# ON DIFFERENTIAL EQUATIONS OF VON GEHLEN AND ROAN

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**Abstract.** Polynomials appearing in the description of ground states of superintegrable chiral Potts models are shown to satisfy a special class of generalised hypergeometric differential equations after a simple modification. This proves a conjecture of von-Gehlen and Roan.

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**1. Introduction.** Let  $N \ge 2$  be a positive integer and  $\omega = \exp(2\pi i/N)$  a primitive *N*th root of unity. Take a pair of linear operators  $X, Z \in \operatorname{End}(\mathbb{C}^N)$  that satisfies the following commutation relation and the normalisation condition:

$$ZX = \omega XZ, \quad X^N = Z^N = id.$$

The superintegrable chiral Potts Hamiltonian (see for example [1], [2]) on a chain of length L is a linear operator on  $(\mathbb{C}^N)^{\otimes L}$  defined by

$$H(k') = -\sum_{l=1}^{L} \sum_{n=1}^{N-1} \frac{2}{1-\omega^{-n}} \left( X_l^n + k' Z_l^n Z_{l+1}^{N-n} \right),$$

where k' is a real parameter and  $X_l$  denotes the operator acting on the *l*th component as X and for other components as identity.

Note that if we write

$$H(k') = H_0 + k'H_1,$$

 $H_0$  and  $H_1$  satisfy the Dolan–Grady relation

$$[H_i, [H_i, [H_i, H_j]]] = 4N^2[H_i, H_j], \quad i, j = 0, 1$$

and give a representation of the so-called Onsager algebra, which can also be viewed as either a deformation of the nilpotent part of the affine Lie algebra of type  $A_1^{(1)}$  or a quotient of the loop algebra of  $\mathfrak{sl}_2$ .

The principal problem in statistical mechanics defined by this operator is to find eigenvalues and eigenvectors. Bethe Ansatz affords us a method for such purpose.

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It is known that ground state eigenvalues and eigenvectors are described by zeroes of polynomials  $F_i$  (cf. [1, 2, 3, 4, 6]) defined by the relation

$$\left(\frac{t^N-1}{t-1}\right)^L = \sum_{j=0}^{N-1} t^j F_{j+1}(s), \qquad s = t^N.$$

In [3, 4, 6] von Gehlen and Roan derived a system of first-order differential equation for  $F_j$ .

The vector of polynomials

$$F = {}^t (F_1, F_2, \ldots, F_N)$$

satisfy

$$Ns(s-1)\frac{dF}{ds} = BF,$$

$$B = \begin{pmatrix} d_0 & -Ls & \cdots & -Ls \\ -L & d_1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & -Ls \\ -L & \cdots & -L & d_{N-1} \end{pmatrix},$$

$$d_j = L(N-1)s - j(s-1).$$

When N = 2 (the Ising case) each polynomial satisfies Gauß hypergeometric differential equation. Further by a suitable change of variable the polynomials turn out to be Chebyshev polynomials, and this was convenient for the description of eigenvalues.

Proceeding further they also derived third-order differential equations for the case N = 3. One of them takes the following form:

$$27s^{2}(s-1)^{2}F_{1}^{'''} - 27s(s-1)((2L-4)s+2)F_{1}^{''} + 3(3L^{2}s(4s-1) - 3Ls(10s-7) + 2(s-1)(10s-1))F_{1}^{'} - (L-1)(L(L(8s+1) - 4(s-1))F_{1} = 0.$$

These equations have regular singular points only at  $s = 0, 1, \infty$ , although this in not explicitly mentioned in [3, 4, 6]. They also studied the zeroes of polynomials in the case of N = 3 numerically.

Based on such calculations they conjectured that each of  $F_j$  satisfies an *N*th-order ordinary differential equations of the form that follows.

Conjecture 1.

$$N^{N}s^{N-1}(s-1)^{N-1}\frac{d^{N}F_{j}}{ds^{N}} + \sum_{k=1}^{N-1}N^{k}s^{k-1}(s-1)^{k-1}D_{jk}(s)\frac{d^{k}F_{j}}{ds^{k}} + D_{j0}(s)F_{j} = 0$$

where  $D_{jk}$  are polynomials in *s*.

In this paper we show that after a simple transformation the scalar differential equations in question are generalised hypergeometric differential equations, which form a special class of Fuchsian differential equations which have regular singular points only at three points 0, 1,  $\infty$  and no accessory parameters (rigid system).

We find that defining G by  $G(s) = (s - 1)^{-L}F(s)$  the differential equations for  $G_j$  become a special kind of generalised hypergeometric differential equations.

For a given generalised differential equation, there corresponds a system of firstorder differential equations of Okuba type. The explicit relationship is given for example in [5]. However the converse direction seems not to be known. In fact as we will see in our case each  $G_j$  satisfies different generalised differential equations.

