

EXTENSION THEOREMS FOR SMOOTH FUNCTIONS ON REAL ANALYTIC SPACES AND QUOTIENTS BY LIE GROUPS AND SMOOTH STABILITY

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Abstract

Extension theorems are proved for smooth functions on a coherent real analytic space for which local defining functions exist which are finitely determined in the sense of J. Mather, (1968), and for smooth functions invariant under the action of a compact lie group G , thus providing the main step in the proof that smooth infinitesimal stability implies smooth stability in the appropriate categories. In addition the remaining step for the category of C^∞ G -manifolds of finite orbit type is filled in.

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1. Introduction

Propositions 1 and 2 of Mather (1969), the essential parts of J. Mather's proof that C^∞ infinitesimal stability implies C^∞ stability for a C^∞ proper map $f: N \rightarrow P$ where N and P are manifolds, will go through for a C^∞ proper map between other " C^∞ -objects" N and P which are "embedded" in R^n and R^p if there are continuous mappings (extensions) from the spaces $C^\infty(N)$ and $C^\infty(P)$ of C^∞ functions on N and P to $C^\infty(R^n)$ and $C^\infty(R^p)$ which are right inverses for the restriction maps $C^\infty(R^n) \rightarrow C^\infty(N)$ and $C^\infty(R^p) \rightarrow C^\infty(P)$ (see Mather (1969) page 283). For coherent real analytic spaces, for which everywhere locally a suitable set of defining functions can be found which have a contact finitely determined germ in the sense of Mather (see condition F below), such extensions are found (Section 5); similarly for C^∞ G manifolds of finite orbit type and their rings of G invariant C^∞ functions where G is a compact lie

group (Section 6) — the “embedding” here is a G invariant map into a Euclidean space with trivial G action. The remaining condition needed to complete the proof that C^∞ infinitesimal stability implies C^∞ stability for a proper G invariant C^∞ map between C^∞ G manifolds of finite orbit type, namely that the spaces of C^∞ G invariant vector fields on the manifolds and “along f ” be finitely generated over the appropriate rings of G invariant smooth functions, follows easily from Hilbert’s invariant theory and Schwarz (1975) (Section 7).

Proofs in Sections 4 and 5 depend heavily on results from Malgrange’s book, *Ideals of Differentiable Functions*, and the approach in Section 6 follows Schwarz. In Section 2 results needed on the local structure of real analytic sets are quoted, in Section 3 the “finitely determined” condition F for a real analytic set X is introduced and a proof given that a certain semi-analytic local stratification of X is “homogeneous” and in Section 4 an extension theorem is proved for the C^∞ Taylor fields on a real analytic set to be used in Section 5.

NOTATION. $E(A)$ = space of Taylor fields on $A \subset \mathbb{R}^n$. $I(B, A)$ = subspace of $E(A)$ consisting of those fields which vanish to infinite order on $B \subset A$. $C(A)$ = space of smooth ($\equiv C^\infty$) functions on A . All are given the Whitney C^∞ topology based on compact supports.

If G is a group acting on (A, B) then a G -suffix will denote the subspace consisting of G invariant elements, for example $E_G(A)$ = space of G invariant Taylor fields on $A \subset \mathbb{R}^n$ when the group G acts on \mathbb{R}^n and $G(A) = A$. $I(\phi, A) = E(A)$; $C(\mathbb{R}^n) = E(\mathbb{R}^n) \rightarrow E(A)$, the restriction is onto; $C(A) = C(\mathbb{R}^n)/(S(A))$, where $S(A)$ is the ideal in $C(\mathbb{R}^n)$ of functions vanishing on A .

2. Local analytic sets

Let X be an analytic subset of \mathbb{R}^n , that is, X is closed and at each point x of X there is a neighbourhood U and an analytic function $f: U \rightarrow \mathbb{R}^p$ such that $X \cap U = f^{-1}(0)$. Then by the local parametrization theorem (see Malgrange (1966) in particular pages 51–53 and 57–59) for analytic sets for a suitable neighbourhood V of $x = 0$ in X , $X \cap V = \bigcup_{i=1}^r X_i$ where the X_i are closed subsets and $X'_i = X_i - D_i$, where $D_i = \bigcup_{j < i} (X_i \cap X_j)$, is open in X_i and a non-singular locally closed analytic submanifold of V such that

- (1) $X'_i = \{x = (x', \phi_i(x'))\}; x' \in U_i\}$ for a suitable product neighbourhood of 0 of the form $V'_i \times V''_i$ where V'_i and V''_i are neighbourhoods of 0 in $k(i)$ and $l(i)$ dimensional euclidean spaces respectively and a function $\phi_i: U_i \rightarrow V''_i$ where U_i is an open set in V'_i whose boundary is

contained in $\delta_i = \Delta_i^{-1}(0)$ for a suitable analytic $\Delta_i: V'_i \rightarrow R$. $0 \in \delta_i$ and $D_i \subseteq \delta_i \times V''_i$. The coordinate functions of ϕ_i are quasi-holderian and together with all their derivatives are multipliers for $I(V'_i - U_i, V'_i)$.

- (2) For a positive integer m if

$$Q_i = \{(x', x''); x' \in U_i, \|x'' - \phi_i(x')\| < d(x', \delta_i)^m\}$$

then Q_i and Q_j intersect for $i > j$ only if $D_i \cap X'_j \neq \emptyset$. X'_i is contained in an analytic subset of X of dimension $k(i)$ which intersects Q_i in X'_i and in which it is a "sheet".

- (3) There are $C > 0$ and $\alpha > 0$ such that $|\Delta_i(x')| \geq Cd(x', \delta_i)^\alpha$ for $x' \in V'_i$. Multiplication by Δ_i gives a homeomorphism of $I(V'_i - U_i, V'_i)$.
- (4) There are $B > 0$, $\beta > 0$ such that $d(x', \delta_i) \geq Bd(x, D_i)^\beta$ for $x = (x', x'') \in X \cap V$. It can also be assumed that each U_i is connected.

Let X be now a (closed) semianalytic subset of R^n , that is, X is closed and at each point of R^n there is a neighbourhood U such that $X \cap U$ is the union of finitely many sets each of which is given by finitely many analytic equations and inequalities. From Mather (1973), for example, (where a finer Whitney stratification is obtained) the above parametrisation result also holds in the semianalytic case. In what follows we are concerned only with the germ of X at x so that V will be variable.

3. Condition F

Following Mather, $L^N(n)$ denotes the group under composition of N -jets at 0 of diffeomorphisms of $(R^n, 0)$ and the contact group $K^n(n, p)$ is the group under composition of N -jets at 0 of diffeomorphisms H of $(R^n \times R^p, 0)$ of the form $H(x, y) = (h(x), h'(y))$ with $h'_i(0) = 0$ and $h(0) = 0$. Suppose that at the point $x \in X$, where X is an analytic subset of R^n , the function f can be chosen such that

- (a) f is analytically contact finitely determined (see Mather (1968)), that is, there is $N_1 > 0$ such that each local analytic vector field along f at x vanishing to order N_1 at x is of the form $tf(\alpha) + f^*(m)\theta$ where α is a local analytic vector field vanishing at x in R^n , tf is given by right composition with the derivative of f , m is a local analytic function in R^p vanishing at the origin and θ is a local analytic vector field along f ,
- (b) if $f^{(N)}: V \rightarrow J^N(n, p)$ is the N -jet of f then for V sufficiently small

$f^{(N)}(V)$ is contained in a neighbourhood of $f^{(N)}(x)$ which meets only finitely many orbits of the contact group $K^N(n, p)$, for an $N \geq N_1$.

