CONNECTIVITY OF RANDOM $k$-NEAREST-NEIGHBOUR GRAPHS

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Abstract

Let $\mathcal{P}$ be a Poisson process of intensity one in a square $S_n$ of area $n$. We construct a random geometric graph $G_{n,k}$ by joining each point of $\mathcal{P}$ to its $k \equiv k(n)$ nearest neighbours. Recently, Xue and Kumar proved that if $k \leq 0.074 \log n$ then the probability that $G_{n,k}$ is connected tends to 0 as $n \to \infty$ while, if $k \geq 5.1774 \log n$, then the probability that $G_{n,k}$ is connected tends to 1 as $n \to \infty$. They conjectured that the threshold for connectivity is $k = (1 + o(1)) \log n$. In this paper we improve these lower and upper bounds to 0.3043 $\log n$ and 0.5139 $\log n$, respectively, disproving this conjecture. We also establish lower and upper bounds of 0.7209 $\log n$ and 0.9967 $\log n$ for the directed version of this problem. A related question concerns coverage. With $G_{n,k}$ as above, we surround each vertex by the smallest (closed) disc containing its $k$ nearest neighbours. We prove that if $k \leq 0.7209 \log n$ then the probability that these discs cover $S_n$ tends to 0 as $n \to \infty$ while, if $k \geq 0.9967 \log n$, then the probability that the discs cover $S_n$ tends to 1 as $n \to \infty$.

Keywords: Random geometric graph; connectivity; Poisson process

2000 Mathematics Subject Classification: Primary 05C80
Secondary 82B43

1. Introduction

Suppose that $n$ radio transceivers are scattered at random over a desert. Each radio is able to establish a direct two-way connection with the $k$ radios nearest to it. In addition, messages can be routed via intermediate radios, so that a message can be sent indirectly from radio $S$ to radio $T$ through a series of radios $S = S_1, S_2, \ldots, S_n = T$, each one having a direct connection to its predecessor. How large does $k$ have to be to ensure that any two radios can communicate (directly or indirectly) with each other?

To make this question precise, we define a random geometric graph $G(A, \lambda, k)$, as follows. Let $\mathcal{P}$ be a Poisson process of intensity $\lambda$ in a region $A$, and join every point of $\mathcal{P}$ to its $k$ nearest neighbours. We would like to know the values of $k$ for which the resulting graph $G(A, \lambda, k)$...
is likely to be connected. Throughout this paper, distance is measured using the Euclidean $l^2$-norm, and is denoted by $\| \cdot \|$.

There are two equivalent ways of viewing the problem. The first is to fix the area $A$ and let $\lambda \to \infty$. In the second formulation, we instead fix $\lambda = 1$ and let the region $A$ grow while keeping its shape fixed, so that the expected number of points in $A$ again increases. As this is the formulation we will use, we abbreviate $G(A, 1, k)$ to $G(A, k)$. We will take $A = S_n$, the square of area $n$ (not side-length $n$), which ensures that the expected number of points in our region is $n$. (However, as it turns out, the shape is essentially irrelevant.) Thus we are interested in the values of $k \equiv k(n)$ for which $G_{n, k} := G(S_n, k)$ is likely to be connected, as $n \to \infty$.

Much of the previous work on this problem has been done with the above application (namely, to wireless, ad-hoc networks) in mind. In [6]–[8], [12], [16], and [17] the network was modelled as a Poisson process in the plane, while in [9] the nodes (or transceivers) were located along a line.

Before we get to our main results, we observe that two essentially trivial arguments give the right order of magnitude for $k$: specifically, that there exist positive constants $c_1$ and $c_2$ such that if $k \leq c_1 \log n$ then the probability that $G_{n, k}$ is connected tends to 0 as $n \to \infty$ while, if $k \geq c_2 \log n$, then the probability that $G_{n, k}$ is connected tends to 1 as $n \to \infty$. (All logarithms in this paper are to the base $e$.) Throughout this paper, we will say that an event occurs with high probability (w.h.p.) if it occurs with a probability tending to 1 as $n \to \infty$. Thus, if $k \leq c_1 \log n$ then $G_{n, k}$ is disconnected w.h.p. and if $k \geq c_2 \log n$ then $G_{n, k}$ is connected w.h.p.

Let us tessellate the square $S_n$ with small squares $Q_i$ of area $\log n - O(1)$, where the (positive) $O(1)$ term is chosen so that the side-length of $Q_i$ exactly divides that of $S_n$. Then the probability that a small square contains no points of the process is $e^{-\log n + O(1)} = O((n^{-1}) = o((\log n)/n)$, so that, w.h.p., every small square contains at least one point. Using the inequality $r! \equiv (r/e)^r$, the probability that a disc of radius $(5 \log n)^{1/2}$ (area $5\pi \log n$) contains more than $k = [5\pi e \log n] < 42.7 \log n$ points is at most

$$e^{-5\pi \log n} \left( \frac{(5 \pi \log n)^{k+1}}{(k+1)!} \right) \left( 1 + \frac{5\pi \log n}{k+2} + \cdots \right)$$

$$\leq e^{-5\pi \log n} (1 + e^{-1} + e^{-2} + \cdots) = o(n^{-1}),$$

so that, w.h.p., every point has at most $k$ points within a distance $(5 \log n)^{1/2}$. Thus, w.h.p., every point of $G_{n, k}$ contained in a square $Q_i$ is joined to every other point in $Q_i$ and also to every point in every adjacent square. This is enough to make $G_{n, k}$ connected.

Furthermore, if $k$ is much smaller than $\log n$ then, w.h.p., $G_{n, k}$ will not be connected. To see this, consider a configuration of three concentric discs $D_1$, $D_2$, and $D_3$, of radii $r$, $3r$, and $5r$, respectively, where $\pi r^2 = k + 1$. We call the configuration bad if (i) $D_1$ contains at least $k + 1$ points, (ii) the annulus $D_3 \setminus D_1$ contains no points, and (iii) the intersection of $D_3 \setminus D_3$ with any disc of radius $2r$ centred at a point $P$ on the boundary of $D_3$ contains at least $k + 1$ points. Now, if a bad configuration occurs anywhere in $G_{n, k}$, then $G_{n, k}$ will not be connected, because the $k$ nearest neighbours of a point in $D_1$ all lie within $D_1$ and the $k$ nearest neighbours of a point outside $D_3$ all lie outside $D_3$. Hence, there will be no edge of $G_{n, k}$ connecting $D_1$ to $S_n \setminus D_3$. Condition (i) holds with a probability of approximately $\frac{1}{2}$, condition (ii) holds with probability of approximately $\frac{1}{2}$, and condition (iii) holds with probability $1 - o(1)$, since a disc of radius $2r$ around a point on the boundary of $D_3$ is very likely to contain at least $2(k + 1)$ points. Hence, for $k \leq \frac{1}{2}(1 - \varepsilon)(\log n)$, the probability of a configuration being bad is $p \geq \left( \frac{1}{2} - o(1) \right) n^{-1+\varepsilon}$. Since we can fit $Cn/\log n$ copies of $D_3$ into $S_n$, and each is
independently bad with probability $p$, the probability that $G_{n,k}$ is connected is at most

$$(1 - p)^{\lfloor c \log n \rfloor} \leq \exp(-C' n^{c}/\log n) \to 0,$$

for $k \leq \frac{1}{2}(1 - \epsilon)(\log n)$ and some positive constants $C$ and $C'$.

These elementary arguments indicate that we should focus our attention on the range $k = \Theta(\log n)$. Indeed, defining $c_l$ and $c_u$ by

$$c_l = \sup\{ c : P(G_{n,\lfloor c \log n \rfloor} \text{ is connected} \to 0 \}$$

and

$$c_u = \inf\{ c : P(G_{n,\lfloor c \log n \rfloor} \text{ is connected} \to 1 \},$$

we have just shown that

$$0.125 \leq c_l \leq c_u \leq 42.7.$$

By making use of a substantial result of Penrose [13], Xue and Kumar [18] improved the upper bound to

$$c_u \leq 5.1774,$$

although a bound of

$$c_u \leq \left( \frac{2 \log \left( \frac{4\pi/3 + \sqrt{3}/2}{\pi + 3\sqrt{3}/4} \right)}{1} \right)^{-1} \approx 3.8597$$

can be found in earlier work of Gonzáles-Barrios and Quiroz [5]. It seems likely that $c_l = c_u = c$, and Xue and Kumar asked whether or not $c = 1$. In this paper we improve the above bounds considerably, disproving the conjecture $c = 1$.

The methods used in this paper are new, and specific to this problem. However, it is interesting to compare our results with those relating to two similar problems. The first also concerns a Poisson process of intensity 1 in a region $A$. This time we join each point to all other points within a radius $r$, obtaining the graph $G_r(A)$: we will refer to this as the disc model. This model originated in a paper of Gilbert [4]. He considered the model in the infinite plane, and was interested in the probability $P_r(\infty)$ that an arbitrary vertex of $G_r(\mathbb{R}^2)$ belongs to an infinite connected component of $G_r(\mathbb{R}^2)$. Define $r_{\text{crit}}$ to be the supremum of those $r$ for which $P_r(\infty) = 0$. Gilbert showed that

$$1.75 \leq \pi r_{\text{crit}}^2 \leq 17.4.$$

Simulations [1], [15] suggest that $\pi r_{\text{crit}}^2 \approx 4.512$. The study of $G_r(\mathbb{R}^2)$ is known as continuum percolation, and is the subject of a monograph by Meester and Roy [11]. Many authors reserve the phrase ‘random geometric graphs’ for the graphs $G_r(A)$; however, we will use it in a more general context, so that it includes the graphs $G_{n,k}$ as well.

Regarding connectivity, Penrose [13], [14] showed that if $A = S_\pi$ and $\pi r^2 = c \log n$, so that each point has on average $c \log n$ neighbours, then there is a critical value of $c$, in the sense described above, which equals 1. This is the result used by Xue and Kumar in the work cited above. There is an analogous result for classical random graphs: if in a random graph $G = G(n, p)$ the average degree is $c \log n$, then, if $c < 1$, w.h.p. $G$ is not connected while, if $c > 1$, w.h.p. $G$ is connected. In both cases, the obstruction to connectivity is the existence of isolated vertices (in the sense that, w.h.p., the graph becomes connected as soon as it has no isolated vertices).
In our problem, we expressly forbid isolated vertices; indeed, each vertex has degree at least \( k \). Thus the obstruction to connectivity must involve more complicated extremal configurations, making it harder to obtain precise results. Another complication is that the average vertex degree is not exactly \( k \), but somewhere between \( k \) and \( 2k \). (In fact, it is easy to show that, for \( k \to \infty \), the average degree is \( (1 + o(1))k \).) This motivates the study of the directed case, where, in a Poisson process of intensity 1 in a region \( A \), we place directed edges pointing away from each point towards its \( k \) nearest neighbours. This ensures that, in the resulting graph \( \tilde{G}(A, k) \), every vertex has an out-degree of exactly \( k \). Again, we will only consider the case \( \bar{A} = S_n \); furthermore, we let \( k = \lfloor c \log n \rfloor \) and write \( G_{n,k} = \tilde{G}(S_n, k) \). In this variant, we wish to know how large \( c \) should be to guarantee a directed path between any two vertices w.h.p. Clearly, the threshold value of \( c \), if it exists, will be as least as large as in the undirected case. We provide upper and lower bounds for this problem as well.

At first sight it might seem that the following random graph problem might shed some light on the situation: in a graph on \( n \) vertices, join each vertex to \( k \) randomly chosen others. For what values of \( k \) is the resulting graph \( G_{n,k} \)-out connected w.h.p.? Surprisingly, this question was posed by Ulam [10] in 1935 – also see page 40 of [2]. We have expressly forbidden isolated vertices here, as well. However, it is easy to show that even \( k = 2 \) is enough to ensure connectivity w.h.p. In contrast, for the directed version of the problem, where we send a directed edge from each vertex to \( k \) randomly chosen others, and ask for a directed path between any two vertices, we need \( k \approx \log n \), the main obstruction to connectivity being vertices with zero in-degree.