The detailed proof will appear elsewhere.

**2.** A normal form of differential equations. The differential equations for *G* takes the following form:

$$N\frac{dG}{ds} = \left(-\frac{L}{s-1}A_1 + \frac{1}{s}A_0\right)G,$$

$$A_1 = \begin{pmatrix} 1 & \cdots & 1\\ \vdots & \ddots & \vdots\\ 1 & \cdots & 1 \end{pmatrix}, \quad A_0 = \begin{pmatrix} 0 & 0 & \cdots & 0\\ L & -1 & \ddots & \vdots\\ \vdots & \ddots & \ddots & 0\\ L & \cdots & L & -N+1 \end{pmatrix}$$

First we look for an *N*th-order matrix *P* and numbers  $a_j$ ,  $b_j$  which satisfy the following relations:

$$\frac{1}{N}LPA_{1} = \begin{pmatrix} 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \\ a_{0} & a_{1} - b_{1} \cdots & a_{N-2} - b_{N-2} & a_{N-1} - b_{N-1} \end{pmatrix} P, \quad (1)$$

$$\frac{1}{N}PA_{0} = \begin{pmatrix} 0 & 1 & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ & \ddots & \ddots & \ddots & \vdots \\ & & \ddots & 0 \\ 0 & & \cdots & 0 & 1 \\ 0 & -b_{1} & \cdots & -b_{N-2} & -b_{N-1} \end{pmatrix} P. \quad (2)$$

If we can find such non-singular matrix P, then the first component  $(PG)_1$  of PG is annhilated by the generalised hypergeometric differential operator with the parameters  $a_j, b_j$ :

$$s\left(\sum_{j=0}^{N}a_{j}\vartheta^{j}\right) - \sum_{j=1}^{N}b_{j}\vartheta^{j}, \quad \vartheta = s\frac{d}{ds}, \quad a_{N} = 1, \ b_{N} = 1.$$
(3)

Factorising as

$$\sum_{j=0}^{N} a_j \vartheta^j = \prod_{j=1}^{N} (\vartheta + \alpha_j), \tag{4}$$

$$\sum_{j=1}^{N} b_j \vartheta^j = \vartheta \prod_{j=1}^{N-1} (\vartheta + \beta_j - 1),$$
(5)

we have another form of generalised hypergeometric differential operator.

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# 3. Transformation matrix. Define

$$c_i = (r(N, i-1, x) - s(N, i-1))/(-N)^{N-i+1}, \quad f_i = -s(N, i-1)/(-N)^{N-i+1}$$

where r(N, i, x) is defined by

$$\sum_{i=0}^{N} r(N, i, x)t^{i} = \prod_{j=1}^{N} (t + x - j + 1)$$

and s(N, i) denotes the Stirling number of the first kind.

We set

$$p_{ij} = (-1)^{N+j} \sum_{s=0}^{j-1} {\binom{N-L-1}{s} \binom{L}{j-1-s} (L+s)^{i-1} / (-N)^{i-1}}$$

and consider the square matrix P of order N with its (i, j) entries  $p_{ij}$ .

**PROPOSITION 1.** The matrix P satisfies

$$\frac{L}{N}P\begin{pmatrix}1 & \cdots & 1\\ \vdots & \ddots & \vdots\\ 1 & \cdots & 1\end{pmatrix} = \begin{pmatrix}0 & \cdots & 0\\ \vdots & & \vdots\\ 0 & \cdots & 0\\ c_1 & \cdots & c_N\end{pmatrix}P,$$
$$\frac{1}{N}P\begin{pmatrix}0 & 0 & \cdots & 0\\ L & -1 & \ddots & \vdots\\ \vdots & \ddots & \ddots & 0\\ L & \cdots & L & -N+1\end{pmatrix} = \begin{pmatrix}0 & 1 & 0 & \cdots & 0\\ \vdots & \ddots & \ddots & \ddots & \vdots\\ & & \ddots & 0\\ 0 & & \cdots & 0 & 1\\ 0 & f_2 & \cdots & f_{N-1} & f_N\end{pmatrix}P.$$

**4.** Inverse matrix. Define  $q_{ij}$  by the relation

$$\sum_{j=0}^{N-1} q_{i,j+1} t^j = \prod_{k=0}^{i-2} (t-L-k) \prod_{k=i}^{N-1} (t-k).$$

The matrix Q with entries  $(-N)^{j-1}q_{ij}$  satisfies the relation

$$QP = \prod_{k=1}^{N} (-L+k)I_N,$$

where  $I_N$  is the identity matrix of order N.

