A BOUNDARY MAXIMUM PRINCIPLE FOR STATIONARY PAIRS OF VARIFOLDS WITH FIXED CONTACT ANGLE

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Abstract In this note, we establish a boundary maximum principle for a class of stationary pairs of varifolds satisfying a fixed contact angle condition in any compact Riemannian manifold with smooth boundary.

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1. Introduction

Minimal surfaces – critical points of the area functional with respect to local deformations – are fundamental objects in Riemannian geometry, and attracted the attention of many mathematicians. In this note, we establish a boundary maximum principle for the generalized minimal hypersurfaces in any Riemannian manifolds, having constant contact angle θ_0 with the boundary.

In all follows, let (N^*, g) be a smooth, connected, compact (n + 1)-dimensional Riemannian manifold with non-empty boundary ∂N^* . With a slight abuse of notation, we also use $\langle \cdot, \cdot \rangle$ to denote the Riemannian metric of N^* and denote by ∇ the Levi-Civita connection of N^* . Let ν_{N^*} denote its unit normal along ∂N^* , pointing into N^* . For any smooth, compact, properly embedded hypersurface $S \subset N^*$ whose boundary lies in ∂N^* , fix an orientation given by the unit normal vector field ν_S , and let Ω be the closure of the enclosed region of S with ∂N^* such that ν_S points inside Ω , set $T = \partial \Omega \cap \partial N^*$. See Figure 1 for illustration, where $\mu, \bar{\mu}$ denote the inwards pointing unit conormals of $S \cap T$ in S and T respectively.

Let A^S denote the shape operator of S in N^* with respect to ν_S , i.e. $A^S(u) = -\nabla_u \nu_S$ for any $u \in \Gamma(TS)$. We say that S is strongly mean convex at a point $p \in S$, if

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Figure 1. Hypersurface S having constant contact angle θ_0 with the boundary ∂N^* .

$$\kappa_1 + \ldots + \kappa_n > 0,$$

where $\kappa_1 \leq \ldots \leq \kappa_n$ are the principal curvatures of A^S at p.

Our main result is the following boundary maximum principle, established in the context of varifolds with fixed contact angle, we refer to §2 for the precise definition and statement.

1.1. Main result

Theorem 1.1. Given $\theta_0 \in (0, \pi/2)$, let S be a smooth, compact, properly embedded hypersurface, meeting ∂N^* with a constant angle θ_0 , that is, $\langle \nu_S, \nu_{N^*} \rangle = -\cos \theta_0$ along $\partial N^* \cap S$. Suppose that S is strongly mean convex at a point $p \in \partial S$.

Then, for any fine θ_0 -stationary pair $(V, W) \in \mathcal{V}_n(N^*) \times \mathcal{V}_n(\partial N^*)$, p is not contained in the support of ||V||, if one of the following cases happens¹:

i. ||V|| is supported in Ω , ||W|| is supported in T, and $||V||(\partial N^*) = 0$;

ii. ||V|| is supported in Ω , ||W|| is supported in T, and ∂N^* is mean convex in N^* .

¹ As pointed out to us by a referee, the following two conditions are sufficient also if they are locally true at p.



Figure 2. Local orthogonal foliations and orthonormal frame.

The maximum principle for minimal submanifolds has been proved in various contexts. The interior maximum principle for C^2 -hypersurfaces is a direct consequence of the well-known Hopf's boundary point lemma [6, Lemma 3.4]. It is then generalized to arbitrary codimension by Jorge-Tomi [8]. In the non-smooth case, White [15] established the interior maximum principle in the context of minimal varieties, in any codimension. Recently, Li-Zhou generalized the main result of [15] to the free boundary setting, they established a boundary maximum principle for free boundary minimal varieties (free boundary stationary varifolds), in arbitrary codimension [11, Theorem 1.2].

As argued in [11], in the smooth, codimension-1 case, the boundary maximum principle for free boundary hypersurface amounts to be a simple application of Hopf's lemma. Meanwhile, one can also derive a boundary maximum principle for a generic contact angle $\theta_0 \in (0, \pi)$ by virtue of Hopf's lemma, see e.g. [10, Lemma 1.13]. Therefore our main result Theorem 1.1 serves as a generalization of this classical result and of course as an extension of [11, Theorem 1.2] from $\theta_0 = \pi/2$ to $\theta_0 \in (0, \pi/2)$.

Our strategy of proof follows largely from [11]. In the free boundary case (S meets ∂N^* orthogonally), Li-Zhou managed to prove their main result by a contradiction argument. Precisely, they constructed a test vector field X, which strictly decreases the first variation of the free boundary stationary varifold. To construct such X, they first constructed local orthogonal foliations near p [11, Lemma 2.1]. By virtue of such foliations, they found a local orthonormal frame e_1, \ldots, e_{n+1} of N^* near p, see [11, Figure 2] also Figure 2 for illustration. The key point is that, locally near the free boundary, for any $q \in \partial N^*$, there holds $e_{n+1}(q) \in T_q \partial N^*$, which motivates their choice of test vector field X. In our case, intuitively we would like to seek some tangential variation X to test the first variation for θ -stationary pair of varifolds (as in Definition 2.1). However, we only managed to prove a weaker boundary maximum principle in a preliminary version of this manuscript [17, Theorem 1.1]. In fact, the strong maximum principle does not hold for a general stationary pair of varifolds (see Examples 2.6, A.1). Motivated by this, we introduce a new class of pairs of varifolds, called fine θ -stationary pair (defined in Definition 2.3), which allows us to test not only the tangential (with respect to ∂N^*) variation but also the normal one (with respect to S), as what Li-Zhou have done in [11]. Testing the stationarity of the fine pair (V, W) with normal variation, we find: the strictly mean convexity of S at p forces X to increase the normal variation of V, which violates the stationarity of the fine pair (V, W).

1.2. Organization of the paper

In §2, we briefly recall some definitions from geometric measure theory and give a precise definition of the fine θ -stationary pair of varifolds. In §3, we prove our main result Theorem 1.1.

2. Varifolds with fixed contact angle

Let us begin by recalling some basic concepts of varifolds, we refer to [1, 13, 14, Chapter 8] for detailed accounts.

2.1. Varifolds

The space of *n*-varifolds in \mathbf{R}^L , denoted by $\mathbf{V}_n(\mathbf{R}^L)$, is the set of all positive Radon measures on the Grassmannian $\mathbf{R}^L \times G(L, n)$ equipped with the weak topology. The weight and mass of a varifolds $V \in \mathbf{V}_n(\mathbf{R}^L)$ is denoted respectively by ||V|| and $\mathbf{M}(V) :=$ $||V||(\mathbf{R}^L)$. For any Borel set $A \subset \mathbf{R}^L$, we denote by $V \sqcup A$ the restriction of V to $A \times$ G(L, n). The support of V, $\operatorname{spt}||V||$, is the smallest closed subset $B \subset \mathbf{R}^L$ such that $V \sqcup (\mathbf{R}^L \setminus B) = 0$. For any C^1 map $f : \mathbf{R}^L \to \mathbf{R}^L$, the continuous pushforward map $f_{\#} : \mathbf{V}_n(\mathbf{R}^L) \to \mathbf{V}_n(\mathbf{R}^L)$ is defined as in [13, 2.1(18)(h)]. We denote by $\mathbf{RV}_n(\mathbf{R}^L)$ the set of rectifiable n-varifolds in \mathbf{R}^L , see [13, 2.1(18)(d)].

