## $\lambda(n)-P A R A M E T E R$ FAMILIES

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(received March 29, 1969)

I is an interval of $R$, the set of real numbers, $n$ is a positive integer and $F \subset C^{j}(I)$ for $j \geq 0$ large enough so that the following definitions are possible:
(i) Let $\lambda(n)=\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{k}\right)$ where $k, \lambda_{1}, \lambda_{2}, \ldots, \lambda_{k}$ are positive integers and $\lambda_{1}+\lambda_{2}+\ldots+\lambda_{k}=n$. Then $\lambda(n)$ is an ordered partition of $n$. The set of all such partitions of $n$ is denoted by $P(n)$.
(ii) Let $\lambda(n) \in P(n)$ be given. The family $F$ of real valued functions on $I$ is said to be a $\lambda(n)$-parameter family on $I$ in case for any choice of points $x_{1}<x_{2}<\ldots<x_{k}$ in I and any set of $n$ real
numbers $y_{i}{ }^{(j)}$ there is a unique $f \in F$ satisfying

$$
\begin{equation*}
f^{(j)}\left(x_{i}\right)=y_{i}^{(j)}, j=0,1,2, \ldots, \lambda_{i}-1, i=1,2, \ldots, k \tag{1}
\end{equation*}
$$

If $F$ is a $\lambda(n)$-parameter family for $\lambda(n)=(1,1, \ldots, 1)$, then $F$ is called an $n$-parameter family. (See [5].) If $F$ is a $\lambda(n)$-parameter family on $I$ for $\lambda(n)=n$, i.e., all conditions are specified at one point, then we will say that initial value problems are uniquely solvable in $F$ on I. If $F$ is a $\lambda(n)$-parameter family on $I$ for all $\lambda(n) \in P(n)$, then $F$ is called an unrestricted $n$-parameter family on I. (See [11.)
P. Hartman [1] proved the following:

THEOREM. A family $F \subset C^{n-1}(I)$, where $I$ is an open interval of $R$, is an unrestricted $n$-parameter family on $I$ if and only if $F$ is an $n$-parameter family on $I$ and initial value problems are uniquely solvable in $F$ on $I$.
Z. Opial [4] gave a very nice short proof of Hartman's result in the case that $F$ is the solution set for an $n^{\text {th }}$ order homogeneous linear differential equation with summable coefficients. Opial's proof uses the linearity of $F$ ( $F$ is an $n$-dimensional real vector space) and the continuity with respect to initial values.

Canad. Math. Bull. vol. 12, no. 2, 1969

What happens if I is not open? In [1] Hartman poses that question for I closed, but does not resolve it. We give here an example to show that neither Hartman's Theorem nor Opial's Theorem is valid if I is closed. Before giving the example we have the following definition and lemma:
(iii) Let $L_{n}[y]=y^{(n)}+a_{n-1} y^{(n-1)}+\ldots+a_{1} y^{\prime}+a_{0} y=0$ be a homogenous linear differential equation with continuous coefficients on I. For each $s \in I$ let $K(x, s)$ be the solution to the initial value problem

$$
L_{n}[y]=0, y(s)=y^{\prime}(s)=\ldots=y^{(n-2)}(s)=0=y^{(n-1)}(s)-1
$$

$K$ is called the Cauchy function for $L_{n}$.
(iv) $L_{n}$ (or $L_{n}[y]=0$ ) is said to be disconjugate on $I$ in case no nontrivial solution to $L_{n}[y]=0$ has more than $n-1$ zeros (counting multiplicity) on I .

Clearly $L_{n}$ being disconjugate on I implies that
(2) $\operatorname{sgn} K(x, s)=\operatorname{sgn}(x-s)^{n-1}$ for all $x$ and $s$ in I.

$$
(\operatorname{sgn} x=0 \text { if } x=0,1 \text { if } x>0,-1 \text { if } x<0 .)
$$

The lemma in [2] states that the converse is also true for $n=3$. We state that lemma here and supply it with a quite different proof.