All our results will apply not only for Poisson processes, but also for \( n \) points placed in a square of area \( n \) according to the uniform distribution. Indeed, one can view our Poisson process as simply the result of placing \( n \) points in the square, where \( X \sim \text{Poisson}(n) \). For more details, see [13] and [18].

2. Results

Our main result concerns the undirected random geometric graph \( G_{n,k} \).

**Theorem 1.** If \( c \leq 0.3043 \) then \( P(G_{n,\lfloor c \log n \rfloor} \text{ is connected}) \to 0 \) as \( n \to \infty \). If \( c > 1/\log 7 \approx 0.5139 \) then \( P(G_{n,\lfloor c \log n \rfloor} \text{ is connected}) \to 1 \) as \( n \to \infty \). Thus

\[
0.3043 \leq c_1 \leq c_0 \leq 0.5139.
\]

The lower bound is proved in Theorem 4, below, while the upper bound is proved in Theorem 7. The argument for the lower bound is essentially a modification of that given in the introduction, while the proof of the upper bound is more involved.

For the directed graph \( \tilde{G}_{n,k} \), we have the following result. (Note that a directed graph is connected if, given any two vertices \( x \) and \( y \), there is a directed path from \( x \) to \( y \).)

**Theorem 2.** If \( c \leq 0.7209 \) then \( P(\tilde{G}_{n,\lfloor c \log n \rfloor} \text{ is connected}) \to 0 \) as \( n \to \infty \). If \( c \geq 0.9967 \) then \( P(\tilde{G}_{n,\lfloor c \log n \rfloor} \text{ is connected}) \to 1 \) as \( n \to \infty \).

Finally, let \( \mathcal{P}_n \) be a Poisson process giving rise to the random geometric graph \( G_{n,k} \). For a vertex \( x \in V(G_{n,k}) \), the vertex set of \( G_{n,k} \), we define the disc \( B_k(x) \) to be the smallest closed disc containing the \( k \) nearest neighbours of \( x \). Thus, in \( G_{n,k} \), \( x \) is (almost surely) joined to every vertex in its disc \( B_k(x) \). We say that \( \mathcal{P}_n \) is a \( k \)-cover if the discs \( B_k(x) \) cover \( S_n \), and we prove the following result in Section 6.
Theorem 3. If \( c \leq 0.7209 \) then \( \mathbb{P}(\mathcal{P}_n \text{ is a } \lfloor c \log n \rfloor \text{-cover}) \to 0 \) as \( n \to \infty \). If \( c \geq 0.9967 \) then \( \mathbb{P}(\mathcal{P}_n \text{ is a } \lfloor c \log n \rfloor \text{-cover}) \to 1 \) as \( n \to \infty \).

3. Lower bounds

We start by proving a useful lemma. For any region \( S \subseteq \mathbb{R}^2 \), write \( |S| \) for the Lebesgue measure of \( S \).

Lemma 1. Let \( A_1, \ldots, A_r \) be disjoint regions of \( \mathbb{R}^2 \) and \( \rho_1, \ldots, \rho_r \geq 0 \) real numbers such that \( \rho_i |A_i| \in \mathbb{Z} \). The probability that a Poisson process with intensity 1 has precisely \( \rho_i |A_i| \) points in each region \( A_i \) is then

\[
\exp \left\{ \sum_{i=1}^r \left( \rho_i - 1 - \rho_i \log \rho_i \right) |A_i| + O(r \log \sum \rho_i |A_i|) \right\},
\]

with the convention that \( 0 \log 0 = 0 \), and where \( \log_+ x = \max\{\log x, 1\} \).

Proof. Let \( n_i = \rho_i |A_i| \). The probability in question is given exactly by

\[
p = \prod_{i=1}^r \left( e^{-|A_i|} \left| \frac{|A_i|^{n_i}}{n_i!} \right| \right).
\]

Taking logarithms and using Stirling’s formula gives

\[
\log p = \sum_{i=1}^r (-|A_i| + n_i \log |A_i| - n_i \log n_i + n_i + O(\log n_i))
\]

\[
= \sum_{i=1}^r (n_i - |A_i| - n_i \log \rho_i) + O(r \log_+ \max n_i)
\]

\[
= \sum_{i=1}^r (\rho_i - 1 - \rho_i \log \rho_i) |A_i| + O(r \log \sum \rho_i |A_i|),
\]

from which the result follows.

Theorem 4. If \( c \leq 0.3043 \) then \( \mathbb{P}(\mathcal{G}_{n, \lfloor c \log n \rfloor} \text{ is connected}) \to 0 \) as \( n \to \infty \).

Proof. We first illustrate the proof with a simpler proof that \( c < c_0 = 1/(\log 50 + 8 \log 25) \approx 0.2739 \) suffices in the statement of the theorem. Let \( D \) be a disc with radius \( 5r_0 \). Relative to \( D \), let \( A_1 \) be a concentric disc with radius \( r_0 \), \( A_2 \) a concentric annulus with radii \( r_0 \) and \( 3r_0 \), and divide the remaining area \( A \) into \( N-2 \) (mostly square) regions \( A = \bigcup_{3 \leq i \leq N} A_i \), with each \( A_i \) of diameter at most \( \varepsilon r_0 \) (see Figure 1). We define the densities \( \rho_i \) by \( \rho_1 = 2 \rho = \frac{50}{18} \), \( \rho_2 = 0 \), and \( \rho_i = \rho = \frac{25}{18} \) for \( i \geq 3 \), and suppose that \( \rho_i |A_i| \in \mathbb{Z} \) and that exactly \( \rho_i |A_i| \) points lie in each \( A_i \). (Note that \( \sum_{i=1}^N \rho_i |A_i| = |D| \), so the number of points in \( D \) is as expected.)

Pick a point \( x \) at radius \( r \geq 3r_0 \) from the centre of \( D \), and let \( D_x \) be the disc about \( x \) of radius \( r - (1 + \varepsilon)r_0 \), for some small \( \varepsilon > 0 \). Then \( x \) is at least \( \varepsilon r_0 \) closer to all points in \( D_x \) than it is to any point in \( A_1 \). If \( r = 3r_0 \) and \( \varepsilon \) is sufficiently small, then \( |D_x \cap A| \geq \left( \frac{1}{2} + \delta \right)|D_x| \) for some \( \delta > 0 \), independent of \( \varepsilon \). Hence, for sufficiently small \( \varepsilon \), \( |D_x \cap A| \geq 2|A| \). If we move the point \( x \) radially outwards from the centre of \( D \), the discs \( D_x \) form a nested family. Thus, \( |D_x \cap A| \geq 2|A| \) for all \( x \). If some \( A_i, i \geq 3 \), intersects \( D_x \cap A \), then all points in \( A_i \) are
closer to $x$ than they are to any point of $A_1$. Hence, the $2|A_1|\rho = \rho_1|A_1|$ points of the Poisson process closest to $x$ all lie outside $A_1$. Clearly, if $x \in A_1$ then any point in $A_1$ is closer to $x$ than it is to any point outside $A_1$. Hence, if we choose $r_0$ so that $\rho_1|A_1| = k + 1 = \lceil c \log n \rceil + 1$, the points in $A_1$ form a connected component of $G_{n,k}$. If $S_n$ contains such a configuration then $G_{n,k}$ is disconnected.

Now, $\rho_1|A_1| = k + 1$, $\rho_2|A_2| = 0$, and $\sum \rho_i|A_i| = 9\rho_1|A_1| = 9(k + 1)$ are all integers. It is easy to see that if $n$ (and, hence, $k$ and $r_0$) are large enough, one can choose the regions $A_i$, $i \geq 3$, so that (i) $\rho_i|A_i| \in \mathbb{Z}$ for all $i$, (ii) the diameters of the $A_i$, $i \geq 3$, are at most $\varepsilon r_0$, and (iii) the number of regions $N$ is bounded above by some function of $\varepsilon$, independently of $n$.

By Lemma 1, the probability of each $A_i$ containing exactly $\rho_i|A_i|$ points is

$$p = \exp\left(-\left(\log \frac{50}{18} + 8 \log \frac{25}{18}\right)\rho_1|A_1| + O(N \log |D|)\right) = n^{-c/\log n + o(1)}.$$

Since we can place $\Theta(n/\log n)$ disjoint regions $D$ in $S_n$, the probability of at least one such configuration occurring in $S_n$ tends to $1$ as $n \to \infty$ when $c < c_0$.

To improve this bound, fix an $\alpha$ with $0 < \alpha \leq \frac{1}{3}$. Let $\varepsilon \in (0, \alpha)$ and assume that the circles in Figure 1 now have radii $(\alpha - \varepsilon)r_0$, $r_0$, and $(2 - \alpha)r_0$, in increasing order. That is, let $A_1$ be the inner disc of radius $(\alpha - \varepsilon)r_0$, let $A_2$ be the surrounding annulus with outer radius $r_0$, and divide the remaining area $A$ into regions $A_i$, $i = 3, \ldots, N$, each with diameter at most $\varepsilon r_0$, and area at least $1$ (which is certainly possible if $\varepsilon r_0$ is sufficiently large). We will define a function $\rho(r)$ that gives the approximate density of points in the regions $A_i$, where $r$ is the distance from $O$, the centre of $D$. Let $B$ be the disc of radius $\alpha r_0$ about $O$, so $B$ is just a little larger than $A_1$. For $r \leq \alpha r_0$, $\rho(r)$ will be a constant and we will require there to be exactly $\rho_1|A_1| = \lceil \rho(r)B \rceil + 1$ points of $\mathcal{P}$ in $A_1$. For $\alpha r_0 < r < r_0$, $\rho(r) = 0$ and we will require that $A_2$ contains no points of the process. For $r \geq r_0$, $\rho(r)$ will be a continuous function and the number of points in $A_i$ will be $\rho_i|A_i| = \lceil \int_{A_i} \rho(r) \, dA \rceil + 1$. The function $\rho(r)$ will be determined later, but will be of the form $\rho(r) = \rho_0(r/r_0)$, where $\rho_0$ may depend on $\alpha$ but will be independent of $n$, $r_0$, and $\varepsilon$. We will also see that $|\log \rho(r)|$ is bounded on $B \cup A$.

We now perform a similar calculation to the above, requiring that there be at least $k + 1$ points in $A_1$ and, for each point $x$ at distance $r \geq r_0$ from $O$, at least $k + 1$ points in $A$ closer to $x$ than they are to any point of $A_1$. As before, the worst case is when $x$ is at a distance $r = r_0$ from $O$, and it is enough to ensure that the sets that intersect the disc $D_{(1-\varepsilon)r_0}(x)$ of radius $(1-\varepsilon)r_0$ about $x$ contain at least $k + 1$ points. Thus, it is enough to have $\int_{D_{1-\varepsilon r_0}(x) \cap A} \rho r \, dA \geq c \log n$. 