Let us proceed and define varifolds in N^* , by virtue of the Nash embedding theorem, we can assume that N^* is isometrically embedded as a closed subset of some \mathbf{R}^L . Here we follow the notations in [13] (which is slightly different from [1], see also [12, Section 2.2]). Since N^* is a submanifold of class 1 of \mathbf{R}^L , we define the Grassmann bundle by $G_n(N^*) = (N^* \times G(L, n)) \cap \{(x, P) : P \subset T_x N^*\}; G_n(\partial N^*)$ is understood in the same way, and since ∂N^* is *n*-dimensional, we have $G_n(\partial N^*) = \{(x, T_x \partial N^*) : x \in \partial N^*\}.$

In this note, we mainly work with the following spaces of vector fields,

$$\begin{aligned} &\mathfrak{X}(\mathbf{R}^L) := \{ \text{the space of } C^1 \text{-vector fields on } \mathbf{R}^L \}, \\ &\mathfrak{X}(N^*) := \{ X \in \mathfrak{X}(\mathbf{R}^L) : X(p) \in T_p N^* \quad \text{for all } p \in N^* \}, \\ &\mathfrak{X}_t(N^*) := \{ X \in \mathfrak{X}(N^*) : X(p) \in T_p(\partial N^*) \quad \text{for all } p \in \partial N^* \}. \end{aligned}$$

Notice that at any $p \in \partial N^*$, $T_p N^*$ is exactly the *n*-dimensional half-space in \mathbf{R}^L with boundary $T_p(\partial N^*)$.

We define the space of rectifiable *n*-varifolds in N^* , denoted by $\mathcal{RV}_n(N^*)$, to be the set of all rectifiable *n*-varifolds in \mathbf{R}^L with $\operatorname{spt}||V|| \subset N^*$. Moreover, $\mathcal{V}_n(N^*)$ is defined

to be the closure, in the weak topology, of $\mathcal{RV}_n(N^*)$. Note that in general, $\mathcal{V}_n(N^*)$ is a proper subset of $\mathbf{V}_n(\mathbf{R}^L) \cap \{V : \operatorname{spt} ||V|| \subset N^*\}$, and in fact, if $V \in \mathcal{V}_n(N^*)$, then one has (see [13, 2.1(18)(g)]):

$$V(G_n(\mathbf{R}^L) \setminus G_n(N^*)) = 0.$$

Similar property holds for those $W \in \mathcal{V}_n(\partial N^*)$.

Let $V \in \mathcal{V}_n(N^*)$, if $X \in \mathfrak{X}(N)$ generates a one-parameter family of diffeomorphisms ϕ_t of \mathbf{R}^L with $\phi_t(N^*) \subset N^*$ (at a point p on ∂N^* , one considers the tangent space $T_p N^*$ as the half (n + 1)-space obtained by the blow-up of N^* at p), then $(\phi_t)_{\#} V \in \mathcal{V}_n(N^*)$ and one can consider its first variation along X [1, (4.2), (4.4)]:

$$\delta V[X] := \frac{\mathrm{d}}{\mathrm{d}t} \mid_{t=0} \mathbf{M}((\phi_t)_{\#}V) = \int_{G_n(N^*)} \mathrm{div}_P X(x) \mathrm{d}V(x, P),$$

here $\operatorname{div}_P X(x) = D_{e_i} X \cdot e_i$, where $\{e_1, \ldots, e_n\} \subset P$ is any orthonormal basis. In particular, for $W \in \mathcal{V}_n(\partial N^*)$, we have:

$$\delta W[X] = \int_{G_n(\partial N^*)} \operatorname{div}_P X(x) \mathrm{d} W(x, P) = \int_{\partial N^*} \operatorname{div}_{\partial N^*} X(x) \mathrm{d} ||W||(x).$$
(2.1)

2.2. Contact angle condition for varifolds

Let us first introduce the contact angle condition for varifolds, which, to the author's knowledge, was brought up in [9] formally, and then extended to a weaker form in [5].

Definition 2.1. (Contact angle condition, [5, Definition 3.1]). Given $\theta \in (0, \pi)$, we say that the pair $(V, W) \in \mathcal{V}_n(N^*) \times \mathcal{V}_n(\partial N^*)$ satisfies the contact angle condition θ , if there exists a ||V||-measurable vector field $\mathbf{H} \in \mathcal{L}^1(N^*, ||V||)$ with $\mathbf{H}(x) \in T_x \partial N^*$ for ||V||-a.e. $x \in \partial N^*$, such that for every $X \in \mathfrak{X}_t(N^*)$, it holds²:

$$\begin{split} \delta_{F_{\theta}}(V,W)[X] &:= \int_{G_{n}(N^{*})} \operatorname{div}_{P} X(x) \mathrm{d}V(x,P) - \cos \theta \int_{G_{n}(\partial N^{*})} \operatorname{div}_{P} X(x) \mathrm{d}W(x,P) \\ &= -\int_{N^{*}} \langle X(x), \mathbf{H}(x) \rangle \, \mathrm{d}||V||(x). \end{split}$$

In particular, we say that (V, W) is a θ -stationary pair if in addition, $\mathbf{H} = 0$ for a.e. $x \in \operatorname{spt}[|V|]$.

² We note that our definitions of varifolds are different from that of [3, 5], where a k-varifold on $A \subset \mathbf{R}^L$ is defined to be a positive Radon measure on $A \times G(L, k)$. Here, we can rewrite the second term by virute of (2.1).

An important proposition³ for the pair of varifolds with fixed contact angle is that they have bounded first variation and satisfies the following first variation formula.

Proposition 2.2. ([5, Proposition 3.1]). Given $\theta \in [\pi/2, \pi)$, let $(V, W) \in \mathcal{V}_n(N^*) \times \mathcal{V}_n(\partial N^*)$ have fixed contact angle θ . Then $V - \cos \theta W$ has bounded first variation. More precisely, there exists a positive Radon measure σ_V on ∂N^* and a continuous vector field $\tilde{\mathbf{H}}$, such that:

$$\int_{G_n(N^*)} \operatorname{div}_P X(x) \mathrm{d}V(x, P) - \cos\theta \int_{G_n(\partial N^*)} \operatorname{div}_P X(x) \mathrm{d}W(x, P) = -\int_{N^*} \langle X, \mathbf{H} \rangle \,\mathrm{d}||V|| \\ - \int_{\partial N^*} \langle X, \tilde{\mathbf{H}} \rangle \,\mathrm{d}\left(||V|| - \cos\theta||W||\right) + \int_{\partial N^*} \langle X, -\nu_{N^*} \rangle \,\mathrm{d}\sigma_V, \quad \forall X \in \mathfrak{X}(N^*),$$
(2.2)

where **H** is as in Definition 2.1; $\tilde{\mathbf{H}}$ is the mean curvature of ∂N^* in N^* , given by:

$$\widetilde{\mathbf{H}}(x) = \nu_{N^*}(x) \operatorname{div}_{\partial N^*}(-\nu_{N^*}(x)), \quad \text{for every } x \in \partial N^*,$$

and we denote by $\tilde{H}(x) = \operatorname{div}_{\partial N^*}(-\nu_{N^*}(x))$ so that $\tilde{\mathbf{H}}(x) = \tilde{H}(x)\nu_{N^*}(x)$.

