# INFINITE QUASI-NORMAL MATRICES 

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1. Introduction. If $A$ is a finite matrix with complex elements, and if $A=A^{T}$ (where $A^{T}$ denotes the transpose of $A$ ), it is known (see [8]) that there exists a unitary matrix $U$ such that $U A U^{T}=D$ is a real diagonal matrix with non-negative elements which is a canonical form for $A$ relative to the given $U, U^{T}$ transformation. If $A$ is a quasi-normal matrix, i.e. a complex matrix such that $A A^{C T}=A^{T} A^{C}$ (where $A^{C}$ denotes the complex conjugate of $A$ and $A^{C T}$ denotes the complex conjugate transpose), it is known by $[\mathbf{6} ; \mathbf{1 0}]$ that a necessary and sufficient condition for this to occur is that there exist a unitary matrix $U$ such that $U A U^{T}$ is a direct sum of non-negative real numbers and of matrices of the form

$$
\left[\begin{array}{rr}
a & b \\
-b & a
\end{array}\right]
$$

where $a$ and $b$ are non-negative real numbers. If $A=-A^{T}$, the $a$ 's are 0 and a special case of this form results (see [9], also). Here the analogous normal forms are obtained for the case of infinite matrices which represent completely continuous operators in Hilbert space $l^{2}$. The point of view involves operator theory to some extent, but ultimately the matrix point of view since the results are concerned essentially with normal forms of matrices.
2. The transpose operator. First, the following facts are recalled relating to a completely continuous operator $\mathscr{A}$ in complex Hilbert space $l^{2}$. Let $A=\left(a_{i j}\right)$ be an infinite matrix which represents $\mathscr{A}$ relative to a given orthonormal basis. It is known that $\mathscr{A}$ has a polar decomposition $\mathscr{A}=\mathscr{U} \mathscr{P}$ where $\mathscr{P}$ is a positive Hermitian operator, $\mathscr{U}$ is a partially isometric operator whose initial set is the closure of the range of $\mathscr{P}$ and whose final set is the closure of the range of $\mathscr{A}$, and where $\mathscr{U}$ is unique. (See [7;3], or [4].) It is also true that $\mathscr{P}=\mathscr{U}^{*} \mathscr{A}$ (where $\mathscr{U}^{*}$ denotes the adjoint of $\mathscr{U}$ ) is completely continuous, that $\mathscr{U}^{*} \mathscr{U} \mathscr{P}=\mathscr{P}$ (see [4, p. 264, solution 105] or [7, p. 5]), and that $\mathscr{A}=\mathscr{U} \mathscr{P}=\mathscr{Q} \mathscr{U}$ where $\mathscr{U} \mathscr{P} \mathscr{U}^{*}=\mathscr{Q}$ is positive Hermitian. Relative to the given basis let $\mathscr{A}=\mathscr{U} \mathscr{P}=\mathscr{Q} \mathscr{U}$ have the matrix representation $A=U P=Q U$ where $A=\left(a_{i j}\right), U=\left(u_{i j}\right), P=\left(p_{i j}\right)$, and $Q=\left(q_{i j}\right)$. This is true since to the product of operators there corresponds the product of corresponding matrices relative to the same basis. $U=\left(u_{i j}\right)$ is not necessarily unitary.

The transpose of $\mathscr{A}$, denoted by $\mathscr{A}^{T}$, is a linear transformation on the conjugate space with a matrix representation which is the transpose of $A$, relative to the appropriate basis. For purposes here, a transpose of $\mathscr{A}$ is defined which is an operator on the same space $l^{2}$ but also has a matrix representation which is the transpose of $A$. This is done as follows and the author is indebted to William L. Armacost who supplied the details in the following four paragraphs when the question of defining such a transpose arose in this work.

Let $\left\{e_{i}\right\}$ be the usual orthonormal basis of $l^{2}$ and let $x=\sum_{i=1}^{\infty} x_{i} e_{i} \in l^{2}$. Define a transformation $\mathscr{C}$ as follows:

$$
\mathscr{C} x=\sum_{i=1}^{\infty} \dot{x}_{i} e_{i},
$$

which is in $l^{2}$. This is a conjugate-linear (or "semilinear") transformation from $l^{2}$ onto $l^{2}$ which is one-to-one and has the following properties (see [5, p. 357]): $\mathscr{C}^{2}=\mathscr{I}$ so $\mathscr{C}^{-1}=\mathscr{C} ; \mathscr{C}(x+y)=\mathscr{C} x+\mathscr{C} y ; \mathscr{C}(a x)=\bar{a} \mathscr{C}(x)$ for any complex scalar $a$ where $\bar{a}$ denotes the conjugate of $a$. Also if $(x, y)$ denotes scalar or inner product, then $(\mathscr{C} x, y)=\overline{(x, \mathscr{C} y)}$ and $(\mathscr{C} x, \mathscr{C} y)=\overline{(x, y)}=$ $(y, x)$; the latter implies $(\mathscr{C} x, \mathscr{C} x)=\|\mathscr{C} x\|^{2}=\|x\|^{2}$ so $\|C x\|=\|x\|$ (where $\|x\|$ denotes the norm of $x$ ) for any $x$ in $l^{2}$. This means $\mathscr{C}$ is an isometric mapping.