Figure 1: Lower bound, undirected case.
Now define
\[ g(r) = \frac{1}{\pi} \cos^{-1}\left( \frac{r^2 + r_0^2 - (1 - \alpha)^2 r_0^2}{2nr} \right), \]
which is the proportion of the circle of radius \( r \), centre \( O \), that lies in \( D_{(1-\alpha)r_0}(x) \). Hence,
\[ \int_{D_{(1-\alpha)r_0}(x) \cap A} \rho \, dA = \int_{r_0}^{(2-\alpha)r_0} \rho(r) 2\pi rg(r) \, dr = \int_A \rho g \, dA, \]
and it is enough to impose the following conditions on \( \rho(r) \):
\[ \int_B \rho \, dA = \int_A \rho g \, dA = c \log n. \tag{1} \]

Let \( \delta_i \) bound the variation of \( \rho \log \rho \) across any of the sets \( A_i, i \geq 3 \). By the above assumptions, we can choose \( \delta_i \) independently of \( r_0 \) and \( n \), with \( \delta_i \to 0 \) as \( \epsilon \to 0 \). Now, by Lemma 1, the probability \( \rho \) of such a configuration occurring is given by
\[ -\log p = \int_D (\rho - 1 - \rho \log \rho) \, dA + O(N \log |D| + N \delta_i |D| + \epsilon c(\log n)/\alpha), \tag{2} \]
where the error terms include the error term of Lemma 1 plus \( N - 2 \) error terms of magnitude \( O(1 + \delta_i |A_i|) \) and one of magnitude \( O(1 + \epsilon \rho_i |A_i|/\alpha) \), these arising from the differences between \( \int_{A_i} (\rho - 1 - \rho \log \rho) \, dA \) and \( (\rho_i - 1 - \rho_i \log \rho_i)|A_i| \), for \( i = 1, \ldots, N \).

The function \( \rho(r) \) is chosen to maximize the above integral subject to (1). Using the method of Lagrange multipliers, we maximize
\[ \int_D (\rho - 1 - \rho \log \rho) \, dA - \mu \int_B \rho \, dA - \nu \int_A g \, dA \tag{3} \]
and, by applying the calculus of variations, we obtain
\[ \rho(r) = \begin{cases} 
\exp(\mu) & \text{if } r \leq \alpha r_0, \\
0 & \text{if } r \in (\alpha r_0, r_0), \\
\exp(vg(r)) & \text{if } r \geq r_0,
\end{cases} \]
where the constants \( \mu \) and \( \nu \) are chosen so that
\[ \int_B \rho \, dA = \int_A \rho g \, dA \quad \text{and} \quad \int_D (\rho - 1) \, dA = 0. \]
(The second condition comes from varying the scale \( r_0 \), which implies that the expression (3) should equal 0.) It is easy to check that each value of \( \alpha \) gives a unique value of \( \mu \) and \( \nu \), and that the conditions assumed for \( \rho(r) \) above do indeed hold. Also, \( |D| = O(\log n) \) and \( N = O(\epsilon^{-2}) \), so by taking, say, \( \epsilon \sim (\log n)^{-1/3} \), \( \epsilon r_0 \to \infty \) and the error term in (2) is \( o(\log n) \). Substituting this into (2), we get
\[ -\log p = (c(\mu + v) + o(1)) \log n. \]
Since we can place \( \Theta(n/\log n) \) disjoint copies of \( D \) inside \( S_n \), \( G_{n,k} \) is disconnected w.h.p. whenever \( c < (\mu + v)^{-1} \). Finally, optimizing over \( \alpha \) gives a value of \((\mu + v)^{-1}\) just larger than 0.3043 when \( \alpha = 0.3302 \).

Note that we were lucky that the optimum value of \( \alpha \) was less than \( \frac{1}{2} \). For \( \alpha > \frac{1}{2} \), the distances between points in \( A_1 \) could be larger than the distance from \( A_1 \) to \( A \). Hence, we would need more points in \( A_1 \), and we would need to cut \( A_1 \) into smaller regions with varying densities, in a similar manner as was \( A \).
Theorem 5. If \( c \leq 0.7209 \) then \( P(G_{n,[c \log n]} \text{ is connected}) \to 0 \) as \( n \to \infty \).

Proof. We first illustrate the proof with a simpler proof that \( c < c_1 = 1/(6 \log \frac{1}{2}) \approx 0.5793 \) suffices in the statement of the theorem. Let \( D \) be a disc with radius \( 2r_0 \) and centre \( O \), let \( A_1 \) be a disc with centre \( O \) and radius \( \varepsilon r_0 \), \( A_2 \) an annulus with centre \( O \) and radii \( \varepsilon r_0 \) and \( r_0 \), and divide the remaining annulus \( A \) of \( D \) into regions \( A_1, \ldots, A_N \), each with diameter at most \( \varepsilon r_0 \), as before (see Figure 2). We also define the densities \( \rho_i \) by \( \rho_2 = 0 \) and \( \rho_i = \rho = \frac{c}{2} \) for \( i \geq 3 \), and suppose that there is one point of the Poisson process in \( A_1 \) and that \( \rho_i |A_i| \) points of the Poisson process lie in each \( A_i \) for \( i \geq 2 \).

Pick a point \( x \) at distance \( r \geq r_0 \) from \( O \) and let \( D_x \) be the disc about \( x \) of radius \( r - 2\varepsilon r_0 \). Then \( x \) is at least \( \varepsilon r_0 \) closer to every point in \( D_x \) than it is to \( A_1 \). As \( r \) moves radially outwards, \( D_x \cap A \) increases, so \( |D_x \cap A| \) is at least as large as its value for \( r = r_0 \). In this case, \( |D_x \cap A| > \frac{1}{2} \pi r_0^2 \) for sufficiently small \( \varepsilon \). If some \( A_j, i \geq 3 \), intersects \( D_x \cap A \), then all points in \( A_i \) are closer to \( x \) than they are to \( O \), so the \( \frac{1}{2} \rho \pi r_0^2 / 2 \) points closest to \( x \) lie outside \( A_1 \). Choose \( r_0 \) so that \( \frac{1}{2} \rho \pi r_0^2 = k + 1 = |c \log n| + 1 \). Then the unique point in \( A_1 \) has zero in-degree and, if \( S_n \) contains such a configuration, \( G_{n,k} \) is disconnected. As before, by fixing \( \varepsilon > 0 \) and assuming that \( n \) is sufficiently large, we can choose the \( A_i \) so that \( \rho_i |A_i| \in \mathbb{Z} \) and \( N \) is bounded by a function of \( \varepsilon \), independently of \( n \). Now, by Lemma 1, the probability of such a configuration is

\[
p = \exp\left(-4\pi r_0^2 \log \frac{4}{3} + O((\log |A_1|)/|A_1|) + O(N \log |D|)\right) = n^{-c/c_1 + o(1)}.
\]

Since we can find \( \Theta(n/\log n) \) disjoint copies of \( D \) in \( S_n \), the probability of at least one such configuration occurring tends to \( 1 \) as \( n \to \infty \), provided that \( c < c_1 \).

To improve this bound, we follow the proof of Theorem 4 and make the assumption that the \( \rho_i \) are given by a function \( \rho(r) \) of the distance \( r \) to the centre of \( D \). We will define the \( A_i \) exactly as in Theorem 4, with a small \( \alpha > 0 \), but insist now that \( A_1 \) contains precisely one point of \( \mathcal{P} \) and that \( \rho(r) = 0 \) for all \( r < r_0 \). We obtain (2) again (with the last term in the error estimate replaced with \( \log |A_1| \)), which we wish to maximize subject to the conditions that \( \rho(r) = 0 \) for \( r \leq r_0 \) and \( \int_A \rho \, dA = c \log n \). To do this we maximize (3) without the \( \mu \int_B \rho \, dA \) term. After optimizing, we obtain

\[
\rho(r) = \begin{cases} 
0 & \text{if } r \leq r_0, \\
\exp(vg(r)) & \text{if } r > r_0,
\end{cases}
\]

where

\[
v(r) = \frac{1}{2} \rho \pi r^2 \log \frac{4}{3} + \frac{1}{2} \log \frac{4}{3} + O((\log |A_1|)/|A_1|) + O(N \log |D|) = c/c_1 + o(1).
\]

As \( r \to \infty \), the last term in the error estimate is negligible, and hence

\[
\int_{r_0}^{\infty} \rho \pi r^2 \, dr = 4.4974 + O(1).
\]

Since \( \rho(r) \) is a increasing function of \( r \) and \( \rho(r) \to c \) as \( r \to \infty \), we have

\[
\int_{r_0}^{\infty} \rho \pi r^2 \, dr = c \log n + O(1).
\]

Theorem 4 follows.

\[\Box\]
where \( \nu = \nu(\alpha) \) is chosen so that \( \int_0^\rho (\rho - 1) \, dA = 0 \). On substituting this back into (2) and choosing \( \varepsilon \sim (\log n)^{-1/3} \), we find that \( -\log p = (c\nu + o(1)) \log n \). As before, we can find \( \Theta(n/\log n) \) disjoint discs \( D \). Hence, provided that \( c < \nu^{-1} \), the graph \( G_{n,k} \) is disconnected w.h.p., with an isolated point as an in-component, with a vertex of in-degree 0. Finally, for sufficiently small \( \alpha \), \( v^{-1} \) is just larger than 0.7209.

4. Upper bounds

In this section, we will establish upper bounds for the directed and undirected cases. The basic arguments are simple but, in both cases, the situation is complicated by points near the boundary. In principle, these should be less of a problem than in the disc model; unfortunately, for both problems the most natural arguments run into trouble at the boundary. For the moment we will ignore boundary effects, and assume that all points are normal: a point \( P \) is normal if the smallest circle containing its \( k \) nearest neighbours all lie below it. The probability that a normal point is extreme is \( 2^{-k} \) such a line’ argument.

Theorem 6. Let \( c > 1/\log 2 \approx 1.4427 \). Then, the probability that \( G_{n,\lfloor c \log n \rfloor} \) contains a component consisting entirely of normal points tends to 0 as \( n \to \infty \).

Proof. Suppose that \( G_{n,\lfloor c \log n \rfloor} \) has a component \( G' \) containing only normal points. Let \( P \) be the ‘northernmost’ point of \( G' \). Then \( P \) is ‘extreme’ in the sense that its \( k = \lfloor c \log n \rfloor \) nearest neighbours all lie below it. The probability that a normal point is extreme is \( 2^{-k} \), and so the expected number of extreme normal points is at most \( n 2^{-k} = o(1) \). Thus, the probability of such a \( G' \) arising tends to 0 as \( n \to \infty \).

As an aside, we can consider the analogous problem on the torus, rather than on the square \( S_n \). Unfortunately, the above proof does not show that the corresponding graph on the torus is connected w.h.p. for \( c > 1/\log 2 \), since a component on the torus need not have any extreme points.

Next, we establish an upper bound. The proof splits into two parts. In the first part (Lemma 6, below), we show that there do not exist two ‘large’ components; indeed, we show that, even if \( k \) is far smaller than \( \log n \), two such components do not exist. Secondly we show that there are no small components.

We will use the following simple lemma, which bounds the edge-lengths. There are many results in the literature bounding the Poisson distribution; we give a simple bound in a form convenient for our needs.

Lemma 2. Fix \( c > 0 \) and set

\[
c_+ = ce^{-1-1/c} \quad \text{and} \quad c_+ = 4e(1+c).
\]

If \( r \) and \( R \) are such that \( \pi r^2 = c_- \log n \) and \( \pi R^2 = c_+ \log n \), then, w.h.p., every vertex in \( G_{n,\lfloor c \log n \rfloor} \) is joined to every other vertex within a distance \( r \), and no vertex is joined to a vertex at a distance greater than \( R \). The same is true for the directed model \( \tilde{G}_{n,\lfloor c \log n \rfloor} \).

Proof. This lemma will follow from simple properties of the Poisson distribution. We write \( D_\rho(P) \) for the open disc of radius \( \rho \) centred at \( P \) (a vertex of \( G_{n,k} \)), fix \( k = \lfloor c \log n \rfloor \), and suppose that the vertex \( P \) is not joined to every other vertex of \( G_{n,k} \) in \( D_r(P) \cap S_n \). Then \( D_r(P) \cap S_n \), which has area at most \( \lambda := \pi r^2 = c_- \log n \), contains at least \( k \) additional vertices
bounded by a geometric series):

\[ p = e^{-\lambda} \sum_{l=0}^{\infty} \frac{\lambda^l}{l!} < e^{-\lambda} \frac{\lambda^k}{k^k} < e^{-\lambda} \frac{\lambda^k}{k^k} \left( \frac{\lambda e}{k} \right)^k \]

\[ = \frac{c}{c_-} n^{c_-(\log(c_-/c)+1)-c_-} (1 + o(1)), \]

which is \( o(n^{-1}) \) provided that

\[ c_- < c \quad \text{and} \quad c_-(\log(c_-/c)+1) - c_- < -1, \]

which is true for \( c_- \) as given in the statement of the theorem.

