains controlled by the physics near the advancing contact line, and the quasi-static blister solutions calculated in § 5 still apply, but match to alternative peeling solutions at their edge.

All of the asymptotic results in this paper can be directly translated to cover other microscopic mechanisms with a fixed height scale H_p , by simply replacing h_0 with a suitable $O(1)$ multiple of H_p . Two such examples are when the no-slip condition on the sheet and base are replaced by a Navier-slip condition with a small slip length λ (e.g. Hocking 1983), or when the base has a porous upper layer of thickness b and permeability k through which the fluid also flows (e.g. Hewitt, Chini & Neufeld 2018). For these cases, the lubrication equation (2.4a) is modified to

$$\mathbf{q} = -\frac{h^3 + 6\lambda h^2}{12\mu} \nabla p \text{ or } \mathbf{q} = -\frac{h^3 + 12kb}{12\mu} \nabla p, \quad (8.1)$$

respectively, and due to the additional mobility as $h \rightarrow 0$, these models admit travelling-wave solutions which touch down with $h(R) = h'(R) = q(R) = 0$. After solving the peeling-by-bending equations analogous to (4.3a), we obtain the peeling speed (4.7) with h_0 replaced by 1.037968λ or $0.959070(kb)^{1/3}$, respectively; consequently the results (5.5), (5.12) and (5.17) for $R(t)$ simply acquire the same modification. The peeling-by-pulling results (4.13), (5.7) and (5.15), however, apply with h_0 replaced by λ or $(kb)^{1/3}$ directly, since any $O(1)$ prefactor inside the \ln_* has no leading-order effect, while the logarithmic corrections calculated in appendix C would need different values for C_p .

Alternatively, the viscous resistance to motion might cause the pressure near the advancing contact line to drop to a critical value $-P_p$ (relative to the ambient) at which gases come out of solution or the liquid itself evaporates, resulting in the fluid lagging behind the point where the sheet contacts the base, and the gap between the fluid and the contact point being filled with inviscid vapour at constant pressure $-P_p$ (e.g. Hewitt *et al.* 2015). In this case, or any other with a fixed microscopic pressure scale, a scaling analysis for the peeling wave with a given pressure scale P_p yields

$$\dot{R} \propto \frac{B^{3/2} \kappa^{7/2}}{12\mu P_p^{1/2}} \text{ or } \dot{R} = \frac{T\alpha^3}{12\mu \ln[(RP_p/\alpha T)^3]}, \quad (8.2)$$

for peeling by bending and peeling by pulling, respectively. The resulting power-law exponents for each regime are shown in the second column of table 1.

Another possibility is that the elastic sheet model (2.2) breaks down near the contact line, due to the horizontal peeling length scale being sufficiently small that it is comparable

to the sheet thickness d . In this case, the full equations of linear elasticity apply instead (e.g. Lister *et al.* 2019), and, provided that the spreading is controlled by viscous dissipation on this scale, a balance in the travelling-wave equation (4.1) with $\ell_p = d$ yields

$$\dot{R} \propto \frac{Bdk^3}{12\mu} \text{ or } \dot{R} = \frac{T\alpha^3}{12\mu \ln[(R/d)^3]}. \quad (8.3)$$

The resulting power-law exponents, for this case and any other with a fixed peeling length scale ℓ_p , are shown in the third column of table 1.

Finally, it is also possible that the spread of the blister is not dynamically controlled by viscous resistance, but rather (quasi-)statically controlled by a surface energy, in that increasing the peeled area (e.g. $A = \pi R^2$ in the axisymmetric case) by a given increment dA requires a fixed energy γdA . This could be due to bonds between the sheet and the plate requiring a fracture energy to break (e.g. Lister *et al.* 2019), van der Waals forces (e.g. Hosoi & Mahadevan 2004) or magnetic attraction (e.g. Ball & Neufeld 2018). It could also be due to surface tension (with coefficient $\gamma/2$) around an injected pancake-shaped gas bubble filling the blister (e.g. Peng *et al.* 2015). A balance between the elastic or gravitational energy released by the blister spreading and the surface-energy requirement for peeling then yields the quasi-static conditions (e.g. Landau & Lifshitz 1986)

$$\kappa^2 = \frac{2\gamma}{B}, \quad \alpha^2 = \frac{2\gamma}{T} \text{ or } \zeta^2 = \frac{2\gamma}{\rho g}. \quad (8.4)$$

Solving for $R(t)$ using the blister solutions in § 5 yields the power laws shown in the fourth column of table 1.