Let $\mathscr{A}$ be a bounded linear operator mapping $l^{2}$ into $l^{2}$ with $\left(\mathscr{A} e_{j}, e_{i}\right)=a_{i j}$ relative to a basis $\left\{e_{i}\right\}$. Let $\overline{\mathscr{A}}$ be the operator defined by $\overline{\mathscr{A}}=\mathscr{C} \mathscr{A} \mathscr{C}$. Then $\overline{\mathscr{A}}$ is a linear operator mapping $l^{2}$ into $l^{2}$ (since $\overline{\mathscr{A}}(x+y)=\mathscr{C} \mathscr{A} \mathscr{C}(x+y)=$ $(\mathscr{C A} \mathscr{C} x)+(\mathscr{C} \mathscr{A} \mathscr{C} y)$ and since
$\overline{\mathscr{A}}(a x)=(\mathscr{C} \mathscr{A} \mathscr{C})(a x)=(\mathscr{C} \mathscr{A})(\bar{a} \mathscr{C} x)=\mathscr{C}(\bar{a} \mathscr{A} \mathscr{C} x)=\overline{\bar{a}} \mathscr{C} \mathscr{A} \mathscr{C} x=a \overline{\mathscr{A}} x)$. $\overline{\mathscr{A}}$ is bounded. (For

$$
\|\overline{\mathscr{A}}\|=\sup _{\|x\|=1}\left\|\overline{\mathscr{A}}_{x \|}=\sup _{\|x\|=1}\right\| \mathscr{C} \mathscr{A} \mathscr{C} x\left\|=\sup _{\|x\|=1}\right\| \mathscr{A} \mathscr{C} x \|
$$

since $\mathscr{C}$ is an isometry. The latter, since $\mathscr{C}$ is a one-to-one onto isometry, is equal to

$$
\sup _{\left\|\mathscr{C}_{x \|=1}\right\| \mathscr{A}} \mathscr{C} x\left\|=\sup _{\|x\|=1}\right\| \mathscr{A} x\|=\| A \|<\infty
$$

so $\overline{\mathscr{A}}$ is bounded.) And, finally, $\left(\overline{\mathscr{A}}_{j}, e_{i}\right)=\bar{a}_{i j}$ since

$$
\left(\overline{\mathscr{A}} e_{j}, e_{i}\right)=\left(\mathscr{C} \mathscr{A} \mathscr{C} e_{j}, e_{i}\right)=\overline{\left(\mathscr{A} \mathscr{C} e_{j}, \mathscr{C} e_{i}\right)}=\overline{\left(\mathscr{A} e_{j}, e_{i}\right)}=\bar{a}_{i j}
$$

Next, define the T-transpose of $\mathscr{A}$, denoted by $\mathscr{A}^{\mathbf{T}}$, to be the linear transformation $\mathscr{A}^{\mathbf{T}}=\overline{\mathscr{A}}^{*}=\mathscr{C} \mathscr{A}^{*} \mathscr{C}_{\mathscr{C}}$ where $\mathscr{A}^{*}$ is the adjoint of $\mathscr{A}^{\left(\mathscr{A}^{\mathbf{T}}\right.}$ is a linear transformation on $l^{2}$ into $l^{2}$ for which the usual transpose properties hold:

$$
(\mathscr{A} \mathscr{B})^{\mathbf{T}}=\mathscr{B}^{\mathbf{T}} \mathscr{A}^{\mathbf{T}},(\mathscr{A}+\mathscr{B})^{\mathbf{T}}=\mathscr{A}^{\mathbf{T}}+\mathscr{B}^{\mathbf{T}}
$$

and $\left(\mathscr{A}^{\mathbf{T}}\right)^{\mathbf{T}}=\mathscr{A}$. Also,

$$
\left(\mathscr{A}^{\mathbf{T}} e_{j}, e_{i}\right)=\left(\overline{\mathscr{A}}^{*} e_{j}, e_{i}\right)=\overline{\left(e_{j}, \mathscr{A} e_{i}\right)}=\left(\mathscr{A} e_{i}, e_{j}\right)=a_{j i}
$$

so the matrix of $\mathscr{A}^{\mathbf{T}}$ is the transpose of the matrix of $\mathscr{A}$.

Other properties of $\mathscr{A}^{\mathbf{T}}$ are as follows: $\left(\mathscr{A}^{*}\right)^{\mathbf{T}}=\mathscr{C} \mathscr{A} \mathscr{C}=\overline{\mathscr{A}} \cdot \mathscr{A}^{\mathbf{T}}=\overline{\mathscr{A}}^{*}=$ $(\overline{\mathscr{A}})^{*}$ since $(\mathscr{C A} \mathscr{C})^{*}=\mathscr{C} \mathscr{A}^{*} \mathscr{C}$ because

$$
\begin{array}{r}
((\mathscr{C} \mathscr{A} \mathscr{C}) x, y)=\overline{(\mathscr{A} \mathscr{C} x, \mathscr{C} y)}=\overline{(\mathscr{C} x, \mathscr{A} * \mathscr{C} y)}=\overline{\overline{(x, \mathscr{C} \mathscr{A} * \mathscr{C} y)}}= \\
(x, \mathscr{C} \mathscr{A} * \mathscr{C} y)
\end{array}
$$

