Asymptotics applied to nonlinear boundary-value problems

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We announce results of Landesman-Lazer type for boundary-value problems for ordinary differential equations. Details will appear elsewhere.

We announce results for boundary-value problems. We look for solutions of

(1)
$$Lu(t) = g(u(t)) - f(t)$$

on $[0, \pi]$, where $f \in L^{\infty}[0, \pi]$, $g : R \to R$ is smooth, and Lu = a(t)u'' + b(t)u' + c(t)u is a regular differential operator with smooth coefficients incorporating either Dirichlet or periodic boundary conditions such that N(L), the kernel of L, is non-trivial. (In the case of periodic boundary conditions, we assume that a, b, and c are periodic.) Our results show the importance of asymptotics in the study of these problems.

Suppose that $h \in N(L) \setminus \{0\}$ and $k \in N(L^*)$ such that $\int_0^{\pi} k^2 = 1$, and let $R_1 = \{f \in L^{\infty}[0, \pi] : (1) \text{ has a solution}\}$.

1. Non self-adjoint problems

We assume periodic boundary conditions, and assume that $\int_0^{\pi} a^{-1}b \neq 0$ and h has a zero in $[0, \pi]$. (The other cases behave like the self-

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adjoint case.) Then h spans N(L). We let

$$E_{0} = \{ v \in L^{\infty}[0, \pi] : \langle v, k \rangle = 0 \},$$

where \langle , \rangle denotes the usual scalar product. Assume that lim $g(y) = I^{\pm}$ exist (and are finite) and that $I^{-} < g(y) < I^{+}$ for all $y \rightarrow \pm \infty$

$$y$$
 . Let

$$\begin{split} \mu_1 &= \int_{h>0} k \ , \ \mu_2 = \int_{h<0} k \ , \ \beta_1 = I^- \int_0^{\pi} k^+ + I^+ \int_0^{\pi} k^- \ , \\ \beta_2 &= I^+ \int_0^{\pi} k^+ + I^- \int_0^{\pi} k^- \ (\text{where } k^+ = \sup\{k, 0\} \text{ and } k^- = k - k^+) \ , \\ A_1 &= \{\alpha \in R : \left(I^+ \mu_1 + I^- \mu_2 - \alpha\right) \left(I^- \mu_1 + I^+ \mu_2 - \alpha\right) \leq 0\} \ , \ A_2 = \inf A_1 \ , \\ \text{and } A_3(v) &= \{\alpha \in R : v + \alpha k \in R_1\} \ . \ \text{We find that } A_1 \subset \{\beta_1, \beta_2\} \ (\text{since } h \text{ and } k \text{ have no common zero}). \ \text{There are examples where } A_2 = \emptyset \ (\text{that is, is empty}). \ \text{However, } A_1 \neq \emptyset \ \text{and } A_2 \neq \emptyset \ \text{if } L \ \text{is "nearly self-adjoint".} \end{split}$$

THEOREM 1. (i) If
$$v \in E_0$$
, then $A_3(v) \neq \emptyset$, and
 $A_2 \subseteq A_3(v) \subset (\beta_1, \beta_2)$.
(ii) $\beta_2 = \sup\{\alpha : \alpha \in A(v), v \in E_0\}$ and
 $\beta_1 = \inf\{\alpha : \alpha \in A(v), v \in E_0\}$.
(iii) $A_3(v) \setminus A_1$ is relatively closed in $(\beta_1, \beta_2) \setminus A_1$.
(iv) If $Lv = a(v) = f$, $\{f\}$ is bounded (in $L^{\infty}[0, \pi]$) and

(iv) If $Lu_n = g(u_n) - f_n$, $\{f_n\}$ is bounded (in $L^{\sim}[0, \pi]$) and $\langle u_n, h \rangle \to \infty$ as $n \to \infty$, then $\langle f_n, k \rangle \to I^+ \mu_1 + I^- \mu_2$ as $n \to \infty$. (A similar result holds if $\langle u_n, h \rangle \to -\infty$.)

The result is proved by standard arguments. Part (ii) is proved by constructing suitable u_n so that $g(u_n) - Lu_n$ has the required property. If $\sup\{|g'(y)| : y \in R\}$ is sufficiently small, it can be shown that $A_3(v)$ is an interval. A version of Theorem 1 holds much more generally.

(In the case of a multi-dimensional kernel, we define A_2 by requiring that an appropriate degree be non-zero.)