(a) and (b) together make up the condition F on X at x . We can also assume that at points of V the germs of f are ($\cong N_1$) contact finitely determined as this condition is an open one. In the “nice” range of dimensions (Mather (1970)), which includes $p < 7, n \geq p + 3$, almost all maps f satisfy condition F but in general the orbit structure of $J^N(n, p)$ is infinite over a subset of codimension $< n$ (Mather (1973)). The orbits are non-closed semi-algebraic and their closures semi-algebraic so that the inverse images of the orbits under $f^{(N)}$ give a semi-analytic stratification of V , that is, $V = \bigcup_{i=1}^l V_i$ with the V_i having properties like the X_i in Section 2 and each V_i mapping to a single orbit in $J^N(n, p)$. By intersecting this stratification with that for X we may suppose that each X'_i (in the notation of 2) maps to a single orbit (and f is ($\cong N_1$) determined at all points of $X \cap V$).

Let $W = X'_i, \phi = \phi_i, t = x', k = k(i)$ and take $z \in W$ with coordinates translated to make $z = 0$. Let B^k be a disk in $U = U_i$ and let $i: B^k \rightarrow W$, where $i(t) = (x', \phi(x'))$ in previous notation, $i(0) = 0$. As $f^{(N)}$ maps W to a single $K^N(n, p)$ orbit, by choosing an analytic section of the map from $K^N(n, p)$ to the orbit (and taking B^k sufficiently small), there is an analytic $B^k \rightarrow K^N(n, p), t \rightarrow k_t = (h_t, h'_{t,x})$, where $h_t \in L^N(n), h'_{t,x} \in L^N(p), t \in B^k$ and x is near 0 in R^n , such that

$$(A) \quad f^{(N)}(i(t)) = k_t(f^{(N)}(0)) [= h'_{t,x}(f^{(N)}(0)(z)) \text{ at } x, \text{ where } z = h_t^{-1}(x)].$$

Let C denote the set of analytic local maps from R^n to R^p sending 0 to 0 and let $g_t \in C$ be given by $g_t = k_t(f)$, where we identify elements of L^N in terms of the chosen coordinates with polynomial mappings of degree N . Let $B^k \times I \rightarrow C, (t, u) \rightarrow f_{t,u}$ be given by

$$f_{t,u}(x) = (1 - u)f(x + i(t)) + ug_t(x).$$

$g_t(x)$ and $f(x + i(t))$ have the same N -jets (and $N \geq N_1$) so that the vector field $g_t(x) - f(x + i(t))$ along $f_{t,u}$ for varying $(t, u) \in B^k \times I$ (obtained by differentiating $f_{t,u}$ with respect to u) is in the image of $(\tau f_{t,u}, \eta f_{t,u})$ where η denotes the map $M \times \theta \rightarrow \theta$, where M is the ideal of local analytic R^p functions vanishing at 0 and θ denotes the set of local analytic vector fields along f , given by $(m, \phi) \rightarrow f^*(m)\phi$ for $m \in M, \phi \in \theta$. Integrating the chosen vector fields, which can be supposed to depend analytically on (t, u) (see Mather (1968)) gives, for B^k sufficiently small, analytic local diffeomorphisms $H_{t,x}$ of R^p at 0 and G_t of R^n at 0 depending analytically on $t \in B^k, x \in R^n$ near 0 such that

$$H_{i,w}(f_{i,0}(w)) = f_{i,1}(x), \quad \text{where } w = G_i^{-1}(x).$$

From (A) it follows that if $f^{(t)}$ denotes the germ of f near $i(t)$ then

$$f^{(t)}(x) = J_{i,w}(f^{(0)}(w)), \quad \text{where } w = K_i^{-1}(x),$$

for K_i and $J_{i,x}$ locally defined analytic diffeomorphisms of R^n and R^p respectively, depending analytically on t and x , where K_i maps 0 to $i(t)$ and $J_{i,x}$ fixes 0 . In particular K_i maps $f^{-1}(0)$ into itself.

Let Q' be a tubular neighbourhood of $W|_i(B_1^k)$, where $B_1^k \subset B^k$ is a smaller ball, with transverse cells in the V'' direction. By choosing the transverse cells Q'_i suitably and sufficiently small it can be supposed that the map $L_i: Q'_0 \rightarrow Q'_i$ sending x'' to the point where $\bigcup_i K_i(x'')$ intersects Q'_i is an analytic diffeomorphism and so

PROPOSITION 1. $L: B_1^k \times Q'_0 \rightarrow Q'$, where $L(t, x'') = L_i(x'')$, is an analytic diffeomorphism with $L(B_1^k \times (Q'_0 \cap X)) = Q' \cap X$.

(That is the transverse germ of X along $W = X'_i$ is locally trivial or, in other words, the stratification is homogeneous.) Using the product structure functions in Q'_0 vanishing in $Q'_0 \cap X$ may be extended to functions vanishing on X in some neighbourhood (this is used in Section 5).

4. Extension for $E(X)$

In this section X denotes a closed semi-analytic set; the notation of Section 2 is used except that suffixes are dropped so that $V' = V'_i$, etcetera. For a sufficiently large even integer N and small enough $V' \subseteq \{x'; d(x', \delta) < 1\}$ we have $0 \leq \Delta(x')^N \leq d(x', \delta)^m$, for $x' \in V'$ where m is as in Section 2(2), and by (3) of Section 2 there is $p > 0$ such that $d(x', \delta)^p \leq \Delta(x')^N$. If $g(x') = \Delta(x')^N$ then

$$d(x', \delta)^p \leq g(x') \leq d(x', \delta)^m \quad \text{for } x' \in V'.$$

Multiplication by any power of g gives homeomorphisms of $I(V' - U, V')$, $I(\delta, Z)$, where $Z = U \cup \delta$, and of $I(D, Y)$, where $Y = W \cup D$ (see Malgrange (1966), chapter 4).

In terms of the coordinates (x', x'') elements of $I(D, Y)$ are the form $F = \{f^\lambda; \lambda \in N^n = N^k \times N^l\}$ (where N is the natural numbers) and each $f^\lambda(x)$ tends to 0 as x in Y tends to D faster than any positive power of $d(x, D)$. Malgrange (1966, page 64) defines a continuous (and obviously injective) map $\pi: I(D, Y) \rightarrow I_l(\delta, Z)$, where $I_l(\delta, Z)$ denotes the N^l -fold cartesian power of $I(\delta, Z)$, by $\{f^\lambda; \lambda \in N^n\} \rightarrow \{h^\mu(x') = f^{0 \times \mu}(x', \phi(x'')); \mu \in N^l\}$. [Notice that

$0 \times \mu \in 0 \times N^l \subset N^k \times N^l = N^n$; (1) and (4) of Section 2 are used in showing that π is well defined and continuous].