for all $x$ and $y$ in $l^{2}$. If $\mathscr{A}$ is Hermitian, so is $\mathscr{A}^{\mathbf{T}}$ since $\left(\mathscr{A}^{\mathbf{T}}\right)^{*}=\left(\mathscr{C} \mathscr{A}^{*} \mathscr{C}\right)^{*}=$ $(\mathscr{C} \mathscr{A} \mathscr{C})^{*}=\mathscr{C} \mathscr{A}^{*} \mathscr{C}=\mathscr{A}^{\mathbf{T}}$. If $\mathscr{A}$ is unitary, so is $\mathscr{A}^{\mathbf{T}}$, since if $\mathscr{A}$ is unitary, $\mathscr{A}_{\mathscr{A}^{*}}=\mathscr{A}^{*} \mathscr{A}=\mathscr{I}$ and so

$$
\begin{aligned}
\left(\mathscr{A}^{\mathbf{T}}\right)^{*} \mathscr{A}^{\mathbf{T}} & =\left(\mathscr{C} \mathscr{A}^{* \mathscr{C}}\right)^{*}(\mathscr{C} \mathscr{A} * \mathscr{C})=(\mathscr{C} \mathscr{A} \mathscr{C})\left(\mathscr{C} \mathscr{A}^{* \mathscr{C}}\right) \\
& =\mathscr{C} \mathscr{A}^{*} \cdot \mathscr{C}=\mathscr{C} \mathscr{C}=\mathscr{I}
\end{aligned}
$$

and similarly $\mathscr{A}^{\mathbf{T}}\left(\mathscr{A}^{\mathbf{T}}\right)^{*}=\mathscr{I}$. Similarly, if $\mathscr{A}$ is a partial isometry, then so is $\mathscr{A}^{\mathbf{T}}$. (It is also evident that if $\mathscr{A}$ is unitary so is $\overline{\mathscr{A}}$, and if $\mathscr{A}$ is Hermitian, so is $\overline{\mathscr{A}}$.) Also, $\left(\mathscr{A}^{\mathbf{T}}\right)^{*}=\left(\mathscr{A}^{*}\right)^{\mathbf{T}}$.

Furthermore, if $\mathscr{A}$ is completely continuous, so is $\overline{\mathscr{A}}$, and therefore so is $\mathscr{A}^{\mathbf{T}}=(\overline{\mathscr{A}})^{*}$. It is to be shown that if $x_{n} \rightharpoonup x$, i.e., if $x_{n}$ converges to $x$ weakly, then $\overline{\mathscr{A}} x_{n} \rightarrow \overline{\mathscr{A}} x$, i.e., $\overline{\mathscr{A}} x_{n}$ converges to $\overline{\mathscr{A}} x$ strongly. This will follow if it is shown that $x_{n} \rightharpoonup x$ implies $\mathscr{C} x_{n} \rightharpoonup \mathscr{C} x$ which in turn implies $\overline{\mathscr{A}} x_{n} \rightarrow \overline{\mathscr{A}} x$.
 $\mathscr{C}(\mathscr{C} y)\left|=\left|\overline{\left(x_{n}-x, \mathscr{C} y\right)}\right|=\left|\left(x_{n}-x, \mathscr{C} y\right)\right| \rightarrow 0\right.$ for each $y$ in $l^{2}$ since $z_{n} \rightharpoonup z$ if and only if $\left(z_{n}, y\right) \rightarrow(z, y)$ for each $y$ in $l^{2}$. So $\mathscr{C} x_{n} \rightharpoonup \mathscr{C} x$. Since $\mathscr{A}$ is completely continuous, $\mathscr{A} \mathscr{C}_{n} \rightarrow \mathscr{A} \mathscr{C} x$. Therefore,
$\left\|\overline{\mathscr{A}} x_{n}-\overline{\mathscr{A}} x\right\|=\left\|\mathscr{C} \mathscr{A} \mathscr{C} x_{n}-\mathscr{C} \mathscr{A} \mathscr{C} x\right\|=\left\|\mathscr{C}\left(\mathscr{A} \mathscr{C} x_{n}-\mathscr{A} \mathscr{C} x\right)\right\|=$

$$
\left\|\mathscr{A} \mathscr{C} x_{n}-\mathscr{A} \mathscr{C} x\right\| \rightarrow 0
$$

so $\overline{\mathscr{A}}$ is completely continuous.
Let $\mathscr{A}^{\mathbf{T}}$ denote the transpose of $\mathscr{A}$, as above, and let $A^{T}$ denote the transpose of matrix $A$ relative to a given basis. Since $\mathscr{A}=\mathscr{U} \mathscr{P}=\mathscr{Q} \mathscr{U}$, then $\mathscr{A}^{\mathbf{T}}=$ $\mathscr{P}^{\mathbf{T}} \mathscr{U}^{\mathbf{T}}=\mathscr{U}^{\mathbf{T}} \mathscr{Q}^{\mathbf{T}}$, and so $A^{T}=P^{T} U^{T}=U^{T} Q^{T}$, where $\mathscr{U}^{\mathbf{T}}$ and $U^{T}$ are partial isometries, $\mathscr{P}^{\mathbf{T}}, \mathscr{Q}^{\mathbf{T}}, P^{T}$ and $Q^{T}$ Hermitian.
3. The T-symmetric case. Let $\mathscr{A}$ be a completely continuous operator in $l^{2}$ such that relative to some orthonormal basis $\left\{e_{i}\right\},\left(\mathscr{A} e_{j}, e_{i}\right)=\left(\mathscr{A}^{\mathbf{T}} e_{j}, e_{i}\right)$, i.e., $a_{i j}=a_{j i}$ for $A$ determined by $\mathscr{A}$ relative to this basis. (That such operators and matrices do exist and non-trivially is evident if one takes a completely continuous operator $\mathscr{B}$, and forms $\mathscr{B}+\mathscr{B}^{\mathbf{T}}$ which is in $l^{2}$ and completely continuous, since $\mathscr{B}^{\mathbf{T}}$ is such.) Such an operator $\mathscr{A}$ for which the above is true will be called T-symmetric and denoted by $\mathscr{A}=\mathscr{A}^{\mathbf{T}}$.