Since the expected number of vertices in \( S_n \) is \( n \), the expected number of vertices of \( P \) such that \( D_r(P) \cap S_n \) contains at least \( k \) additional vertices is \( o(1) \) and, hence, the probability that there is any such vertex \( P \) in \( G_{n,k} \) is \( o(1) \), as claimed.

The proof of the upper bound is almost the same. Let \( R \) satisfy \( \pi R^2 = c_+ \log n \). If a vertex is joined to another at a distance at least \( R \), then the circle of radius \( R \) about one of the two, \( P \) say, contains at most \( k \) additional vertices of \( G_{n,k} \). The area of \( D_R(P) \cap S_n \) is at least \( \frac{4}{3} \pi R^2 = \frac{1}{2} c_+ \log n \). Hence, the probability that this occurs for a particular vertex can be bounded by

\[ p = e^{-\lambda} \sum_{l=0}^{k} \frac{\lambda^l}{l!} < e^{-\lambda} \frac{\lambda^k}{k^k} < e^{-\lambda} \frac{\lambda^k}{k^k} \left( \frac{\lambda e}{k} \right)^k \]

\[ = \frac{c_+}{c_-} n^{c_+ (\log(c_-/c)+1)-c_-} (1 + o(1)), \]

which is \( o(n^{-1}) \) provided that

\[ c_+ > 4c \quad \text{and} \quad c_+ (\log(c_-/c)+1) - \frac{1}{4} c_+ < -1, \]

which holds for \( c_+ \) as given in the statement of the theorem (using the inequality \( \log((c+1)/c) \leq 1/c \)). Hence, the probability that we have any such vertex \( P \) is \( o(1) \).

**Remark.** We claim only that the above result holds w.h.p. In fact, for any fixed constant \( K \), we can find \( c_- \) and \( c_+ \) such that it holds with probability \( 1 - O(n^{-K}) \).

The next two lemmas state simple facts about the components of \( G_{n,k} \).

**Lemma 3.** No two edges belonging to different components of \( G_{n,k} \) may cross.

**Proof.** Let \( G_1, G_2, \ldots, G_N \) be the components of \( G_{n,k} \). Suppose that \( i_1 i_2 = e_i \in E(G_i) \) and \( j_1 j_2 = e_j \in E(G_j) \) for \( i \neq j \), and that \( e_i \) and \( e_j \) cross. (Here, \( E(G_i) \) and \( E(G_j) \) are the edge sets of \( G_i \) and \( G_j \), respectively.) Then, considering \( e_i \), if \( i_2 \) is one of the \( k \)th-nearest neighbours of \( i_1 \), then \( \|i_1 - i_2\| > \|i_1 - i_2\| \) while, if \( i_1 \) is one of the \( k \)th-nearest neighbours of \( i_2 \), then \( \|i_1 - i_2\| > \|i_1 - i_2\| \). Therefore, in either case, \( e_i \) is not the longest edge of the triangle \( i_1 i_2 j_1 \), and so the angle \( i_1 i_2 j_1 \) is less than \( \frac{1}{2} \pi \). However, this applies to all four angles of the quadrilateral \( i_1 j_1 i_2 j_2 \), which gives a contradiction.

**Lemma 4.** With \( r \) as in Lemma 2, w.h.p. the distance between any two edges belonging to different components of \( G_{n,k} \) is at least \( \frac{1}{4} r \).
Thus we can decompose $B$ into exactly two components each of (Euclidean) diameter at least $\frac{1}{2} - 2r$ of $e_i$.

Suppose otherwise. Let $z$ be the foot of the perpendicular from $j_1$ onto the line through $i_j i_2$, so that $\|j_1 - z\| \leq \frac{1}{2}r$. If $z$ does not lie between $i_1$ and $i_2$ then the minimum distance between $e_i$ and $j_1$ is attained at one of the endpoints of the edge, say $i_1$, and thus $\|i_1 - j_2\| \leq \frac{1}{2}r$, so that the edge $i_1 j_1$ is in $G_{n,k}$, by Lemma 2. Now suppose that $z$ does lie between $i_1$ and $i_2$, and assume that the edge $e_i$ is present because $i_2$ is one of the $k$ nearest neighbours of $i_1$. Also suppose that $z$ lies within a distance $\frac{1}{2}r$ of $i_2$. Then

$$\|i_2 - j_1\| \leq \|i_2 - z\| + \|z - j_1\| \leq \frac{1}{2}r + \frac{1}{2}r = r$$

and, thus, by Lemma 2, the edge $i_2 j_1$ is contained in $G_{n,k}$. Otherwise,

$$\|z - i_2\| > \frac{1}{2}r \geq \|z - j_1\|$$

and so

$$\|i_1 - j_1\| \leq \|i_1 - z\| + \|z - j_1\| = (\|i_1 - i_2\| - \|i_2 - z\|) + \|z - j_1\| < \|i_1 - i_2\|,$$

so that, since $i_1 i_2$ is an edge, so is $i_1 j_1$. In each case, $j_1$ is in the same component as $e_i$.

Next we need a geometric lemma.

**Lemma 5.** Let $A$ be the graph of the $l \times l$ square integer grid $\{1, \ldots, l\}^2 \subset \mathbb{R}^2$ with edges of unit length. Suppose that $A \subset V(A_1)$, with both $A$ and $A^c = V(A_1) \setminus A$ connected in $A_1$. Let $\partial A$ denote the set of vertices of $A^c$ that are adjacent to vertices of $A$. Then the set $\partial A$ is diagonally connected, i.e. connected if we include all edges of length less than or equal to $2^{1/2}$.

**Proof.** Let $B$ be the set of edges from an element of $A$ to an element of $A^c$ and let $B'$ be the corresponding edges in the dual lattice. If we consider $B'$ as a subgraph of the dual lattice then every vertex has even degree except those vertices corresponding to the boundary of $A_1$. Thus we can decompose $B'$ into edge-disjoint subgraphs, each of which is either a cycle, or a path starting and ending at a boundary. Any such cycle or path splits $A_1$ into two components. Since the entirety of any connected set must lie within the same component, we see that all of $A$ lies within the same component and all of $A^c$ lies within the same component. This implies that the cycle or path partitions $A_1$ into exactly $A$ and $A^c$, and hence comprises all of $B'$. Thus, $\partial A$ is diagonally connected and the result follows.

The following lemma asserts that there are no two large components.

**Lemma 6.** Fix $c > 0$. Then there exists a constant $c'$ such that the probability that $G_{n,[c \log n]}$ contains two components each of (Euclidean) diameter at least $c'(\log n)^{1/2}$ tends to 0 as $n \to \infty$.

**Proof.** Fix $c'$ to be chosen later, and let $D = c'(\log n)^{1/2}$. Let $c_\ll$ be as in Lemma 2 and let $r$ satisfy $\pi r^2 = c_\ll \log n$. By Lemma 2, w.h.p. every vertex is joined to every other vertex within a distance $r$. Thus, we may ignore all configurations for which this does not hold. Also, by assumption and the definition of $D$, there exist two components $G_1$ and $G_2$ of $G := G_{n,[c \log n]}$, each of diameter at least $D$. Let $G_3$ consist of the rest of the vertices.
We tessellate the square $S_n$ with squares of side $r/20^{1/2}$/; letting $l = (20n)^{1/2}/r$, we identify the squares with the square grid $\Lambda_l = \mathbb{Z}_l^2$. (Here, and in the proof of Lemma 7, below, we assume for convenience that $r/20^{1/2}$ divides $n^{1/2}$.) We colour the squares as follows: colour red any square containing a vertex of $G_1$ or intersecting an edge of $G_1$; colour blue any square containing a vertex of $G_2$ or intersecting an edge of $G_2$; and colour black the remaining squares containing a vertex. All other squares we call empty and colour white. This colouring is well defined, by Lemma 4. The same lemma also shows that a red square can only be adjacent to another red square or to an empty square, since any two points in adjacent squares must be within a distance $5^{1/2}(r/20^{1/2}) = \frac{1}{4}r$. In addition, the set of red squares and the set of blue squares each forms a connected component in $\Lambda_l$.

Since $G_1$ and $G_2$ have diameter at least $D$, the set of red squares and the set of blue squares are each connected, there must be at least $D/r$ red squares and $D/r$ blue squares. Let $U$ be the set of red squares and let $V = U^c$ be the complement of $U$. $V$ splits into components $V_1, V_2, \ldots, V_s$ for some $s \geq 1$. Since the blue squares are connected, at most one of these components, say $V_1$, can contain blue squares. Furthermore, let $U_1 = V_1^c$; i.e. $U$ and all the components of $U^c$ that do not contain any blue squares. Note that both $U_1$ and $U_1^c$ are connected, and that each contains at least $D/r$ squares, since all the red squares lie in $U_1$ and all the blue squares lie in $V_1 = U_1^c$. Finally, let $\partial U_1$ be the set of squares not in $U_1$ but adjacent to at least one square in $U_1$. Each square in $\partial U_1$ is empty, and the set is a diagonally connected component, since both $U_1$ and $U_1^c = V_1$ are connected.

By the vertex isoperimetric inequality in the grid [3],

$$|\partial U_1| \geq \min\{(2|U_1|)^{1/2}, (2|U_1^c|)^{1/2}\} \geq (D/r)^{1/2}.$$ 

Hence, if we have $G_1$ and $G_2$, both with diameter at least $D$, we can find a set, connected in $\Lambda_l$ and of size $K = (D/r)^{1/2} = (\pi c^2/c_-)^{1/4}$, consisting entirely of empty squares. To complete the proof we just need to show that such a set is unlikely to exist.

We use the following graph-theoretic lemma: for any graph $G$ with maximum degree $\Delta$, the number of connected subsets of size $n$ containing a particular vertex $v_0$ is at most $(e\Delta)^n$.

Define $\Lambda^* = \Lambda_l$ as the graph with vertex set $\Lambda_l$ and edges joining diagonally connected vertices.

The graph $\Lambda^*_l$ has maximum degree 8, so the number of connected sets of $K$ squares in $\Lambda^*_l$, containing a particular square, is at most $(8e)^K$. There are $l^2 \leq n$ squares in $\Lambda_l$, so the total number of connected sets of size $K$ is at most $n(8e)^K$. Therefore, the probability $p$ that any connected set $K$ consists entirely of empty squares satisfies

$$p \leq n(8e)^K e^{-K r^2/20} \leq n \exp(K (\log(8e) - \frac{1}{20}r^2)) \leq n^{1-Kc_-/20c_-+o(1)},$$

which tends to 0 provided that we chose $c'$ and, thus, $K$ large enough. Hence, the probability that there are two components with diameter at least $D$ tends to 0 as $n$ tends to infinity.