LEMMA 1. Let $a_{0}$, $a_{1}$ and $a_{2}$ be continuous on $I$. If $K(x, s)>0$ for all x and s in I with $\mathrm{x} \neq \mathrm{s}$, then $\mathrm{L}_{3}[\mathrm{y}]=0$ is disconjugate on I .

Proof. Let $s_{1}, s_{2}$ and $s_{3}$ be three distinct points in $I$. Then $K\left(x, s_{1}\right), K\left(x, s_{2}\right)$ and $K\left(x, s_{3}\right)$ are linearly independent on $I$. Suppose that $c_{1} K\left(x, s_{1}\right)+c_{2} K\left(x, s_{2}\right)+c_{3} K\left(x, s_{3}\right)=0$ for all $x$ in I. Put $\mathrm{x}=\mathrm{s}_{1}, \mathrm{~s}_{2}$ and $\mathrm{s}_{3}$. The resulting homogeneous system of equations in $c_{1}, c_{2}$ and $c_{3}$ has only the solution $c_{1}=c_{2}=c_{3}=0$.

Now suppose that $y=y_{0}(x)$ is a non-trivial solution to $L_{3}[y]=0$ on I, and let $y_{0}(x)$ have three zeros in I. Clearly $y_{0}(x)$ cannot have a double zero, so let the zeros be $s_{1}, s_{2}$ and $s_{3}$. Then there are constants
$c_{1}, c_{2}$ and $c_{3}$ so that $y_{0}(x)=c_{1} K\left(x, s_{1}\right)+c_{2} K\left(x, s_{2}\right)+c_{3} K\left(x, s_{3}\right)$ for all $x$ in I. But then $c_{1}=c_{2}=c_{3}=0$ as above. Hence $L_{3}$ is disconjugate.

Example: (This example is from the author's doctoral dissertation written under the direction of Professor L. K. Jackson at the University of Nebraska; see [3].) Let $F$ be the set of solutions to the differential equation

$$
\begin{equation*}
x^{3} y^{\prime \prime \prime}+4 x^{2} y^{\prime \prime}+3 x y^{\prime}+y=0 \tag{3}
\end{equation*}
$$

on the interval $\left[1, x_{0}\right]$ where $x_{0}$ is the first zero of $\frac{1}{x}+\sin \log x-\cos \log x$ to the right of 1 . We will show that $F$ is a 3 -parameter family on $\left[1, x_{0}\right]$ but $F$ is not an unrestricted 3 -parameter family on $\left[1, x_{0}\right]$. The Cauchy function for (3) is given by $K(x, s)=\frac{s^{2}}{2}\left(\frac{s}{x}+\sin \log \frac{x}{s}-\cos \log \frac{x}{s}\right)$, so $K\left(x_{0}, 1\right)=0$ and $K(x, 1)>0$ for $1<x<x_{0} . K(x, s)=s^{2} K\left(\frac{x}{s}, 1\right)$, so $K(x, s)>0$ for $s<x<x_{0} s$. Also, one can show, using derivatives, that $K(x, s)>0$ if $1<s \leq x_{0}$ and $x<s$. Hence (3) is disconjugate on $\left[1, x_{0}\right.$ ) and $\left(1, x_{0}\right]$ by Lemma 1. Let $y=y_{0}(x)$ be a solution to (3) satisfying $0=y_{0}(1)=y_{0}\left(x_{0}\right)=y_{0}(c), \quad 1<c<x_{0}$. Then $y_{0}(x)=c_{1} u_{1}(x)+c_{2} K(x, 1)$ where $c_{1}$ and $c_{2}$ are constants and $u_{1}(x)=\frac{1}{2 x}+\frac{3}{2} \sin \log x-\frac{1}{2} \cos \log x$. Now $\exp (5 \pi / 4)<x_{0}<\exp (4 \pi / 3)$, so that $u_{1}\left(x_{0}\right)<0$ and therefore $y_{0}(c)=0$ implies that $c_{2}=0$; so by the linearity of $F$ we conclude that $F$ is a 3-parameter family on $\left[1, x_{0}\right]$, but clearly $F$ is not an unrestricted 3 -parameter family on $\left[1, x_{0}\right]$ since $y \equiv 0$ and $y=K(x, 1)$ both satisfy $0=y(1)=y^{\prime}(1)=y\left(x_{0}\right)$.