8.2. Generalizations to other related problems

We have considered injecting the liquid with a specified volume $V(t)$ or equivalently flux $\dot{V}(t)$. For an alternative injection strategy, such as a specified (effective) pressure or specified height, or something more exotic like a height-dependent injection flux (e.g. Kiradjev, Breward & Griffiths 2019), the blister solutions (5.4), (5.6) and (5.13) can be used with $V(t)$ depending on t and R so as to achieve the desired effect, and the new differential equations obtained for $R(t)$ can be integrated to yield the solution. Similarly, if there is a slow temporal and/or gentle spatial variation in the physics (such as the value of h_0) at the contact line then the peeling laws (§ 4) still apply but the final integration of the equation for $R(t)$ is different.

For spreading in two horizontal dimensions with non-axisymmetric spatial variations or initial conditions, although the blister shape cannot be solved for analytically in general, the asymptotic decomposition can still be employed to simplify the problem. Instead of fully resolving the contact-line dynamics, a numerical method can be employed to simply track the location of the contact line and solve for a quasi-static constant-pressure blister shape within it. The curvature or slope at the contact line then determines the speed at which it advances.

For a viscous fluid spreading in the thin gap between an inner rigid cylinder and an outer concentric elastic cylindrical shell (e.g. Elbaz & Gat 2016), the axial evolution equation for the axisymmetric layer thickness h is given by

$$\dot{h} = \left(\frac{h^3}{12\mu} p' \right)', \quad p = Bh'''' - Th'' + \frac{Ed}{a^2} h, \quad (8.5a,b)$$

where primes denote differentiation with respect to the axial coordinate z , T is the axial tension in the sheet, a is the radius of the rigid cylinder, and the remaining quantities are defined as before. We recognize this as being identical to our equations (2.3) and (2.4) for two-dimensional spreading, but with an elastic term (due to the hoop tension in the cylindrical shell) taking the place of the gravity term, so all of our asymptotic results also apply directly to this geometry.

Finally, as mentioned in § 1, the deflection and consequential stretching of the sheet generates additional tension. Assuming that this induced tension scales like $Ed(H/R)^2$, we find that it is negligible compared with the externally imposed tension T provided that $H/R \ll \sqrt{T/Ed}$. However, even when $T = 0$, the results in this paper for bending and gravity may be valid. For example, if $H \ll d$ (i.e. the deflection remains much smaller than the sheet thickness), then the induced tension is negligible compared with bending everywhere, since the blister radius R is smaller than the transition length scale $\sqrt{B/(Ed(H/R)^2)} \sim Rd/H$.

When the induced tension does become significant, the main principle of separation of scales between the blister and peeling regions still holds, but with modified solutions for the blister and peeling regions. We study this case in more detail in Peng & Lister (2020).

8.3. Conclusion

Although the pressure expression (2.3) is very simple with only three terms, these bending, tension and gravity driving forces can be combined in seven different ways as shown in figure 2, each leading to a distinct asymptotic spreading regime, in both two-dimensional and axisymmetric geometries. Coupled with the different possible peeling physics controlling the spreading, this leads to a vast range of asymptotic regimes as listed in table 1. Although many of the spreading exponents are numerically similar and may be difficult to distinguish experimentally, each regime is governed by a genuinely different physical balance and has a different dependence on the physical parameters of the system.

Acknowledgements

G.G.P. was supported by an EPSRC PhD studentship. All research data supporting this publication are directly available within this publication.

Declaration of interests

The authors report no conflict of interest.

Appendix A. Numerical method

The governing equations (2.3)–(2.7) are solved in non-dimensional form using a fully implicit (backward-Euler) finite-difference scheme with a rescaled spatial coordinate $\xi = x/R(t)$ or $\xi = r/R(t)$ instead of x or r . The rescaling introduces the unknown speed R in the governing equations, which is determined by the additional condition $h = h_0$ at $\xi = 1$.

