# ON ASYMPTOTICALLY NONEXPANSIVE SEMIGROUPS OF MAPPINGS 

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1. Introduction. A selfmapping $f$ of a metric space $(X, d)$ is nonexpansive ( $\varepsilon$-nonexpansive) if $d(f(x), f(y)) \leq d(x, y)$ for all $x, y \in X$ (respectively if $d(x, y)<\varepsilon$ ). In [1], M. Edelstein proved that a nonexpansive mapping $f$ of $E^{n}$ admits a fixed point provided the $f$-closure of $E^{n}$ (i.e. the set of all points which are cluster points of $\left\{f^{n}(x)\right\}$ for some $x$ ) is nonempty. R. D. Holmes [2] considered commutative semigroups of selfmappings of a metric space and obtained fixed point theorems for such semigroups under certain contractivity conditions.

In this note, we consider asymptotically nonexpansive semigroups $G$ which are defined analogously to the asymptotic contractions considered in [2]. For a general metric space $X$, we obtain results parallel to those of [1], and in the special case where $X=E^{n}$, we prove, under certain conditions, that there exists a point $z$ such that $G$ acts on the orbit of $z$ as a semigroup of translations. As a corollary, it follows that if some orbit is bounded, $G$ has a common fixed point.
2. Definitions and Notation. Throughout, ( $X, d$ ) (or simply $X$ ) will denote a metric space and $E^{n}$ the $n$-dimensional Euclidean space. Let $G: X \rightarrow X$ denote the collection of mappings $g: X \rightarrow X, g \in G$, where $G$ is a commutative semigroup of mappings with identity $\left({ }^{2}\right)$. Set $G(x)=\{g(x): g \in G\}$ (the orbit of $x$ ), $G(A)=\{g(x)$ : $g \in G, x \in A\}$ and $G \mid A=\{g \mid A: g \in G\}$ for $A \subseteq X$. A fixed point for $G$ will be a point $z \in X$ such that $g(z)=z$ for all $g$ in $G$.
If $G: X \rightarrow X$, we say that $G$ is asymptotically nonexpansive if for all $x, y$ in $X$
(2.1) there exists $g \in G$ such that for all $f \in G, d(f g(x), f g(y)) \leq d(x, y)$.

If there is an $\varepsilon>0$ such that whenever $d(x, y)<\varepsilon,(2.1)$ holds, then $G$ is called $\varepsilon$-asymptotically nonexpansive. $G$ is said to be asymptotically ( $\varepsilon$-asymptotically) isometric if

> for all $x, y \in X$ (with $d(x, y)<\varepsilon)$ there exists $g \in G$ such that for all $f$ in $G$, $d(f g(x), f g(y))=d(x, y)$.

By the $G$-closure of $X$ (denoted by $X^{G}$ ) we shall mean the set

$$
\begin{equation*}
\{z \in X \mid \exists x \in X \text { such that } \forall f \in G, \varepsilon>0, \exists g \in G \text { with } d(f g(x), z)<\varepsilon\} . \tag{2.3}
\end{equation*}
$$

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$\left.{ }^{(2}\right)$ The presence of an identity is not essential for our results, and is assumed for convenience only.

In the case when $G$ is generated by a single mapping $f$, the $G$-closure of $X$ is precisely the $f$-closure of $X$ as defined in [1].

If $A \subseteq E^{n}, \operatorname{co} A(\overline{\operatorname{co}} A)$ denotes the convex hull (closed convex hull) of $A$. If $G: E^{n} \rightarrow E^{n}$ and $z \in E^{n}$ is such that $G \mid G(z)$ is a semigroup of translations, then $z$ will be called a $T$-point (translational point) for $G$.

## 3. Asymptotically nonexpansive semigroups in general metric spaces.

Proposition 1. Let $G: X \rightarrow X$ be $\varepsilon$-asymptotically nonexpansive and $z \in X^{G}$. Then
$\forall f \in G, \varepsilon>0 \exists g \in G$ such that $d(f g(z), z)<\varepsilon$ (i.e. in condition (2.3), $x$ can be replaced by $z$ ).