The following analog for the finite case will be shown:
Theorem 1. If $A$ is the matrix, relative to an orthonormal basis, of a completely continuous operator $\mathscr{A}=\mathscr{A}^{\mathbf{T}}$, i.e. such that $A=A^{T}$, there is a unitary matrix $U$ such that $U A U^{T}=D$ is a real diagonal matrix.

If $\mathscr{A}=\mathscr{A}^{\mathbf{T}}$, then from the above it follows that $A=U P=A^{T}=U^{T} Q^{T}$ where $P=P^{C T}$ (where the latter denotes the complex conjugate-transpose of $P)$ and $Q^{T}=\left(Q^{T}\right)^{C T}=Q^{C}$. This means that $P=Q^{T}$; for $\mathscr{P}_{2}=\mathscr{A}^{*} \mathscr{A}=$ $\left(\mathscr{A}^{*}\right)^{\mathbf{T}} \mathscr{A}^{\mathbf{T}}=\left(\mathscr{A} \mathscr{A}^{*}\right)^{\mathbf{T}}=\left(\mathscr{Q}^{2}\right)^{\mathbf{T}}=\left(\mathscr{Q}^{\mathbf{T}}\right)^{2}$ and since $\mathscr{P}$ and $Q^{\mathbf{T}}$ are positive operators, it follows that $\mathscr{P}=\mathscr{Q}^{\mathbf{T}}$ and $P=Q^{T}$.

Therefore $A=U P=Q U=P^{T} U$. Since $\mathscr{A}$ is completely continuous, $\mathscr{P}$ and $\mathscr{Q}$ are completely continuous Hermitian operators so there exist (infinite) unitary matrices $W$ and $V$ such that $W P W^{C T}=D$ and $V Q V^{C T}=D_{1}$ are real diagonal matrices. In particular assume $D$ is diagonal with real diagonal elements $\lambda_{i}$ where $\lim \lambda_{i}=0$ as $i$ becomes infinite. Then it follows that $W^{C} A W^{C T}=W^{C} U W^{C T} W P W^{C T}=W^{C} P^{T} W^{T} W^{C} U W^{C T}$ or, if $X=W^{C} U W^{C T}$, $X D=D X$ and $X$ is such that $U$ is the matrix of a partial isometry and $W^{C}$ and $W^{C T}$ are unitary. Since $\mathscr{U}$ is a partial isometry, $\mathscr{U} * \mathscr{U}=K$ is such that $\mathscr{K}^{2}=\mathscr{K}$ is Hermitian (see [2, p. 153], for example) which means that $U^{C T} U=\left(U^{C T} U\right)^{2}$ so that

$$
\begin{aligned}
\left(W U^{C T} W^{T}\right)\left(W^{C} U W^{C T}\right) & =\left(W U^{C T} W^{T}\right)\left(W^{C} U W^{C T}\right)\left(W U^{C T} W^{T}\right)\left(W^{c} U W^{C T}\right) \\
& =\left(W U^{C T} W^{T} W^{c} U W^{C T}\right)^{2}
\end{aligned}
$$

or $X^{C T} X=\left(X^{C T} X\right)^{2}$. There are two possible cases. (a) If no $\lambda_{i}=0$ in $D$, then since $\lim _{i \rightarrow \infty} \lambda_{i}=0$, there can be only a finite number $l$ of the $x_{i}$ such that $\lambda_{1}=\lambda_{2}=\ldots \lambda_{l}$ is the $\lambda_{i}$ of largest value. Since $X$ commutes with $D, X=$ $X_{1} \dot{+} X^{\prime}$ where $X_{1}$ is of finite dimension $l$. Then $X^{c T} X=\left(X^{C T} X\right)^{2}$ which is Hermitian. (It follows that the roots of $X_{1}{ }^{C T} X_{1}$ are either 1,0 or both.) From $U^{C T} U P=P$ follows $W U^{C T} W^{T} W^{C} U W^{C T} W P W^{C T}=W^{C T} P W$ or $X^{C T} X D=$ $D$. This means that $X_{1}{ }^{C T} X_{1} \lambda_{1}=\lambda_{1} I_{1}$ where $\lambda_{1} \neq 0$ and so $X_{1}{ }^{C T} X_{1}=I_{1}$, where $I_{1}$ is a suitably finite-dimensional identity matrix, so that $X_{1}$ is unitary. $X^{\prime}$ can now be treated in the same way and by such successive steps involving $\lambda_{i}$ of like value, $X=X_{1} \dot{+} X_{2} \dot{+} X_{3} \dot{+} \ldots$ where the latter is a direct sum of the $X_{i}$ and conformable to the blocks of like diagonal elements in $D$ and where each such $X_{i}$ has the properties of $X_{1}$ above. (b) If some $\lambda_{i}=0$ (either finite or infinite in number) by following the stepwise process described above $D$ can become a direct sum of such $\lambda_{i} I_{i}$ blocks, $\lambda_{i} \neq 0$, interspersed with direct sums of 0 's. If $X=\left(x_{s t}\right)$ and if 0 appears in the $i-i$ and $j$ - $j$ positions of $D$ for $i \neq j$ then $x_{i i}, x_{i j}, x_{j i}$, and $x_{j j}$ are not necessarily 0 . (The matrix composed of all such $x_{i j}$ is the matrix of a partial isometry.) But $X$ is such that $W^{C} A W^{C T}=$ $D X$ is a direct sum of $\lambda_{i} X_{i}, \lambda_{i} \neq 0$, interspersed with 0 's along the diagonal. If for some $k$ all $\lambda_{i}=0$ for $i>k$, then $D$ may be taken to be in the form $\lambda_{1} I_{1}+\lambda_{2} I_{2} \dot{+} \ldots \dot{+} \lambda_{t-1} I_{t-1} \dot{+} 0$ (where 0 is an infinite matrix of 0 's) with the $\lambda_{i} \neq 0$. In this case $W^{C} A W^{C T}=W^{C} U P W^{C T}=W^{C} U W^{C T} W P W^{C T}=$ $X D=\lambda_{1} X_{1} \dot{+} \lambda_{2} X_{2} \dot{+} \ldots \dot{+} \lambda_{t-1} X_{t-1} \dot{+} 0$ where the latter is an infinite matrix of zeros.