Without the rescaling, the size of the time step would be limited by the fast time scale ℓ_p/R of translation of the peeling wave, which is many orders of magnitude smaller than t at late times. The rescaling, however, naturally incorporates this translation so that $h(\xi, t)$ evolves on the time scale t , allowing the time step to be a reasonable fraction of t even at

extremely late times. The time step is automatically adjusted to ensure accuracy to within 1% by comparing each single step with two steps of half the size.

The spatial grid is also automatically adapted to the solution. The distance D between the first location ($\xi = 1$) where h crosses h_0 and the second such location is used as an estimate of the wavelength in the peeling region, and the domain is set to extend in $\xi > 1$ at least $10D$ ahead of the first crossing with a grid spacing at most $0.01D$. As ξ decreases away from the peeling region in $0 \leq \xi < 1$, the grid spacing is set to increase approximately like $0.01(1 - \xi)$. This guarantees that all regions are spatially resolved to within 1%.

Appendix B. General quasi-static blister solutions

The general quasi-static solution of the blister equation (5.1) with the symmetry condition (5.3) is of the form

$$\text{2-D: } h_b(x) = C_1 + C_2 \cosh(\lambda_+ x) + C_3 \cosh(\lambda_- x), \quad (\text{B } 1a)$$

$$\text{Axi: } h_b(r) = C_1 + C_2 I_0(\lambda_+ r) + C_3 I_0(\lambda_- r), \quad (\text{B } 1b)$$

where I_0 is the modified Bessel function of the first kind and order zero, the (potentially complex) roots λ of the equation $B\lambda^4 - T\lambda^2 + \rho g = 0$ are given by

$$\lambda_{\pm} = \frac{1}{2L_{BT}} \sqrt{1 \pm \sqrt{1 - 4 \frac{L_{BT}^2}{L_{TG}^2}}}, \quad (\text{B } 1c)$$

and L_{BT} and L_{TG} are given in (3.2). The constants $C_{1,2,3}$ are determined by the volume constraint (5.2) and the clamping conditions (4.6) for matching to a peeling-by-bending travelling-wave solution.

If the peeling length scale $\ell_p \gg L_{BG}, L_{BT}$ then bending forces can be neglected everywhere. The solution of the reduced blister equation $p_b = -T\nabla^2 h_b + \rho g h_b$ (5.1) and symmetry condition $h'(0) = 0$ (5.3) then has the form

$$\text{2-D: } h_b = C_1 + C_2 \cosh(x/L_{TG}), \quad \text{Axi: } h_b = C_1 + C_2 I_0(r/L_{TG}), \quad (\text{B } 2a,b)$$

where the constants $C_{1,2}$ are determined by (5.2) and (4.10).

Appendix C. Logarithmic corrections for peeling by pulling

In this appendix, we present the method for determining the appropriate $O(1)$ numerical coefficient inside $\ln_*(\cdot)$ in the results of § 5.3. This changes the leading-order result by a relative order $O(1/\ln(H/h_0))$, where for the purposes of scaling analysis we can ignore the difference between $\ln_*(\cdot)$ and $\ln(\cdot)$ and also neglect any exponentiation of the argument of those functions. This logarithmically small correction is thus asymptotically negligible but may be significant in practice. The correction is due to the viscous pressure drop inside the quasi-static blister. We treat the two-dimensional case in detail, and give the results for the axisymmetric case in appendix C.4.

C.1. *The two-dimensional blister solution*

In the blister region, we introduce $O(1)$ non-dimensional variables and substitute into the governing equation (2.4) with $p = -Th'$,

$$h(x, t) = \frac{V}{R} \hat{h}(\hat{x}, t), \quad \hat{x} = \frac{x}{R} \Rightarrow \frac{TV^3}{12\mu R^7} (-\hat{h}^3 \hat{h}''')' = -\frac{\dot{R}}{R} (\hat{x} \hat{h})' + \frac{\dot{V}}{V} \hat{h} + \dot{\hat{h}}. \tag{C1}$$

