# EXACT SOLUTIONS OF TWO NONLINEAR EQUATIONS AND HYPERCIRCLE ESTIMATES 

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#### Abstract

In a recent paper estimates of the solutions of two nonlinear differential equations were made by use of the hypercircle method. Here exact solutions are given which are compared with those estimates.


## 1. Introduction

In a recent paper [1] estimates for the solution of certain nonlinear differential equations were found by use of the hypercircle method. In this note it is pointed out that both examples considered in [1] admit exact solutions and comparison is made with the trial functions previously used. Of course, the general method described in [1] is still available for problems in which the exact solution is not known.

## 2. Solution for example 1

The first example concerned the nonlinear ordinary differential equation problem

$$
\left.\begin{array}{rl}
\frac{d^{2} \phi}{d x^{2}} & =\phi+\phi^{2} / 4, \quad-1<x<1  \tag{1}\\
\phi(-1) & =\phi(1)=1
\end{array}\right\}
$$

The solution of this problem is given in terms of Jacobian elliptic functions as follows. Multiplication of the equation in (1) by $d \phi / d x$ and integration leads to

$$
\begin{equation*}
\frac{d \phi}{d x}=\left[\phi^{2}-\phi_{0}^{2}+(1 / 6)\left(\phi^{3}-\phi_{0}^{3}\right)\right], \tag{2}
\end{equation*}
$$

on using the evenness of the solution in $x$, and setting $\phi(0)=\phi_{0}$, as yet unknown. Previous results in [1] show that $\phi^{\prime}$ vanishes only at the origin in [0,1], and that $\phi$ is monotonic increasing in this interval.

Separation of variables in (2) and integration leads to the solution

$$
\begin{equation*}
\phi(x)=\phi_{0}-u_{1} s c^{2}\left(\left.\lambda^{-1} 6^{-\frac{1}{2}} x \right\rvert\, m\right) \tag{3}
\end{equation*}
$$

with the notation of [3], and where

$$
\left.\begin{array}{l}
u_{1,2}=-3\left(1+\phi_{0} / 2\right) \pm \frac{1}{2}\left[3\left(2-\phi_{0}\right)\left(6+\phi_{0}\right)\right]^{\frac{1}{2}}  \tag{4}\\
\lambda^{-1}=\frac{1}{2}\left(-u_{2}\right)^{\frac{1}{2}} \quad \text { and } \quad m=\left(u_{1}-u_{2}\right) /\left(-u_{2}\right)
\end{array}\right\}
$$

In order to satisfy the boundary conditions in (1), we require that $\phi_{0}$ satisfies

$$
\begin{equation*}
\phi_{0}=1+u_{1} s c^{2}\left(\left.\lambda^{-1} 6^{-\frac{1}{2}} \right\rvert\, m\right) \equiv f\left(\phi_{0}\right), \tag{5}
\end{equation*}
$$

and $\phi_{0}$ must be found by numerical iteration. This can be a tedious process unless a good initial estimate of $\phi_{0}$ is available; happily this is provided by the previous estimate 0.6100 in [1]. Since $\left|f^{\prime}(0.6100)\right| \simeq 0.07$, the iteration $\phi_{r+1}=f\left(\phi_{r}\right)$ converges reasonably quickly to the value $\phi_{0}=0.60850$, and the comparison in Table 1 of the exact solution $\phi$ of (1) with our trial function $\phi_{1}$ of [1] can be made.

TABLE 1
Comparison of exact solution $\phi$ and trial function $\phi_{1}$ of example 1

| $x$ | 0.0 | $\pm 0.2$ | $\pm 0.4$ | $\pm 0.6$ | $\pm 0.8$ | $\pm 1.0$ |
| :--- | :---: | :---: | :---: | :---: | :---: | ---: |
| $\phi$ | 0.60850 | 0.62258 | 0.66557 | 0.73977 | 0.84918 | 1.0 |
| $\phi_{1}$ | 0.60100 | 0.61696 | 0.66484 | 0.74464 | 0.85636 | 1.0 |

The mean-square error is found by numerical integration (Simpson's rule with $h=0.05$ ) :

$$
\begin{equation*}
\left\langle\phi-\phi_{1}, \phi-\phi_{1}\right\rangle=\int_{-1}^{1}\left(\phi-\phi_{1}\right)^{2} d x=5.5 \times 10^{-5}, \tag{6}
\end{equation*}
$$

so that the upper bound of [1], $E\left(\phi_{1}\right)=44 \times 10^{-5}$ is conservative, as could be expected with this simple function $\phi_{1}$.