Theorem 1 suggests that, unlike the self-adjoint case, it is impossible to obtain a simple formula for R_1 . A natural question is whether $A_1 \subseteq A_3(v)$. In general this is false, since there is an example where $A_3(v) = A_2$ for some $v \in E_0$. We need the following lemma.

LEMMA 1. (i) If $v \in E_0$, there is a connected set T of solutions of

$$Lu = Pg(u) - v$$

(where $Pw = w - \langle w, k \rangle k$) such that $\{\langle u, h \rangle : u \in T\} = R$.

(ii) If $g'(y) \neq 0$ as $|y| \neq \infty$, then there is a K > 0 such that, for each α with $|\alpha| \geq K$, (2) has a unique solution $\alpha h + \Delta(\alpha)$ with $\langle \Delta(\alpha), h \rangle = 0$ and the mapping $\alpha \neq \Delta(\alpha)$ is smooth.

The first part is proved by a standard degree argument while the second is proved by combining the argument in the example in [1] with the implicit function theorem.

Assume now that $g'(y) \to 0$ as $|y| \to \infty$. By combining a study of the asymptotic behaviour of $t'(\alpha)$ as $|\alpha| \to \infty$ (where

$$t(\alpha) = \int_0^{\pi} g(\alpha h + \Delta(\alpha))k$$

with Theorem 1 (*iv*), we can obtain information on $A_3(v)$. For example, if $t'(\alpha) < 0$ for $|\alpha|$ large and $I^+\mu_1 + I^-\mu_2 > I^-\mu_1 + I^+\mu_2$, then $A_1 \subseteq \operatorname{int} A_3(v)$. We illustrate what can be obtained by giving the asymptotic formula for $t'(\alpha)$ as $\alpha + \infty$ in two cases. If $g'(y) \sim |y|^{-\beta}$ as $|y| \neq \infty$, where $\beta < 2$, then $t'(\alpha) \sim \alpha^{-\beta} \int_0^{\pi} |h|^{-\beta}hk$ as $\alpha \neq \infty$. If $y^{\beta}g'(y) \neq 0$ as $|y| \neq \infty$ for some s > 2 and h has two zeros x_0, x_1 in $[0, \pi]$, then

$$t'(\alpha) \sim \alpha^{-2} \left[\left[\tau_1 + \tau_2 \right] \int_{-\infty}^{\infty} g'(y) y dy - \left\{ s_1 \tau_1 + s_2 \tau_2 \right\} (I^+ - I^-) \right] .$$

Here, for i = 0, 1, $\tau_i = |h'(x_i)|^{-1}k(x_i)$ and s_i is the value at x_i of a solution of Lw = P(r-v), where $r(t) = I^+$ if $h(t) \ge 0$ and $r(t) = I^-$ otherwise. Note that, in the second case, the asymptotic formula depends on v, while in the first it does not.

We now briefly discuss the case where g is sublinear and $g(y) \operatorname{sgn} y \to \infty$ as $|y| \to \infty$. There is an example where g is odd and $g(y) = |y|^t \operatorname{sgn} y$ for |y| large (where $0 < t < \frac{1}{2}$) but $R_1 \neq L^{\infty}[0, \pi]$. This contrasts with the self-adjoint case (as in [2]). Sufficient conditions for R_1 to be $L^{\infty}[0, \pi]$ can easily be found if g has power growth.

Some of the above results can be extended to boundary-value problems for elliptic partial differential equations. It is more difficult to construct counter-examples for this case but it would appear unlikely that this case is better behaved than the case of ordinary differential equations considered above.

2. The case where $g(y) \rightarrow 0$ as $|y| \rightarrow \infty$ and L is self-adjoint

We consider the case where h(x) > 0 on $(0, \pi)$. We assume Dirichlet boundary conditions. (The other case is much easier.) We say that g is regular if $g'(y) \leq 0$ for |y| large.

THEOREM 2. Suppose that $yg(y) \ge 0$ for |y| large and either

(i) $\int_{0}^{\infty} g(y)ydy > 0$ and $\int_{-\infty}^{0} g(y)ydy > 0$ (where the integrals may be infinite), or

(ii) g is regular,
$$\int_{-\infty}^{0} g(y)ydy < 0$$
 and $\int_{0}^{\infty} g(y)ydy < 0$.

Then there exists $\varepsilon : E_0 \neq (0, \infty)$ such that $\alpha h + v \in \mathbb{R}_1$ if $|\alpha| \leq \varepsilon(v)$.