5. Scalar differential operator. Assume L > N. Then using Proposition 1 we see that the entries in (1), (2) are given by

$$b_j = -(-N)^{-N+j-1} s(N, j-1),$$
  

$$a_j = (-N)^{-N+j-1} N^{-N+j-1} r(N, j-1, -L).$$

The corresponding Nth-order differential operator (3) is expressed as

$$s\prod_{k=1}^{N}\left(\vartheta+\frac{L+k-1}{N}\right)-\prod_{k=1}^{N}\left(\vartheta+\frac{k-1}{N}\right).$$

Defining H = PG, we see that the first component  $H_1$  is annihilated by the above operator.

Further using the inverse matrix Q components of G are given as

$$G_{i} = \sum_{j=1}^{N} (-N)^{j-1} q_{ij} H_{j} / \prod_{k=1}^{N} (k-L)$$
  
=  $(-1)^{N-1} \prod_{k=0}^{i-2} (N\vartheta + L + k) \prod_{k=i}^{n-1} (N\vartheta + k) H_{1}.$ 

Defining

$$L_{i} = s \prod_{k=1}^{n} (N\vartheta + L + i + k - 2) - \prod_{k=1}^{n} (N\vartheta + i - k)$$

and using

$$\vartheta s = s(\vartheta + 1),$$

we have the following.

THEOREM 1.

$$L_i G_i = 0, \quad i = 1, \dots, N.$$

Rewriting these differential equations those for  $F_j$  and assuming that L is a positive integer, we proved the conjecture of von Gehlen and Roan.

6. Power series solutions at s = 0. Here we assume that L is a positive integer. Let us consider generalised hypergeometric series

$$F\begin{pmatrix} \alpha_1, & \alpha_2, & \cdots, & \alpha_n \\ \beta_1, & \beta_2, & \cdots, & \beta_{n-1}, & 1 \ \end{vmatrix} s \\ = \sum_{k=0}^{\infty} \frac{(\alpha_1)_k (\alpha_2)_k \cdots (\alpha_n)_k}{(\beta_1)_k (\beta_2)_k \cdots (\beta_{n-1})_k k!} s^k, \\ (\alpha)_k = \alpha(\alpha+1) \cdots (\alpha+k-1), \end{cases}$$

where  $\alpha_1, \ldots, \alpha_n, \beta_1, \ldots, \beta_{n-1}$  are parameters. The symbols  $(\alpha)_k$  are sometimes called Pochhammer symbol.

As is known solutions of generalised hypergeometric differential equation (3) around s = 0 are given by

$$F\begin{pmatrix} \alpha_1, & \alpha_2, & \cdots, & \alpha_n \\ \beta_1, & \beta_2, & \cdots, & \beta_{n-1}, & 1 \\ \end{vmatrix}$$

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with  $\alpha_1, \ldots, \alpha_N, \beta_1, \ldots, \beta_{N-1}$  defined by the relations (4), (5) and also

$$s^{1-\beta_{j}}F\begin{pmatrix}1+\alpha_{1}-\beta_{j}, & \cdots, & 1+\alpha_{j-1}-\beta_{j},\\ 1+\beta_{1}-\beta_{j}, & \cdots, & 1+\beta_{j-1}-\beta_{j}\\ 1+\alpha_{j}-\beta_{j}, & 1+\alpha_{j+1}-\beta_{j}, & \cdots, & 1+\alpha_{N}-\beta_{j}\\ 2-\beta_{j}, & 1+\beta_{j+1}-\beta_{j}, & \cdots, & 1+\beta_{N-1}-\beta_{j} & 1 \mid s\end{pmatrix},$$

for j = 1, ..., N - 1.

Therefore in our case the power series solutions of  $L_i f = 0$  are given by the following generalised hypergeometric series:

$$F\left(\begin{array}{cccc} \frac{L+i-1}{N}, & \frac{L+i}{N}, & \cdots, & \frac{L+N-1}{N}, & \cdots, & \frac{L+i+N-2}{N}\\ \frac{i}{N}, & \frac{i+1}{N}, & \cdots, & 1, & \cdots, & \frac{i+N-1}{N} \end{array} |s\right)$$

In our case since the parameters are special, the product of Pochhammer symbols in the coefficients are simplified. As a result we have the following series:

$$\sum_{k=0}^{\infty} \frac{(L+i-1)_{kN}}{(i)_{kN}} s^k.$$

We see that these are essentially a sum of binominal series in  $s^{1/N}$ :

$$\frac{1}{N} \sum_{j=0}^{N} f_i(\omega^j s^{1/N}), \quad \omega = \exp(2\pi i/N),$$
$$f_i(x) = \sum_{n=0}^{\infty} \frac{(L+i-1)_n}{(i)_n} x^n$$
$$= \frac{1}{\binom{-L}{i-1}} \left( x^{1-i}(1-x)^{-L} - x^{1-i} \sum_{k=0}^{i-2} \binom{-L}{k} (-x)^k \right)$$

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