**Theorem 7.** If $c > 1/\log 7 \approx 0.5139$ then $P(G_n, [c \log n] \text{ is connected}) \to 1$ as $n \to \infty$.

**Proof.** Let $k = \lfloor c \log n \rfloor$. We will show that, for any fixed $c' > 0$, there is no component $G' \subset G := G_{n,k}$ with diameter less than $c'(\log n)^{1/2}$ w.h.p. This, together with Lemma 6, will prove the result. By Lemma 2, we may assume that the $k$ nearest neighbours of any point all lie within a distance $R$, where $\pi R^2 = c_+ \log n$, as above.
Thus, the number of choices for the $A$ are now only $O((n^2)^{1/2})$. Then, writing $A = O((\log n)^{3/2})$ (some of the $P_i$ may coincide). The bisectors of the exterior angles of $H$ divide the exterior of $H$ into six regions $H_i$, each of which is bounded by two bisectors and $t_i$. Consider the smallest disc $D_i$ centred at $P_i$ and containing its $k$ nearest neighbours. By assumption, all of the $D_i$ are contained in $S_n$. Write $A_i = H_i \cap D_i$ and number the sets so that, without loss of generality, $|A_1| \leq |A_i|$ for all $i$. Then, writing $A = H \cap D_1$ and noting that $|A| \leq |A_1|$ (since $A_1$ does not meet the boundary of $S_n$), we obtain $|A| \leq 1/2 |A \cup \bigcup A_i|$.

Now we require that there be exactly $k$ points in the region $A \cup \bigcup A_i$, and that they all lie within $A$. The probability of this happening is at most $7^{-k}$. However, the number of choices for the regions $A$ and $A_i, i = 1, \ldots, 6$, can be estimated as follows. There are $O(n)$ choices for the point $P_1$ (w.h.p.), and, fixing $P_1$, there are, w.h.p., $O(\log n)$ choices for each of $P_2, \ldots, P_6$ (since they lie within a distance $c'(\log n)^{1/2}$ of $P_1$), and $O((\log n)^6)$ choices for the six radii of the $D_i$, since each is determined by a point within a distance $R$ of the corresponding $P_i$. Thus, the number of choices for the $A$ and $A_i$ is $O(n(\log n)^{11})$, which is $n^{1+o(1)}$, and the probability that we have a $G'$ of diameter at most $c' \log n$ is at most $n^{1+o(1)}7^{-k}$, which is $o(1)$ for $c > 1/\log 7$.

The above argument applies if $G'$ is not too close to the boundary of $S_n$. Suppose now that $G'$ is within a distance $R$ of the boundary, but a distance greater than $R$ from a corner of $S_n$. In this case, we ignore the two tangents whose normal vectors point out of $S_n$, and define $H$ and the relevant $H_i$ and $A_i$ as the intersections of the previously defined $H, H_i$, and $A_i$ with $S_n$ (see Figure 4(a)). For the horizontal boundaries, we rotate the tangents by 90 degrees. Now, supposing again that $|A_1| \leq |A_i|$ for all $i$, and writing $A = H \cap D_1$ as before, we obtain $|A| \leq 1/2 |A \cup \bigcup A_i|$. Therefore, the probability that all $k$ points in $A \cup \bigcup A_i$ are actually contained in $A$ is at most $5^{-k}$. Thus the probability of finding such a small component lying near the boundary is $n^{1/2+o(1)}5^{-k}$, which is $o(1)$ for $c > 1/\log 7 > 1/2 \log 5$. (Note that there are now only $O((n \log n)^{1/2})$ choices for $P_1$.)

Figure 3: The hexagon $H$. 

Firstly, let us assume that such a small component $G'$ exists and that $G'$ contains only normal points. Consider the six tangents $t_i, i = 1, \ldots, 6$, to the convex hull of $G'$ that are inclined at angles 0, $\frac{1}{7}\pi$, and $\frac{2}{7}\pi$ to the horizontal. These tangents form a hexagon $H$ containing $G'$, as shown in Figure 3, and each tangent $t_i$ intersects $G'$ at a point $P_i \in V(G')$ (some of the $P_i$ may coincide). The bisectors of the exterior angles of $H$ divide the exterior of $H$ into six regions $H_i$, each of which is bounded by two bisectors and $t_i$. Consider the smallest disc $D_i$ centred at $P_i$ and containing its $k$ nearest neighbours. By assumption, all of the $D_i$ are contained in $S_n$. Write $A_i = H_i \cap D_i$ and number the sets so that, without loss of generality, $|A_1| \leq |A_i|$ for all $i$. Then, writing $A = H \cap D_1$ and noting that $|A| \leq |A_1|$ (since $A_1$ does not meet the boundary of $S_n$), we obtain $|A| \leq 1/2 |A \cup \bigcup A_i|$.

Now we require that there be exactly $k$ points in the region $A \cup \bigcup A_i$, and that they all lie within $A$. The probability of this happening is at most $7^{-k}$. However, the number of choices for the regions $A$ and $A_i, i = 1, \ldots, 6$, can be estimated as follows. There are $O(n)$ choices for the point $P_1$ (w.h.p.), and, fixing $P_1$, there are, w.h.p., $O(\log n)$ choices for each of $P_2, \ldots, P_6$ (since they lie within a distance $c'(\log n)^{1/2}$ of $P_1$), and $O((\log n)^6)$ choices for the six radii of the $D_i$, since each is determined by a point within a distance $R$ of the corresponding $P_i$. Thus, the number of choices for the $A$ and $A_i$ is $O(n(\log n)^{11})$, which is $n^{1+o(1)}$, and the probability that we have a $G'$ of diameter at most $c' \log n$ is at most $n^{1+o(1)}7^{-k}$, which is $o(1)$ for $c > 1/\log 7$.

The above argument applies if $G'$ is not too close to the boundary of $S_n$. Suppose now that $G'$ is within a distance $R$ of the boundary, but a distance greater than $R$ from a corner of $S_n$. In this case, we ignore the two tangents whose normal vectors point out of $S_n$, and define $H$ and the relevant $H_i$ and $A_i$ as the intersections of the previously defined $H, H_i$, and $A_i$ with $S_n$ (see Figure 4(a)). For the horizontal boundaries, we rotate the tangents by 90 degrees. Now, supposing again that $|A_1| \leq |A_i|$ for all $i$, and writing $A = H \cap D_1$ as before, we obtain $|A| \leq 1/2 |A \cup \bigcup A_i|$. Therefore, the probability that all $k$ points in $A \cup \bigcup A_i$ are actually contained in $A$ is at most $5^{-k}$. Thus the probability of finding such a small component lying near the boundary is $n^{1/2+o(1)}5^{-k}$, which is $o(1)$ for $c > 1/\log 7 > 1/2 \log 5$. (Note that there are now only $O((n \log n)^{1/2})$ choices for $P_1$.)

Figure 3: The hexagon $H$. 

Firstly, let us assume that such a small component $G'$ exists and that $G'$ contains only normal points. Consider the six tangents $t_i, i = 1, \ldots, 6$, to the convex hull of $G'$ that are inclined at angles 0, $\frac{1}{7}\pi$, and $\frac{2}{7}\pi$ to the horizontal. These tangents form a hexagon $H$ containing $G'$, as shown in Figure 3, and each tangent $t_i$ intersects $G'$ at a point $P_i \in V(G')$ (some of the $P_i$ may coincide). The bisectors of the exterior angles of $H$ divide the exterior of $H$ into six regions $H_i$, each of which is bounded by two bisectors and $t_i$. Consider the smallest disc $D_i$ centred at $P_i$ and containing its $k$ nearest neighbours. By assumption, all of the $D_i$ are contained in $S_n$. Write $A_i = H_i \cap D_i$ and number the sets so that, without loss of generality, $|A_1| \leq |A_i|$ for all $i$. Then, writing $A = H \cap D_1$ and noting that $|A| \leq |A_1|$ (since $A_1$ does not meet the boundary of $S_n$), we obtain $|A| \leq 1/2 |A \cup \bigcup A_i|$.

Now we require that there be exactly $k$ points in the region $A \cup \bigcup A_i$, and that they all lie within $A$. The probability of this happening is at most $7^{-k}$. However, the number of choices for the regions $A$ and $A_i, i = 1, \ldots, 6$, can be estimated as follows. There are $O(n)$ choices for the point $P_1$ (w.h.p.), and, fixing $P_1$, there are, w.h.p., $O(\log n)$ choices for each of $P_2, \ldots, P_6$ (since they lie within a distance $c'(\log n)^{1/2}$ of $P_1$), and $O((\log n)^6)$ choices for the six radii of the $D_i$, since each is determined by a point within a distance $R$ of the corresponding $P_i$. Thus, the number of choices for the $A$ and $A_i$ is $O(n(\log n)^{11})$, which is $n^{1+o(1)}$, and the probability that we have a $G'$ of diameter at most $c' \log n$ is at most $n^{1+o(1)}7^{-k}$, which is $o(1)$ for $c > 1/\log 7$.

The above argument applies if $G'$ is not too close to the boundary of $S_n$. Suppose now that $G'$ is within a distance $R$ of the boundary, but a distance greater than $R$ from a corner of $S_n$. In this case, we ignore the two tangents whose normal vectors point out of $S_n$, and define $H$ and the relevant $H_i$ and $A_i$ as the intersections of the previously defined $H, H_i$, and $A_i$ with $S_n$ (see Figure 4(a)). For the horizontal boundaries, we rotate the tangents by 90 degrees. Now, supposing again that $|A_1| \leq |A_i|$ for all $i$, and writing $A = H \cap D_1$ as before, we obtain $|A| \leq 1/2 |A \cup \bigcup A_i|$. Therefore, the probability that all $k$ points in $A \cup \bigcup A_i$ are actually contained in $A$ is at most $5^{-k}$. Thus the probability of finding such a small component lying near the boundary is $n^{1/2+o(1)}5^{-k}$, which is $o(1)$ for $c > 1/\log 7 > 1/2 \log 5$. (Note that there are now only $O((n \log n)^{1/2})$ choices for $P_1$.)
Finally, if some point of $G'$ is within a distance $R$ of a corner of $S_n$, we have $\|A\| \leq \frac{1}{2}\|A \cup \bigcup_{i} A_i\|$ (see Figure 4(b)) and, thus, the probability of all $k$ points in $A \cup \bigcup_{i} A_i$ lying in $A$ is at most $3^{-k}$. Here, the shape of the region $H$ is not critical – we only need to ensure that the reflections of $H$ in the tangents $t_i$ are disjoint and lie within $S_n$. Hence, the probability of finding a small component lying at a corner is $o(1)3^{-k} = o(1)$, there now being only $O(\log n)$ choices for $P_1$.

4.1. The directed case

As in the undirected case, we first show that, w.h.p., there do not exist two large components. The proof is very similar to that in the undirected case, so we sketch the parts that are the same and concentrate on the differences. The first key difference is that in a directed graph there is no clear idea of what constitutes a component. We define two such notions, which will be sufficient to satisfy our needs: a set $C$ is an out-component if, for some $x_0$, it is of the form $\{y: \text{there exists a directed path from } x_0 \text{ to } y\}$; and it is an in-component if it is of the form $\{y: \text{there exists a directed path from } y \text{ to } x_0\}$. If the graph is undirected then both of these reduce to the normal definition of component. The following lemma is analogous to Lemma 6.

**Lemma 7.** Fix $c > 0$ and let $k = \lceil c \log n \rceil$. Then there exists $c'$ such that the probability that $\vec{G}_{n,k}$ contains an in-component and an out-component that are disjoint and both of diameter at least $c'(\log n)^{1/2}$ tends to 0 as $n \to \infty$.

**Proof.** As before, fix $c'$ to be chosen later and let $D = c'(\log n)^{1/2}$. This time, since we will also need an upper bound on the edge-length, let $c_-$ and $c_+$ be as in Lemma 2 and let $r$ and $R$ satisfy $\pi r^2 = c_- \log n$ and $\pi R^2 = c_+ \log n$, respectively. We may ignore all configurations that have two points separated by a distance at most $r$ and which are not joined, or have two points separated by a distance at least $R$ and which are joined.