Let

$$M = \{(x', x''); \|x''\| < g(x'), x' \in U\} \subset V' \times R^l.$$

$$\pi': I(\delta \times 0; V' \times 0) \rightarrow I_l(\delta, Z),$$

where $V' \times 0 \subset V' \times R^l$, is defined similarly to π and is obviously continuous. Since the components of ϕ and their derivatives are multipliers for $I(\delta, Z)$ the map $I(V' \times R^l - M, V' \times R^l) \rightarrow I(V - Q, V)$ induced by $(x', x'') \rightarrow (x', x'' - \phi(x'))$ is continuous and so in order to construct a continuous "extension" $E: I(D, Y) \rightarrow I(V - Q, V)$ such that E composed with the restriction $I(V - Q, V) \rightarrow I(D, Y)$ is the identity it is sufficient to construct a continuous $E: I_l(\delta, Z) \rightarrow I(V' \times R^l - M, V' \times R^l)$ which when composed with the restriction to $I(\delta \times 0, Z \times 0)$ followed by π' gives the identity.

PROPOSITION 2. $\pi: I(D, Y) \rightarrow I_l(\delta, Z)$ is a homeomorphism and there is a continuous $E: I(D, Y) \rightarrow I(V - Q, V)$ such that the restriction map $E(V) \rightarrow I(D, Y)$ is a left inverse for jE , where j is the inclusion $I(V - Q, V) \subseteq E(V)$.

PROOF. Malgrange (1966, page 65) shows that π is onto: the method is easily refined to give a continuous inverse. Put $x = x', y = x''$ for convenience. Let $B(r)$ be a smooth non-negative function $R \rightarrow R$ identically one in a neighbourhood of 0 and identically zero for $r \geq 1$ and let $S(r)$ be a smooth monotone function defined on the nonnegative real line into R such that $S(r) \leq \min(1/r, 1)$ for all r , $= 1$ for $r \leq 1/2$ and $= 1/r$ for $r \geq 2$. If $A = \{a_\mu(x); \mu \in N^l\} \in I_l(\delta, Z)$ the function $E(A)$ will be constructed of the form

$$\sum_{m=0}^{\infty} B\left(\frac{\|y\|}{g(x)\alpha_m(x)}\right) \left(\sum_{|\mu|=m} a_\mu(x)y^\mu\right) = \sum_{m=0}^{\infty} G_m,$$

say, for suitable smooth $\alpha_m(x)$, $0 < \alpha_m(x) \leq 1$, chosen to depend on $\{a_\mu(x); |\mu| = m\}$.

We can suppose that V' is compact in order to avoid taking k -norms with respect to varying compact sets. Evaluating a derivative of G_m of order n gives an expression which is a linear combination with integer coefficients of products of derivatives of orders $\leq n$ of the a_μ (with $|\mu| = m$), $g\alpha_m$ and B with y^λ and negative powers of $g\alpha_m$ (the highest negative power being $-2n$), and if $n \leq m - 1$ then

$$\|G_m\|_{(x,y),n} \leq CL(\alpha_m)H(a_\mu)\|y\|^{m-n}, \quad \text{for } \|y\| < g(x)\alpha_m(x)$$

$$\text{and } = 0 \quad \text{for } \|y\| \geq g(x)\alpha_m(x)$$

where C is a constant independent of n and A , $H(a_\mu) = \sum_{|\mu|=m} \|a_\mu\|_{x,m}$, and $L(\alpha_m) = \sum_{i=0}^{m-1} \|\alpha_m\|_m^i$. If $\alpha'_m(x) = S(m 2^m CH(a_\mu))$ then

$$CH(a_\mu) \|y\|^{m-n} < \frac{2^{-m}}{m} \quad \text{for } \|y\| < g(x)\alpha'_m(x), \text{ and } 0 \text{ otherwise.}$$

If $\alpha_m(x) = \alpha'_m(x)/L(\alpha'_m)$ then $\alpha_m(x) < \alpha'_m(x)$ and $L(\alpha_m) < m$ (as $\|\alpha_m\|_m \leq 1$) so that

$$\begin{aligned} \|G_m\|_{m-1} &< 2^{-m} \quad \text{for } \|y\| < g(x)\alpha_m(x) \\ &= 0 \quad \text{otherwise.} \end{aligned}$$

Hence $E(A)$ converges to a smooth function on $V' \times R^l$. $E(A)$ depends continuously on $A \in E(Z)^{N^l}$. Since each $a_\mu(x) \in I_l(\delta, Z)$ and g^{-1} is a multiplier for $I_l(\delta, Z)$, any derivative of each partial sum $\sum_{m \leq M} G_m$ tends to zero faster than any power of $d(x, \delta)$ as x approaches δ . Note that the method, when A is in $E(Z)^{N^l}$ and not necessarily in $I_l(\delta, Z)$ (for example A a constant function), will give $E(A)$ not necessarily smooth along δ but at least a multiplier for $I_l(\delta, Z)$.

An extension $E: E(V \cap X) \rightarrow E(V)$ which is a right inverse for the restriction can be constructed inductively over $Y_k = \bigcup_{i \leq k} X_i$, $k = 1, \dots, s$ (in the notation of §2) in the obvious way: if E_{k-1} is an extension for $E(Y_{k-1})$, E is the extension constructed above for $I(Y_{k-1}, Y_k)$ and $g \in E(Y_k)$ then put $E_k(g) = E(g - r''E_{k-1}r'(g)) + E_{k-1}(r'(g))$ where r' is the restriction $E(Y_k) \rightarrow E(Y_{k-1})$ and r'' is the restriction $E(V) \rightarrow E(Y_k)$.

PROPOSITION 3. *There is a continuous $E: E(V \cap X) \rightarrow E(V)$ such that $r \circ E = 1$ where r is the restriction $E(V) \rightarrow E(V \cap X)$.*

COROLLARY. *If \tilde{X} is a semi-analytic subset of the set X , $x \in X$ and V is a suitably chosen neighbourhood of x then there is an extension $E: I(V \cap \tilde{X}, V \cap X) \rightarrow I(V \cap \tilde{X}, V)$.*

PROOF. A local decomposition as in Section 2 can be made with $X_1 = \tilde{X} \cap V$ and then the above method gives the result.