If V is a C^2 -hypersurface in N^* (similar with the hypersurface S considered in the introduction), we denote by Ω the enclosed region of V and ∂N^* , $T := \partial \Omega \cap \partial N^*$ is the wetting hypersurface with respect to V and $\overline{\mu}$ is the inwards pointing unit conormal of $V \cap T$ in T, then the first variation of V with respect to the direction $X \in \mathfrak{X}(N^*)$ is just

$$\delta V(X) := \frac{\mathrm{d}}{\mathrm{d}t} \mid_{t=0} \operatorname{Area}(\psi_t(V)) = \int_V \operatorname{div}_V X \mathrm{d}\mathcal{H}^n$$
$$= -\int_V \langle X, H \rangle \, \mathrm{d}\mathcal{H}^n - \int_{\partial V} \langle X, \mu \rangle \, \mathrm{d}\mathcal{H}^{n-1},$$

where ψ_t is the flow of X at the time t, H is the inwards pointing mean curvature vector of V and μ is the inwards pointing unit conormal of ∂V in V. If V meets ∂N^* with constant contact angle θ , notice that along ∂N^* , we have $\mu = \cos \theta \bar{\mu} + \sin \theta \nu_{N^*}$ (see Figure 1), we thus obtain,

$$\begin{split} \int_{\partial V} \langle X, \mu \rangle \, \mathrm{d}\mathcal{H}^{n-1} &= \cos \theta \int_{\partial V} \langle X, \bar{\mu} \rangle \, \mathrm{d}\mathcal{H}^{n-1} + \sin \theta \int_{\partial V} \langle X, \nu_{N^*} \rangle \, \mathrm{d}\mathcal{H}^{n-1} \\ &= -\cos \theta \left(\int_T \mathrm{div}_{\partial N^*} X \, \mathrm{d}\mathcal{H}^n + \int_T \left\langle X, \tilde{H} \right\rangle \, \mathrm{d}\mathcal{H}^n \right) \\ &+ \sin \theta \int_{\partial V} \left\langle X, \nu_{N^*} \right\rangle \, \mathrm{d}\mathcal{H}^{n-1}, \end{split}$$

 3 As noted before, our definitions of varifolds are different from [5]. However, the proof therein, which is based on [3, Corollary 4.6] and [4, Proposition 3.17], works finely for our definitions.

where we used the contact angle condition to derive the first equality and the divergence theorem for the second equality. In this case, it is clear that the Radon measure σ_V in Proposition 2.2 is just $\sin\theta \mathcal{H}^{n-1} \cup (\partial V)$. On the other hand, for $X \in \mathfrak{X}_t(N^*)$, one has:

$$\int_{T} \operatorname{div}_{\partial N^{*}} X \, \mathrm{d}\mathcal{H}^{n} = \int_{\partial V} \langle X, -\bar{\mu} \rangle \, \mathrm{d}\mathcal{H}^{n-1} = \frac{1}{\sin\theta} \int_{\partial N^{*}} \langle X, -\bar{\mu} \rangle \, \mathrm{d}\sigma_{V}.$$

Moreover, consider the set $\partial N^* \setminus T$, it is easy to see that for $X \in \mathfrak{X}_t(N^*)$, there holds:

$$\int_{\partial N^* \setminus T} \operatorname{div}_{\partial N^*} X \mathrm{d}\mathcal{H}^n = -\int_{\partial N^* \setminus T} \operatorname{div}_{\partial N^*} X \mathrm{d}\mathcal{H}^n$$

Enlightened by this simple observation, we introduce the following definition that is stronger than Definition 2.1.

Definition 2.3. For $\theta \in [\pi/2, \pi)$, let $(V, W) \in \mathcal{V}_n(N^*) \times \mathcal{V}_n(\partial N^*)$ have fixed contact angle θ and let $\sigma_V, \mathbf{H}, \tilde{\mathbf{H}}$ be as in Proposition 2.2. We say that (V, W) is a fine θ -pair if there exists $\tilde{\mu} \in \mathcal{L}^1(\partial N^*, \sigma_V)$ with $\tilde{\mu}(x) \in T_x \partial N^*$ and $|\tilde{\mu}(x)| = 1$ for a.e. $x \in \operatorname{spt}\sigma_V$, such that: for every $X \in \mathfrak{X}_t(N^*)$, there holds:

$$\int_{G_n(\partial N^*)} \operatorname{div}_P X(x) \mathrm{d}W(x, P) = \int_{\partial N^*} \operatorname{div}_{\partial N^*} X \mathrm{d}||W|| = \frac{1}{\sin \theta} \int_{\partial N^*} \langle X, \tilde{\mu} \rangle \, \mathrm{d}\sigma_V.$$
(2.3)

For $\theta \in (0, \pi/2)$, we say that $(V, W) \in \mathcal{V}_n(N^*) \times \mathcal{V}_n(\partial N^*)$ is a fine θ -pair if there exists $\tilde{W} \in \mathcal{V}_n(\partial N^*)$ such that:

- (1) (V, \tilde{W}) is a fine $(\pi \theta)$ -pair (in this case $\pi \theta \in (\pi/2, \pi)$, let $\sigma_V, \mathbf{H}, \tilde{\mathbf{H}}, \tilde{\mu}$ be the resulting notations);
- (2) For any $X \in \mathfrak{X}_t(N^*)$, there holds

$$\int_{\partial N^*} \operatorname{div}_{\partial N^*} X \mathrm{d} ||W|| = -\int_{\partial N^*} \operatorname{div}_{\partial N^*} X \mathrm{d} ||\tilde{W}||.$$
(2.4)

In particular, we say that (V, W) is a fine θ -stationary pair if in addition, $\mathbf{H} = 0$ for a.e. $x \in \operatorname{spt}[|V|]$.