Let $G_1$ be an out-component and $G_2$ an in-component, both of diameter at least $D$, and let $G_3$ comprise the rest of the vertices. This time, edges of $G_i$ and $G_j$ may cross for $i \neq j$; however, it is still true that no vertex outside $G_1$ may lie within a distance $\frac{1}{2}r$ of an edge of $G_1$. Indeed, the proof of Lemma 4 shows that (with notation as in that proof), in this case, either $i_1j$ or $i_2j$ is a directed edge in $\vec{G}_{n,k}$. Thus, since $G_1$ is an out-component, $j \in G_1$. (Note that it is important that $G_1$ is an out-component: $j \notin G$, if the latter is an in-component.)
Again, we tessellate the square with squares of side $r/20^{1/2}$; letting $l = (20n)^{1/2}/r$, we identify the squares with the square grid $\Lambda_n$. We colour the squares almost exactly as before; that is, we colour red the squares containing a vertex of $G_1$ or intersecting an edge of $G_1$, colour blue the squares containing a vertex of $G_2$ (note that we do not colour the squares intersecting an edge of $G_2$, as that might conflict with the squares already coloured), colour black the remaining squares containing a vertex, and, finally, colour the empty squares white. As before, the colouring is well defined and, also, we see that a red square can only be adjacent to another red square or to an empty square. In addition, the set of red squares forms a connected component of squares.

This time, since no point is joined to another at a distance greater than $R$, there must be at least $D/R$ red squares, and at least $D/R$ blue squares. Let $U$ be the set of red squares and let $V = U^c$ be the complement of $U$. $V$ splits into components $V_1, V_2, \ldots, V_s$ for some $s \geq 1$. This time the blue squares need not be connected and so need not all be in the same set $V_i$: suppose that the components that contain blue squares are $V_1, V_2, \ldots, V_s$. Furthermore, let $U_1 = U \cup \bigcup_{r=t+1} V_i$; i.e. $U$ and all the components of $U^c$ that do not contain any blue squares. $U_1$ and $U_1^c$ each contain at least $D/R$ squares, since all of the red squares lie in $U_1$ and all of the blue squares lie in $U_1^c$. Finally, let $\partial U_1$ be the set of squares not in $U_1$ but adjacent to at least one square in $U_1$. Each square in $\partial U_1$ lies in $\partial U$, so is empty. The set $\partial U_1$ is not necessarily a connected component of squares in $\Lambda_1$; however, we will show that for some $d$, it is connected in $\Lambda_{1,d}$, the $d$th power of the lattice $\Lambda_1$, where we join vertices if their separation distance in the lattice (i.e. their 'l1-distance') is at most $d$.

Let $d = 2\lfloor 20^{1/2}R/r \rfloor$, in which case the blue squares are joined in $\Lambda_{1,d}$, and suppose that $\partial U_1$ is not connected in $\Lambda_{1,d}$; i.e. that we can partition $\partial U_1$ into two nonempty sets $A$ and $B$ with no square in $A$ within a distance $d$ of any square in $B$. For $i \leq t$, write $\partial V_i$ for $\partial U_1 \cap V_i$. Since $V_i$ and $V_i^c$ are both connected in $\Lambda_1$, $\partial V_i$ is connected in $\Lambda_{1,2}$ and, hence, $A$ and $B$ are both the unions of such $\partial V_i$. Every $V_i$ with $i \leq t$ contains a blue square, so there must be a pair $i, j \leq t$ with $\partial V_i \subseteq A$ and $\partial V_j \subseteq B$, and blue squares $b_i$ and $b_j$ with $b_i \in V_i, b_j \in V_j$, and $l_1$-distance $d(b_i, b_j) \leq d$. The shortest path from $b_i$ to $b_j$ in $\Lambda_1$ passes through $\partial V_i$ and $\partial V_j$ and has length at most $d$, so $d(\partial V_i, \partial V_j) < d$, contradicting the assumption that $\partial V_i$ and $\partial V_j$ were in different components of $\Lambda_{1,d}$.

As before, by the vertex isoperimetric inequality in the grid [3],

$$|\partial U_1| \geq \min\{(2|U_1|)^{1/2}, (2|U_1^c|)^{1/2}\} \geq (D/R)^{1/2}.$$ 

Hence, if we have $G_1$ and $G_2$ both with diameter at least $D$, we can find a set, connected in $\Lambda_{1,d}$ and of size $K = (D/R)^{1/2} = (\pi c^2/c_+)^{1/4}$, consisting entirely of empty squares. Once again, to complete the proof, we will show that it is unlikely that such a set exists.

$\Lambda_{1,d}$ has maximum degree $2d^2 + 2d$. Thus, applying the graph-theoretic lemma stated in the undirected case, the number of connected sets of $K$ squares in $\Lambda_{1,d}$, containing a particular square, is at most $(e(2d^2 + 2d))^K \leq (4ed^2)^K$. Since there are $l^2 \leq n$ squares in $\Lambda_1$, the probability $p$ that there exists a set of empty squares connected in $\Lambda_{1,d}$ satisfies

$$p \leq n(4ed^2)^K e^{-Kr^2/20} \leq n \exp(K(\log(4ed^2) - \frac{1}{2}r^2)) \leq n^{1-Kc_+/20\pi+o(1)}.$$
Theorem 8. If $c \geq 0.9967$ then $P(\tilde{G}_{n, [c \log n]}$ is connected) $\to$ 1 as $n \to \infty$.

Proof. Suppose that $k = [c \log n]$ and that $\tilde{G} := \tilde{G}_{n, k}$ is not connected. Then there will be two points $x, y \in V(\tilde{G})$ such that there is no directed path from $x$ to $y$. We consider two subsets of $V(\tilde{G})$, $C_x$ and $C_y$, defined as follows:

$$C_x = \{x\} \cup \{x': \text{there is a directed path from } x \text{ to } x'\}$$

and

$$C_y = \{y\} \cup \{y': \text{there is a directed path from } y' \text{ to } y\}.$$

$C_x$ and $C_y$ are disjoint since, if we had $z \in C_x \cap C_y$, there would be a directed path from $x$ to $z$ and another directed path from $z$ to $y$, giving us a directed path from $x$ to $y$.

Lemma 7 shows that there exists a $c' > 0$ such that the probability that both $C_x$ and $C_y$ have diameter of radius $c'(\log n^{1/2})$ tends to 0. The proof of Theorem 7 shows that the probability that an out-component $C_x$ exists with diameter less than $c'(\log n^{1/2})$ tends to 0, since $c > 1/\log 7$. We can then complete the proof by showing that, for all $c' > 0$, the probability that an in-component $C_y$ exists with diameter less than $c'(\log n^{1/2})$ also tends to 0.

However, we first illustrate the proof with a simpler proof that $c \geq 1.0293 > 1/\log 3$ is sufficient in the statement of the theorem, where $\gamma = (\frac{3\pi}{2} + \frac{1}{21/2})/\frac{3\pi}{2} + \frac{1}{21/2}$. Suppose first that no point of $C_y$ lies within a distance $R$ of the boundary of $S_n$, where $R$ is as in Lemma 2. Let $z \notin C_y$ be the closest point of $V(\tilde{G}) \setminus C_y$ to $C_y$, and let $y_z$ be its nearest neighbour in $C_y$. Write $\rho = \|y_z - z\|$ for the distance between them, and, for an arbitrary point $P$, write $D_\rho(P)$ for the open disc of radius $\rho$, centred at $P$. Consider the left-most point $y_1$ and the right-most point $y_r$ of $C_y$: there can be no points in $B = D_\rho(y_1) \cup D_\rho(y_r)$, i.e. in the left half of $D_\rho(y_1)$ or the right half of $D_\rho(y_r)$. By the proof of Lemma 2, we may assume that $D_\rho(y_1)$ contains at least $k$ points. Hence, $\rho < R$, $B$ is contained within $S_n$, and $|B| = |D_\rho(x)| = \pi \rho^2$. On the other hand, there are at least $k$ points in $A = D_\rho(z) \setminus D_\rho(y_1)$ (shown in Figure 5(a)), since otherwise $z$ would send a directed edge to either $y_z$ or to a point $y' \in D_\rho(z) \cap D_\rho(y_r)$. The first possibility contradicts the hypothesis that $z \notin C_y$ and, for the second possibility, we must have $y' \notin C_y$ to ensure that $z \notin C_y$; then, however, $y' \notin C_y$ is closer to $C_y$ than is $z$, contradicting the choice of $z$. Therefore, there must be at least $k$ points in $A \cup B$, and they must all lie in $A \setminus B$.

The probability of this happening is at most $(|A \setminus B|/|A \cup B|)^k \leq (|A|/(|A| + |B|))^k = \gamma^{-k}$. 

---

**Figure 5:** Upper bound, directed case. (B not shown.)
The number of choices for \( z, y_z, y_t, \) and \( y_r \) is \( O(n(\log n)^3) \), so the probability that such a configuration occurs anywhere is at most \( n^{1+o(1)}r^{-k} \), which is \( o(1) \) for \( c > 1/\log r \).

If some point of \( C_y \) is close to either an edge or a corner of \( S_n \), we use a single half-disc or quarter-disc for \( B \), and an argument similar to the one used to complete the proof of Theorem 7 shows that the probability of finding a small \( C_y \) near the boundary is also \( o(1) \). (With a little more work, we can obtain a slight improvement by showing that there is a region \( C \subseteq A \) containing no points in its interior.)

Suppose that \( w \in D_\rho(z) \). Write \( \rho' = \| w - y_z \| \) and set

\[
A_1 = (A \setminus D_\rho'(w)) \setminus B, \\
A_2 = (A \cap D_\rho'(w)) \setminus B, \\
A_3 = (D_\rho'(w) \setminus (D_\rho(z) \cup D_\rho(y_z))) \setminus B, \\
A_4 = B, 
\]

as illustrated in Figure 5(b) (for simplicity, the set \( B \) is not shown). Writing \( n_i \) for the number of points (other than \( y_z, z, \) or \( w \)) in region \( A_i \), we see that the following relations must hold:

\[
n_1 + n_2 \geq k - 1, \quad n_3 + n_2 \geq k - 1, \quad n_4 = 0. \tag{4}
\]

We need to show that, for some \( w \), the probability \( p \) of such an arrangement is small. By Lemma 1, we have

\[
\log p = \sum_{i=1}^{3} (n_i - |A_i| - n_i \log(n_i/|A_i|)) + O(\log \sum n_i). \tag{5}
\]

We now maximize the right-hand side of (5). Since (4) becomes more likely if \( |A_1|, |A_2|, \) or \( |A_3| \) is increased, we may assume that \( B \) is disjoint from \( A \cup D_\rho'(w) \). Also, as we will only be interested in ratios of areas, we first maximize (5) under uniform scaling of areas, giving

\[
n_1 + n_2 + n_3 = |A_1| + |A_2| + |A_3| + |A_4|. 
\]

We now vary the \( n_i \), subject to the constraint that \( n_1 + n_2 \) and \( n_3 + n_2 \) are fixed. This gives

\[
\eta := \frac{n_2}{|A_2|} = \frac{n_1}{|A_1|} = \frac{n_3}{|A_3|}. 
\]

Also, by varying \( n_1 \) alone, we see that either \( n_1 + n_2 = k - 1 \) or \( n_1 = |A_1| \). Similarly, by varying \( n_3 \) alone, we see that either \( n_3 + n_2 = k - 1 \) or \( n_3 = |A_3| \). Hence,

\[
\log p = \sum_{i=1}^{3} -n_i \log \frac{n_i}{|A_i|} + O\left( \log \sum_{i=1}^{3} n_i \right) \\
= -n_1 \log \frac{n_1}{|A_1|} - n_3 \log \frac{n_3}{|A_3|} - n_2 \log \left( \frac{n_1 n_3}{|A_1||A_3|} \right) + O\left( \log \sum_{i=1}^{3} n_i \right) \\
= -(n_1 + n_2) \log \frac{n_1}{|A_1|} - (n_3 + n_2) \log \frac{n_3}{|A_3|} + O\left( \log \sum_{i=1}^{3} n_i \right) \\
= -(k - 1) \log \left( \frac{n_1 n_3}{|A_1||A_3|} \right) + O\left( \log \sum n_i \right). 
\]
Therefore, \( p = \eta^{-(k-1)n^{o(1)}} \).