Integration using the injection condition (2.7) yields

$$-\hat{h}''' = \frac{12\mu R^7}{TV^3} \left[-\frac{\dot{R}}{R} \frac{\hat{x}}{\hat{h}^2} + \frac{\dot{V}}{V} \frac{\int_0^{\hat{x}} \hat{h} d\hat{x} - 1}{\hat{h}^3} + \frac{\int_0^{\hat{x}} \dot{\hat{h}} d\hat{x}}{\hat{h}^3} \right], \tag{C2}$$

which suggests an asymptotic expansion of the form

$$\hat{h} = \hat{h}_0(\hat{x}) + \frac{12\mu R^7}{TV^3} \left[\frac{\dot{R}}{R} \hat{h}_{1R}(\hat{x}) + \frac{\dot{V}}{V} \hat{h}_{1V}(\hat{x}) \right] + O\left(\frac{1}{\ln(H/h_0)^2}\right). \tag{C3}$$

Here, $\hat{h}_0(\hat{x}) = \frac{3}{2}(1 - \hat{x}^2)$ is the leading-order solution, \hat{h}_{1R} and \hat{h}_{1V} represent the $O(12\mu R^7/TV^3 t) = O(1/\ln(H/h_0))$ corrections from the viscous pressure drops due to the outward spreading of the blister and to the injection flow from the origin into the blister, and there is no contribution at this order from the last term in (C2) since \hat{h}_0 is independent of t .

As these logarithmic corrections are $O(1/\ln(H/h_0)) = O(1/\ln(R/\ell_p))$, we can safely neglect any quantities that are algebraically small (compared with the leading order), such as $O(h_0/H)$ or $O(\ell_p/R)$. Hence, as the height scale of the peeling region is $h_0 \ll H$, the blister solution satisfies $\hat{h} \approx 0$ at the edge. Thus, both $\hat{h}_1 = \hat{h}_{1R}$ and $\hat{h}_1 = \hat{h}_{1V}$ satisfy the conditions $\hat{h}'_1(0) = \hat{h}_1(1) = \int_0^1 \hat{h}_1 d\hat{x} = 0$. The (C2) then yields

$$\hat{h}_{1R}''' = \frac{\hat{x}}{\hat{h}_0^2} = \frac{4}{9} \frac{\hat{x}}{(1 - \hat{x}^2)^2}, \quad \hat{h}_{1V}''' = \frac{\int_{\hat{x}}^1 \hat{h}_0 d\hat{x}}{\hat{h}_0^3} = \frac{4}{27} \frac{\hat{x}^3 - 3\hat{x} + 2}{(1 - \hat{x}^2)^3}, \tag{C4a,b}$$

with the solutions

$$\hat{h}_{1R} = \frac{1 - \hat{x}}{9} \ln(1 - \hat{x}) + \frac{1 + \hat{x}}{9} \ln(1 + \hat{x}) + \frac{1 - \hat{x}^2}{6} - \frac{2 \ln 2}{9}, \tag{C5a}$$

$$\hat{h}_{1V} = -\frac{(1 - \hat{x})^2}{36} \ln(1 - \hat{x}) + \frac{3\hat{x}^2 - 6\hat{x} - 5}{108} \ln(1 + \hat{x}) + \frac{3\hat{x}^2 + 2\hat{x} - 5 + 8 \ln 2}{108}. \tag{C5b}$$

C.2. *The peeling-by-pulling region*

For the peeling region, the (4.3b), (4.4) and (4.8) remain the same, since all corrections are of algebraic order such as $O(h_0/H)$ or $O(\ell_p/R)$. (In particular, the condition $F''(\infty) = 0$ (4.8) for matching to the blister solution applies, as its second derivative is of order $O(H/R^2) \ll O(h_0/\ell_p^2)$.) Hence, the peeling solution is still given by the solution

shown in figure 4(b), and the effect of the logarithmic corrections is only in altering the length scale ℓ_p .