Now we consider the case $\theta \in (0, \pi/2)$ and (V, W) is a fine θ -pair, by definition there exists $\tilde{W} \in \mathcal{V}_n(\partial N^*)$ such that (V, \tilde{W}) is a fine $(\pi - \theta)$ -pair, and from (2.3) and (2.4), we see that for any $X \in \mathfrak{X}_t(N^*)$,

$$\int_{\partial N^*} \operatorname{div}_{\partial N^*} X \mathrm{d}||W|| = -\int_{\partial N^*} \operatorname{div}_{\partial N^*} X \mathrm{d}||\tilde{W}|| = -\frac{1}{\sin(\pi - \theta)} \int_{\partial N^*} \langle X, \tilde{\mu} \rangle \,\mathrm{d}\sigma_V$$
$$= \frac{1}{\sin\theta} \int_{\partial N^*} \langle X, -\tilde{\mu} \rangle \,\mathrm{d}\sigma_V. \tag{2.5}$$

Since ∂N^* is a smooth hypersurface in N^* , a standard computation then gives that, for any $X \in \mathfrak{X}(N^*)$,

$$\int_{\partial N^*} \operatorname{div}_{\partial N^*} X \mathrm{d} ||\tilde{W}|| = \int_{\partial N^*} \operatorname{div}_{\partial N^*} (X^T + X^{\perp}) \mathrm{d} ||\tilde{W}|| = \frac{1}{\sin \theta} \int_{\partial N^*} \langle X, \tilde{\mu} \rangle \, \mathrm{d}\sigma_V - \int_{\partial N^*} \left\langle X, \tilde{\mathbf{H}} \right\rangle \mathrm{d} ||\tilde{W}||, \qquad (2.6)$$

here the tangential and normal part of X are stated with respect to ∂N^* , to derive the second equality we have used (2.3) for \tilde{W} (notice that $\sin(\pi - \theta) = \sin \theta$) and the fact that $\tilde{\mu}(x) \in T_x \partial N^*$ for a.e. $x \in \operatorname{spt} \sigma_V$.

If in addition, the fine θ -pair (V, W) is stationary, then (2.2) yields:

$$\int_{G_n(N^*)} \operatorname{div}_P X(x) \mathrm{d}V(x, P) - \cos(\pi - \theta) \int_{\partial N^*} \operatorname{div}_{\partial N^*} X \mathrm{d}||\tilde{W}||$$

= $-\int_{\partial N^*} \left\langle X, \tilde{\mathbf{H}} \right\rangle \mathrm{d}\left(||V|| - \cos(\pi - \theta)||\tilde{W}||\right) + \int_{\partial N^*} \left\langle X, -\nu_{N^*} \right\rangle \mathrm{d}\sigma_V,$

taking (2.6) into account, this reads:

$$\int_{G_n(N^*)} \operatorname{div}_P X(x) \mathrm{d}V(x, P) \\
= \frac{\cos \theta}{\sin \theta} \int_{\partial N^*} \langle X, -\tilde{\mu} \rangle \, \mathrm{d}\sigma_V - \int_{\partial N^*} \tilde{H} \langle X, \nu_{N^*} \rangle \, \mathrm{d}||V|| + \int_{\partial N^*} \langle X, -\nu_{N^*} \rangle \, \mathrm{d}\sigma_V. \quad (2.7)$$

Remark 2.4. In Definition 2.3, for the case $\theta \in (0, \pi/2)$ we require the existence of $\tilde{W} \in \mathcal{V}_n(\partial N^*)$ with desired properties. Note that these properties clearly hold when W is the naturally induced rectifiable varifold of a smooth compact domain $T \subset \partial N^*$, since we can simply take \tilde{W} to be the naturally induced rectifiable varifold of $\partial N^* \setminus T$. The statement here remains true if T is a Caccioppoli set (set of finite perimeter) in ∂N^* .

Remark 2.5. In Theorem 1.1, we consider the cases when V is supported in Ω and W is supported in $T = \partial \Omega \cap \partial N^*$. Thanks to (2.5), we know that as a positive Radon measure on ∂N^* , σ_V is supported on T. Therefore when testing the first variation (2.7), it suffice to consider the behaviour of X on Ω .

We end this section by giving an example of a pair of varifolds that satisfies the contact angle condition but violates the conclusion of Theorem 1.1, revealing the necessity of defining fine θ -pair. The construction in the following example is inspired by another example (Example A.1) shown to the author by Gaoming Wang when a preliminary version of this manuscript is reviewed and somewhat becomes the major motivation of this paper and the strong maximum principle for pairs of stationary rectifiable cones derived in [16, Lemma 2.16].



Figure 3. Example 2.6.

Example 2.6. Let N^* be the unit ball in the plane \mathbb{R}^2 centred at the origin, ∂N^* is then the unit sphere. Let p_1, p_2 be two points on ∂N^* such that the line segment joining them, say L, has contact angle $\frac{\pi}{3}$ with ∂N^* . Let S be a mean convex curve joining p_1 and p_2 in N^* to enclose a domain Ω so that S has a contact angle $\theta_0 = \arccos \frac{1}{4}$ with ∂N^* . Let V be the naturally induced multiplicity 1 varifold by L, let W be the multiplicity 2 varifold induced by $\partial \Omega \cap \partial N^*$ (see Figure 3).

Then, (V, W) is a θ_0 -stationary pair but not a fine θ_0 -stationary pair, with ||V|| supported in Ω .

Proof. A direct computation shows that: for any $X \in \mathfrak{X}(N^*)$,

$$\begin{split} \int_{G_1(N^*)} \operatorname{div}_P X(x) \mathrm{d}V(x,P) &= \int_L \operatorname{div}_L X(x) \mathrm{d}\mathcal{H}^1(x) = \langle X(p_1), -\mu_L(p_1) \rangle \\ &+ \langle X(p_2), -\mu_L(p_2) \rangle \\ &= \frac{1}{2} \sum_{i=1}^2 \langle X(p_i), -\bar{\mu}(p_i) \rangle + \frac{\sqrt{3}}{2} \sum_{i=1}^2 \langle X(p_i), -\nu_{N^*}(p_i) \rangle, \quad (2.8) \end{split}$$

where we have used the fact that $-\mu_L(p_i) = \cos \frac{\pi}{3}(-\bar{\mu}(p_i)) + \sin \frac{\pi}{3}(-\nu_N * (p_i)).$

Similarly, one has

$$\int_{G_1(\partial N^*)} \operatorname{div}_P X(x) \mathrm{d}W(x, P) = \int_{\partial N^* \cap \partial \Omega} 2 \operatorname{div}_{\partial N^*} X(x) \mathrm{d}\mathcal{H}^1(x)$$
$$= 2 \sum_{i=1}^2 \left\langle X(p_i), -\bar{\mu}(p_i) \right\rangle - \int_{\partial N^* \cap \partial \Omega} \left\langle X(x), \tilde{\mathbf{H}}(x) \right\rangle \mathrm{d}||W||(x).$$
(2.9)

It is then easy to see that for any $X \in \mathfrak{X}_t(N^*)$ (recall that $\cos \theta_0 = \frac{1}{4}$),

$$\int_{G_1(N^*)} \mathrm{div}_P X(x) \mathrm{d} V(x, P) - \cos \theta_0 \int_{G_1(\partial N^*)} \mathrm{div}_P X(x) \mathrm{d} W(x, P) = 0,$$

which shows that (V, W) is a θ_0 -stationary pair.