From $A=U P=Q U=A^{T}=U^{T} Q^{T}=U^{T} P$ or $A=U P=U^{T} P$ follows $W^{C} A W^{C T}=W^{C} U W^{C T} W P W^{C T}=W^{C} U^{T} W^{C T} W P W^{C T}=X D=X^{T} D$. This means that each $X_{i}$ corresponding to $\lambda_{i} \neq 0$ is such that $\lambda_{i} X_{i}=\lambda_{i} X^{T}$ or that
$X_{i}=X_{i}{ }^{T}$ where $X_{i}$ is unitary. So for each $X_{i}$, for which $\lambda_{i} \neq 0$, there exists a real orthogonal matrix $W_{i}$ such that $W_{i} X_{i} W_{i}{ }^{T}$ is complex diagonal and unitary. (For if $M=M_{1}+i M_{2}, M_{1}$ and $M_{2}$ real, is unitary and symmetric, $M_{1}$ and $M_{2}$ are commutative real symmetric matrices which can be diagonalized by the same real orthogonal matrix.) So there is a complex unitary matrix $T$ (a direct sum of $W_{i}$ and 1 's corresponding to 0 's in $D$ ) such that $T A T^{T}$ is a diagonal matrix with diagonal elements of the form $\lambda \mu, \lambda$ real (including 0 ) and approaching 0 as one moves along the diagonal and $|\mu|=1$. If $S$ is the diagonal matrix with diagonal elements $\mu^{-1 / 2}$ in corresponding position, when $\lambda \neq 0$ and 1 when $\lambda=0, S$ is unitary and $S T A T^{T} S^{T}$ is a real diagonal matrix with diagonal elements $\lambda_{i}$ where $\lambda_{i} \rightarrow 0$ as $i \rightarrow \infty$.
4. The T-skew symmetric case. Let $\mathscr{A}$ be a completely continuous operator in $l^{2}$ such that relative to some orthonormal basis $\left\{e_{i}\right\},\left(\mathscr{A} e_{j}, e_{i}\right)=$ $-\left(\mathscr{A}^{\mathbf{T}} e_{j}, e_{i}\right)$, i.e., $a_{i j}=-a_{j i}$ for $A=\left(a_{i j}\right)$ determined by $\mathscr{A}$ relative to this basis. (That such operators and matrices do exist is evident if one takes a completely continuous operator $\mathscr{B}$ as before and forms $\mathscr{B}-\mathscr{B}^{\mathbf{T}}$ which is in $l^{2}$ and completely continuous.) Such an operator will be called T-skewsymmetric and denoted by $\mathscr{A}^{\mathbf{T}}=-\mathscr{A}$.

The following analog for the finite case is to be shown:
Theorem 2. If $A$ is the matrix, relative to an orthonormal basis, of a completely continuous operator $\mathscr{A}=-\mathscr{A}^{\mathbf{T}}$, i.e. such that $A=-A^{T}$, there is a unitary matrix $U$ such that $U A U^{T}$ is a direct sum of 0 's and of matrices of the form

$$
\left[\begin{array}{cc}
0 & \lambda_{i} \\
-\lambda_{i} & 0
\end{array}\right]
$$