However, the matching of slopes between the blister and peeling regions requires knowing the far-field behaviour of the slope $F'(X)$ to a more accurate degree than (4.9). Again using the approximation $-1 = F^2 F'''$, which has an algebraically small $O(1/X)$ error in the far field, we find, by imposing $F'' \rightarrow 0$, the generic far-field behaviour

$$F \sim X(3 \ln X)^{1/3} \left[1 - \frac{C_p}{\ln X} - \frac{10}{27} + \frac{C_p^2}{(\ln X)^2} + O\left(\frac{1}{(\ln X)^3}\right) \right] \text{ as } X \rightarrow \infty. \tag{C 6}$$

The value of the constant C_p is obtained from a numerical solution of the full travelling-wave equation (4.3b) as

$$C_p = 0.423087. \tag{C 7}$$

(In order to calculate this value of C_p accurately, which requires reaching sufficiently large values of $\ln X$ that the subdominant terms in (C 6) can be easily distinguished, we used the transformation $X = Y + e^Y$, $G(Y) = (F(X) - 1)/(1 + e^Y)$ and solved numerically for $G(Y)$ instead, using the transformed form of (4.3b), (4.4a) and (C 6) together with a translated form $G(0) = 0.5$ of (4.4) for simplicity, which only introduces an algebraically small error. We discretized the system used a fourth-order finite-difference method on a uniform grid with step size $\Delta Y = 0.001$ in the domain $|Y| \leq Y_{max} = 1000$ and calculated the solution using Newton–Raphson iteration, and verified that the result (C 7) changes by less than 10^{-6} when ΔY is reduced by a factor 10 or Y_{max} is increased by a factor 10.)

C.3. Completing the matching

We now need to match the slopes, $-h'$, of the blister and peeling solutions. The first-order corrections do not yield a fixed value analogous to α , so instead we need to impose that the asymptotic behaviours of the slopes agree. A careful analysis reveals that there is an intermediate region involving logarithmic quantities (see Hocking (1983) for details), but its effect is equivalent to matching the asymptotic expansion of $(-h')^3$ directly between the blister and peeling regions as we now proceed to do.

The result $-\hat{h}'_0(1) = 3$ and the limiting behaviours of the blister solutions (C 5),

$$-\hat{h}'_{1R} \sim \frac{\ln(1 - \hat{x}) + 3 - \ln 2}{9}, \quad -\hat{h}'_{1V} \sim \frac{-1/3}{9} \text{ as } \hat{x} \rightarrow 1^-, \tag{C 8a,b}$$

yield, using the definition of α in (5.6) and the leading-order power-law exponents from (5.7),

$$(-h')^3 = \alpha^3 + \frac{12\mu\dot{R}}{T} \left[9 + 3 \ln \frac{R-x}{R} - 3 \ln 2 - \frac{7\beta}{3\beta+1} + O\left(\frac{1}{\ln(H/h_0)}\right) \right]. \tag{C 9}$$

Similarly, the far-field behaviour of the peeling solution (C 6),

$$(F')^3 = 3 \ln X + (3 - 9C_p) + O\left(\frac{1}{\ln X}\right) \text{ as } X \rightarrow \infty, \tag{C 10}$$

yields

$$(-h')^3 = \frac{12\mu\dot{R}}{T} \left[3 \ln \frac{R-x}{h_0(T/12\mu\dot{R})^{1/3}} + 3 - 9C_p + O\left(\frac{1}{\ln(H/h_0)}\right) \right]. \tag{C 11}$$

Equating (C 9) and (C 11) then yields

$$\frac{T\alpha^3}{12\mu\dot{R}} = \ln \frac{12\mu\dot{R}}{T\alpha^3} + 3 \ln \frac{2R\alpha}{h_0} - 6 - 9C_p + \frac{7\beta}{3\beta + 1} + O\left(\frac{1}{\ln(H/h_0)}\right), \tag{C 12}$$

and hence, after exponentiation of both sides and using the definition (4.12) of $\ln_*(\cdot)$,

$$\dot{R} = \frac{T\alpha^3}{12\mu \ln_*[(cR\alpha/h_0)^3]}, \quad \text{with } c = 2 \exp\left(-2 - 3C_p + \frac{7\beta}{3(3\beta + 1)}\right), \tag{C 13}$$

to the required degree of accuracy.

