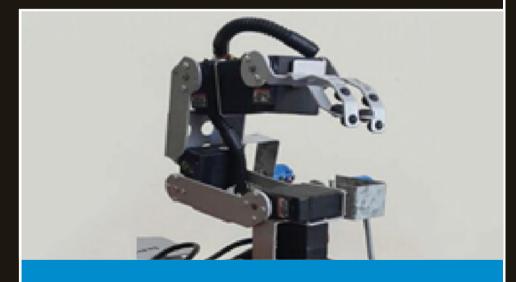
Volume 39 Part 10

# ROBOTICA



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teleoperation and haptic interfaces; robot motion planning; and artificial intelligence. In addition, papers that apply techniques from Robotics to other fields are also welcome. Examples include dynamics

and control models applied to biological systems, the description of

implementations of robots in factories, service and agricultural settings,

and general mechatronic design. Works may be theoretical, computa-

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Cover Image: Design and Implementation of a Cable Inspection Robot for Cable-Stayed Bridges by Zhipeng Wang, Bin He, Yanmin Zhou, Ke Liu and Chenghong Zhang. Figure 20 'Active vehicle obstacle climbing experiment (1.5 mm height obstacle)'.