## ERRATUM

# Direct construction of optimized stellarator shapes. Part 3. Omnigenity near the magnetic axis - ERRATUM 

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Below we clarify the conventions used for normalization in our paper (Punk, Landreman \& Herlander 2019), and correct some associated errors in the equations. The validity of the numerical solutions and the main conclusions of the paper are unaffected by these corrections.

Following Garren \& Boozer (1991), we define the expansion parameter as $\epsilon=\sqrt{\psi}$ so that the magnetic field can be expressed to first order as $B(\epsilon, \theta, \varphi) \approx B_{a}(\varphi)(1+$ $\epsilon \sqrt{2 / B_{a}(\varphi)} \kappa^{s}(\varphi) \eta_{\mathrm{GB}}(\varphi) \cos [\theta-\alpha(\varphi)]$ ), where the ' $\eta$ ' of Garren \& Boozer (1991) is here denoted $\eta_{\mathrm{GB}}$; see their (79). For simplicity, we introduced the quantity $d$, related to $\eta_{\mathrm{GB}}$ by

$$
\begin{equation*}
d(\varphi)=\sqrt{\frac{2}{B_{a}(\varphi)}} \kappa^{s}(\varphi) \eta_{\mathrm{GB}}(\varphi), \tag{0.1}
\end{equation*}
$$

so that the magnetic field to first order becomes

$$
\begin{equation*}
B(\epsilon, \theta, \varphi) \approx B_{a}(\varphi)(1+\epsilon d(\varphi) \cos [\theta-\alpha(\varphi)]) \tag{0.2}
\end{equation*}
$$

as correctly written in (6.1) of our paper.
Our definitions for $d$ and $\epsilon$ affect the forms of the first order components of the coordinate mapping, $X_{1}$ and $Y_{1}$. These quantities are introduced in the text at the beginning of § 7, where the the coordinate mapping $x$ to first order should read

$$
\begin{equation*}
\boldsymbol{x} \approx \boldsymbol{r}_{0}+\epsilon\left(X_{1} \boldsymbol{n}^{s}+Y_{1} \boldsymbol{t}^{s}\right) \tag{0.3}
\end{equation*}
$$

Note the factor of $\epsilon$ is missing in the paper. The form of $X_{1}$ was correctly given by (7.1), but that for $Y_{1}$, (7.2), should read

$$
\begin{equation*}
Y_{1}=\frac{2}{B_{a}(\varphi) \bar{d}(\varphi)}\{\sin [\theta-\alpha(\varphi)]+\sigma(\varphi) \cos [\theta-\alpha(\varphi)]\} \tag{0.4}
\end{equation*}
$$

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with the correction being the factor of $1 / B_{a}(\varphi)$.
Our forms of $B, X_{1}$ and $Y_{1}$ can be compared with (79)-(81) of Garren \& Boozer (1991), and can be seen to agree, given our definitions of $\epsilon, d$ and $\bar{d}$, and the substitution $\kappa \rightarrow \kappa^{s}$. A related error was introduced into the definition of $P$ immediately following (7.7), which should read

$$
\begin{equation*}
P=1+B_{a}^{2} \bar{d}^{4} / 4 \tag{0.5}
\end{equation*}
$$

The solutions presented in § 8 remain valid, but we note that $d$ defined in (8.4) (also depicted in figure $2 b$ ) misses a factor of $\sqrt{2}$, and should read

$$
\begin{equation*}
d(\varphi)=\sqrt{2}[1.08 \sin (\varphi)+0.26 \sin (2 \varphi)+0.46 \sin (3 \varphi)] \tag{0.6}
\end{equation*}
$$

Finally, there is a typo, unrelated to the preceding issues: following (7.10) it should read $\Delta \varphi(\varphi)=\varphi-\varphi_{b}(\varphi)$.

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