Is Hartman's Theorem valid on a half open interval? If $F$ is linear and $\mathrm{n}=3,4$ or 5 , then the answer is yes. The author conjectures that if $F$ is linear and $I$ is half open, then Hartman's Theorem is correct. A proof of this for the general case (n arbitrary) has not yet been given.

A natural question which arises is whether Lemma 1 generalizes, and, if so, how. It is easy to give an example to show that (2) does not imply disconjugacy for $L_{n}$ if $n>3$; for instance, for $L_{n}[y] \equiv y^{(n)}+y^{(n-2)}$, (2) is satisfied on $(-\infty, \infty)$, but $L_{n}$ is clearly not disconjugate on $(-\infty, \infty)$.

One generalization of Lemma 1 is the following theorem:

THEOREM 1. Let $F$ be a linear $\lambda(n)$-parameter family on $I$ for $\lambda(n)=(2,1,1, \ldots, 1), \lambda(n)=(1,1, \ldots, 1,2)$ and $\lambda(n)=(2,1,1, \ldots, 1,2)$. Then $F$ is an $n$-parameter family on $I$.

Proof. Let $f$ be a non-trivial member of $F$ satisfying $f\left(x_{1}\right)=f\left(x_{2}\right)=\ldots=f\left(x_{n}\right)=0$ where $x_{1}<x_{2}<\ldots<x_{n}$ are points in I. Define $g \in F$ by $g\left(x_{1}\right)=g^{\prime}\left(x_{1}\right)-f^{\prime}\left(x_{1}\right)=g\left(z_{3}\right)=g\left(z_{4}\right)=\ldots=g\left(z_{n-2}\right)=$ $g\left(x_{n}\right)=g^{\prime}\left(x_{n}\right)=0$, where $z_{i}=\left(x_{i}+x_{i+1}\right) / 2$ for $i=3,4, \ldots, n-2$. By hypothesis we must have $f^{\prime}(x) \neq 0$ for $x=x_{1}, x_{2}, x_{n-1}$ and $x_{n}$. But $g^{\prime}\left(x_{1}\right)=f^{\prime}\left(x_{1}\right) \neq 0$, so $g(x)$ does not vanish identically on I. $g$ has a double zero at $x_{n}$ and zeros at $x_{1}, z_{3}, z_{4}, \ldots, z_{n-2}$, so these points are the only zeros of $g$. If $f$ changes sign at all the points $x_{i}$, then $f-g$ changes sign in each of the intervals $\left(x_{3}, z_{3}\right),\left(z_{3}, z_{4}\right)$, $\left(z_{4}, z_{5}\right), \ldots,\left(z_{n-3}, z_{n-2}\right) . f-g$ also changes sign in $\left(z_{n-2}, x_{n}\right)$ since $g^{\prime}\left(x_{n}\right)=0 \neq f^{\prime}\left(x_{n}\right), f\left(x_{n-1}\right)=f\left(x_{n}\right)=0, f$ changes sign at $x_{n-1}$ and $g\left(z_{n-2}\right)=g\left(x_{n}\right)=0$. So $f-g$ has a double zero at $x_{1}$ and $n-2$ other zeros. This contradicts the uniqueness of solutions to (1) in $F$ for $\lambda(n)=(2,1,1, \ldots, 1)$. If $f$ does not change sign at all the points $x_{i}$, let $s$ be the number of points $x_{i}, i=3,4, \ldots, n-1$ at which $f$ changes sign and let $d$ be the number of points $x_{i}, 3 \leq i \leq n-2$, at which $f$ does not change sign. Then $s+d=n-3$. To each zero $x_{i}$ at which $f$ changes sign there corresponds a point $p_{i}, z_{i-1}<p_{i}<z_{i}, i=4,5, \ldots, n-2$ and $z_{n-2}<p_{n-2}<x_{n}$, such that $f-g$ changes sign. Hence we have at least $s$ changes of sign of $f-g$. Let $d_{1}$ be the number of double zeros $x_{i}$ of $f$ (i.e. $f$ does not change sign at $x_{i}$ ) such that $f$ and $g$ have the same $\operatorname{sign}$ in $\left(x_{i}-\delta, x_{i}+\delta\right)$ for $\delta>0$ sufficiently small. There are two zeros of $f-g$ in $\left(z_{i-1}, z_{i}\right)$ for each of these $d_{1}$ double zeros of $f . f-g$ has a double zero at $x_{1}$ and as we have shown above, at least $s+2 d_{1}+1$ other zeros in $I$. But since $f$ and $g$ are not identical, we must have $s+2 d_{1}+1<n-2$, i.e., $2 d_{1}<n-s-3=d$, and then $2\left(d-d_{1}\right)>d$. At the remaining $d-d_{1}$ points $x_{i}$ at which $f$ does not change sign we must have $a \delta>0$ so that $f(x)$ and $g(x)$ have opposite signs for $0<\left|x-x_{i}\right|<\delta$. Then for $\varepsilon>0$ small enough the graphs of $f$ and $-\varepsilon g$ will intersect at two points (in $\left.\left(z_{i-1}, z_{i}\right)\right)$ separated by $x_{i}$. Hence for $\varepsilon>0$ small enough there will be two points in $\left(z_{i-1}, z_{i}\right)$ at which $f+\varepsilon g$ changes sign. This will give $2\left(d-d_{1}\right)$ changes of sign for $f+\varepsilon g$. Also to each $p_{i}$ there corresponds a $q_{i}, z_{i-1}<q_{i}<z_{i}$
and $z_{n-2}<q_{n-2}<x_{n}$, at which $f+\varepsilon g$ changes sign. This follows since $f\left(x_{i}\right)=0, f^{\prime}\left(x_{i}\right) \neq 0, f(x) \neq 0$ for $x$ in $\left(z_{i-1}, z_{i}\right)$ with $x \neq x_{i}$, and $-\varepsilon g\left(z_{i-1}\right)=-\varepsilon g\left(z_{i}\right)=0 . f+\varepsilon g$ must vanish in $\left(z_{n-2}, x_{n}\right)$, since $f\left(x_{n-1}\right)=f\left(x_{n}\right)=g\left(x_{n}\right)=g\left(z_{n-2}\right)=0$ and $f^{\prime}\left(x_{n}\right) \neq 0=g^{\prime}\left(x_{n}\right)$. So we will have $2\left(d-d_{1}\right)+s \geq d+s+1=n-2$ changes of sign in $\left(x_{1}, x_{n}\right)$. This is impossible (as we showed in the first part of this proof) since $f+\varepsilon g$ will also have zeros (simple) at $X_{1}$ and $X_{n}$, and we know that $f+\varepsilon g$ is in $F$ because $F$ is a linear family on $I$. Hence no such non-trivial $f \in F$ can exist. This shows that uniqueness of solutions of (1) in $F$ for $\lambda(n)=(1,1, \ldots, 1)$. The existence of solutions of (1) in $F$ for the same $\lambda(n)$ follows immediately from uniqueness since $F$ is linear. To show this let $\left\{f_{1}, f_{2}, \ldots, f_{n}\right\}$ be a basis for $F$. Then there exist $n$ constants $c_{1}, c_{2}, \ldots, c_{n}$ so that n $f=\sum_{i=1} \quad c_{i} f_{i}$. But the $n \times n$ system of linear equations generated by (1) from this representation of $f$ must (by uniqueness) have a non-zero coefficient determinant, and hence that system has a solution. This proves the theorem. We here note that in general for a linear family $F$ uniqueness of solutions of (1) in $F$ for a given $\lambda(n)$ implies the existence of solutions of (1) in $F$ for that $\lambda(n)$.