This is proved by using Lemma 1 (*i*) and by estimating $\int_0^{\pi} g(\alpha h + \omega(\alpha))h$ where $|\alpha|$ is large. (Here $\alpha h + \omega(\alpha) \in T$. Note that ω may be multivalued.) It is more convenient to study $\int_0^{\pi} \alpha^2 g(\alpha h + \omega(\alpha))h$. We use changes of variable of the form $u = \alpha h'(0)x$.

Theorem 2 still holds if L is not self-adjoint. Moreover, the result readily generalises to elliptic partial differential equations. (We need to assume that $y^2g(y) \neq 0$ in case (*ii*).) The methods in §4 of [3] can be used to deduce more precise information on R_1 .

The above method can be used if h has zeros in $(0, \pi)$. Theorem 2 holds in this case if $\int_{-\infty}^{\infty} g(y)ydy$ diverges. If $\int_{-\infty}^{\infty} g(y)ydy$ converges and g is regular, there exist $a, b \in R$ and a linear map $l: E_0 \neq R$ such that $v + \alpha h \in R_1$ for $|\alpha| \leq \varepsilon$ (where $\varepsilon > 0$) if

$$(a-l(v))(b-l(v)) > 0$$
. (For example, if $\int_{-\infty}^{\infty} g(y)dy = 0$ and

 $h'(0) = -h'(\pi)$, this last condition becomes $\int_{-\infty}^{\infty} g(y)ydy \neq 0$.) There is an example where (a-l(v))(b-l(v)) < 0 and $v \notin R_1$. Our methods can be used to obtain results for periodic boundary conditions and to obtain partial results for elliptic partial differential equations when h has interior zeros (mainly when N(L) is one-dimensional). This is much more complicated due to the greater variety of possible behaviour of h near zeros. We must replace $\int_{-\infty}^{\infty} g(y)ydy$ by $\int_{-\infty}^{\infty} g(y)|y|^{1/m} \operatorname{sgn} ydy$, where

 $m \ge 1$, *m* depends on the behaviour of *h* near its zeros, *m* may be arbitrarily large, and m = 1 in the "generic" case.

3. The case where $g(y) = a \sin y$ We first assume Dirichlet boundary conditions. THEOREM 3. Assume that $h''(x) \neq 0$ whenever h'(x) = 0 and that there exists an x_0 such that $h'(x_0) = 0$ and $h'(x) \neq 0$ whenever $x \neq x_0$ and $|h(x)| = |h(x_0)|$. Then there exists $\varepsilon : E_0 \neq (0, \pi)$ such that $\alpha h + v \in R_1$ if $|\alpha| \leq \varepsilon(v)$. Moreover, if $f \in E_0$, (1) has an infinite number of solutions.

As before, we prove this by examining the asymptotic behaviour of $\int_0^{\pi} \sin(\alpha h + \omega(\alpha))h$. It is more convenient to study $\int_0^{\pi} \exp(i\alpha h)s(\alpha) ,$ where $s(\alpha)(x) = \exp(i\omega(\alpha)(x))h(x)$. We do this by the method of stationary phase (as in §2.9 of [4]). (Although $s(\alpha)$ depends on α , $s(\alpha)$, $(s(\alpha))'(x)$, $(s(\alpha))''(x)$ are uniformly bounded and $s(\alpha)$ has a limit as $|\alpha| \neq \infty$.) We find that $\int_0^{\pi} \sin(\alpha h + \omega(\alpha))h$ oscillates and tends to zero as $|\alpha| \neq \infty$. This gives the result.

The above method still applies if the technical assumptions on h are weakened except that there may be a proper subset of E_0 for which our proof fails. The above method can also be applied to some elliptic partial differential equations in two or three dimensions and to some periodic boundary-value problems when h is non-constant. This last problem behaves a little differently if h is constant. In this case, Lu = g(u) - f has an infinite number of solutions for each f in R_1 and R_1 is still closed but we do not know if $E_0 \subseteq \operatorname{int} R_1$. (It is possible to obtain partial results. For example, $E_0 \subseteq R_1$ if L is self-adjoint.) If h(x) > 0 on $(0, \pi)$, the methods of §4 of [3] can be used to obtain more precise information on R_1 .

The results in 2-3 partially answer a problem raised by Fucík in a lecture at Oberwolfach in 1976.

References

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