To see that (V, W) is not a fine θ_0 -stationary pair, let us consider the multiplicity 2 varifold induced by $\partial N^* \setminus \partial \Omega$, denoted by \tilde{W} . Clearly for any $X \in \mathfrak{X}_t(N^*)$, we have:

$$\int_{\partial N^*} \operatorname{div}_{\partial N^*} X \mathrm{d}||W|| = -\int_{\partial N^*} \operatorname{div}_{\partial N^*} X \mathrm{d}||\tilde{W}||, \qquad (2.10)$$

and (V, W) is a $(\pi - \theta_0)$ -stationary pair. It then follows from (2.8), (2.9), (2.10) and Proposition 2.2 that σ_V in this case is given by $\frac{\sqrt{3}}{2}\mathcal{H}^0 {\scriptscriptstyle L}\{p_1, p_2\}$. However, notice that for any $X \in \mathfrak{X}_t(N^*)$,

$$\begin{split} \int_{G_1(\partial N^*)} \operatorname{div}_P X(x) \mathrm{d}\tilde{W}(x,P) &= \int_{\partial N^* \setminus \partial \Omega} 2 \operatorname{div}_{\partial N^*} X(x) \mathrm{d}\mathcal{H}^1(x) \\ &= 2 \left(\langle X(p_1), \bar{\mu}(p_1) \rangle + \langle X(p_2), \bar{\mu}(p_2) \rangle \right) \\ &\neq \frac{1}{\frac{\sqrt{15}}{4}} \int_{\partial N^*} \langle X, \bar{\mu} \rangle \, \mathrm{d}\sigma_V, \end{split}$$

and hence (V, W) is not a fine θ_0 -stationary pair. Clearly ||V|| is supported in Ω , which completes the proof.

3. Proof of Theorem 1.1

As illustrated in § 1, we need the following foliations, see [11, Lemma 2.1] for the free boundary case. To prove the following lemma, we will exploit the Fermi coordinate system at p. For discussions on Fermi coordinate, see for example [7, Section 6] and [12, Appendix A].

Lemma 3.1. For any properly embedded hypersurface S, having constant contact angle $\theta_0 \in (0, \pi/2)$ with ∂N^* , there exists a constant $\delta > 0$; a neighbourhood $U \subset N^*$ containing $p \in S \cap \partial N^*$; and foliations $\{S_s\}, \{T_t\}$, with $s \in (-\delta, \delta), t \in (0, \delta)$, of $U, U \cap \Omega$, respectively; such that $S_0 = S \cap U$, and S_s intersects T_t orthogonally for every s and t. In addition, each hypersurface S_s meets ∂N^* with constant contact angle θ_0 .

Proof. We first extend S locally near p to a foliation $\{S_s\}$ such that each S_s meets ∂N^* with constant contact angle θ_0 . This can be done by a simple modification of [11, Lemma 2.1].

Let (x_1, \ldots, x_{n+1}) be a local Fermi coordinate system of N^* centered at p, such that $x_1 = \text{dist}_{N^*}(\cdot, \partial N^*)$. Furthermore, we assume that (x_2, \ldots, x_{n+1}) is a local Fermi coordinate system of ∂N^* , relative to the hypersurface $S \cap \partial N^*$; that is, x_{n+1} is the signed distance in ∂N^* from $S \cap \partial N^*$.

In the rest of this paper, we denote by $B_{r_0}^+ = \{x_1^2 + \ldots x_n^2 < r_0^2 \mid x_1 \ge 0, x_{n+1} = 0\}$ the *n*-dimensional half ball in the Fermi coordinate. Since *S* meets ∂N^* with a constant contact angle $\theta_0 \in (0, \pi)$, we can express *S* in such local coordinates as the graph $x_{n+1} =$ $f(x_1, \ldots, x_n)$ of a function *f* defined on a half ball $B_{r_0}^+$, such that f = 0 along $B_{r_0}^+ \cap$ $\{x_1 = 0\}$. Moreover, due to the contact angle condition, we can carry out the following computation, see also [2, Section 7.1] for a detailed computation of minimal graphs on manifolds.

First we fix some notations. Let g_{ij} denote the metric on N^* in the local Fermi coordinate (x_1, \ldots, x_{n+1}) . Set \bar{e}_i to be the vector field $\frac{\partial}{\partial x_i}$ so that $\langle \bar{e}_i, \bar{e}_j \rangle = g_{ij}$. For simplicity, we define a positive smooth function W_f by

$$W_{f}^{2}(x_{1},\dots,x_{n}) = g^{n+1,n+1} + \sum_{i,j=1}^{n} g^{ij}(x_{1},\dots,x_{n},f(x_{1},\dots,x_{n})) \frac{\partial f}{\partial x_{i}} \frac{\partial f}{\partial x_{j}} - 2\sum_{l=1}^{n} g^{l,n+1} \frac{\partial f}{\partial x_{l}}.$$
(3.1)

Now, let ν denote the outwards pointing unit normal of S, computing as [2, (7.11)], we obtain:

$$\langle \nu, \bar{e}_i \rangle = \frac{1}{W_f} \frac{\partial f}{\partial x_i}, \quad i = 1, \dots, n.$$
 (3.2)

In particular, since S meets ∂N^* with contact angle θ_0 , we have $\langle \nu, \bar{e}_1 \rangle = \cos \theta_0$ along $\{x_1 = 0\}$, and hence (3.2) yields:

$$\frac{\partial f}{\partial x_1}(0, x_2, \dots, x_n) = \cos \theta_0 W_f(0, x_2, \dots, x_n) \quad \text{on } \{x_1 = 0\}.$$
(3.3)

Note that on N^* we have $g_{11} = 1, g_{1k} = 0$ for k = 2, ..., n+1 since $x_1 = \text{dist}_{N^*}(\cdot, \partial N^*)$, and on $\{x_1 = 0\} \subset \partial N^*$ we have $g_{n+1,n+1} = 1, g_{n+1,l} = 0$ for l = 2, ..., n since x_{n+1} is the signed distance function in ∂N^* from $S \cap \partial N^*$. Recall also that $0 = f(0, x_2, ..., x_n)$, (3.1) when restricted to $\{x_1 = 0\}$ thus reads:

$$W_f^2(0, x_2..., x_n) = 1 + \left(\frac{\partial f}{\partial x_1}(0, x_2, ..., x_n)\right)^2,$$
 (3.4)

since the other partial derivatives of f vanish. Combining this with (3.3), we get:

$$\frac{\partial f}{\partial x_1}(0, x_2, \dots, x_n) = \cot \theta_0, \quad W_f(0, x_2, \dots, x_n) = \frac{1}{\sin \theta_0}$$

In view of this, the translated graphs,

$$x_{n+1} = f(x_1, \dots, x_n) + s =: f_s(x_1, \dots, x_n),$$

then gives a local foliation $\{S_s\}$ near p, and we can show that each leaf S_s is a hypersurface in N^* which meets ∂N^* with constant contact angle θ_0 along its boundary $S_s \cap \partial N^*$. Indeed, a direct computation gives that:

$$\frac{\partial f_s}{\partial x_1}(0, x_2, \dots, x_n) = \frac{\partial f}{\partial x_1}(0, x_2, \dots, x_n) = \cot \theta_0.$$

Since $f_s = s$ along $\{x_1 = 0\}$, we may argue as (3.4) to find that along $\{x_1 = 0\}$,

$$W_{f_s}^2(0, x_2, \dots, x_n) = 1 + \left(\frac{\partial f_s}{\partial x_1}(0, x_2, \dots, x_n)\right)^2 = \frac{1}{\sin^2 \theta_0}.$$

It is then easy to see that along $\{x_1 = 0\}$,

$$\frac{\partial f_s}{\partial x_1}(0, x_2, \dots, x_n) = \cos \theta_0 W_{fs}(0, x_2, \dots, x_n),$$

which implies that S_s touches ∂N^* with constant contact angle θ_0 according to (3.3).