Define \( \gamma' \) by \((\log \gamma')^{-1} = 0.9967\) and let \( C \) be the set of points \( w \in A \) such that
\[
\sum_{i=1}^{3} |A_i| > \gamma' |A_2| + \sqrt{4\gamma'|A_1||A_3|} \quad \text{and} \quad |A_3| < 2|A_1|.
\]

We will show that, with the above constraints,
\[
\eta = \frac{n_{2}|A_2|}{|A_1||A_3|} > \gamma'.
\]

If \( n_3 + n_2 > k - 1 = n_1 + n_2 \) then \( n_3 = |A_3| \) and, so, \( 2|A_1| > |A_3| = n_3 > n_1 = \eta |A_1| \).
However, then \( \eta < 2 \) and \( |A_1| + |A_2| + |A_4| = n_1 + n_2 < 2(|A_1| + |A_2|) \), contradicting the fact that \( |A_1| + |A_2| < |A_4| \). On the other hand, if \( n_1 + n_2 > k - 1 = n_3 + n_2 \) then
\[
|A_1| = n_1 > n_3 = \eta |A_3|; \quad \text{but} \quad |A_3| \geq |A_1|, \quad \text{so this means that} \quad \eta \leq 1. \]
Then, however,
\[
|A_1| + n_2 + n_3 \leq |A_1| + |A_2| + |A_3| \quad \text{and so} \quad |A_4| \leq 0, \quad \text{a contradiction. Similarly, if} \quad n_1 + n_2 > k - 1 \quad \text{and} \quad n_3 + n_2 > k - 1 \quad \text{then} \quad \eta = 1 \quad \text{and, again,} \quad |A_4| \leq 0. \]

Hence, we may assume that \( n_1 + n_2 = n_3 = k - 1 \) and \( n_1 = n_3 \), so that \( \sum_{i=1}^{3} |A_i| = n_2 + (n_1 + n_3) = n_2 + (n_1 + n_3) = n_2 + (4n_1 n_3)^{1/2} = \eta |A_2| + (4\eta |A_1||A_3|)^{1/2} \). This then implies that \( \eta > \gamma' \), as required. Computer calculations show that \((|B| + |A \setminus C|)/|A \setminus C| > \gamma' \). Supposing that the region \( C \) contains no points in its interior, we have at least \( k \) points in the region \((A \setminus C) \cup B\), all of which are constrained to lie in \( A' = A \setminus (C \cup B) \) (see Figure 5(c)). This event has probability at most \( \gamma'^{-k}n^{o(1)} = o(n^{-1}) \).

On the other hand, the probability that there exists a configuration with a point \( w \in C \) is also at most \( \gamma'^{-k}n^{o(1)} = o(n^{-1}) \). Therefore, w.h.p. \( G \) is connected.

5. A sharp threshold

Theorems 4 and 7 show that if \( n = n(k) \leq e^{k/0.5139} \) then \( \lim_{k \to \infty} P(G_{n,k} \text{ is connected}) = 1 \), and that if \( n = n(k) \geq e^{k/0.3043} \) then \( \lim_{k \to \infty} P(G_{n,k} \text{ is connected}) = 0 \). The authors have no doubt that there is a constant \( c, 1/0.5139 < c < 1/0.3043 \), such that if \( \varepsilon > 0 \), then, for \( n = n(k) \leq e^{(c-\varepsilon)k} \), we have \( \lim_{k \to \infty} P(G_{n,k} \text{ is connected}) = 1 \) and, for \( n = n(k) \geq e^{(c+\varepsilon)k} \), we have \( \lim_{k \to \infty} P(G_{n,k} \text{ is connected}) = 0 \). Although the authors cannot show the existence of this constant \( c \), let alone determine it, in this brief section we will show that the transition from connectedness to disconnectedness is considerably sharper than these relations indicate: the length of the window is \( O(n) \) rather than \( n^{1+o(1)} \). To formulate this result, for \( k \geq 1 \) and \( 0 < p < 1 \), we set
\[
n_k(p) = \max\{n: P(G_{n,k} \text{ is connected}) \geq p\}.
\]

**Theorem 9.** Let \( 0 < \varepsilon < 1 \) be fixed. Then, for sufficiently large \( k \),
\[
n_k(\varepsilon) \leq C(\varepsilon)(n_k(1-\varepsilon) + 1),
\]
where
\[
C(\varepsilon) = [(6/\varepsilon) \log(1/\varepsilon) + 1]^2.
\]

**Proof.** Write \( M = [(6/\varepsilon) \log(1/\varepsilon) + 1] \) and \( N = n_k(1-\varepsilon) + 1 \), so that the probability that we have at least two components in \( G_{N,k} \) is at least \( \varepsilon \). By Theorems 4 and 7, we may assume, by taking \( k \) sufficiently large, that \( 0.3043 \log N < k < 0.5139 \log N \). Therefore, by Lemma 2, we see that, w.h.p., no edge in \( G_{N,k} \) has length greater than \( R = (c_+(\log N)/\pi)^{1/2} \).
We say that a point $x \in V(G_{N,k})$ is close to a side $s$ of $S_N$ if $x$ is less than a distance $2R$ from $s$, and call a component $G'$ of $G_{N,k}$ close to $s$ if it contains points that are close to $s$. Furthermore, we say that $x \in V(G_{N,k})$ is central if it is not close to any side $s$ of $S_N$, and call a component $G'$ of $G_{N,k}$ central if it consists entirely of central points. Finally, we call a component $G'$ of $G_{N,k}$ small if it has diameter at most $c'(\log N)^{1/2}$, where $c'$ is as in Lemma 6.

By Lemma 6, with probability greater than $\frac{1}{2}\varepsilon$, $G_{N,k}$ contains a small component, which can be close to at most two sides of $S_N$. We write $\alpha$ for the probability that we have a small central component of $G_{N,k}$, $\beta$ for the probability that we have a small component of $G_{N,k}$ that is close to exactly one side of $S_N$, and $\gamma$ for the probability that we have a component of $G_{N,k}$ that is close to two sides of $S_N$ (so that it lies at a corner of $S_N$). Thus, we have $\alpha + \beta + \gamma > \frac{1}{2}\varepsilon$, and the proof of Theorem 7 shows that

$$\gamma = n^{o(1)}3^{-k} \rightarrow 0$$

as $k \rightarrow \infty$. Therefore we may assume that at least one of $\alpha$ and $\beta$ is greater than $\frac{1}{2}\varepsilon$ (although we do not know which one). If we specify one side $s$ of $S_N$, the probability that we obtain a small component $G'$ that is close only to $s$ is thus at least $\frac{1}{4}\varepsilon$.

Now we take a larger square $S_{M^2N}$, and tessellate it with copies of $S_N$. We only consider the small squares of the tessellation that are incident with the boundary of $S_{M^2N}$. In particular, considering the sides of these copies of $S_N$ lying on the boundary of $S_{M^2N}$, we see that we have $4(M-1)$ independent opportunities to obtain a small component $G'$ in one of the small squares, $S$, say, in such a way that $G'$ can only intersect the boundary of $S$ on the boundary of $S_{M^2N}$. Such a component will also be isolated in $G_{M^2N,k}$, since, w.h.p., no edge of $G_{M^2N,k}$ has length greater than $(c_+ (\log M^2N)/\pi)^{1/2} < 2R$ for sufficiently large $k$ (and, thus, $N$). Therefore, if $p$ is the probability that $G_{M^2N,k}$ is connected, we have

$$p < (1 - \frac{1}{24\varepsilon})^{6(M-1)} < e^{-(\varepsilon/6)(M-1)} < \varepsilon,$$

completing the proof.

6. Coverage

Let $\mathcal{P}_n$ be a Poisson process of intensity 1 in the square $S_n$. For any $x \in \mathcal{P}_n$, let $r(x, k)$ be the distance from $x$ to its $k$th-nearest neighbour (or infinite, if no such neighbour exists), and let $B_k(x) = D_{r(x,k)}(x) \cap S_n$. Also, let $C_k(\mathcal{P}_n) = \bigcup_{x \in \mathcal{P}_n} B_k(x)$; we say that $\mathcal{P}_n$ is a $k$-cover if $C_k(\mathcal{P}_n) = S_n$.

Before proving Theorem 3, we first prove a short lemma bounding the Poisson distribution.

Lemma 8. Suppose that $\mathcal{P}$ is a Poisson process of intensity 1 in the square $S_n$, and fix $c$ and $\varepsilon > 0$. Then, there exists $\delta > 0$ such that, w.h.p., there does not exist a point $x$ of the process with

$$r(x, \lfloor c \log n \rfloor) - r(x, \lfloor (c - \varepsilon) \log n \rfloor) < \delta \sqrt{\log n}.$$  

(6)

Proof. Let $k = \lfloor c \log n \rfloor$ and $k' = \lfloor (c - \varepsilon) \log n \rfloor$. By Lemma 2, we may assume that no edge in $G_{n,k}$ is longer than $R = c_m (\log n)^{1/2}$, where $c_m = (c_+ / \pi)^{1/2}$ in our earlier notation. For a fixed point $x$, condition (6) only holds if the annulus of width $\delta (\log n)^{1/2}$ and outer diameter $r(x, k)$ contains at least $\lfloor \varepsilon \log n \rfloor - 1$ points. This annulus, $A$, say, has area at most $2\pi \delta (\log n)^{1/2} = 2\pi \delta c_m \log n$. 

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The number of points in $A$ is stochastically dominated by a Poisson distribution with mean $2\pi \delta c_m \log n$. Thus, the probability $p$ that there are more than $[\varepsilon \log n] - 1$ points in $A$ satisfies
\[
\log p \leq -2\pi \delta c_m \log n - \varepsilon \log n \log \left( \frac{\varepsilon}{e2\pi \delta c_m} \right) + O(\log \log n),
\]
which is less than $-\log n$ provided that we choose $\delta$ small enough. Hence, the probability that any point fails to satisfy (6) is $o(1)$.

**Theorem 10.** Fix $c > c' > 0$. If, w.h.p., $\tilde{G}_{n, [c' \log n]}$ does not have a vertex of in-degree 0, then (w.h.p.) $\tilde{P}_n$ is a $[c' \log n]$-cover. Conversely, suppose that, w.h.p., $\tilde{P}_n$ is not a $[c' \log n]$-cover; then (w.h.p.) $\tilde{G}_{n, [c \log n]}$ does not have a vertex of in-degree 0. Consequently, if $c \leq 0.7209$ then, w.h.p., $\tilde{P}_n$ is not a $[c \log n]$-cover while, if $c \geq 0.9967$, w.h.p. $\tilde{P}_n$ is a $[c \log n]$-cover.

**Proof.** Let $k = [c \log n]$ and $k' = [c' \log n]$. Suppose that it is not true that, w.h.p., $\tilde{P}_n$ is a $k$-cover. Then there exists $\varepsilon > 0$ such that, for infinitely many $n$, the probability that $\tilde{P}_n$ is not a $k$-cover is at least $\varepsilon$. Let $n' = n(1 + 1/\log n)$. We will show that
\[
P(\tilde{G}_{n', k'} \text{ has a vertex of in-degree 0}) \geq \varepsilon'
\]
for some $\varepsilon' > 0$.