Proof. Let $x$ be as in (2.3) and suppose that $f \in G, \varepsilon>0$. It clearly follows from (2.3) that $\exists g_{0} \in G$ so that $d\left(g_{0}(x), z\right)<\varepsilon / 2$, and $G$ being $\varepsilon$-asymptotically nonexpansive, $\exists g_{1} \in G$ such that $\forall h \in G, d\left(h g_{1} g_{0}(x), h g_{1}(z)\right) \leq d\left(g_{0}(x), z\right)<\varepsilon / 2$. Replacing $f$ in (2.3) by $f g_{1} g_{0}$, we can find a $g_{2} \in G$ such that $d\left(f g_{2} g_{1} g_{0}(x), z\right)<\varepsilon / 2$. Setting $g=g_{2} g_{1}$ and $h=f g_{2}$, we have $d(g f(z), z) \leq d\left(f g_{2} g_{1}(z), f g_{2} g_{1} g_{0}(x)\right)+d\left(f g_{2} g_{1} g_{0}(x), z\right)$ $<\varepsilon / 2+\varepsilon / 2=\varepsilon$.

Lemma 1. Under the hypotheses of Proposition 1, $G \mid G(z)$ is an e-asymptotic isometry.

Proof. Suppose that contrary to the assumption $\exists f_{1}, f_{2} \in G$ with $d\left(f_{1}(z), f_{2}(z)\right)<\varepsilon$ and such that $\forall g \in G, \exists f \in G$ for which $d\left(f g f_{1}(z), f g f_{2}(z)\right) \neq d\left(f_{1}(z), f_{2}(z)\right)$. Since $G$ is $\varepsilon$-asymptotically nonexpansive, there is a $g_{0} \in G$ such that

$$
\delta=d\left(f_{1}(z), f_{2}(z)\right)-d\left(g_{0} f_{1}(z), g_{0} f_{2}(z)\right)>0
$$

Also replacing $x$ and $y$ in (2.1) by $g_{0} f_{1}(z), g_{0} f_{2}(z)$ respectively, we obtain a $g_{1} \in G$ such that

$$
d\left(f g_{1} g_{0} f_{1}(z), f g_{1} g_{0} f_{2}(z)\right) \leq d\left(g_{0} f_{1}(z), g_{0} f_{2}(z)\right), \quad \forall f \in G
$$

Now by Proposition 1, $d\left(h_{0} g_{1} g_{0}(z), z\right)$ can be made so small that the continuity of $f_{1}$ and $f_{2}$ will imply the existence of an $h_{0} \in G$ for which

$$
d\left(h_{0} g_{1} g_{0} f_{1}(z), f_{1}(z)\right)<\delta / 2 \quad \text { and } d\left(h_{0} g_{1} g_{0} f_{2}(z), f_{2}(z)\right)<\delta / 2
$$

Hence

$$
\begin{aligned}
d\left(f_{1}(z), f_{2}(z)\right) & \leq d\left(f_{1}(z), h_{0} g_{1} g_{0} f_{1}(z)\right)+d\left(h_{0} g_{1} g_{0} f_{1}(z), h_{0} g_{1} g_{0} f_{2}(z)\right)+d\left(h_{0} g_{1} g_{0} f_{2}(z), f_{2}(z)\right) \\
& <\delta / 2+d\left(g_{0} f_{1}(z), g_{0} f_{2}(z)\right)+\delta / 2
\end{aligned}
$$

which is impossible.
Now it follows from Lemma 1 that if $G$ is asymptotically nonexpansive and $z \in X^{G}$, then $G \mid G(z)$ is an asymptotic isometry. An even stronger conclusion is obtained in the following

Proposition 2. If $G: X \rightarrow X$ is asymptotically nonexpansive and $z \in X^{G}$, then $G \mid G(z)$ is an isometry.

Proof. We have to show that $\forall f_{1}, f_{2}, g_{0} \in G, d\left(g_{0} f_{1}(z), g_{0} f_{2}(z)\right)=d\left(f_{1}(z), f_{2}(z)\right)$. By Lemma $1, \exists g_{1}, g_{2} \in G$ such that for all $f$, we have

$$
d\left(f g f_{1}(z), f g f_{2}(z)\right)=d\left(f_{1}(z), f_{2}(z)\right)
$$

and

$$
d\left(f g_{2} g_{0} f_{1}(z), f g_{2} g_{0} f_{2}(z)\right)=d\left(g_{0} f_{1}(z), g_{0} f_{2}(z)\right)
$$

Substituting $g_{2} g_{0}$ and $g_{1}$ for $f$ in the first and second equalities respectively, and applying commutativity of $G$, the result follows.

