

A CHARACTERIZATION OF (−1, −1)-FREUDENTHAL–KANTOR TRIPLE SYSTEMS

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(Received 11 November 2010; accepted 11 April 2011)

Abstract. In this paper, we discuss a connection between (−1, −1)-Freudenthal–Kantor triple systems, anti-structurable algebras, quasi anti-flexible algebras and give examples of such structures. The paper provides the correspondence and characterization of a bilinear product corresponding a triple product.

2010 *Mathematics Subject Classification.* 17A40, 17B60.

1. Introduction. The history of nonassociative algebras, the subject of this paper, started with Hamilton, Cayley and Hurwitz and further with Artin and Zorn, who studied alternative and nearly associative algebras. Thereafter, Freudenthal [10], Tits [53], Kantor [34, 35, 36] and Koecher [39, 40] studied constructions of Lie algebras from nonassociative algebras and triple systems, in particular Jordan algebras, while Allison [1, 2] defined the concept of structurable algebras, containing Jordan algebras. Recently, we have studied constructions of Lie superalgebras as well as Lie algebras from triple systems [25, 27, 30–32]. As a continuation of [30, 31], we are interested in characterizing the structure properties [7, 20, 28] of the subspace L_{-1} of the five graded Lie (super)algebra $L(\varepsilon, \delta) := L_{-2} \oplus L_{-1} \oplus L_0 \oplus L_1 \oplus L_2$, $[L_i, L_j] \subseteq L_{i+j}$, associated with an (ε, δ) -Freudenthal–Kantor triple system. In particular, we deal with a characterization of triple systems from the point of view of a bilinear product by means of anti-structurable algebras or balanced property. Specially, Jordan and Lie (super)algebras [9, 13, 52] play an important role in many mathematical and physical subjects [5, 11–14, 16, 26, 29, 37, 47, 48, 55, 56]). We also note that the construction and characterization of these algebras can be expressed in terms of triple systems [20, 23, 24, 28, 38, 49] by using the standard embedding method [22, 41, 42, 50, 54].

* Research partially supported by Grant-in-Aid for Scientific Research (No. 19540042 (C), (2)), Japan Society for the Promotion of Science.

† Research partially supported by Japan Society for the Promotion of Science (No. 19540042 (C), (2)).

‡ Research supported by U.S. Department of Energy Grant No. DE-FG02-91ER40685.

As for δ -structurable algebras, the motivation for the study of such nonassociative algebras is as follows. The existence of the class of structurable algebras is an important generalization of Jordan algebras giving a construction of Lie algebras. Hence, from our concept, by means of triple products, we define a generalization of such class to construct Lie (super)algebras.

Summarizing the content, we give the introduction in Section 1. In Section 2, we present definitions and preamble. In Section 3, we present the study of $(-1, -1)$ -Freudenthal–Kantor triple systems and anti-structurable algebras and the correspondence and characterization of a bilinear product corresponding a triple product and study the structure of a broader class of algebras, i.e. anti-structurable and quasi-flexible algebras, which generalize structurable and flexible algebras.

2. Definitions.

2.1. (ε, δ) -Freudenthal–Kantor triple systems. We are concerned in this paper with triple systems which have finite dimension over a field Φ of characteristic $\neq 2$ or 3 .

In order to render this paper as self-contained as possible, we recall first the definition of a generalized Jordan triple system of second order (for short GJTS of 2nd order).

A vector space V over a field Φ endowed with a trilinear operation $V \times V \times V \rightarrow V$, $(x, y, z) \mapsto (xyz)$ is said to be a *GJTS of 2nd order* if the following conditions are fulfilled:

$$(ab(xyz)) = ((abx)yz) - (x(bay)z) + (xy(abz)), \quad (2.1)$$

$$K(K(a, b)x, y) - L(y, x)K(a, b) - K(a, b)L(x, y) = 0, \quad (2.2)$$

where $L(a, b)c := (abc)$ and $K(a, b)c := (acb) - (bca)$.

A *Jordan triple system* (for short JTS) satisfies (2.1) and the identity $(abc) = (cba)$.

We can generalize the concept of GJTS of 2nd order as follows (see [14, 15, 18–22, 54] and the earlier references therein). For $\varepsilon = \pm 1, \delta = \pm 1$, a triple product that satisfies

$$(ab(xyz)) = ((abx)yz) + \varepsilon(x(bay)z) + (xy(abz)), \quad (2.3)$$

$$K(K(a, b)x, y) - L(y, x)K(a, b) + \varepsilon K(a, b)L(x, y) = 0, \quad (2.4)$$

where

$$L(a, b)c := (abc), \quad K(a, b)c := (acb) - \delta(bca), \quad (2.5)$$

is called an (ε, δ) -Freudenthal–Kantor triple system (for short (ε, δ) -FKTS).

REMARK. We note that the concept of GJTS of 2nd order coincides with that of $(-1, 1)$ -FKTS. Thus, we can construct the simple Lie algebras by means of the standard embedding method [6, 14–18, 22, 25, 27, 36, 54].

For an (ε, δ) -FKTS U , we denote

$$A(a, b) := L(a, b) - \varepsilon L(b, a), \quad (2.6)$$

where $L(a, b)$ is defined by (2.5). Then $A(a, b)$ is an anti-derivation of U [31], that is

$$[A(a, b), L(c, d)] = L(A(a, b)c, d) - L(c, A(a, b)d). \tag{2.7}$$

An (ε, δ) -FKTS U is called *unitary* if the identity map Id is contained in $\kappa := K(U, U)$ i.e., if there exist $a_i, b_i \in U$, such that $\sum_i K(a_i, b_i) = Id$.