Now by choosing a locally finite partition of unity on X with supports in sets of the form $V \cap X$ as above and ‘‘piecing together’’ in the usual way gives, since the topology is based on compact supports:

THEOREM 1. *If $X \supset \tilde{X}$ are closed semi-analytic subsets of R^n then there is a continuous $E: I(\tilde{X}, X) \rightarrow I(\tilde{X}, R^n)$ which is a right inverse for the restriction $I(\tilde{X}, R^n) \rightarrow I(\tilde{X}, X)$.*

5. Extension for $C(X)$; X coherent of type F

Suppose now that X satisfies condition F on V and is also coherent on V . (Coherence means that there are analytic functions on V vanishing on X whose germs at each point of $X \cap V$ generate the ideal of local analytic functions vanishing on X .) Let W be as in Section 3 and $\pi: E(W) \rightarrow E(U)^{n'}$ as in Section 4. If G in $E(W)$ has x'' -component G'' then $\pi(G) = T^*(G'')$ where $T(x', x'') = (x', x'' + \phi(x'))$ for $(x', x'') \in U \times V''$. G'' can be regarded as a collection of elements of $R_{x'}$, the power series ring in $x'' - \phi(x')$, for $x' \in U$: under T^* it is possible to identify $R_{x'}$ with the power series ring in x'' . $R_{x'} = \prod_{m=0}^{\infty} R_{m,x'}$ where $R_{m,x'}$ is the homogeneous part of degree m of $R_{x'}$.

We let $S_{x'} \subset R_{x'}$ denote the formal local ideal of power series vanishing on $X \cap (x' \times V'')$ at $(x', \phi(x'))$; $S_{x'}$ is the completion of the local ideal of smooth functions vanishing on $X \cap (x' \times V'')$ at $(x', \phi(x'))$ with respect to the local ring at $(x', \phi(x'))$ of smooth functions on $x' \times V''$. We let $S \subset I = I_r(\delta, Z)$ be the subspace of smooth functions vanishing on X and $I_m = \{g^\mu(x') \in I; g^\mu = 0 \text{ unless } |\mu| = m\}$, so that $I = \prod_{m=0}^{\infty} I_m$. By Malgrange (1966, Chapter 6) and Proposition 1,

$$S = \{g^\mu(x') \in I; g^\mu(x') \in S_{x'} \text{ for all } x' \in U\}.$$

Further denote by $S_{m,x'}$ the image of $S_{x'} \cap \prod_{p \geq m} R_{p,x'}$ in $R_{m,x'}$ under the quotient map

$$\prod_{p \geq m} R_{p,x'} \rightarrow \left(\prod_{p \geq m} R_{p,x'} \right) / \left(\prod_{p \geq m+1} R_{p,x'} \right) \approx R_{m,x'}, \text{ for } x' \in U, m \in \mathbb{N}$$

and let

$$S_m = \{g^\mu(x') \in I_m; g^\mu(x') \in S_{m,x'} \text{ for } |\mu| = m \text{ and } x' \in U\}.$$

The usual Euclidean product on R^l induces an inner product on the symmetric powers of R^l , and hence on $R_{m,x'}$ which is naturally isomorphic to the m -th symmetric power and we let

$$T_m = \{g^\mu(x') \in I_m; g^\mu(x') \text{ belongs to the orthogonal complement in } R_{m,x'} \text{ of } S_{m,x'} \text{ for } x' \in U\}.$$

The dimension of $S_{m,x'}$ is independent of $x' \in U$ by Proposition 1.

PROPOSITION 4. $I_m \rightarrow S_m \times T_m$, given by orthogonal projection, is a homeomorphism.

PROOF. For a function α on V we denote by $\alpha^{(m)}(x)$ the $m - x''$ -jet of α at $x \in V$. We may assume that U is connected since for a suitable choice of V

it has only finitely many components (Malgrange (1966)) and we need to show that orthogonal projection into S_m is continuous.

By coherence, given $x' \in U$ there are $n_m = \sum_{p \leq m} \dim S_{p,x'}$ analytic functions defined on V and vanishing on X such that their $m - x''$ -jets at $(x', \phi(x'))$ together span $\prod_{p \leq m} S_{p,x'}$ and by suitably choosing a collection A of n_m monomials of degrees less than or equal to m in the x'' it can be supposed that their A -components are independent at $(x', \phi(x'))$. The set of points in V where their A -components are dependent is of course an analytic subset of V and the intersection of this set with W is of dimension $< k$. Hence, by the descending chain condition for analytic germs, there are sets of analytic functions on V $\{\phi_{ij}, \psi_{ik}; j = 1, \dots, n_{m-1}, k = 1, \dots, n_m - n_{m-1}\}$ for i in a finite indexing set K , and collections A_i and $B_i, i \in K$, of n_m (respectively $n_m - n_{m-1}$) monomials in the x'' of degrees $\leq m - 1$ (respectively m) such that $\bigcap_{i \in K} (W \cap Y_i) = \phi$, where $Y_i = Y_{i,1} \cup Y_{i,2}$ and

$$Y_{i,1} = \{x \in V; \text{the } A_i\text{-components of the } \phi_{ij}^{(m)}(x), \\ j = 1, \dots, n_{m-1}, \text{ are dependent}\}$$

$$Y_{i,2} = \{x \in V; \text{the } (A_i \cup B_i)\text{-components of the } \phi_{ij}^{(m)}(x) \text{ and } \psi_{ik}^{(m)}(x), \\ j = 1, \dots, n_{m-1}, k = 1, \dots, n_m - n_{m-1}, \text{ are dependent}\}.$$

If the determinants of the matrices composed of the A_i (respectively $A_i \cup B_i$) components of the $\phi_{ij}^{(m)}(x)$ (respectively $\phi_{ij}^{(m)}(x)$ and $\psi_{ik}^{(m)}(x)$) are $\gamma_i(x)$ (respectively $\nu_i(x)$) for $x \in V$ then $Y_{i,1} = \gamma_i^{-1}(0)$ and $Y_{i,2} = \nu_i^{-1}(0)$.

Let $Y = \bigcap_i Y_i, D' = \delta \times V''$ and let $\pi: V' \times V'' \rightarrow V'$ denote the projection. If $H, J \subseteq V$ and p is a positive integer let $S(H, J, p) = \{x \in V; d(x, H) < d(x, J)^p\}$. By the separation property of the $Y_i \cup D'$ relative to their intersection $Y \cup D'$ and similarly for $Y \cup D'$ and $W \cup D'$ there are p' and p such that

$$(5.1) \quad \bigcap_i S(Y_i \cup D', Y \cup D', p') = \phi \\ = S(Y \cup D', D', p) \cap S(W \cup D', D', p).$$

On $\sim Y_i$ given $h(x) \in E(V)$ there are unique $h'_{ii}(x)$ such that $h^{(m)}(x) - \sum h'_{ii}(x) \phi_{ii}^{(m)}(x)$, where $h^{(m)}(x)$ denotes the $m - x''$ -jet of $h(x)$ at x , has A_i -component zero and each $\gamma_i h'_{ii}$ has an everywhere analytic extension to V . In particular for $h = \psi_{ij}$ denote the corresponding h'_{ii} by μ_{ij} . The $\mu_{ij}(x)$ are multipliers for $I(D', V)$ outside $S(Y \cup D', D', p)$ and $S(Y_i \cup D', Y \cup D', p')$ (see Malgrange (1966) page 59). Let

$$\beta_{ij}(x) = \psi_{ij}^{(m)}(x) - \sum_i \lambda_{ij}(x') \phi_{ii}^{(m)}(x), \quad \text{where } \lambda_{ij}(x') = \mu_{ij}(x', \phi(x')).$$