We substitute α^3 from (5.6) and separate variables (ignoring the argument of \ln_*) to obtain

$$7R^6\dot{R} \approx \frac{189 TQ^3 t^{3\beta}}{12\mu \ln_*[(cR\alpha/h_0)^3]}. \tag{C 14}$$

We integrate both sides, making use of the approximate formula (valid for arbitrary positive constants a, b and B)

$$\int \frac{at^{a-1}}{\ln_*[Bt^b]} dt \approx \frac{t^a}{\ln_*[Bt^b \exp(-b/a)]}, \tag{C 15}$$

and the fact that, in this case, the argument $(cR\alpha/h_0)^3$ of \ln_* is an approximate power of t with exponent $b = 3(4\beta - 1)/7$, from (5.7). Then, solving for $R(t)$ using the formula

$$R^a = \frac{A}{\ln_*[BR^{-b}]} \Leftrightarrow R^a = \frac{\frac{a}{a-b}A}{\ln_*\left[\frac{a}{a-b} (B^a/A^b)^{1/(a-b)}\right]}, \tag{C 16}$$

yields the result

$$2\text{-D: } R(t) = 2.29 \left(\frac{TQ^3 t^{3\beta+1}}{(3\beta + 1) 12\mu \ln_*[(c_1 12\mu Q^4 t^{4\beta-1}/Th_0^7)^{3/4}]} \right)^{1/7}, \tag{C 17a}$$

$$c_1 = \exp\left(-1.842 - 21C_p - \frac{28}{9(3\beta + 1)}\right) (3\beta + 1). \tag{C 17b}$$

C.4. The axisymmetric case

In the axisymmetric case, the non-dimensionalization and expansion

$$h = \frac{V}{R^3} \hat{h}(\hat{r}, t), \quad \hat{r} = \frac{r}{R}, \quad \hat{h} = \hat{h}_0 + \frac{12\mu R^{10}}{TV^3} \left[\frac{\dot{R}}{R} \hat{h}_{1R}(\hat{r}) + \frac{\dot{V}}{V} \hat{h}_{1V}(\hat{r}) \right] + \dots \tag{C 18}$$

and leading-order result $\hat{h}_0 = (2/\pi)(1 - \hat{r}^2)$ yield the first-order equations

$$\left(\frac{1}{\hat{r}}(\hat{r}\hat{h}'_{1R})'\right)' = \frac{\hat{r}}{\hat{h}_0^2} = \frac{\pi^2}{4} \frac{\hat{r}}{(1 - \hat{r}^2)^2}, \quad \left(\frac{1}{\hat{r}}(\hat{r}\hat{h}'_{1V})'\right)' = \frac{\int_{\hat{x}}^1 \hat{h} \hat{r} d\hat{r}}{\hat{h}_0^3} = \frac{\pi^2}{16} \frac{1}{\hat{r}(1 - \hat{r}^2)}, \tag{C 19a,b}$$

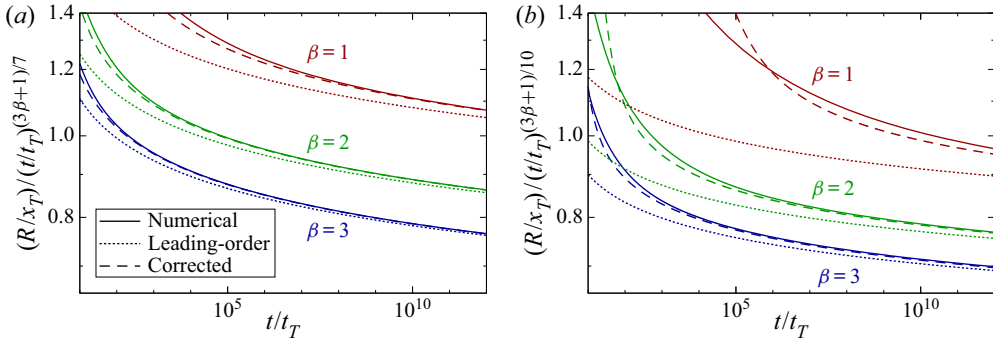


FIGURE 8. Comparison of numerical and asymptotic results for the evolution of $R(t)$ in the tension-dominated (a) two-dimensional and (b) axisymmetric cases, for three values of the power-law exponent β , rescaled using (C 24).

