# On the complex complementarity problem 

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The complex linear complementarity problem considered here is the following: Find $z$ such that

$$
\begin{aligned}
& M z+q \in S^{*}, \quad z \in S \\
& \operatorname{Re}\left[z^{H} M z+z^{H} q\right]=0
\end{aligned}
$$

where $S$ is a polyhedral convex cone in $c^{p}, S^{*}$ the polar cone, $M \in C^{p \times p}$ and $q \in c^{p}$.

Generalizing earlier results in real and complex space, it is shown that if $M$ satisfies $\operatorname{Re}^{H} M z \geq 0$ for all $z \in C^{P}$ and if the set satisfying $M z+q \in S^{*}, z \in S$ is not empty, then a solution to the complex linear complementarity problem exists. If $\operatorname{Rez}^{H} M z>0$ unless $z=0$, then a solution to this problem always exists.

## Introduction

Recently, McCallum [8] introduced the complex linear complementarity problem and established conditions for the existence of solutions. McCallum dealt with the problem where each of the constraints was restricted to a sector in the complex plane. Here we give conditions for the existence of solutions to the more general complex linear complementarity problem where the constraints are restricted to polyhedral cones.

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## Notation and statement of problem

For brevity, we shall use much of the notation of [8].
Superscript $H$ denotes conjugate transpose. Let $S$ denote a polyhedral cone in $C^{n}$, then the polar of $S$ is defined by

$$
S^{*}=\left\{w \in C^{n}: z \in S \Rightarrow \operatorname{Re}\left(x^{H} z\right) \geq 0\right\} .
$$

The following observations follow readily from the definition of $S^{*}$ [2]:
if $S$ and $T$ are polyhedral cones in $C^{n}$, then

$$
(S \times T)^{*}=S^{*} \times T^{*} ;
$$

if $S=C^{n}$, then $S^{*}=\{0\}$;
if $S=R_{+}$, then $S^{*}=\{z \in C: \operatorname{Re} z \geq 0\}$.
The complex complementarity problem (CCP) we shall deal with is the following:

Let $M \in c^{p \times p}, q \in d^{p}, S \subset d^{p}$, a convex polyhedral cone.
PROBLEM (CCP). Find $z \in C^{D}$ such that
(1)
(2)

$$
\begin{gather*}
M z+q \in S^{*}, \\
z \in S, \\
\operatorname{Re}\left[z^{H}(M z+q)\right]=0 . \tag{3}
\end{gather*}
$$

Closely related to this problem is the complex quadratic programming problem.

$$
\begin{aligned}
& \text { PROBLEM Q1. Minimize } \quad f(z) \equiv \operatorname{Re}\left[z^{H} M z+z^{H} q\right] \\
& \text { subject to (1) and (2). }
\end{aligned}
$$

A solution to Problem (CCP) is clearly an optimal solution of Problem Ql. The reverse need not be true since, for optimal $z_{0}$, we may have $f\left(z_{0}\right)>0$. We shall later state some restrictions on $M$ that assure that $f\left(z_{0}\right)=0$.

## Complex alternative theorems

Let $A \in C^{m \times n}, A_{1} \in C^{m \times n_{1}}, A_{2} \in C^{m \times n_{2}} ;$ and let $s \subset C^{n}$, $S_{1} \subset C^{n_{1}}, S_{2} \subset C^{n_{2}}, T \subset C^{m}$ be polyhedral convex cones. We shall make use of the following result of Ben-Israel [3]:

THEOREM 1. The system

$$
\begin{equation*}
A_{1} x_{1}+A_{2} x_{2} \in-T, \quad 0 \neq x_{1} \in S_{1}, \quad x_{2} \in S_{2} \tag{4}
\end{equation*}
$$

has a solution if, and only if,

$$
\begin{equation*}
A_{1}^{H} y \in \operatorname{int} S_{1}^{*}, A_{2^{2}} y \in S_{2}^{*}, \quad y \in T^{*} \tag{5}
\end{equation*}
$$

has none.
THEOREM 2. The system

$$
\begin{equation*}
A z-b \in T, \quad z \in S \tag{6}
\end{equation*}
$$

has a solution, if and only if,

$$
\begin{equation*}
-A^{H} v \in S^{*}, \quad v \in T^{*}, \quad \operatorname{Re} b^{H} v>0 \tag{7}
\end{equation*}
$$

has none.
Proof. (6) is equivalent to

$$
\begin{equation*}
-A z+b \xi \in-T, \quad z \in S, \quad 0 \neq \xi \in R_{+} \tag{8}
\end{equation*}
$$

By Theorem 1, (8) has a solution, if and only if,

$$
\begin{equation*}
-A^{H} v \in S^{*}, \quad b^{H} v \in \operatorname{int}\left(R_{+}\right)^{*}, \quad v \in T^{*} \tag{9}
\end{equation*}
$$

Since $b^{H} v \in \operatorname{int}\left(R_{+}\right)^{*}$ means $\operatorname{Re} b^{H} v>0$, (9) yields (7).
COROLLARY. Let $M \in c^{\times x}, q \in c^{p}, S \subset c^{p}$, a polyhedral convex cone. Then the set satisfying $M z+q \in S^{*}, z \in S$ is nonempty if, and only if,

$$
\begin{equation*}
-M^{H} v \in S^{*}, \quad v \in S, \quad \operatorname{Re} q^{H} v<0 \tag{10}
\end{equation*}
$$

has no solution.
Proof. In Theorem 2, take $n=m=p, A=M, b=-q$, and

## Complex quadratic programming

We shall utilize the following duality theorem for complex quadratic programming of [1]:

THEOREM 3. Let $B \in C^{n \times n}$ be positive semi-definite Hermitian. Let $A \in C^{m \times n}, b \in C^{m}, c \in C^{n}$ and $s \subset C^{n}, T \subset C^{m}$ be convex polyhedral cones. Consider the pair of problems
$\begin{aligned} \text { PROBLEM PI. } & \text { Minimize } \quad F(x) \equiv \operatorname{Re}\left[\frac{\gamma_{2}}{} x^{H} B x+c^{H} x\right] \\ & \text { subject to } A x-b \in T,\end{aligned}$

$$
x \in S
$$

PROBLEM P2. Maximize $g(y, z) \equiv \operatorname{Re}\left[-\frac{1}{2} y^{H} B y+b^{H} z\right]$

$$
\text { subject to }-A^{H} z+B y+c \in S^{*} \text {, }
$$ $z \in T^{*}$.

If Problem PI has an optimal solution $x_{0}$, then there exists a vector $z_{0}$ such that $\left(x_{0}, z_{0}\right)$ is an optimal solution of Problem P2; and

$$
F\left(x_{0}\right)=g\left(x_{0}, z_{0}\right)
$$

We want to modify Theorem 3 so as to eliminate the restriction in Pl that $B$ must be hermitian. We note that, even if $B$ is not hermitian,

$$
B=\left(B+B^{H}\right) / 2+\left(B-B^{H}\right) / 2 .
$$

Since $z^{H}\left[\left(B-B^{H}\right) / 2\right] z$ is pure imaginary,

$$
\begin{equation*}
\operatorname{Re} z^{H} B z=\operatorname{Re} z^{H}\left[\left(B+B^{H}\right) / 2\right] z, \tag{11}
\end{equation*}
$$

where $\left(B+B^{H}\right) / 2$ is always hermitian. This suggests the following definitions:
$B \in C^{n \times n}$ (not necessarily hermitian) is said to be positive semi-definite if

$$
\operatorname{Re} z^{H} B z \geq 0 \text { for all } z \in C^{n}
$$

and positive definite if

$$
\begin{equation*}
\operatorname{Re} z^{H} B z>0 \text { unless } z=0 . \tag{13}
\end{equation*}
$$

(11) and Theorem 3 lead to the following:

THEOREM 4. If Problem Pl, with $B$ positive semi-definite but not necessarily hermitian, has an optimal solution $x_{0}$, then there exists a vector $z_{0}$ such that $\left(x_{0}, z_{0}\right)$ is an optimal solution of

PROBLEM $\mathrm{P} 2^{\prime}$. Maximize $g(y, z) \equiv \operatorname{Re}\left[-\frac{3}{2} y^{H} B y+b^{H} z\right]$

$$
\text { subject to } \begin{aligned}
A^{H} z+\left[\left(B+B^{H}\right) / 2\right] y+c & \in S^{*}, \\
& z \in T^{*},
\end{aligned}
$$

and $F\left(x_{0}\right)=g\left(x_{0}, z_{0}\right)$.

Solvability of the complex complementarity problem
We now state some conditions that assure the existence of a solution of Problem (CCP).

THEOREM 5. Let $M \in C^{\times p}$ be positive semi-definite. If the set of feasible solutions of Problem Q1 is non-empty, then there exists a vector $z_{0}$ such that $f\left(z_{0}\right)=0$.

Proof. The dual of Problem Ql is
PROBLEM Q2. Maximize $G(y, v) \equiv \operatorname{Re}\left[-y^{H} M y-v^{H} q\right]$

$$
\begin{equation*}
\text { subject to } M^{H} v+M y+M^{H} y+q \in S^{*} \tag{14}
\end{equation*}
$$

$$
\begin{equation*}
v \in S \tag{15}
\end{equation*}
$$

Since the feasible set of Q1 is nonempty and the quadratic objective function is bounded below (by zero), Ql achieves a minimum for some optimal vector $z_{0}[6],[8]$. By Theorem 4, there exists $v_{0}$ such that $\left(z_{0}, v_{0}\right)$ is optimal for Q2 and

$$
\begin{equation*}
f\left(z_{0}\right)=\operatorname{Re}\left[z_{0}^{H} M z_{0}+z_{0}^{H} q\right]=\operatorname{Re}\left[-z_{0}^{H} M z_{0}-v_{0}^{H} q\right]=G\left(z_{0}, v_{0}\right) . \tag{16}
\end{equation*}
$$

From (15) and (1),

$$
\begin{equation*}
\operatorname{Re}\left[v_{0}^{H} M z_{0}+v_{0}^{H} q\right] \geq 0 \tag{17}
\end{equation*}
$$

From (2) and (14),

$$
\begin{equation*}
\operatorname{Re}\left[-z_{0}^{H} M^{H} v_{0}+z_{0}^{H} M z_{0}+z_{0}^{H} M^{H} z_{0}+z_{0}^{H} q\right] \geq 0 . \tag{18}
\end{equation*}
$$

Noting that $\operatorname{Re} v_{0}^{H} M z_{0}=\operatorname{Re} z_{0}^{H} M^{H} v_{0}$, and that $\operatorname{Re} z_{0}^{H} M z_{0}=\operatorname{Re} z_{0}^{H} M^{H} z_{0}$, adding (17) and (18) gives

$$
\begin{equation*}
\operatorname{Re}\left[-v_{0}^{H} q-z_{0}^{H} M z_{0}\right] \leq \operatorname{Re}\left[z_{0}^{H} M z_{0}+z_{0}^{H} q\right] \tag{19}
\end{equation*}
$$

From (16), the inequality in (19), and hence also in (17) and (18) must be satisfied as equalities, that is,

$$
\begin{gather*}
\operatorname{Re}\left[v_{0}^{H} M z_{0}+v_{0}^{H} q\right]=0,  \tag{20}\\
\operatorname{Re}\left[-z_{0}^{H} M^{H} v_{0}+z_{0}^{H} M z_{0}+z_{0}^{H} M^{H} z_{0}+z_{0}^{H} q^{H}\right]=0 .
\end{gather*}
$$

(1) and (2) give

$$
\begin{equation*}
\operatorname{Re}\left[z_{0}^{H} M z_{0}+z_{0}^{H} q\right] \geq 0 \tag{22}
\end{equation*}
$$