λ_{ij} is a multiplier for $I(\delta, Z)$ by (5.1) on $\sim U_i$ where $U_i = \pi(S(Y_i \cup D', Y \cup D', p) \cap W)$. If $\alpha_{ij}(x') = \beta_{ij}(x', \phi(x'))$ then $\{\alpha_{ij}(x'); j = 1, \dots\}$ spans $S_{m,x'}$ at each point $x' \in \sim U_i$. The $\alpha_{ij}(x')$ are also multipliers on $\sim U_i$ for $I(\delta, Z)$. When the standard monomial generators of degree m (that is fields $\{g^\mu\}$ such that $g^\mu(x') = 0$ except for one λ of degree m and $g^\lambda(x') = 1$) are projected orthogonally onto S_m and the answer expressed in terms of the α_{ij} the coefficients are multipliers for $I(\delta, Z)$ on $U - U_i$. As $\bigcup_i (U - U_i) = U$ orthogonal projection of I_m to S_m is continuous.

COROLLARY 1. I is homeomorphic to $S \oplus T$ where $T = \prod_{m=0}^\infty T_m$.

PROOF. S is a closed subspace of I (by Malgrange's result) and obviously T is also. $\sigma_m : I \rightarrow T_m$ is defined inductively such that $\tau_m(x) = [(\sigma_0, \dots, \sigma_m)(x) - x]$ is in S modulo $\prod_{p>m} I_p$. If $z = (\tau_m(x) - y)$ belongs to $\prod_{p>m} I_p$ for some y in S then $\sigma_{m+1}(x)$ is the projection of z modulo $\prod_{p>m+1} I_p$ into T_{m+1} . $\sigma = (\sigma_0, \sigma_1, \dots) : I \rightarrow T$ is continuous and $(\sigma(x) - x)$ belongs to S by Malgrange's result.

COROLLARY 2. There is a continuous map $E' : S \rightarrow I(V - Q, V) \cap J$ which is a right inverse for the restriction, where J denotes the ideal of C^∞ functions vanishing on X .

PROOF. By the note to Proposition 2 there are functions χ'_i on V with values between 0 and 1 satisfying (in the notation of Proposition 4)

$$\begin{aligned} \chi'_i(x) &= 1 \quad \text{on } S(Y_i \cup D', Y \cup D', q) \\ &= 0 \quad \text{outside } S(Y_i \cup D', Y \cup D', p') \end{aligned}$$

for some $q > p'$ and which are multipliers for $I(Y \cup D', V)$. Outside $S(Y \cup D', D', p)$ and so on $S(W \cup D', D', p)$ they are multipliers for $I(D', V)$. Let $\{\chi_i\}$ be the partition of unity on $V - (Y \cup D')$ corresponding to the set $\{1 - \chi'_i\}$.

From the proof of Proposition 4 the derivatives of $\beta_{ij}(x)$ of order $n = 0, 1, \dots, m - 1$, are bounded by an expression of the form

$$\|x'' - \phi(x')\|^{m-n} d(x, D')^{-N(m)} \text{ on } V'' \times (U - V_i), \quad \text{where}$$

$$(5.2) \quad \begin{aligned} V_i &= \pi(S(Y_i \cup D', Y \cup D', q) \cap W), \\ \text{and if } n \geq m &\text{ by } d(x, D')^{-N(n)} \text{ for suitable integers } N(n). \end{aligned}$$

Let f be in $S \cap \prod_{p \geq m} I_m$ (that is an x'' -Taylor field on W vanishing to order $m - 1$, formally vanishing on the germ of X along W and flat along D') and with support in $\sim V_i$. Then there are unique $f_j(x') \in I(\delta, Z)$ vanishing outside V_i such that $f - \sum_j \alpha_{ij} f_j$ vanishes to order m . In the notation of the proof of

Proposition 2 ($x = x', y = x''$ etcetera) by (5.2), since on Z , $d(x', \delta)^{-1}$ is maximized by some power of g^{-1} which is a multiplier for $I(\delta, Z)$, $\alpha_m(x)$ can again be chosen to depend continuously on the f_j such that

$$G_m(x, y) = \sum_j B \left(\frac{\|y\|}{g(x)\alpha_m(x)} \right) \beta_{ij}(x, y + \phi(x))f_j(x)$$

satisfies $\|G_m\|_{m-1} < 1/2^m |K|$. Generally, when f has unrestricted support, $f(x')$ can be expressed as a sum $\sum_i \chi_i(x', \phi(x'))f(x')$, and then G_m can be found for the i -th function in the sum and summing gives G_m for f satisfying $\|G_m\|_{m-1} < 1/2^m$. $G_m(x', x'' - \phi(x'))$ is in J . Finally if h is in S then $E'(h) = \sum_{M=0}^\infty G_M$ where the G_M are defined inductively such that the Taylor field along $U \times 0$ of $h - \sum_{M < m} G_M$ is in $\Pi_{M \equiv m} I_M$. G_m is then constructed as above with $f = h - \sum_{M < m} G_M$ along $U \times 0$.

PROPOSITION 5. *There is a continuous $E: C(X \cap V) \rightarrow C(V)$ which is a right inverse for the restriction.*

PROOF. As in Proposition 3, E is constructed inductively over $Y_k = \bigcup_{i \leq k} X_i$. Suppose that $E_{k-1}: E(Y_{k-1}) \rightarrow E(V)$ is such that (a): $(r'r''E_{k-1}(g) - g)$ belongs to $S(Y_{k-1})$ for all g in $E(Y_{k-1})$, where $r'': E(V) \rightarrow E(Y_k)$ and $r': E(Y_k) \rightarrow E(Y_{k-1})$ are the restrictions and $S(Y_{k-1})$ denotes the set of restrictions to Y_{k-1} of the set J of functions vanishing on X , and (b): $E_{k-1}(g)$ depends only on g modulo $S(Y_{k-1})$. We will now find a similar E_k .

The last corollary gives (as in the proof of Proposition 3) $E': S(Y_{k-1}) \rightarrow J$, a right inverse for the restriction. Let $\pi: I(Y_{k-1}, Y_k) \rightarrow T$ be the projection given by the first corollary (where T is a complement for $S(Y_k) \cap I(Y_{k-1}, Y_k)$) and let $E: I(Y_{k-1}, Y_k) \rightarrow E(V)$ be the original extension. If g is a Taylor field on Y_k let $E_k(g) = E_{k-1}(r'(g)) + E(\pi(h - r''E'r'(h)))$, where $h = g - r''E_{k-1}r'(g)$. [Compare with Proposition 3: the "correcting" term $r''E'r'(h)$ is needed since E_{k-1} only extends $r'(g)$ modulo $S(Y_{k-1})$.]