conditions $\hat{h}'_1(0) = \hat{h}_1(1) = \int_0^1 \hat{h}_1 2\pi \hat{r} d\hat{r} = 0$ and solutions

$$\hat{h}_{1R} = \frac{\pi^2}{128} (\hat{r}^2 \ln \hat{r}^2 + (1 - \hat{r}^2) \ln(1 - \hat{r}^2) - \text{Li}_2(\hat{r}^2) + \hat{r}^2 - 1) + \frac{\pi^4}{768}, \tag{C 20a}$$

$$\hat{h}_{1V} = \frac{\pi^2}{32} \text{Li}_2(\hat{r}^2) + \frac{\pi^2}{16} (1 - \hat{r}^2) - \frac{\pi^4}{192}, \tag{C 20b}$$

where $\text{Li}_2(x) = \int_x^1 \ln(t)/(t - 1) dt$ is the dilogarithm.

The peeling-by-pulling solution from appendix C.2 applies, so equating (C 11) to

$$(-h')^3 \sim \alpha^3 + \frac{12\mu\dot{R}}{T} \left[6 + 3 \ln \frac{2x_p}{R} - \frac{3}{4} \frac{10\beta}{3\beta + 1} + O\left(\frac{1}{\ln(H/h_0)}\right) \right] \tag{C 21}$$

from (C 20) yields

$$\dot{R} = \frac{T\alpha^3}{12\mu \ln_*[(cR\alpha/h_0)^3]}, \quad \text{with } c = \frac{1}{2} \exp\left(-1 - 3C_p + \frac{5\beta}{2(3\beta + 1)}\right), \tag{C 22}$$

and hence, after integration, the result

$$\text{Axi: } R(t) = 1.48 \left(\frac{TQ^3 t^{3\beta+1}}{(3\beta + 1) 12\mu \ln_*[(c_2 12\mu Q^2 t^{2\beta-1}/Th_0^5)^{3/2}]} \right)^{1/10}, \tag{C 23a}$$

$$c_2 = \exp\left(-6.174 - 15C_p - \frac{5}{2(3\beta + 1)}\right) (3\beta + 1). \tag{C 23b}$$

C.5. Comparison with numerical results

In the purely tension-dominated case, rescaling h by h_0 , and x or r and t by

$$\text{2-D: } x_T = \left(\frac{T^\beta h_0^{3\beta+1}}{(12\mu)^\beta Q} \right)^{1/(4\beta-1)}, \quad t_T = \left(\frac{Th_0^7}{12\mu Q^4} \right)^{1/(4\beta-1)}, \tag{C 24a}$$

$$\text{Axi: } x_T = \left(\frac{T^\beta h_0^{3\beta+1}}{(12\mu)^\beta Q} \right)^{1/(4\beta-2)}, \quad t_T = \left(\frac{Th_0^5}{12\mu Q^2} \right)^{1/(2\beta-1)}, \quad (\text{C } 24b)$$

leaves the exponent β as the only non-dimensional parameter. Figure 8 shows the evolution of the radius $R(t)$ in a compensated log–log plot where the main time dependence $t^{(3\beta+1)/7}$ or $t^{(3\beta+1)/10}$ has been divided out. The main asymptotic results (5.7) indeed capture the leading-order behaviour correctly, and the logarithmic corrections in (C 17) and (C 23) improve the agreement considerably.