where $\lambda_{i}$ is real and $\lim \lambda_{i}=0$ as $i \rightarrow \infty$.
The proof parallels that as found in the reference [9] given above. If $\mathscr{A}=-\mathscr{A}^{\mathbf{T}}$, then $\mathscr{A}=\mathscr{U} \mathscr{P}=\mathscr{Q}^{\mathscr{U}}=-\mathscr{A}^{\mathbf{T}}=-\mathscr{P}^{\mathbf{T}} \mathscr{U}^{\mathbf{T}}=-\mathscr{U}^{\mathbf{T}} \mathscr{Q}^{\mathbf{T}}$ which means $A=U P=Q U=-P^{T} U^{T}=-U^{T} Q^{T}$. As before, $P^{2}=\left(Q^{T}\right)^{2}$ from which $P=Q^{T}$. $\left(P=-Q^{T}\right.$ would not be possible since $Q^{T}$ is positive and $P$ must also be positive.) The proof proceeds, in the reference given, by considering the non-singular and singular case. Here the proof is along lines similar to the T-symmetric case as follows. Let $W P W^{C T}=D$ be real diagonal with diagonal elements $\lambda_{i}$ where $W$ is unitary. From $A=U P=Q U=P^{T} U$ it follows, as above, that $X=W^{C} U W^{C T}$ is such that $X D=D X$, and if no $\lambda_{i}=0$, $X$ is a direct sum of $X_{1}, X_{2}, \ldots$, each finite dimensional; and if some $\lambda_{i}=0$ then $D X$ is a direct sum of finite dimensional $\lambda_{i} X_{i}$ interspersed with direct sums of 0 's. As before, the finite-dimensional $X_{i}$ are unitary and from $A=$ $U P=-U^{T} P$, it follows that $X D=-X^{T} D$ and so each finite dimensional $X_{i}=-X_{i}{ }^{T}$. By [9, Lemma 1, p. 438], if $X$ is a (finite-dimensional) complex, unitary, skew-symmetric matrix, there exists a complex unitary $V$ such that
$V X V^{T}=E$ is a direct sum of $2 \times 2$ matrices of the form

$$
\left[\begin{array}{rr}
0 & 1 \\
-1 & 0
\end{array}\right] .
$$

An inspection of the proof of that lemma reveals that the $V$ described is actually a product of matrices $S T$ where $T$ is real orthogonal such that $T X T^{T}$ is a direct sum of $2 \times 2$ blocks of the form

$$
\left[\begin{array}{rr}
0 & \alpha  \tag{i}\\
-\alpha & 0
\end{array}\right]
$$

where $\alpha$ is non-zero complex and $\alpha \bar{\alpha}=1$. In the present case if $T_{i}$ is the real orthogonal matrix which performs this on the $X_{i}$, then if $T$ is the corresponding direct sum of 1 's (corresponding to 0 's in the diagonal of $D$ ) and of these $T_{i}, T W^{C} A W^{C T} T^{T}$ is a direct sum of 0 's and of $\lambda_{i} A_{i}, \lambda_{i} \neq 0$, where each $A_{i}$ is a direct sum of $2 \times 2$ matrices of the form (i). If $\alpha=e^{i \theta}$ and $S$ is an appropriate direct sum of 1 's and of $2 \times 2$ matrices of the form

$$
\left[\begin{array}{ll}
0 & \mathrm{e}^{-i \theta / 2} \\
-\mathrm{e}^{-i \theta / 2} & 0
\end{array}\right],
$$

then $S T W^{C} A W^{C T} T^{T} S^{T}$ is a direct sum of matrices of the form

$$
\left[\begin{array}{cc}
0 & \lambda_{i} \\
-\lambda_{i} & 0
\end{array}\right]
$$

where $\lambda_{i} \rightarrow 0$ as $i \rightarrow \infty$.
5. The quasi-normal case. Let $\mathscr{A}$ be a completely continuous operator. Then so are $\mathscr{A}_{\mathscr{A}^{*}}, \mathscr{A}^{*} \mathscr{A}$ and $\left(\mathscr{A}^{*} \mathscr{A}\right)^{\mathbf{T}}=\mathscr{A}^{\mathbf{T}}\left(\mathscr{A}^{*}\right)^{\mathbf{T}}=\mathscr{A}^{\mathbf{T}}\left(\mathscr{A}^{\mathbf{T}}\right)^{*}$. By definition, an operator $\mathscr{A}$ will be said to be quasi-normal if $\mathscr{A}_{\mathscr{A}^{*}}=\left(\mathscr{A}^{*} \mathscr{A}\right)^{\mathrm{T}}=$ $\mathscr{A}^{\mathbf{T}}\left(\mathscr{A}^{*}\right)^{\mathbf{T}}=\mathscr{A}^{\mathbf{T}} \overline{\mathscr{A}}$. (That such operators do exist may be seen as follows. Let $\mathscr{B}$ be an operator which, relative to some orthonormal basis, has an infinite matrix which is a direct sum of matrices of the form

$$
\left[\begin{array}{rr}
a_{i} & b_{i}  \tag{ii}\\
-b_{i} & a_{i}
\end{array}\right]
$$

where the $a_{i}$ and $b_{i}$ are non-negative real numbers and $\sum_{i=1}^{\infty}\left(a_{i}{ }^{2}+b_{i}{ }^{2}\right)<\infty$. Then $\mathscr{B}$ is a completely continuous operator (see [2, Exercise 1, p. 177]). Let $\mathscr{U}$ be a unitary operator, and so $\mathscr{U}^{\mathbf{T}}$ is also unitary. Then $\mathscr{U} \mathscr{B} \mathscr{U}^{\mathbf{T}}$ is completely continuous and meets, non-trivially, the above definition, as can be directly verified.)