THEOREM 2. *If X is a coherent analytic subset of R^n satisfying F everywhere there exists a continuous $E: C(X) \rightarrow C(R^n)$ which is a right inverse for the restriction.*

(There is also a relative version to Theorem 2.) [Added in revision: the assumption of coherence in Theorem 2 is not needed. The assumption of condition F can also be removed (see G. Wells (1977)), so that infinitesimal stability implies stability in general for proper smooth maps of closed real semianalytic subsets of R^m into a manifold.] Mather's proof (1969) that infinitesimal stability implies stability now goes over immediately using Theorem 2 to proper smooth mappings of X into a manifold (for further details see Wells (preprint)).

6. G invariant smooth functions

The general reference to the next few paragraphs is Schwarz (1975). Let G be a compact lie group acting orthogonally on R^n and let $\phi: R^n \rightarrow R^N$ be a polynomial map, with homogeneous polynomial coordinate functions, into a trivial G -space R^N such that $\phi^*P(R^N) = P_G(R^n)$, where $P(R^N)$ is the ring of polynomials on R^N and $P_G(R^n)$ is the ring of G invariant polynomials on R^n . The existence of ϕ is given by Hilbert's invariant theory — see Dieudonné (1970). $\phi(R^n)$ is a semialgebraic set which it will turn out has a stratification with homogeneous strata. Let H be the stabilizer at $x \in R^n$ with orbit $V = Gx$ and let W be the set of points in orbits containing points with stabilizer H ; W is a locally closed submanifold of R^n . Let E be the subspace of the tangent space at x of R^n perpendicular to V . H maps V into itself fixing x and so maps E to itself. We will identify tangent spaces at points in Euclidean space with affine subspaces in the usual way. If $E = E_1 \oplus E_2$ (orthogonal decomposition), where E_2 is a linear subspace of E fixed by H , then by taking sufficiently small (closed) balls $B_i \subset E_i$ at the origins, $i = 1, 2$, we can suppose that B_2 is a subset of $W \cap B$, where $B = B_1 \times B_2$, and $G(B)$ is a tubular neighbourhood over $G(B_2)$ with transverse cells of the form $g(B_1 \times x)$ for $g \in G$, $x \in B_2$. If E_2 is chosen as large as possible and B sufficiently small then $B_2 = W \cap B$.

As is well known G invariant functions on $G(B)$ can be identified with H invariant functions on B . By choosing B sufficiently small the restrictions ϕ'_i to $B \subset E$ of the functions ϕ_i generate the H invariant analytic functions of E restricted to B (Schwarz). Let (x_1, \dots, x_q) , respectively (y_1, \dots, y_m) , be linear coordinates on E_1 , respectively E_2 , let $\psi_1(x), \dots, \psi_p(x)$ be a minimal generating set consisting of homogeneous polynomials for $P_H(E_1)$, and let P_i , $i = 1, 2, \dots$ be monomials in the ψ_j which are homogeneous in the x such that the $P_i(\psi_j(x))$ of degree k , $k = 0, 1, 2, \dots$ form a linear basis for the space of H invariant polynomials of degree k on E_1 . $\{y_1, \dots, y_m, \psi_1, \dots, \psi_p\}$ is a minimal generating set for $P_H(E)$ and $\{y^\alpha P_i(\psi_j)$; degree $(P_i(\psi_j(x))) + |\alpha| = k\}$ is a linear basis for the homogeneous polynomials in $P_H(E)$ of degree k . The ϕ'_i can be expressed uniquely in terms of the $y^\alpha P_i(\psi)$ and hence in the form $\phi'_i(x, y) = F_i(y, \psi(x))$ where the $F_i(y, z)$, $y \in R^m$, $z \in R^p$, are polynomials and F is an embedding on $B' = B_2 \times B_3 \subseteq R^m \times R^p$ into R^N if B_2 is sufficiently small and for a choice of ball B_3 at 0 in R^p (Schwarz). Then also

$$(6.1) \quad \phi' | (\phi'')^{-1}(B') = F \circ \phi'',$$

where ϕ'' is given by $(x, y) \rightarrow (y, \psi(x))$. By choosing sufficiently small balls (and by the existence of tubular neighbourhoods) there is an embedding

$F': B_2 \times B_3 \times B_4 \rightarrow R^N$, where B_4 is a ball at 0 in R^{N-m-p} , extending $F = F'|_{B_2 \times B_3 \times 0}$ and such that $F'(B_2 \times B_3 \times B_4) \cap \phi(R^n) = F(B_2 \times B_3)$. By changing coordinates on R^p if necessary we can suppose that $\psi_i(x) = \sum x_i^2$. Let ψ_i have degree k_i and let $\alpha: R^q_+(z) \rightarrow R^p(z')$ be given by $z'_i = z_i/z_i^{k_i-1}$, where $R^q_+(z) = \{z = (z_1, \dots, z_p) \in R^q; z_1 > 0\}$. $\alpha\psi$ maps lines through the origin in R^q to lines through the origin in R^p . If $B^q \subset R^q$ is the unit ball at the origin then there are constants $A_i > 0$ $i = 1, \dots, p$ such that $|\psi_i(x)| < A_i\psi_i^{k_i}(x)$ for $x \in B^q - \{0\}$ so that $\psi(B^q) \subseteq Y = \{z; z_1 \geq 0, |z_i| \leq A_i z_1^{k_i}\}$. Clearly $\alpha(Y) = \{z'; z'_1 > 0, |z'_i| \leq A_i z'_1\}$; we denote $\alpha(Y)$ by Y' .

α induces a homeomorphism $\alpha^*: I(R^p - Y', R^p) \rightarrow I(R^p - Y, R^p)$ because $(\alpha^{-1})^*$ is obviously continuous and so too is α^* since if $f \in I(R^p - Y', R^p)$ each $\partial^\beta f / \partial z'_\beta(z')$ tends to 0 faster than any power of z'_1 so that $\partial^\beta f / \partial z'_\beta(\alpha(z))$ tends to 0 as $z_1 = (z'_1)^2$ tends to 0 faster than any power of z_1 and hence by the formula for $\partial^\beta / \partial z_\beta(f \circ \alpha)$ the result follows. The following diagram of G invariant maps commutes.

$$\begin{array}{ccc} R^q & \xrightarrow{\psi} & R^q_+ & \xrightarrow{\alpha} & R^p \\ h_1 \uparrow & & & & \uparrow h_2 \\ S^{q-1} \times [0, \infty) & \xrightarrow{\lambda} & S^{p-1} \times [0, \infty) \end{array}$$

where S^{q-1} and S^{p-1} are the unit spheres in R^q and R^p respectively, G acts trivially on R^p and $[0, \infty)$, h_2 is the mapping given by ‘‘polar coordinates’’ on R^p and h_1 is chosen such that λ is a product map and level preserving with respect to projections onto $[0, \infty)$. h_2 and h_1 (using a similar argument to that above for α) induce homeomorphisms

$$\begin{aligned} h_1^*: I_H(0, R^q) &\cong I_H(S^{q-1} \times 0, S^{q-1} \times [0, \infty)) \quad \text{and} \\ h_2^*: I(0, R^p) &\cong I(S^{p-1} \times 0, S^{p-1} \times [0, \infty)). \end{aligned}$$

The restrictions $I(R^p - Y, R^p) \rightarrow I(0, \psi(B^q))$ and $I(R^p - Y', R^p) \rightarrow I(0, \alpha\psi(B^q))$ are both onto (Malgrange).