REFERENCES

- BALL, T. V. & NEUFELD, J. A. 2018 Static and dynamic fluid-driven fracturing of adhered elastica. *Phys. Rev. Fluids* **3** (7), 074101.
- BUNGER, A. P. & CRUDEN, A. R. 2011 Modeling the growth of laccoliths and large mafic sills: role of magma body forces. *J. Geophys. Res.* **116**, B02203.
- CHRISTOV, I. C., COGNET, V., SHIDHORE, T. C. & STONE, H. A. 2018 Flow rate–pressure drop relation for deformable shallow microfluidic channels. *J. Fluid Mech.* **841**, 267–286.
- COX, R. G. 1986 The dynamics of the spreading of liquids on a solid surface. Part 1. Viscous flow. *J. Fluid Mech.* **168**, 169–194.
- ELBAZ, S. B. & GAT, A. D. 2016 Axial creeping flow in the gap between a rigid cylinder and a concentric elastic tube. *J. Fluid Mech.* **806**, 580–602.
- FLITTON, J. C. & KING, J. R. 2004 Moving-boundary and fixed-domain problems for a sixth-order thin-film equation. *Eur. J. Appl. Maths* **15** (6), 713–754.
- GROTBERG, J. B. & JENSEN, O. E. 2004 Biofluid mechanics in flexible tubes. *Annu. Rev. Fluid Mech.* **36**, 121–147.
- HEWITT, D. R., CHINI, G. P. & NEUFELD, J. A. 2018 The influence of a poroelastic till on rapid subglacial flooding and cavity formation. *J. Fluid Mech.* **855**, 1170–1207.
- HEWITT, I. J., BALMFORTH, N. J. & DE BRUYN, J. R. 2015 Elastic-plated gravity currents. *Eur. J. Appl. Maths* **26** (1), 1–31.
- HOCKING, L. M. 1983 The spreading of a thin drop by gravity and capillarity. *Q. J. Mech. Appl. Maths* **36** (1), 55–69.
- HOSOI, A. E. & MAHADEVAN, L. 2004 Peeling, healing, and bursting in a lubricated elastic sheet. *Phys. Rev. Lett.* **93** (13), 137802.
- HUH, C. & SCRIVEN, L. E. 1971 Hydrodynamic model of steady movement of a solid/liquid/fluid contact line. *J. Colloid Interface Sci.* **35** (1), 85–101.
- HUPPERT, H. E. 1982 The propagation of two-dimensional and axisymmetric viscous gravity currents over a rigid horizontal surface. *J. Fluid Mech.* **121**, 43–58.
- KIRADJIEV, K. B., BREWARD, C. J. W. & GRIFFITHS, I. M. 2019 Surface-tension- and injection-driven spreading of a thin viscous film. *J. Fluid Mech.* **861**, 765–795.
- LANDAU, L. D. & LIFSHITZ, E. M. 1986 *Course of Theoretical Physics Vol. 7: Theory of Elasticity*, 3rd edn. Pergamon.
- LISTER, J. R., PENG, G. G. & NEUFELD, J. A. 2013 Viscous control of peeling an elastic sheet by bending and pulling. *Phys. Rev. Lett.* **111**, 154501.
- LISTER, J. R., SKINNER, D. J. & LARGE, T. M. J. 2019 Viscous control of shallow elastic fracture: peeling without precursors. *J. Fluid Mech.* **868**, 119–140.
- PENG, G. G. & LISTER, J. R. 2020 Viscous flow under a stretching and sliding elastic sheet. *J. Fluid Mech.* (submitted).
- PENG, G. G., PIHLER-PUZOVIĆ, D., JUEL, A., HEIL, M. & LISTER, J. R. 2015 Displacement flows under elastic membranes. Part 2: analysis of interfacial effects. *J. Fluid Mech.* **784**, 512–547.
- PIHLER-PUZOVIĆ, D., ILLIEN, P., HEIL, M. & JUEL, A. 2012 Suppression of complex fingerlike patterns at the interface between air and a viscous fluid by elastic membranes. *Phys. Rev. Lett.* **108**, 074502.
- PIHLER-PUZOVIĆ, D., PENG, G. G., LISTER, J. R., HEIL, M. & JUEL, A. 2018 Viscous fingering in a radial elastic-walled Hele-Shaw cell. *J. Fluid Mech.* **849**, 163–191.

- POLLARD, D. D. & JOHNSON, A. M. 1973 Mechanics of growth of some laccolithic intrusions in the Henry mountains, Utah, II: bending and failure of overburden layers and sill formation. *Tectonophysics* **18** (3–4), 311–354.
- REYNOLDS, O. 1886 IV. On the theory of lubrication and its application to Mr. Beauchamp Tower's experiments, including an experimental determination of the viscosity of olive oil. *Phil. Trans. R. Soc. Lond.* **177**, 157–234.
- VOINOV, O. V. 1976 Hydrodynamics of wetting. *Fluid Dyn.* **11** (5), 714–721.
- WANG, Z.-Q. & DETOURNAY, E. 2018 The tip region of a near-surface hydraulic fracture. *J. Appl. Mech.* **85** (4), 041010.