The following theorem results:
Theorem 3. If $A$ is the matrix, relative to an orthonormal basis, of a completely continuous quasi-normal operator $\mathscr{A}$, i.e., $\mathscr{A}_{\mathscr{A}^{*}}=\mathscr{A}^{\mathbf{T}}\left(\mathscr{A}^{*}\right)^{\mathbf{T}}$, there is a unitary matrix $U$ such that $U A U^{T}$ is a direct sum of matrices of the form (ii) above,
where $a_{i}$ and $b_{i}$ are real and $a_{i} \rightarrow 0$ and $b_{i} \rightarrow 0$ as $i$ becomes infinite, and of $1 \times 1$ real $c_{i}$ where $c_{i} \rightarrow 0$ as $i$ becomes infinite.

Let $\mathscr{A}$ be quasi-normal and completely continuous and let $\mathscr{A}=\mathscr{S}+\mathscr{T}$ where $\mathscr{S}=1 / 2\left(\mathscr{A}+\mathscr{A}^{\mathbf{T}}\right)$ and $T=1 / 2\left(\mathscr{A}-\mathscr{A}^{\mathbf{T}}\right)$ so that $\mathscr{S}=\mathscr{S}^{\mathbf{T}}$ and $\mathscr{T}=-\mathscr{T}^{\mathbf{T}}$. The proof proceeds as in the finite case as follows. Since $\mathscr{A}_{\mathscr{A}}{ }^{*}=$ $\mathscr{A}^{\mathbf{T}}\left(\mathscr{A}^{*}\right)^{\mathbf{T}}$, it follows that $(\mathscr{S}+\mathscr{T})\left(\mathscr{S}^{*}+\mathscr{T}^{*}\right)=\left(\mathscr{S}^{\mathbf{T}}+\mathscr{T}^{\mathbf{T}}\right)\left(\mathscr{S}^{*}+\mathscr{T}^{*}\right)^{\mathbf{T}}$ or

$$
\begin{aligned}
(\mathscr{S}+\mathscr{T})\left(\mathscr{S}^{*}+\mathscr{T}^{*}\right) & =(\mathscr{S}-\mathscr{T})\left(\left[\mathscr{S}^{\mathbf{T}}\right]^{*}+\left[\mathscr{T}^{\mathbf{T}}\right]^{*}\right) \\
& =(\mathscr{S}-\mathscr{T})\left(\mathscr{S}^{*}-\mathscr{T}^{*}\right)
\end{aligned}
$$

so $\mathscr{S} \mathscr{S}^{*}+\mathscr{S} \mathscr{T}^{*}+\mathscr{T} \mathscr{S}^{*}+\mathscr{T} \mathscr{T}^{*}=\mathscr{S} \mathscr{S}^{*}-\mathscr{S T}^{*}-\mathscr{T} \mathscr{S}^{*}+\mathscr{T} \mathscr{T}^{*}$ so $\mathscr{S} \mathscr{T}^{*}=-\mathscr{T} \mathscr{S}^{*}$. Relative to the given basis, the corresponding matrix product becomes $S T^{C T}=-T S^{C T}$ or $-S T^{C}=-T S^{C}$ or $S T^{C}=T S^{C}$. By Theorem 1 there exists a unitary matrix $U$ such that $U S U^{T}=D$ is a real diagonal matrix of the form described there. If $U T U^{T}=M$, then $M D=D M^{C}$. If the diagonal elements of $D$ are $d_{i}$, and if $M=\left(t_{i j}\right)$, then $t_{i j} d_{j}=d_{i} \bar{t}_{i j}$ where $t_{j i}=-t_{i j}$. Three possibilities may occur: if $d_{j}=d_{i} \neq 0$, then $t_{i j}$ is real; if $d_{j}=d_{i}=0, t_{i j}$ is arbitrary (though $M=-M^{T}$ still holds); and if $d_{j} \neq d_{i}$, then $t_{i j}=0$, for if $t_{i j}=a+i b$, then $(a+i b) d_{j}=d_{i}(a-i b)$ and $a\left(d_{j}-d_{i}\right)=0$ implies $a=0$ and $b\left(d_{i}+d_{j}\right)=0$ implies $d_{i}=-d_{j}$ (which is not possible since the $d_{i}$ are real and non-negative and $d_{j} \neq d_{i}$ ) or $b=0$ so $t_{i j}=0$.

So if $U S U^{T}=D$ then the following two cases arise: (a) If no $d_{i}=0$, the $d_{i}$ may be arranged so $d_{i} \geqq d_{i+1}$ for $i=1,2,3, \ldots$ and relabelled $d_{1}, d_{2}$, $d_{3}, \ldots$ with $d_{i} \neq d_{j}$ when $i \neq j$. Then $U T U^{T}=T_{1} \dot{+} T_{2} \dot{+} \ldots$ is a direct sum conformable to $D$ where the $T_{i}$ are real, finite dimensional, and infinite in number and $T_{i}=-T_{i}{ }^{T}$; for each such $T_{i}$ there exists a real orthogonal $V_{i}$ such that $V_{i} T_{i} V_{i}{ }^{T}$ is a direct sum of 0 's and of matrices of the form

$$
\left[\begin{array}{rr}
0 & b \\
-b & 0
\end{array}\right]
$$

where $b$ is real (see [1, p. 65] for the real even dimension skew-symmetric matrix case). (b) If some $d_{i}=0$ (either finite or infinite in number) and if $U T U^{T}=\left(t_{i j}\right)$, when 0 is in the $i-i$ and $j-j$ position for $i \neq j$, then $t_{i i}, t_{i j}, t_{j i}$, and $t_{j j}$ are not necessarily 0 but the matrix $T^{\prime}$ composed of all such $t_{r s}$ taken in order (which could be finite or infinite and distributed throughout $U T U^{T}$ ) is complex skew-symmetric. For such a $T^{\prime}$, finite or infinite, there exists a complex unitary $W$ such that $W T^{\prime} W^{T}$ is the direct sum described in Theorem 1 of [ $\mathbf{9}]$ if $T^{\prime}$ is finite, or such that $W T^{\prime} W^{T}$ is the direct sum described in Theorem 2 above if $T^{\prime}$ is infinite.