By Lemma 8, there exists $\delta > 0$ such that, w.h.p., $r(x, k) - r(x, k') \geq \delta (\log n)^{1/2}$ for every $x \in \tilde{P}_n$. Thus,
\[
P(S_n \setminus C_k(\tilde{P}_n)) \text{ contains a ball of radius } \delta \sqrt{\log n} \geq (1 - o(1)) P(\tilde{P}_n \text{ is not a } k\text{-cover}) \geq (1 - o(1)) \varepsilon.
\]

We identify $\tilde{P}_n$ with $\tilde{P}_n \cup \tilde{P}_n/[\log n]$, where all squares are scaled to be the same size as $S_n$. Let $R = (c_{1+}(\log n)/\pi)^{1/2} = c_m(\log n)^{1/2}$ be as in Lemma 2, fix $\tilde{P}_n$ such that $\tilde{G}_{n, k}$ has no edge of length more than $R$, and that $C_k(\tilde{P}_n)^c$ contains a disc of radius $\delta (\log n)^{1/2}$, and let $y$ be the centre of such a disc. The probability that the disc $D_{\delta (\log n)^{1/2}}(y)$ contains exactly one point of $\tilde{P}_n/[\log n]$ is a constant independent of $n$, as is the probability that the disc $D_{\omega_{1+}(\log n)^{1/2}}(y)$ contains no other point of $\tilde{P}_n/[\log n]$. Hence, there exists $\varepsilon_1 > 0$ such that
\[
P(\tilde{G}_{n', k'} \text{ has a vertex of in-degree 0} \mid \tilde{P}_n) \geq \varepsilon_1,
\]
since this event occurs provided that both the previous events do. Combining these facts, we see that
\[
P(\tilde{G}_{n', k'} \text{ has a vertex of in-degree 0}) \geq (1 - o(1)) \varepsilon \varepsilon_1,
\]
as claimed.

Conversely, suppose that it is false that, w.h.p., $\tilde{G}_{n, k}$ does not have a vertex of in-degree 0. As before, this implies that there exists an $\varepsilon > 0$ such that, for infinitely many $n$, the probability that $\tilde{G}_{n, k}$ has a vertex of in-degree 0 is at least $\varepsilon$.

Let $R$ be as in Lemma 2, and fix a configuration $\tilde{P}_n$ with a point $y$ of zero in-degree, no edge-length longer than $R$, and no vertex with more than $c_1 \log n$ neighbouring points within a distance $2R$. The first condition occurs with probability at least $\varepsilon$ and the second condition fails with probability tending to 0, as does the final one, provided that $c_1$ is large enough. (To verify this last assertion, set $c_0 = 4c_{1+}/c_{1-}$ and apply Lemma 2 with $n$ replaced with $n/c_0$. Then no vertex of $S_n \cap \tilde{P}$ contains more than $[c \log n^{1/2}] \leq c c_0 \log n$ neighbouring points within the disc $D_{\delta (\log n)^{1/2}}(y)$.)
a disc of area \( c \log n^w = \pi(2R)^2 \). Now fix \( \delta > 0 \) and let \( n' = (1 - \delta)n \). As before, we identify \( \mathcal{P}_n \) with \( \mathcal{P}_{n'} \cup \mathcal{P}_{\delta n} \) (both scaled to be the same size \( S_n \)) by independently assigning each vertex of \( \mathcal{P}_n \) to \( \mathcal{P}_{\delta n} \) with probability \( \delta \). Then

\[
P(\mathcal{P}_{n'} \text{ is not a } k' \text{-cover } | \mathcal{P}_n) \geq \varepsilon',
\]

since this event occurs under the conditions that, firstly, the point \( y \) is in \( \mathcal{P}_{\delta n} \) and, secondly, no disc of radius \( R \), containing \( y \), contains more than \( k - k' \geq (c - c') \log n - 1 \) points of \( \mathcal{P}_{\delta n} \). The number of points in \( D_{2R}(y) \) is at most \( c_1 \log n \), so the number of points in \( D_{2R}(y) \cap \mathcal{P}_{\delta n} \) is stochastically dominated by the distribution \( \text{Binomial}([c_1 \log n], \delta) \). Thus, with probability at least \( \frac{1}{2} \), \( D_{2R}(y) \) contains at most \( c_1 \delta \log n \) points of \( \mathcal{P}_{\delta n} \). Hence, provided that \( c - c' > c_1 \delta \), the second condition is satisfied with probability at least \( \frac{1}{2} \), for large enough \( n \). The first condition is independent of the second, and occurs with probability \( \delta \). Combining these, we see that

\[
P(\mathcal{P}_{n'} \text{ is not a } k' \text{-cover}) \geq \frac{1}{2}(1 - o(1))\delta \varepsilon'.
\]

7. Numerical results

Computer simulations suggest that, for \( k \geq 3 \), there exists a giant component in \( G_{n,k} \), which contains almost all of the vertices (over 98.5\% of them, for \( k = 3 \)) with a few small isolated components. On the other hand, for \( k \leq 2 \), all components are small. As we are interested mainly in large \( k \), we have confined our numerical results to \( k \geq 3 \), since these are more likely to reflect the situation in which \( k \) is large.

For \( k \geq 3 \), the small components are relatively sparse (more so for larger \( k \)). As a result, we would expect that, for a large rectangular region \( A \), the small components are roughly Poisson distributed with constant density throughout the area \( A \), with perhaps a somewhat different density near the sides and corners of \( A \). Hence, we would expect the average number of small components in \( A \) to be approximately Poisson distributed with mean \( \alpha_k |A| + \beta_k |\partial A| + 4\gamma_k \), where \( \alpha_k \) represents the density of components far from the boundary of \( A \), \( \beta_k \) gives a correction for ‘edge effects’, and \( \gamma_k \) gives a correction for ‘corner effects’. By considering rectangles of various sizes and aspect ratios, we can evaluate the constants \( \alpha_k, \beta_k, \) and \( \gamma_k \) numerically. To do so, computer simulations were performed on large rectangular regions for \( 3 \leq k \leq 8 \), and the numbers and sizes of the small components were recorded. The numbers of components found were fitted according to the linear formula \( \alpha_k |A| + \beta_k |\partial A| + 4\gamma_k \) and, for all \( k \) considered, this did indeed fit the data extremely well. In total, an area of over \( 10^{12} \) was simulated for each \( k \) from 3 to 8. Estimates of \( \alpha_k, \beta_k, \) and \( \gamma_k \) are given in Table 1.

| \( k \) | \(-\log \alpha_k\) | \(-\log \beta_k\) | \(-\log \gamma_k\) | \( \text{E}(|C|)\) |
|---|---|---|---|---|
Figure 6: The probability that $G_{n,k}$ is connected (solid line, left scale), the average number of components (dotted line, right scale), and theoretical predictions based on the number of components being given by $1 + \text{Poisson}(\alpha kn + 4\beta kn^{1/2} + 4\gamma k)$ (dashed line, either scale). Note that, for a given $k$, the lines are indistinguishable for $k > 5$ and sufficiently large $n$. The left-hand scale is exponentially related to the right-hand scale.

The values of $\beta_k$ and $\gamma_k$ are positive, indicating that small components are more common near the boundary and corners of $A$. In Figure 6, we plot both the probability that $G_{n,k}$ is connected and the average number of components against $n$, for $3 \leq k \leq 8$. The predictions based on the assumption that the number of components is distributed as $1 + \text{Poisson}(\alpha kn + 4\beta kn^{1/2} + 4\gamma k)$ are also given and are in excellent agreement for large $n$. We know, from Theorem 7, that $\gamma_k \to 0$; however, it also appears that $\beta_k \ll \alpha_k^{1/2}$. Hence, if $A$ is the square $S_n$ and $n$ is large enough that the $k$-nearest-neighbour model has a reasonable chance of being disconnected, the expected number of components is dominated by the term $\alpha_k n$. We would therefore expect the probability that the model is connected to be approximated very well by $\exp\{-\alpha_k n\}$, and to be fairly insensitive to the shape of the region $S_n$, provided that the boundary is reasonably smooth and not excessively long. We would also expect that, for fixed $n$, the critical value of $k$ occurs when $\alpha_k \sim 1/n$. The data suggests that this critical $k$ is between approximately $0.3 \log n$ and $0.4 \log n$ – consistent with the theoretical bounds – and closer to the lower bound.

If one believes that the lower bound construction of Theorem 4 is in fact asymptotically correct, then the sizes of the components in the interior should be geometrically distributed with minimum value $k + 1$ and ratio approximately $e^{-\mu} \approx 0.3016$, where $\mu$ is the constant found in the proof of Theorem 4. Of course, this assumes that $k$ is very large. For more modest values of $k$, the lower bound construction suggests that the density of components of size $t \geq k + 1$ should be about $\exp[-\eta k^{1/2}]$ for some constant $\eta_k$. To see this, consider a disc of area $t$ containing $t$ points, and insist that a vertex-free annulus of constant width surrounds it. If this width is large enough, the $t$ points inside the disc should form a component, and the vertex-free region is of area $O(t^{1/2})$, so this configuration has a probability of approximately $\exp[-\eta k^{1/2}]$. The component-size distribution for components near the edge of $A$ is different than that for components near the centre of $A$, so we have only considered components far from the boundary of $A$. (Numerical evidence suggests that the components near the boundary are, on average, slightly larger than components far from the boundary.) Table 2 gives the total number of components found in our simulations and the maximum size of a small component. In Figures 7 and 8, we plot the proportion of small components found against their size, first
Table 2: The number and maximum size of the small components in simulation results in an area of size \(2^{60} \approx 10^{12}\).

| \(k\) | \(n_C\) | \(\text{max } |C|\) |
|-----|-------|--------|
| 3   | 2174 360 691 | 547    |
| 4   | 113 019 084  | 106    |
| 5   | 6163 109    | 65     |
| 6   | 334 633     | 37     |
| 7   | 17 923      | 27     |
| 8   | 924         | 20     |

Figure 7: The proportion of small components that are of size \(k + x\) versus \(x\). The dashed line is the theoretical prediction for large \(k\) based on the lower bound argument. The error bars represent one standard deviation.

Figure 8: The proportion of small components that are of size \(x^{1/2}\) for \(3 \leq k \leq 6\). The error bars represent one standard deviation.

using a scale linear in the component size (in Figure 7) and, second, using a scale proportional to the square root of the component size (in Figure 8). For \(k \geq 4\), the plot against \(x^{1/2}\) does indeed appear to be close to linear; however, for \(k = 3\) there appears to be some deviation from linearity. The average small component sizes for components far from the boundary, given by \(E(|C|)\), are displayed in Table 1.
8. Conjectures

We end with three extremely natural open questions that we would very much like to see answered. The first was mentioned briefly in the introduction.

Open Question 1. Is there a critical value of $c$ such that, for $c' < c$, $G_n, [c' \log n]$ is disconnected w.h.p., and, for $c' > c$, $G_n, [c' \log n]$ is connected w.h.p.? In the terminology introduced in the introduction, is it true that $c_1 = c_u$? Is it true for the directed graphs $\vec{G}_{n,k}$?

Open Question 2. For the directed graphs $\vec{G}_{n,k}$, write
\[
\tilde{c}_1 = \sup\{c : P(\vec{G}_{n,c \log n} \text{ is connected}) \rightarrow 0\}, \quad \text{and}
\]
\[
\tilde{c}_{\text{iso}} = \sup\{c : P(\vec{G}_{n,c \log n} \text{ contains a vertex with zero in-degree}) \rightarrow 1\}.
\]
Trivially, we have $\tilde{c}_1 \geq \tilde{c}_{\text{iso}}$. Is it in fact true that $\tilde{c}_1 = \tilde{c}_{\text{iso}}$?

Open Question 3. Is the threshold for connectivity of $G_{n,k}$ sharp in $k$? In other words, setting $k_d(p) = \min\{k : P(G_{n,k} \text{ is connected}) \geq p\}$, is it true that, for any $0 < \varepsilon < 1$, there exists $C(\varepsilon)$ such that $k_n(1 - \varepsilon) < C(\varepsilon) + k_n(\varepsilon)$ for all sufficiently large $n$?

‘Sharpness in $n$’ was proved in Section 5, but perhaps this is more natural.

Acknowledgements

We would like to thank Michael Lemmon and Martin Haenggi for drawing this problem to our attention.

References