LEMMA 1. Let $r, s, t, u, v \in R^+$ with $u < s < t < v$. If there is a continuous $K': I_H(S^{q-1} \times \{s, t\}, S^{q-1} \times [s, t]) \rightarrow E(S^{p-1} \times [u, v])$, a right inverse for λ^* , then there exists a continuous

$$K: I_H(S^{q-1} \times \{0, r\}, S^{q-1} \times [0, r]) \rightarrow I(S^{p-1} \times \{0, r\}, S^{p-1} \times [0, r])$$

which is a right inverse for λ^* and such that if the image of K' is contained in $I(h_2^{-1}(R^p - Y'), S^{p-1} \times [0, \infty))$ then so too is the image of K .

PROOF. It is sufficient to show that K' can be modified to map into $I(S^{p-1} \times \{s, t\}, S^{p-1} \times [s, t])$ which is isomorphic to $I(S^{p-1} \times \{0, r\}, S^{p-1} \times [0, r])$

under a linear homeomorphism of $[s, t]$ with $[0, r]$. In Section 4 a continuous extension $A : E(S^{p-1} \times s) \rightarrow E(S^{p-1} \times I_1)$ was described (where I_1 is a small interval containing s) which has the property that if $\beta \in E(S^{p-1} \times s)$ arises from a function which is zero on the product of a set $X \subset S^{p-1}$ with one of the closed subintervals of I_1 into which s divides I_1 then $A(\beta)$ is zero on $X \times I_1$. $X = \lambda(S^{q-1} \times s)$ here. If $K'(\gamma)$, $\gamma \in I_H(S^{q-1} \times \{s, t\}, S^{q-1} \times [s, t])$, restricts to $\beta \in E(S^{p-1} \times s)$ then subtracting $A(\beta)$ from $F(\gamma)$ (and similarly for t) gives F of the required form. As $h_2^{-1}(Y' - \{0\}) \approx [0, \infty) \times (h_2^{-1}(Y') \cap (S^{p-1} \times 1))$ the rest of the lemma follows automatically.

If $U \subset R^n$ is a submanifold with boundary (and possibly corners) of dimension n then it is well known (see Mather (1969)) that the restriction $E(R^n) \rightarrow E(U)$ splits continuously on the right (for convenience we say that $E(U)$ embeds in $E(R^n)$). If U is G invariant then using the averaging process for functions on R^n [$E(R^n) \rightarrow E_G(R^n)$, $f(x) \rightarrow \int_G f(g(x)) dg$, where dg denotes the normalized Haar measure on G] it follows that $E_G(U)$ embeds in $E_G(R^n)$ also.

COROLLARY. *If there is a continuous right inverse for ψ^* ,*

$$K'' : I_H(\overline{\partial(B^q - B_1^q)}, \overline{(B^q - B_1^q)}) \rightarrow E(R^p),$$

where B^q is a ball at 0 and B_1^q is a sufficiently small ball at 0 in R^q , then the conclusion of Lemma 1 holds.

PROOF. If B_1^q is sufficiently small $(B^q - B_1^q) - \partial B^q$ contains a set of the form $h_1(S^{q-1} \times [s, t])$. Since $I_H(h_1(S^{q-1} \times \{s, t\}), h_1(S^{q-1} \times [s, t]))$ embeds in $I_H(\overline{\partial(B^q - B_1^q)}, \overline{(B^q - B_1^q)})$ and since by multiplying by a smooth bump function which is zero in a suitable neighbourhood of 0 in R^p and outside Y it can be assumed that K'' maps into $I(R^p - Y, R^p)$ the corollary follows immediately (taking account of the remarks preceding the lemma). Note that Lemma 1 and its corollary have a parametrized form, where all spaces are multiplied by a fixed smooth manifold M . $\psi : R^q \rightarrow R^p$ is replaced by $(\psi \times id) : R^q \times M \rightarrow R^p \times M$ etcetera and the deduction is $K : I_H(S^{q-1} \times \{0, r\} \times M, S^{q-1} \times [0, r] \times M) \rightarrow$ etcetera. The proof is the same.

LEMMA 2. *There exists a continuous $J : E_H(0 \times M) \rightarrow E(R^p \times M)$, where 0 is the zero of R^q , which is a right inverse for $(\psi \times id)^*$.*

PROOF. Any $\beta \in E_H(0 \times M)$ is of the form $\{f_i(y)P_i(\psi_j(x))\}$ where the $f_i(y)$ are in $C^\infty(M)$ and are uniquely determined. Let $J'(\beta)$ be the element $\{f_i(y)P_i(z_j)\}$ of $E(0' \times M)$ where $0'$ is the zero of R^p . J is the composition of J' with the extension $E(0' \times M) \rightarrow E(R^p \times M)$ of §4.

COROLLARY. Under the hypothesis of the corollary to Lemma 1 there is a continuous map from $I_H(h_1(S^{q-1} \times r), h_1(S^{q-1} \times [0, r]))$ to $I(\alpha^{-1}h_2(S^{p-1} \times r), \alpha^{-1}h_2(S^{p-1} \times [0, r]))$ which is a right inverse for ψ^* .

PROOF. The corollary to Lemma 1 gives a right inverse for

$$\psi^*: I(\alpha^{-1}h_2(S^{p-1} \times \{0, r\}), \alpha^{-1}h_2(S^{p-1} \times [0, r])) \rightarrow I_H(h_1(S^{q-1} \times \{0, r\}), h_1(S^{q-1} \times [0, r]))$$

and piecing together with J gives the result.

Note that this corollary again holds in parametrized form.

LEMMA 3. Let W' be a G invariant submanifold with boundary of R^n of dimension n and suppose that there is a continuous $E': E_G(W') \rightarrow E(R^n)$ which is a right inverse for ϕ^* and that W' contains all points of B except those in a sufficiently small neighbourhood of $0 \times B_2$. Then there exists a continuous right inverse for $\phi^*: E(R^N) \rightarrow E_G(W)$ where W is a G -invariant submanifold with boundary of dimension contained in the interior of $G(B) \cup W'$ which can be chosen so that $G(B) \cup W' - W$ is as small as required.