COROLLARY. If $F$ is a linear $\lambda(n)$-parameter family on the open interval $I$ for $\lambda(n)=n$ and the values of $\lambda(n)$ as given in Theorem 1 , then $F$ is an unrestricted $n$-parameter family on $I$.

The corollary follows directly from Theorem 1 and Hartman's Theorem.

An affirmative answer to the question $Q$ below would yield another generalization of Lemma 1.
Q. If $F$ is a linear $\lambda(n)$-parameter family on $I$ for $|\lambda(n)| \leq 2$, is $F$ an unrestricted $n$-parameter family on $I$ ? $(|\lambda(n)|$ denotes the length of the partition $\lambda(n)$.) That the answer to $Q$ is yes for $\mathrm{n}=4$ follows from Lemma 1 and from Lemma 2 below. $Q$ is as yet unsolved for $n \geq 5$.

LEMMA 2. If $F$ is a linear $\lambda(n)$-parameter family for $\lambda(n)=(n-1,1)$ and $(n-2,2)$ (or for $\lambda(n)=(1, n-1)$ and $(2, n-2)$ ), then $F$ is an (n-2,1,1)-parameter (or (1, 1, n-2)-parameter) family on I.

Proof. Let $f$ be a non-trivial member of $F$ with $f^{(i)}\left(x_{1}\right)=0$ for $\mathrm{i}=0,1,2, \ldots, \mathrm{n}-3, \mathrm{f}\left(\mathrm{x}_{2}\right)=\mathrm{f}\left(\mathrm{x}_{3}\right)=0$ where $\mathrm{x}_{1}<\mathrm{x}_{2}<\mathrm{x}_{3}$ are three points in I. Let $p=\left(x_{2}+x_{3}\right) / 2$ and pick $g \in F$ satisfying $g(i)\left(x_{1}\right)=0$ for $i=0,1,2, \ldots, n-2$ and $g(p)=f(p) / 2 \neq 0$. (We assume without
loss of generality that $f(x)<0$ in $\left(x_{1}, x_{2}\right)$ and $f(x)>0$ in $\left(x_{2}, x_{3}\right)$.) $g(x)>0$ for $x>x_{1}$, so there are points in $\left(x_{2}, x_{3}\right)$ at which $f(x)-g(x)>0$. Let $M$ be the set of real numbers $\gamma$ such that $f(x)-\gamma g(x)>0$ for some points in $\left(x_{2}, x_{3}\right)$. Let $\gamma_{0}=\sup M$. Then there is a point $x_{0}$ in $\left(x_{2}, x_{3}\right)$ such that $h=f-\gamma_{0} g$ satisfies
$h\left(x_{0}\right)=h^{\prime}\left(x_{0}\right)=0$. Also $h^{(i)}\left(x_{1}\right)=0$ for $i=0,1,2, \ldots, n-3$. $F$ is a $(n-2,2)$-parameter family, so $h(x)=0$ for all $x$ in I. This of course is impossible since $h\left(x_{2}\right)=-\gamma_{0} g\left(x_{2}\right)<0$. The other half of the lemma follows in a similar fashion.

In terms of boundary value problems for ordinary differential equations, question $Q$ can be phrased as follows:

If every two point boundary value problem is solvable, is every boundary value problem solvable?

Acknowledgement. Thanks are due to the University of Alberta and the Canadian Mathematical Congress Summer Research Institute for support of this research.

Added in proof. The author has recently become aware of two papers ([6] and [7]) which answer the last question in the affirmative for a linear differential equation with continuous coefficients.

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