Further, it can be remarked that the trial function $\phi_{1}$ of [1], found by minimizing the hypersphere radius,

$$
\begin{equation*}
\phi_{1}=0.601+0.399 x^{2}, \tag{7}
\end{equation*}
$$

is a close pointwise approximation in $[0,1]$ to the expansion of the exact solution (3) to the same order :

$$
\begin{equation*}
\phi \simeq 0.6085+0.35053 x^{2} . \tag{8}
\end{equation*}
$$

## 3. Solution for example 2

The second example in [1] was the nonlinear boundary-value problem in the plane

$$
\left.\begin{array}{rl}
\nabla^{2} \phi & =k e^{\phi} \quad \text { in } \quad V  \tag{9}\\
\phi & =1 \quad \text { on } \quad B,
\end{array}\right\}
$$

where $V$ is the $\operatorname{disc} r<1$, so that $B$ is given by $r=1$. Here $k$ is a positive real constant. There is a general solution available for the differential equation in (9) (with $k$ positive or negative) due to Liouville [2], and an alternative derivation of this appears in the appendix. It would clearly be of use if the domain $V$ were other than the unit disc, and a conformal map on the unit disc were employed.

However, since in (9) radial symmetry is assumed, there is merely an ordinary differential equation to be solved,

$$
\begin{equation*}
\left(r \phi^{\prime}\right)^{\prime}=k r e^{\phi} \tag{10}
\end{equation*}
$$

where a dash denotes differentiation with respect to $r$. If we differentiate (10) again we get

$$
\begin{equation*}
\left(r \phi^{\prime}\right)^{\prime \prime}=k e^{\phi}\left(1+r \phi^{\prime}\right) \tag{11}
\end{equation*}
$$

Setting

$$
\begin{equation*}
v=1+r \phi^{\prime} \tag{12}
\end{equation*}
$$

and eliminating the exponential by means of (10), we find from (11) that

$$
\begin{equation*}
r v^{\prime \prime}=v v^{\prime} \tag{13}
\end{equation*}
$$

Next, using $v^{\prime \prime}=v^{\prime} d v^{\prime} / d v$, and noting that

$$
\frac{d}{d v}\left(r v^{\prime}\right)=1+r \frac{d v^{\prime}}{d v}
$$

we obtain from (13) that

$$
\begin{equation*}
\frac{d}{d v}\left(r v^{\prime}\right)=v+1 \tag{14}
\end{equation*}
$$

after division by $v^{\prime}$. Integration then gives

$$
r v^{\prime}=\frac{v^{2}}{2}+v+C
$$

and the condition $v=1$ at $r=0$ gives $C=-3 / 2$ since we assume $\phi^{\prime}$ finite in $[0,1]$.
Separation of variables and integration gives $v$ as a rational function of $r^{2}$; then, returning to $\phi^{\prime}$ by (12), another integration gives

$$
\begin{equation*}
\phi=\ln \left\{A\left(a^{2}-r^{2}\right)^{-2}\right\} \tag{15}
\end{equation*}
$$

where $A$ and $a$ are arbitrary constants.
Satisfaction of the differential equation and boundary condition in (9) requires that the constants satisfy the conditions

$$
A=8 a^{2} / k \quad \text { and } \quad e\left(1-a^{2}\right)^{2}=A
$$

Solving the resulting quadratic equation for $a^{2}$ and selecting the root greater than unity, we then obtain the solution

$$
\begin{equation*}
\phi(r)=\ln \left[\left(8 a^{2} / k\right)\left(a^{2}-r^{2}\right)^{-2}\right] \tag{16}
\end{equation*}
$$

with

$$
\begin{equation*}
a^{2}=1+4 /(k e)+\left\{(1+4 /(k e))^{2}-1\right\}^{\frac{1}{2}} \tag{17}
\end{equation*}
$$

Since $a^{\mathbf{2}}$ is greater than unity the solution is continuous in $V$. We now compare it with the hypercircle estimate. Using the exact solution (16) we calculate the meansquare error $\left\langle\phi-\phi_{1}, \phi-\phi_{1}\right\rangle$ of the trial function

$$
\phi_{1}=1+\beta\left(r^{2}-1\right)
$$

used in [1]. A comparison with the upper bound $E\left(\phi_{1}\right)$ for this error is given in Table 2, and again $E\left(\phi_{1}\right)$ is conservative, but could of course be improved by using a more elaborate trial function.