PROOF. By the last corollary and note (with $M = B_2$) for W sufficiently large there are subbundles T and T' of the ball bundles $B_1 \times B_2$ and $B_2 \times B_3$ over B_2 with fibres balls of the same dimension such that $g(T) \cup W' = G(B) \cup W'$, $G(\partial T - (B_1 \times \partial B_2)) \subseteq \text{int } W$, $\phi'(\partial T) \subseteq F(\partial T')$ and there is a right inverse for $\phi^*: I(F(\partial T'), F(T')) \rightarrow I_G(G(\partial T), G(T))$ [recall formula (6.11)]. Since $I(\partial T', T')$ embeds in $I(\partial(T' \times B_4), T' \times B_4)$ there is a right inverse E'' for $\phi^*: I(R^N - F'(T' \times B_4), R^N) \rightarrow I_G(G(\partial T), G(T))$.

Let V be a G -invariant submanifold with boundary of W' of dimension n contained in $\text{int } W'$ with $W' - V$ as small as required and $\partial W'$ intersecting $G(\partial T)$ transversally within $G(\text{int } B_1 \times \partial B_2)$. $I_G(\partial V \cap \overline{V - T}, \overline{V - T})$ embeds in $I_G(\partial V, V)$ which embeds in $E_G(W')$ so that E' gives a right inverse for $\phi^*: E(R^N) \rightarrow I_G(\partial V \cap \overline{V - T}, \overline{V - T})$ and piecing together with E'' gives a right inverse for $\phi^*: E(R^N) \rightarrow I_G(\partial(V \cup G(T)), V \cup G(T))$. If W is a manifold with boundary of dimension n contained in $\text{int}(V \cup G(T))$ then $E_G(W)$ embeds in $I_G(\partial(V \cup G(T)), V \cup G(T))$ and the result follows.

PROPOSITION 6. There exists a G invariant neighbourhood V of 0 in R^n and a continuous $E: E_G(V) \rightarrow C(R^N)$, a right inverse for ϕ^* .

PROOF. We can build V from pieces $G(B)$ starting with points of minimal stabilizers and apply Lemma 3 at each step: there are of course only finitely many orbit types and the quotient by G of the set of points of a given orbit type with stabilizer of type H can be triangulated sufficiently finely over

any compact set (using, say, a linear triangulation of the open subset of $(R^n)_H$ of points with stabilizer H) in order to use maps such as F on neighbourhoods of the pieces.

THEOREM 3. *There exists a continuous $E: C_G(R^n) \rightarrow C(R^n)$ such that $\phi^*E = 1$.*

PROOF. In earlier notation (with $G = H$, $\phi = \psi$, $p = N$, $q = n$, etc.) let M_r be a manifold with boundary of dimension p obtained, say, by thickening $h_2(S^{p-1} \times [0, r]) \cap Y'$ along its corners, containing $\alpha^{-1}(\alpha\psi(R^q) \cap h_2(S^{p-1} \times [0, r]))$ with ∂M_r intersecting this last set in $\alpha^{-1}(\alpha\psi(R^q) \cap h_2(S^{p-1} \times r))$. E given by the proposition gives (as in Lemma 1)

$$E: I_G(h_1(S^{n-1} \times r), h_1(S^{n-1} \times [0, r])) \rightarrow I(\partial M_r, M_r) \quad \text{and}$$

$$E: I_G(h_1(S^{n-1} \times \{s, t\}, h_1(S^{n-1} \times [s, t]))) \rightarrow I(\partial M_s \cup \partial M_t, \overline{M_t - M_s})$$

for some $r > 0$ and $0 < s < t$, where we have taken M_t containing M_s in its interior (as we can obviously suppose). Splitting $[0, \infty)$ into $[0, r] \cup [s_1, t_1] \cup [s_2, t_2] \cup \dots$ where $0 < s_1 < r < s_2 < t_1 < s_3 < t_2 < \dots$ and using a partition of unity gives the result.

COROLLARY. *There is a continuous $C(\phi(R^n)) \rightarrow C(R^n)$, a right inverse for the restriction.*

PROOF. Follows from the theorem and the identification $C(\phi(R^n)) \approx C_G(R^n)$ (Schwarz).

Added in revision: Theorem 3 has also been proved by Mather (unpublished). The proof given here follows the lines laid down by Schwarz more closely.

7. G -stability

Suppose that G , a compact lie group, acts linearly on R^n and R^p and let $f: R^n \rightarrow R^p$ be a proper G invariant smooth map. $P\theta_G(R^n)$ and $P\theta_G(f)$, the spaces of polynomial G invariant vector fields on R^n and along f respectively, are finitely generated over $P_G(R^n)$, and $P\theta_G(R^p)$ is finitely generated over $P_G(R^p)$ (the proof given in Dieudonné (1970) that $P_G^+(R^n)$ is finitely generated over $P_G(R^n)$ goes through for the module case, and the generators are again homogeneous). Let $\{v_i\}$ be a finite generating set for $P\theta_G(R^n)$ over $P_G(R^n)$. Then $\sum_i C(R^n)v_i$ is closed in $C(R^n)$, by a result of Malgrange (1966) generalized by Tougeron (1972), and so $\sum_i C_G(R^n)v_i = (\sum_i C(R^n)v_i) \cap \theta_G(R^n)$ is closed in $\theta_G(R^n)$ and, since elements of $\theta_G(R^n)$ can be approximated arbitrarily closely over compact sets by polynomial vector fields,

$\Sigma_i C_G(R^n)v_i$ is also dense in $\theta_G(R^n)$ and equality follows. Similarly $\theta_G(R^p)$ and $\theta_G(f)$ are also finitely generated over $C_G(R^p)$ and $C_G(R^n)$ respectively.

These remarks, together with Theorem 3, allow Mather's proof that infinitesimal C^∞ stability implies C^∞ stability for a proper map in the G trivial case to go through in the G category for the map f . The converse result follows immediately from the same methods used for the G trivial case (by considering jet spaces — see Mather (1970)).

THEOREM 4. *Let $f: R^n \rightarrow R^p$ be a proper G invariant map between linear G spaces, where G is a compact lie group. Then f is C^∞ G -infinitesimally stable (that is $wf(\theta_G(R^p)) + tf(\theta_G(R^n)) = \theta_G(f)$, in Mather's notation, where wf and tf are induced by composition with f and the derivative of f) if and only if f is C^∞ G -stable (that is if g is a sufficiently close G invariant map to f there exist invariant smooth diffeomorphisms $h: R^n \rightarrow R^n$ and $h': R^p \rightarrow R^p$ such that $g = h'fh^{-1}$).*

COROLLARY. *The theorem holds if R^n and R^p are replaced by C^∞ G manifolds of finite orbit type — (see Schwarz: such a manifold has a G invariant embedding in some R^n and then the usual method (Mather (1968) for reducing questions about the manifold to those about R^n holds).*

[Added in revision: this corollary (at least when the source manifold is compact) has been announced by V. Poenaru (1975).]

8. Conclusion

Transversality theorems (and the use of jet spaces) used to give the result that stability implies infinitesimal stability can also be proved when the target is a manifold and the source a set of the type of Section 5 (the author will consider this question elsewhere). It is a simple exercise to show that $\phi(R^n)$, where ϕ is a Hilbert map, is coherent (clearly it has everywhere irreducible germs and by an argument of Malgrange, given in the preprint cited in the references, the result follows).

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