Remarks. (1) If $G$ is asymptotically contractive and $x \in X^{G}$ then it is readily seen that $x$ is a common fixed point for $G$. Thus Lemma 1 generalizes its counterpart (Theorem 2 in [2, p. 10]).
(2) If the asymptotically nonexpansive semigroup $G$ has a fixed point $\omega \in X$, then for each $z \in X^{G}, G(z)$ lies on a sphere centered at $\omega$. Indeed, if not, then $\exists g \in G$ with $d(g(z), \omega) \neq d(z, \omega)$. In case $d(g(z), \omega)<d(z, \omega)$ we set $\delta=d(z, \omega)-d(g(z), \omega)>0$. Now there is a $g_{1} \in G$ such that $\forall f \in G, d\left(f g_{1} g(z), \omega\right) \leq d(g(z), \omega)$ and $\exists f_{1} \in G$ with $d\left(f_{1} g_{1} g(z), z\right)<\delta$. Now,

$$
\delta=d(z, \omega)-d(g(z), \omega) \leq d(z, \omega)-d\left(f_{1} g_{1} g(z), \omega\right) \leq d\left(f_{1} g_{1} g(z), z\right)<\delta
$$

which is absurd. The case where $d(g(z), \omega)>d(z, \omega)$ can be treated similarly.

## 4. Asymptotically nonexpansive semigroups of mappings in Euclidean spaces.

Theorem 1. Let $G: E^{n} \rightarrow E^{n}$ be asymptotically nonexpansive. If $x \in\left(E^{n}\right)^{G}$, then there exists a $T$-point $z \in \overline{\operatorname{co}} G(x)$ for $G$.

Corollary 1. If $G: A \rightarrow A$ (where $A \subseteq E^{n}$ ) is asymptotically nonexpansive, $A$ contains no nontrivial linear variety and there exists an $x \in A^{G}$ with $\overline{\operatorname{co}} G(x) \subseteq A$, then $\overline{\operatorname{co}} G(x)$ contains a unique fixed point.

A number of properties of isometric and asymptotically nonexpansive semigroups of mappings in $E^{n}$ are needed in the proof of Theorem 1. These are furnished in the following sequence of lemmas.

Lemma 2. Let $G: E^{n} \rightarrow E^{n}$ be asymptotically nonexpansive and $A \subseteq E^{n}$. If $G \mid A$ is an isometry, then $G \mid \operatorname{co} A$ is again an isometry. If in addition, $G(A) \subseteq A$, then $G(\cos A) \subseteq \operatorname{co} A$.

The proof is similar to the corresponding Proposition 2 of [1]. It is also clear that in Lemma 2, we can replace co $A$ by $\overline{\operatorname{co}} A$.

Lemma 3. If $G: E^{n} \rightarrow E^{n}$ is isometric, maps the closed convex set $C$ of $E^{n}$ into itself, $C^{G} \neq \phi$ and $G$ has a $T$-point in $E^{n}$, then $G$ has a $T$-point in $C$.

Proof. Let $A=\overline{\operatorname{co}} G(a)$ for some $a \in C^{a}$. If $x, \omega \in G(a), \exists g_{x}, g_{\omega} \in G$, such that $x=g_{x}(a), \omega=g_{\omega}(a)$. Also since $a \in C^{G}$, given $f, \varepsilon>0, \exists g \in G$ with $\|a-g f(a)\|<\varepsilon$ by Proposition 1. For $z=\lambda x+(1-\lambda) \omega, 0 \leq \lambda \leq 1$, using the facts that $f \mid A$ is affine, and that $G$ is isometric, we obtain

$$
\begin{aligned}
\|z-g f(z)\| & =\| \lambda x+(1-\lambda) \omega-g f(\lambda x+(1-\lambda) \omega \| \\
& \leq \lambda\|x-g f(x)\|+(1-\lambda)\|\omega-g f(\omega)\| \\
& =\lambda\left\|g_{x}(a)-g f g_{x}(a)\right\|+(1-\lambda)\left\|g_{\omega}(a)-g f g_{\omega}(a)\right\| \\
& =\lambda\|a-g f(a)\|+(1-\lambda)\|a-g f(a)\| \\
& =\|a-g f(a)\|<\varepsilon,
\end{aligned}
$$

implying that $z \in C^{G}$. It is easy to check that $C^{G}$ is closed, and hence we conclude that $A \subseteq C^{G}$.