To examine each of these cases consider the following representative sample as a guide in which $U A U^{T}=U S U^{T}+U T U^{T}=$

where the $d_{i}$ are non-zero and $d_{i}>d_{j}$ for $i<j$.
If the number of 0 's in the diagonal of $U S U^{T}$ is finite, so is the number of $T_{i j}$, and a simple rearrangement of the $T_{i j}$ into a single complex skew-symmetric block in the given order is possible under a real orthogonal transformation and this block will correspond to a diagonal of 0 's in $U S U^{T}$ while retaining the diagonal form in the latter. If $V$ is a direct sum of real $V_{i}$ acting on the $T_{i}$ as in (a) and of the appropriate unitary matrix acting on $\left(T_{i j}\right)$ of Theorem 1 of [9], VUA $U^{T} V^{T}$ gives the form desired.

If the number of diagonal 0 's in $U S U^{T}$ is infinite so that $T^{\prime}=\left(T_{i j}\right)$ is infinite, by Theorem 2 in this article there is a unitary matrix $W$ such that $W T^{\prime} W^{T}=F$ is a direct sum of the form of Theorem 2. Let $W=\left(W_{i j}\right)$ be sectioned according to the sectioning of $T^{\prime}=\left(T_{i j}\right)$. Let $V$ be an infinite matrix formed as follows: in $U T U^{T}$ let each $T_{i}$ be replaced by the real orthogonal $V_{i}$ as described in (a) above, and let each $T_{i j}$ be replaced by $W_{i j}$. Then $V U S U^{T} V^{T}=U S U^{T}$, and $V U T U^{T} V^{T}$ has a form in which each $T_{i}$ in $U T U^{T}$ is replaced by the form $F_{i}$ described in ( $a$ ) and each $T_{i j}$ in $U T U^{T}$ is replaced by $F_{i j}$ where $F=\left(F_{i j}\right)$ is sectioned as $\left(T_{i j}\right)$ is. In the sample case above $V U T U^{T} V^{T}$ has the form

$$
\left[\begin{array}{lllllllll}
F_{1} & 0 & & & & & \\
0 & F_{2} & & & & & \\
& & F_{11} & 0 & F_{12} & \cdot & \cdot & \cdot \\
& & 0 & F_{4} & 0 & & & \\
& & -F_{12}^{T} & 0 & F_{22} & \cdot & \cdot & \cdot \\
& & \cdot & & \cdot & & & \\
& & \cdot & & \cdot & & &
\end{array}\right] .
$$

Because of the form of $F$ either $F_{1 j}$, all $j \neq 1$, in the same row as $F_{11}$ are 0 or not. But if not, because of the direct-sum form of $F$, at most one of them, namely $F_{12}$, can be different from 0 and if so, the only nonzero element $a$ in an $F_{12}$ must occur in the lower left corner position (and in the upper right corner position of $-F_{12}{ }^{T}$ ). A suitable interchange of the row and column containing $-a$ and $a$ and of $F_{4}$ can bring the upper left block of $V U T U^{T} V^{T}$ into the desired form without altering the diagonal form of $U S U^{T}$. Repeating this process with each subsequent $F_{i i}$ as needed brings the matrix $A$ into the desired form under the required transformation.

In the case of a finite $n \times n$ matrix with complex elements it is true that every matrix is similar to its transpose. Here, since $\mathscr{A}^{\mathbf{T}}=\mathscr{C} \mathscr{A}^{*} * \mathscr{C}$, it is true if $A$ has a polar form $\mathscr{A}=\mathscr{U} \mathscr{P}, \mathscr{A}^{\mathbf{T}}=\mathscr{C} \mathscr{P} \mathscr{U}^{*} \mathscr{C}=\mathscr{C} \mathscr{U}^{*} \mathscr{U} \mathscr{P} \mathscr{U}^{*} \mathscr{C}=$ $\mathscr{C} \mathscr{U}^{*} \mathscr{A} \mathscr{U}^{*} \mathscr{C}$ but this provides no matrix connection between $A^{T}$ and $A$. For the case in which $\mathscr{A}$ is quasi-normal, the following observation holds. Let $U A U^{T}=F$ be the direct sum as described in the preceding theorem. Then $U A^{T} U^{T}=F^{T}$. If $W$ is an appropriate direct sum of $2 \times 2$ matrices

$$
\left[\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right]
$$

and 1's, $W F W^{T}=F^{T}$ from which $U^{C T} W U A U^{T} W^{T} U^{C}=A^{T}$ or $V A V^{T}=$ $A^{T}$ where $V=U^{C T} W U$ is unitary. Therefore, a linear operator $\mathscr{V}$ on $l^{2}$ does exist so that $\mathscr{V} \mathscr{A}^{V} \mathscr{V}^{\mathbf{T}}=\mathscr{A}^{\mathbf{T}}$.

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