TABLE 2
Mean-square errors and upper bounds, $E\left(\phi_{1}\right)$, example 2

| $k$ | $\beta$ | $10^{4}\left\langle\phi-\phi_{1}, \phi-\phi_{1}\right\rangle$ | $10^{4} E\left(\phi_{1}\right)$ |
| :---: | :---: | :---: | :---: |
| 5 | 1.405 | 81.6 | 1641.5 |
| 2 | 0.8065 | 9.69 | 166.6 |
| 1 | 0.4926 | 1.49 | 22.17 |

The pointwise approximation of $\phi_{1}$ to the power series approximation for

$$
\phi \simeq a+b r^{2}
$$

is not quite as good as in the case of example 1 , but improves as $k$ decreases. For example, for $k=1$ we have

$$
\begin{equation*}
\phi \simeq 0.5252+0.4227 r^{2} \quad \text { and } \quad \phi_{1}=0.5074+0.4926 r^{2} \tag{18}
\end{equation*}
$$

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## Appendix. Derivation of the solution to problem (9)

Liouville's general solution [2] of the differential equation in (9) can be written

$$
\begin{equation*}
\phi=\ln \left\{A F^{\prime}(z) \overline{F^{\prime}(z)} /[F(z) \overline{F(z)}+c]^{2}\right\} \tag{A1}
\end{equation*}
$$

where $A$ and $c$ are arbitrary constants, $z=x+i y, F(z)$ is an arbitrary analytic function of $z$, and the bar denotes the complex conjugate. Both positive and negative values of the parameter $k$ in (9) are allowed.

The following derivation seems a little more direct than the original, and follows at the outset that of Weston [4]. The equation in (9) is

$$
\begin{equation*}
\phi_{z \overline{\mathrm{z}}}=(k / 4) e^{\phi} \tag{A2}
\end{equation*}
$$

where subscripts denote partial derivatives. Differentiating this equation with respect to $z$ we find

$$
\begin{equation*}
\phi_{z z \bar{z}}=\phi_{z \bar{z}} \phi_{z} \tag{A3}
\end{equation*}
$$

having eliminated the exponential. Integration gives

$$
\begin{equation*}
\phi_{z z}-\frac{1}{2} \phi_{z}^{2}=B_{1}(z) \tag{A4}
\end{equation*}
$$

where $B_{1}$ is an analytic function of $z$. Next we differentiate (A2) with respect to $\bar{z}$ obtaining similarly

$$
\begin{equation*}
\phi_{\bar{z} \bar{z}}-\frac{1}{2} \phi_{\bar{z}}^{2}=B_{2}(\bar{z}) \tag{A5}
\end{equation*}
$$

where $B_{2}$ is an antianalytic function of $\bar{z}$ (that is, $\partial B_{2} / \partial z=0$ ).
Now in (A4) set

$$
\begin{equation*}
\phi_{z}=\frac{F^{\prime \prime}(z)}{F^{\prime}(z)}+G(z, \bar{z}) \tag{A6}
\end{equation*}
$$

where $F$ is analytic, the dash denoting the derivative, and $F^{\prime}$ is supposed nonzero in $r<1$. We deduce that $G$ satisfies a Riccati equation

$$
\begin{equation*}
G_{z}=\frac{F^{\prime \prime}}{F^{\prime}} G+\frac{1}{2} G^{2} \tag{A7}
\end{equation*}
$$

Setting, as usual, $G=-2 h_{z} / h$, we solve (A7) for $G$ and find that

$$
\begin{equation*}
\phi_{z}=F^{\prime \prime}(z) / F^{\prime}(z)-2 F^{\prime}(z) k(\bar{z}) /[F(z) k(\bar{z})+n(\bar{z})] \tag{A8}
\end{equation*}
$$

with $k$ and $n$ arbitrary.
Similarly, from (A5) we may deduce that

$$
\begin{equation*}
\phi_{\bar{z}}=\overline{F^{\prime \prime}(z)} / \overline{F^{\prime}(z)}-2 \overline{F^{\prime}(z)} s(z) /[\overline{F(z)} s(z)+p(z)] \tag{A9}
\end{equation*}
$$

with $s$ and $p$ arbitrary. Finally, using $\phi_{z i z}=\phi_{i z}$, we find by comparison that $s(z)=F(z), k(\bar{z})=\overline{F(z)}$, and $n(\bar{z})=p(z)=c$, constant. The solution (A1) is thus established.

In the case of the problem in (9), we set $F(z)=z$ in (A1), and the constants $A$ and $c$ $\left(=-a^{2}\right)$ are determined as in Section 3.

## References

[1]. A. M. Arthurs and V. G. Hart, "The method of the hypercircle for a class of nonlinear equations", $J$. Austral. Math. Soc. B 21 (1979), 75-83.
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