Let $x$ be a $T$-point of $G$. If $x \notin A$, let $y$ be the (unique) point of $A$ nearest to $x$ and $W$ be the supporting hyperplane at $y$ of the closed ball with center $x$ and radius $\|x-y\|$. We claim that $y$ is a $T$-point of $G$.

If $f(x)=x$ for some $f \in G$, then $f(y) \in A,\|x-f(y)\|=\|f(x)-f(y)\|=\|x-y\|$, and the uniqueness property of $y$ imply $f(y)=y$. If $f(x) \neq x$ and the line $L$ containing $f(x)$ and $x$ meets $W$, say at $z$, then since $f \mid L$ is a translation, it is true that for $g=f$ or $g=f^{-1}, x \in[z, g(x)]$ and so $\|g(x)-g(y)\|>\inf \{\|g(x)-u\|: u \in W\}>\|x-y\|$ which is impossible since $g$ is an isometry. Hence $L \cap W=\phi$ so that $L$ is parallel to $W$. We note that the line joining $x$ and $y$ is perpendicular to $W$, and clearly so is the line joining $f(x)$ and $f(y)$. Thus $f(y)-y=f(x)-x$. Hence for $f \in G$, either $f(y)=y$ or $f(y)=y-x+f(x)$. If now, $f, g \in G$ then $f g(y)$ is a translate of $y$. Since $g(y)$ is a translate of $y, f g(y)$ can be expressed as a translate of $g(y)$. In other words, $y$ is a $T$-point of $G$.

Lemma 4. If $G: E^{n} \rightarrow E^{n}$ is isometric, then $G$ has a T-point.
Proof. Let $g$ be a fixed element of $G$. We first show that the set $A_{g}=\{z \mid \exists a$ such that $\forall y \in G(z), g(y)=y+a\}$ is nonempty. If $g$ has a fixed point $z$, then clearly $z \in A_{g}$. So assume that $g$ has no fixed point. Since $g$ is a rigid motion, we can introduce an orthonormal system of coordinates in $E^{n}$ so that if

$$
x=\left(x_{1}, x_{2}, \ldots, x_{n}\right), \quad g(x)=x M+a,
$$

where $M$ is an orthogonal matrix in normal form. In particular suppose

$$
M=\left(\begin{array}{lll}
I_{k} & & \\
& -I_{l} & \\
& & R
\end{array}\right)
$$

where $I_{k}, I_{l}$ are ( $k \times k$, resp. $l \times l$ ) identity matrices and

$$
R=\left(\begin{array}{lllll}
R_{1} & & & & \\
& R_{2} & & & \\
& & \cdot & & \\
& & & \\
& & & \cdot & \\
& & & R_{\frac{n-k-l}{}}^{2}
\end{array}\right)
$$

$$
\text { with } \quad R_{i}=\left(\begin{array}{rr}
\cos \phi_{i} & -\sin \phi_{i} \\
\sin \phi_{i} & \cos \phi_{i}
\end{array}\right) \text {, }
$$

$\phi_{i} \neq m \pi, m=0, \pm 1, \pm 2, \ldots$.
It is fairly easy to show (cf. [1, Lemma 2]) that there exist numbers $\xi_{k+1}, \xi_{k+2}, \ldots$, $\xi_{n}$ so that

$$
\begin{aligned}
g\left(x_{1}, x_{2}, \ldots, x_{k}, \xi_{k+1}, \xi_{k+2}, \ldots,\right. & \left.\xi_{n}\right) \\
& =\left(x_{1}+a_{1}, x_{2}+a_{2}, \ldots, x_{k}+a_{k}, \xi_{k+1}, \xi_{k+2}, \ldots, \xi_{n}\right)
\end{aligned}
$$

and note that the $\xi_{i}$ are unique with the property of remaining fixed.
Suppose $f \in G$ is of the form $f(x)=x N+b$, where

$$
\left.N=\begin{array}{c}
k-k \\
k-k
\end{array} \begin{array}{c:c}
k & n-k \\
D_{1} & D_{2} \\
\hdashline D_{3} & D_{4}
\end{array}\right)
$$