Next, the construction of $\{T_t\}$ which is orthogonal to every leaf of $\{S_s\}$ follows from [11, Lemma 2.1], we include the details here for readers' convenience. Let $q \in N^*$ be a point near p which lies on the leaf S_s . We define $\nu(q)$ to be a unit vector normal to the hypersurface S_s . By a continuous choice of ν it gives a smooth unit vector field in a neighbourhood of p. Since ν is nowhere vanishing near p, the integral curves of ν gives a local 1-dimensional foliation of N^* near p. The desired foliation $\{T_t\}$ is obtained by putting together these integral curves. Precisely, let $\Gamma_t \subset S$ be the parallel hypersurface in S which is of distance t > 0 away from $S \cap \partial N^*$. For $t \ge 0$, set T_t to be the union of all the integral curves of ν which pass through Γ_t . Then, by zooming in at p, we obtain a small $\delta > 0$, and a small set $U \cap \Omega$ (see Figure 2 for illustration), which is indeed foliated by $\{T_t\}_{t \in (0,\delta)}$. On the other hand, $\{S_s\}_{s \in (-\delta,\delta)}$ apparently foliates U. This completes the proof.

The local orthogonal foliation in Lemma 3.1 yields the following orthonormal frame of Ω near p, which is needed in our proof of Theorem 1.1.

Lemma 3.2. ([11, Lemma 2.2]). Let $\{e_1, \ldots, e_{n+1}\}$ be a local orthonormal frame of Ω near p, such that at each $q \in S_s \cap T_t$, $e_1(q)$ and $e_{n+1}(q)$ is normal to $S_s \cap T_t$ inside S_s

and T_t , respectively. In particular, we choose e_{n+1} so that $e_{n+1} = \nu_S$ on S_0 ; $-e_1$ points into N^* along ∂N^* .

Proof of Theorem 1.1. As mentioned in the introduction, we want to construct a test vector field X, having its support arbitrarily close to p in Ω . This is done in the following manner.

Step 1. Constructing a hypersurface S' in N^* , which touches Ω from outside up to second order at p.

For every $\epsilon > 0$ small, we define:

$$\Gamma = \left\{ x \in \partial N^* : \operatorname{dist}_{\partial N^*}(x, \partial S) = \epsilon \operatorname{dist}_{\partial N^*}(x, p)^4 \right\},\$$

which is an (n-1)-dimensional hypersurface in ∂N^* and is smooth in a neighbourhood of p. It has been proved in [11, Section 3, Claim 1] that Γ indeed touches ∂S from outside T up to second order at p.

Now we extend Γ to our desired hypersurface S' in N^* . The construction is as follows. Let (x_1, \ldots, x_{n+1}) be a Fermi coordinate system centred at p as in Lemma 3.1 so that:

(1) $\{x_1 \ge 0\} \subset N^*,$ (2) $\{x_{n+1} = f(x_1, \dots, x_n) \ge 0\} \subset S,$ (3) $\{x_{n+1} \ge f(x_1, \dots, x_n)\} \subset \Omega,$ (4) $\{x_1 = x_{n+1} = 0\} \subset \Gamma.$

Then, we do a slight modification of the Fermi coordinate (x_1, \ldots, x_{n+1}) by further requiring x_{n+1} to agree with the signed distance function from Γ in ∂N^* , and denote this coordinate by $(x_1, \tilde{x}_2, \ldots, \tilde{x}_{n+1})$, correspondingly, S is expressed as the local graph $\tilde{x}_{n+1} = \tilde{f}(x_1, \tilde{x}_2, \ldots, \tilde{x}_n)$. The fact that Γ touches ∂S from outside T at p implies: $\tilde{f}(0, \tilde{x}_2, \ldots, \tilde{x}_n) \geq 0$, with equality holds only at the origin.

In this new Fermi coordinate, we can proceed our construction of S'. Let $\vec{0}$ denote the origin of the Fermi coordinate chart centred at p, we denote by \tilde{g} the metric in this new coordinate, \tilde{W} the counterpart of W (given by (3.1)) in this coordinate. We set S' to be the graph $\tilde{x}_{n+1} = u(x_1, \tilde{x}_2, \ldots, \tilde{x}_n)$ of the smooth function u, defined by:

$$u(x_1, \tilde{x}_2, \dots, \tilde{x}_n) = x_1 \cot \theta_0 + \frac{x_1^2}{2} \frac{\partial^2 f}{\partial x_1^2}(\vec{0}) + \frac{x_1^3}{6} \left(\frac{\partial^3 f}{\partial x_1^3}(\vec{0}) - \epsilon \right).$$

It is clear that u = 0 and $\frac{\partial u}{\partial x_1} = \cot \theta_0$ on $\{x_1 = 0\}$. Since $0 = u(0, \tilde{x}_2, \dots, \tilde{x}_n)$, as computed in (3.4), we have,

$$\tilde{W}_u^2(0, \tilde{x}_2, \dots, \tilde{x}_n) = 1 + \left(\frac{\partial u}{\partial x_1}(0, \tilde{x}_2, \dots, \tilde{x}_n)\right)^2 = \frac{1}{\sin^2 \theta_0},$$

and it is easy to see that on $\{x_1 = 0\}$,

$$\frac{\partial u}{\partial x_1}(0, \tilde{x}_2, \dots, \tilde{x}_n) = \cos \theta_0 \tilde{W}_u(0, \tilde{x}_2, \dots, \tilde{x}_n).$$

These facts imply: (1) S' is an extension of Γ ; (2) S' meets ∂N^* with constant contact angle θ_0 , due to (3.3). By [11, Claim 1], we know that all the partial derivatives (with respect to the coordinates $x_1, \tilde{x}_2, \ldots, \tilde{x}_n$) of u and \tilde{f} agree up to second-order at $\vec{0}$, and for sufficiently small ϵ , $\tilde{f} \geq u$ everywhere in a neighbourhood of p with equality holds only at the origin; that is to say, S' touches Ω from outside up to second-order at p. Step 2. Constructing the test vector field X, which decreases the first variation of V strictly.