(14) and (15) give

$$
\begin{equation*}
\operatorname{Re}\left[-v_{0}^{H} M^{H} v_{0}+v_{0}^{H} M z_{0}+v_{0}^{H} M^{H} z_{0}+v_{0}^{H} q\right] \geq 0 . \tag{23}
\end{equation*}
$$

(20) and (23) yield

$$
\begin{equation*}
\operatorname{Re}\left[-v_{0}^{H} M^{H} v_{0}+v_{0}^{H_{M}^{H}} z_{0}\right] \geq 0 \tag{24}
\end{equation*}
$$

From (21) and (22),

$$
\begin{equation*}
\operatorname{Re}\left[z_{0}^{H} M z_{0}+z_{0}^{H} q\right]=\operatorname{Re}\left[z_{0}^{H} M^{H} v_{0}-z_{0}^{H} M^{H} z_{0}\right] \geq 0 \tag{25}
\end{equation*}
$$

Adding (24) and (25) and noting the positive semi-definiteness of $M$, we obtain
(26) $0 \leq \operatorname{Re}\left[z_{0}^{H} M z_{0}+z_{0}^{H} q\right] \leq \operatorname{Re}\left[-z_{0}^{H} M^{H} z_{0}-v_{0}^{H} M^{H} v_{0}+v_{0}^{H} M^{H} z_{0}+z_{0}^{H}{ }^{H} v_{0}\right]$

$$
=-\operatorname{Re}\left[\left(z_{0}-v_{0}\right)^{H} M^{H}\left(z_{0}-v_{0}\right)\right]=-\operatorname{Re}\left[\left(z_{0}-v_{0}\right)^{H} M\left(z_{0}-v_{0}\right)\right] \leq 0
$$

Thus equality holds throughout (26) giving

$$
\begin{equation*}
f\left(z_{0}\right)=\operatorname{Re}\left(z_{0}^{H} M z_{0}+z_{0}^{H} q\right]=0 . \tag{27}
\end{equation*}
$$

THEOREM 6. Let $M \in c^{p \times p}$ be positive definite. Then the set of feasible solutions of Problem Q1 is non-empty and there exists an optimal vector $z_{0}$ such that (27) holds.

Proof. Suppose that the feasible set of Q1 is empty. By the Corollary to Theorem 2, the system

$$
\begin{gather*}
-M^{H} v \in S^{*}, \quad v \in S  \tag{28}\\
\operatorname{Req}^{H} v<0 \tag{29}
\end{gather*}
$$

has a solution. (28) implies

$$
\operatorname{Re}-v^{H} M^{H} v=\operatorname{Re}-v^{H} M v \geq 0
$$

Since $M$ is positive definite, $v$ must be the zero vector, contradicting (29). Hence the feasible set is nonempty.

The remainder of Theorem 6 now follows from Theorem 5.

## Special cases

If

$$
\begin{equation*}
S=\left\{z \in C^{n}:|\arg z| \leq \beta\right\} \tag{30}
\end{equation*}
$$

and

$$
T=\left\{\omega \in C^{m}:|\arg \omega| \leq \alpha\right\}
$$

for given $\beta \in R_{+}^{n}, \alpha \in R_{+}^{m}, \beta_{i} \leq \pi / 2, \quad i=1, \ldots, n ; \alpha_{i} \leq \pi / 2$, $i=1, \ldots, m$, then Theorem 2 yields a result of Mond and Hanson ([10], Theorem 8). If all vectors and matrices are real and $S=R_{+}^{n}, T=R_{+}^{m}$, then Theorem 2 yields an alternative theorem in real space of Gale ([7],
p. 47).

If $S$ is defined by (30) with $n=p$, Theorem 5 gives the corresponding result of $\mathrm{McCallum}[8]$. If $S=R_{+}^{n}$ and all matrices and vectors are real, then Theorem 5 reduces to the result of Cottle [4] while Theorem 6 gives the corresponding existence theorem of Dorn [5].

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