Now as $f g=g f$, it is easy to see that we must have $D_{2}=0, D_{3}=0$. Thus if $P$ is the projection defined by $P(x)=\left(0,0, \ldots, 0, x_{k+1}, \ldots, x_{n}\right)$ then we have $P f P=P f$. Clearly $P g P=P g$. Hence $P g P f=P g f=P f g=P f P g$ and so $P g$ and $P f$ commute. $P g$ has $\xi=\left(0,0, \ldots, 0, \xi_{k+1}, \ldots, \xi_{n}\right)$ as a unique fixed point, and so $P f(\xi)=\xi$. In particular, if $B=\left\{\left(x_{1}, x_{2}, \ldots, x_{k}, \xi_{k+1}, \ldots, \xi_{n}\right)\right\}, f(B) \subseteq B$, and as $f$ was arbitrary, $G(B) \subseteq B$. Since $g \mid B$ is a translation, $B \subseteq A_{g}$.

Note that $A_{g}$ is a linear variety and that $G\left(A_{g}\right) \subseteq A_{g}$. Now if $V$ is any linear variety with $G(V) \subseteq V$, we must have $V \cap A_{g} \neq \phi$, for if we consider $G \mid V$, then the above argument shows that $A_{g}^{*}=\{z \in V \mid \exists a$ such that $\forall y \in G(z), g(y)=y+a\}$ is nonempty. But $A_{g}^{*} \subseteq V$ and $A_{g}^{*} \subseteq A_{g}$. This implies that for any $f_{1}, f_{2}, \ldots, f_{n+1} \in G$, $\bigcap_{i=1}^{n+1} A_{f_{i}} \neq \phi$. Consider all finite intersections of the $A_{g}$ 's. Each such intersection is a linear variety of dimension $\geq 0$. If $d$ denotes the smallest dimension of such intersections, $d \geq 0$ and there exists a finite family $\left\{A_{g_{t}}\right\}, i=1,2, \ldots, m$ so that $\operatorname{dim}\left\{\bigcap_{i=1}^{m} A_{g_{i}}\right\}=d$. It is clear that if an $A_{g} \neq A_{g_{i}}, i=1,2, \ldots, m$, then $A_{g}$ must con$\operatorname{tain} \bigcap_{i=1}^{m} A_{g_{i}}$, as otherwise $\operatorname{dim}\left\{A_{g} \cap\left(\bigcap_{i=1}^{m} A_{g_{i}}\right)\right\}<d$, a contradiction. This shows that $\bigcap_{g \in G} A_{g} \neq \phi$, and clearly any point of the intersection is a $T$-point.
Proof of Theorem 1. As $x \in\left(E^{n}\right)^{G}$, we know by Proposition 2 that $G \mid G(x)$ is isometric and thus $F=G \mid \overline{\operatorname{co}} G(x)$ is isometric (Lemma 2). As in 3.4, Lemma 1
of [1], $F$ can be extended to $H$ on all of $E^{n}$ such that $H$ is isometric and commutative. By Lemma $4, H$ has a $T$-point $\omega$ and as $H(\overline{\operatorname{co}} G(x)) \subseteq \overline{\operatorname{co}} G(x)$, Lemma 3 implies that $H$ has a $T$-point $z \in \overline{\operatorname{co}} G(x)$. But $H|\overline{\operatorname{co}} G(x)=G| \overline{\operatorname{co}} G(x)$ and $z$ is thus a $T$-point of $G$.

Proof of Corollary 1. As in the proof of Theorem 1, $G \mid \overline{\operatorname{co}} G(x)$ is isometric and thus we can conclude that $\overline{\operatorname{co}} G(x)$ contains a $T$-point $z$. As $A$ contains no nontrivial linear variety, the only translations of $G(z)$ are the trivial ones, i.e. $g(z)=z \forall g \in G$. Uniqueness of $z$ follows from Remark (2) (in the same manner as the corresponding assertion in [1] follows from Remark 2.3 there).

In Corollary 1, we cannot relax the requirement that $A$ contains no nontrivial linear variety. This is exhibited by the example where $n=1, A=E^{1}$ and $G$ is the group of all translations on $E^{1}$. Clearly $A^{G}=E^{1}$, and $\overline{\text { co }} G(x)=E^{1}$ contains no fixed point of $G$.

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