In **Step 1**, we constructed a hypersurface S', meeting ∂N^* with constant contact angle θ_0 , and hence we can use Lemma 3.1 to obtain local foliations $\{S'_s\}$ and $\{T'_t\}$. We define smooth functions s, t in a neighbourhood of p, so that s(q) is the unique s such that $q \in S'_s$. Recall that $s \geq 0$ on Ω .

Claim. $\nabla s = \psi e_{n+1}$ for some smooth function ψ such that $\psi \ge c$ near p for some positive constant c. Here $\{e_1, \ldots, e_{n+1}\}$ is a local orthonormal frame near p, as in Lemma 3.2.

Proof of Claim. Since s is a constant on each leaf S'_s , we have that ∇s is normal to S'_s . It follows from the definition of e_{n+1} that $\nabla s = \psi_1 e_{n+1}$, where ψ_1 is smooth in $U \cap \Omega$.

By continuity, we find that $\psi \ge \psi(p) := c$ near p (without loss of generality, we may assume that $c = \frac{1}{2}$, otherwise we substitute s by $\frac{\psi(p)}{2}s$).

Now we define the test vector field X on N^* near p by:

$$X(q) = \phi(s(q))(-e_{n+1}(q)), \tag{3.5}$$

where $\phi(s)$ is the cut-off function defined by:

$$\phi(s) = \begin{cases} \exp(\frac{1}{s-\epsilon}), & 0 \le s < \epsilon, \\ 0, & s \ge \epsilon. \end{cases}$$

Note that the construction of X is sufficient for our purpose due to Remark 2.5. A direction computation then gives, for $0 \le s < \epsilon$, it holds:

$$\frac{\phi'(s)}{\phi(s)} = -\frac{1}{(s-\epsilon)^2} \le \frac{-1}{\epsilon^2},$$

and hence for any $s \ge 0$, we have,

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$$\phi'(s) \le -\frac{\phi(s)}{\epsilon^2}.\tag{3.6}$$

Since S' touches Ω from outside, we have $s \geq 0$ on Ω , and $\operatorname{spt}(\phi) \cap \Omega$ will be close to p as long as ϵ is small. Thus, if we choose ϵ to be small enough, then in Ω , our test vector field X will have compact support near p. Moreover, since $-e_{n+1}(q)$ points into N^* for all $q \in \partial N^*$, we have that $X \in \mathfrak{X}(N^*)$. This finishes the construction of our test vector field X.

Step 3. Testing the first variation by X.

At each $q \in \Omega$ that is close to p, we consider the bilinear form on $T_q N^*$ defined by:

$$Q(u,v) = \langle \nabla_u X, v \rangle (q).$$

Let $\{e_1, \ldots, e_{n+1}\}$ be a local orthonormal frame near p as in Lemma 3.2. As computed in [11, (3.1)], the bilinear form Q^4 can be expressed in this frame by the following matrix:

$$Q = \begin{bmatrix} \phi A_{11}^{S'_s} & -\phi A_{n+1,j}^{T_t} & 0\\ -\phi A_{i,n+1}^{T_t} & \phi A_{ij}^{S'_s} & 0\\ -\phi A_{n+1,n+1}^{T_t} & -\phi \left\langle \nabla_{e_{n+1}} e_{n+1}, e_j \right\rangle & -\phi' \psi_1 \end{bmatrix},$$

where $i, j = 2, \ldots, n$, and $q \in S'_s \cap T_t$.

Using (3.6) and the strictly mean convexity of S at p, one finds as in [11, Lemma 3.2, Lemma 3.3]: for $\epsilon > 0$ small enough, there holds: $\operatorname{tr}_P Q > 0$ for all n-dimensional subspaces $P \subset T_q N^*$.

Since (V, W) is a fine θ -stationary pair and V is supported in Ω , W is supported in T, we can use X to test the first variation formula (2.7) to find:

$$\begin{split} \int_{G_n(N^*)} \mathrm{tr}_P Q(q) \mathrm{d}V(q, P) &= \frac{\cos \theta_0}{\sin \theta_0} \int_{\partial N^*} \phi(s(q)) \left\langle -e_{n+1}, -\tilde{\mu} \right\rangle(q) \mathrm{d}\sigma_V(q) \\ &- \int_{\partial N^*} \tilde{H}(q) \phi(s(q)) \left\langle -e_{n+1}, \nu_{N^*} \right\rangle(q) \mathrm{d}||V||(q) \\ &+ \int_{\partial N^*} \phi(s(q)) \left\langle -e_{n+1}, -\nu_{N^*} \right\rangle(q) \mathrm{d}\sigma_V(q). \end{split}$$

Recall that S'_s meets ∂N^* with constant contact angle θ_0 , so that at every $q \in \partial N^*$, there exists a unit vector $-\bar{\mu}(q) \in T_q \partial N^*$ such that:

 4 Notice that our choice of vector field (3.5) agrees with the one in [11], up to a different sign.

$$-e_{n+1}(q) = \sin \theta_0(-\bar{\mu}(q)) + \cos \theta_0 \nu_{N^*}(q),$$

which implies

$$\int_{G_n(N^*)} \operatorname{tr}_P Q(q) \mathrm{d}V(q, P) = \cos \theta_0 \int_{\partial N^*} \phi(s(q)) \langle \bar{\mu}, \tilde{\mu} \rangle (q) \mathrm{d}\sigma_V(q) - \cos \theta_0 \int_{\partial N^*} \phi(s(q)) \mathrm{d}\sigma_V(q) - \cos \theta_0 \int_{\partial N^*} \tilde{H}(q) \phi(s(q)) \mathrm{d}||V||(q).$$
(3.7)

Conclusion of the proof.

Recall that as we choose ϵ small enough, in Ω our test vector field X will have compact support close to p, and hence we see from **Step 3** that:

$$\delta V[X] = \int_{G_n(N^*)} \operatorname{div}_P X(x) \mathrm{d} V(x, P) = \int_{G_n(N^*)} \operatorname{tr}_P Q(q) \mathrm{d} V(q, P) > 0,$$
(3.8)

since for any *n*-dimensional affine subspace $P \in T_q N^*$, $\operatorname{div}_P X(q) = \operatorname{tr}_P Q(q) > 0$.

Let us check the sign of the RHS of (3.7). By virtue of the condition $\theta_0 \in (0, \pi/2)$, the fact that $\phi(s(q)) \ge 0$ on $\{s \ge 0\}$, and the fact that $\langle \bar{\mu}(q), \tilde{\mu}(q) \rangle \le 1$ locally near p, we immediately deduce:

$$\int_{G_n(N^*)} \operatorname{tr}_P Q(q) \mathrm{d}V(q, P) \le -\cos\theta_0 \int_{\partial N^*} \tilde{H}(q)\varphi(s(q)) \mathrm{d}||V||(q).$$

For both case **i** and **ii** of Theorem 1.1, we readily see that $\int_{\partial N^*} \tilde{H}(q)\varphi(s(q))d||V||(q) \ge 0$, and thanks to $\theta_0 \in (0, \pi/2)$ again,

$$\int_{G_n(N^*)} \operatorname{tr}_P Q(q) \mathrm{d} V(q, P) \le 0.$$

However, this contradicts to (3.8) and completes the proof.

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Appendix 1. Examples of stationary pairs with contact angle condition

In the appendix, we adopt the following convention: for a smooth curve C in \mathbb{R}^2 and a positive constant $\alpha > 0$, we denote by $\operatorname{var}(C, \alpha)$ the multiplicity α , 1-varifold induced by C. The shorthand $\operatorname{var}(C)$ is used when $\alpha = 1$.

As mentioned before, the following example is provided by Gaoming Wang, we record it here for readers' interest.

Example A.1. Let N^* be an open subset of an upper half-plane in \mathbb{R}^2 and let S be a mean convex curve in N^* to form a domain Ω such that S has contact angle $\theta_0 = \frac{2\pi}{3}$. Let $p = S \cap \partial N^*$, $W = \operatorname{var}(\partial N^* \cap \partial \Omega)$. Choose a ray R such that it has contact angle φ_0 satisfying $\cos \varphi_0 = -\frac{1}{4}$ and let $V = \operatorname{var}(R \cap \Omega, 2)$. Then (V, W) is a φ_0 -stationary pair supported in Ω while the barrier S has contact angle $\theta_0 > \varphi_0$. See Figure A1.

We end this appendix by introducing a way to construct fine stationary pairs of varifolds (V, W), the case that $||V||(\partial N^*) > 0$ is included. We may construct as many as possible examples if we like, but the best situation (in the sense that the barrier has the same contact angle as the fine stationary pair does) seems to be obtained when $||V||(\partial N^*) = 0$.

Example A.2. Let N^* be the unit ball in the plane \mathbb{R}^2 centred at the origin, ∂N^* is then the unit sphere. Let p_1, p_2 be two points on ∂N^* such that the line segment joining them, say L, has contact angle $\theta_0 \in (0, \pi) \setminus \{\frac{\pi}{2}\}$ with ∂N^* , and the enclosed domain is denoted by Ω (see Figure A2). For $\alpha, \beta \geq 0$ to be specified latter, define $V = \operatorname{var}(L) + \operatorname{var}(\partial N^* \cap \partial\Omega, \alpha), W = \operatorname{var}(\partial N^* \cap \partial\Omega, \beta).$

Then, for $0 < \gamma \leq \theta_0$ and $\gamma \neq \frac{\pi}{2}$, the relations:

$$\alpha = -\cos\theta_0 + \sin\theta_0 \frac{\cos\gamma}{\sin\gamma},$$

$$\beta = \frac{\sin\theta_0}{\sin\gamma},$$
(A.1)

define a fine γ -stationary pair (V, W). Moreover, as $\gamma = \theta_0$, one must have $\alpha = 0, \beta = 1$.



Figure A1. Example A.1.



Figure A2. Example A.2.

Proof. For any $X \in \mathfrak{X}(N^*)$, a direct computation shows:

$$\begin{split} \delta V[X] &= \int_{L} \operatorname{div}_{L} X(x) \mathrm{d}\mathcal{H}^{1}(x) + \alpha \int_{\partial N^{*} \cap \partial \Omega} \operatorname{div}_{\partial N^{*}} X(x) \mathrm{d}\mathcal{H}^{1}(x) \\ &= \sum_{i=1}^{2} \left\langle X(p_{i}), -\mu_{L}(p_{i}) \right\rangle + \alpha \sum_{i=1}^{2} \left\langle X(p_{i}), -\bar{\mu}(p_{i}) \right\rangle \\ &- \alpha \int_{\partial N^{*} \cap \partial \Omega} \left\langle X(x), \tilde{\mathbf{H}}(x) \right\rangle \mathrm{d}\mathcal{H}^{1}(x) \\ &= \left(\alpha + \cos \theta_{0}\right) \sum_{i=1}^{2} \left\langle X(p_{i}), -\bar{\mu}(p_{i}) \right\rangle + \sin \theta_{0} \sum_{i=1}^{2} \left\langle X(p_{i}), -\nu_{N^{*}}(p_{i}) \right\rangle \\ &- \int_{\partial N^{*}} \left\langle X(x), \tilde{\mathbf{H}}(x) \right\rangle \mathrm{d}||V||(x), \end{split}$$

where we have used the fact that $-\mu_L(p_i) = \cos \theta_0(-\bar{\mu}(p_i)) + \sin \theta_0(-\nu_{N^*}(p_i))$. Similarly, for the same X, one has:

$$\delta W[X] = \beta \int_{\partial N^* \cap \partial \Omega} \operatorname{div}_{\partial N^*} X(x) \mathrm{d}\mathcal{H}^1(x) = \beta \sum_{i=1}^2 \left\langle X(p_i), -\bar{\mu}(p_i) \right\rangle$$

$$-\int_{\partial N^*} \left\langle X(x), \tilde{\mathbf{H}}(x) \right\rangle \mathrm{d}||W||(x),$$

it follows that:

$$\delta V[X] - \cos \gamma \delta W[X]$$

= $(\alpha + \cos \theta_0 - \beta \cos \gamma) \sum_{i=1}^2 \langle X(p_i), -\bar{\mu}(p_i) \rangle + \sin \theta_0 \sum_{i=1}^2 \langle X(p_i), -\nu_{N^*}(p_i) \rangle$
 $- \int_{\partial N^*} \langle X(x), \tilde{H}(x) \rangle d(||V|| - \cos \gamma ||W||) (x),$

thus to make (V, W) a γ -stationary pair, we have to require that:

$$\alpha + \cos\theta_0 - \beta \cos\gamma = 0, \tag{A.2}$$

in which case (compared to Proposition 2.2) σ_V is given by $\sin \theta_0 \mathcal{H}^0 {\scriptscriptstyle \square} \{p_1, p_2\}$. As shown above, for any $X \in \mathfrak{X}_t(N^*)$, we have,

$$\delta W[X] = \beta \sum_{i=1}^{2} \left\langle X(p_i), -\bar{\mu}(p_i) \right\rangle,$$

and hence to make (V, W) a fine γ -stationary pair, we have to further require that:

$$\beta = \frac{\sin \theta_0}{\sin \gamma}.$$

This, together with (A.2), yields (A.1).

From (A.1), we observe that $\alpha \geq 0$ is in fact equivalent to $\sin(\theta_0 - \gamma) \geq 0$, that is, $0 < \gamma \leq \theta_0 < \pi$, and the equality occurs if and only if $\alpha = 0, \beta = 1$, which completes the proof.

As a specific choice, if we choose $\theta_0 = \frac{\pi}{3}$, $\gamma = \frac{\pi}{6}$, $\alpha = 1, \beta = \sqrt{3}$, then we obtain a fine $\frac{\pi}{6}$ -stationary pair (V, W), with $||V||(\partial N^*) > 0$.