REMARK. We note that a balanced triple system (i.e. it fulfils $K(x, y) = \langle x | y \rangle'$ Id , where $\langle | \rangle'$ is a symmetric bilinear form) is unitary, since $Id \in \kappa = K(U, U)$.

We show in the following remark the equivalence between the balanced notion defined above and the one of [7].

REMARK. We note that for a triple system U with product $()$, the notion of balanced $(-1, -1)$ -FKTS is equivalent to saying that the triple system satisfies (2.3) and

$$(xxy) = (xyx) = \langle x | x \rangle y, \quad x, y \in U, \tag{2.8}$$

where $\langle | \rangle$ is a symmetric bilinear form.

Indeed, if U is a $(-1, 1)$ -FKTS then (2.3) is fulfilled and, by (2.4),

$$K(K(a, b)x, y) - L(y, x)K(a, b) - K(a, b)L(x, y) = 0, \quad a, b, x, y \in U,$$

that is $K(x, y) = L(y, x) + L(x, y) = \langle x | y \rangle' Id$, since $K(x, y) = \langle x | y \rangle' Id$, hence

$$(xwy) + (ywx) = (xyw) + (yxw) = \langle x | y \rangle' w, \quad x, y, w \in U.$$

If we put now $x = y$ in the last line, it follows $2(xwx) = 2(xxw) = \langle x | x \rangle' w$, that is, (2.8) is valid for the symmetric form $\langle | \rangle = \frac{1}{2} \langle | \rangle'$.

In contrast, by linearizing (2.8), we have

$$(xzy) + (yzx) = (xyz) + (zyx) = \langle x | z \rangle y + \langle z | x \rangle y, \quad x, y, z \in U,$$

hence, by (2.5), $K(x, z) = 2 \langle x | z \rangle$, $x, z \in U$, so $K(x, y) = \langle x | y \rangle' Id$, $x, y \in U$.

2.2. δ -structurable algebras. Within the general framework of (ε, δ) -FKTSS $(\varepsilon, \delta = \pm 1)$ and the standard embedding Lie (super)algebra construction studied in [6, 7, 14–16, 27], we define δ -structurable algebras as a class of nonassociative algebras with involution which coincides with the class of structurable algebras for $\delta = 1$ as introduced and studied in [1, 2]. Structurable algebras are a class of nonassociative algebras with involution that include Jordan algebras (with trivial involution), associative algebras with involution, and alternative algebras with involution. They are related to $(-1, 1)$ -FKTSS as introduced and studied in [34, 35] (and further studied in [3, 4, 33, 43–46, 51]). Their importance lies with constructions of five graded Lie algebras $L(-1, 1)$. For $\delta = -1$, the anti-structurable algebras [30] are a new class of nonassociative algebras that may similarly shed light on the notion of $(-1, -1)$ -FKTSS, hence (by [6, 7]) on the construction of Lie superalgebras and Jordan algebras.

Let $(\mathcal{A}, \bar{})$ be a finite-dimensional nonassociative unital algebra with involution (involutive anti-automorphism, i.e. $\overline{\overline{x}} = x, \overline{xy} = \bar{y}\bar{x}, x, y \in \mathcal{A}$) over Φ . Since $\text{char}\Phi \neq 2$, by [1], we have $\mathcal{A} = \mathcal{H} \oplus \mathcal{S}$, where $\mathcal{H} = \{a \in \mathcal{A} | \bar{a} = a\}$ and $\mathcal{S} = \{a \in \mathcal{A} | \bar{a} = -a\}$.

Suppose $x, y, z \in \mathcal{A}$. Put $[x, y] := xy - yx$ and $[x, y, z] := (xy)z - x(yz)$ so $\overline{[x, y, z]} = -[\bar{z}, \bar{y}, \bar{x}]$. The operators L_x and R_x are defined by $L_x(y) := xy, R_x(y) := yx$.

For $\delta = \pm 1$ and $x, y \in \mathcal{A}$ define

$${}^\delta V_{x,y} := L_{L_x(\bar{y})} + \delta(R_x R_{\bar{y}} - R_y R_{\bar{x}}), \tag{2.9}$$

$${}^\delta B_{\mathcal{A}}(x, y, z) := {}^\delta V_{x,y}(z) = (x\bar{y})z + \delta[(z\bar{y})x - (z\bar{x})y], \quad x, y, z \in \mathcal{A}. \tag{2.10}$$

Here ${}^+B_{\mathcal{A}}(x, y, z)$ is called the *triple system obtained from the algebra $(\mathcal{A}, -)$* . We will call ${}^-B_{\mathcal{A}}(x, y, z)$ the *anti-triple system obtained from the algebra $(\mathcal{A}, -)$* . We write for short

$$V_{x,y} := {}^\delta V_{x,y}, \quad B_{\mathcal{A}} := ({}^\delta B_{\mathcal{A}}, \mathcal{A}). \tag{2.11}$$

A unital non-associative algebra with involution $(\mathcal{A}, -)$ is called a *structurable algebra* if

$$[V_{u,v}, V_{x,y}] = V_{V_{u,v}(x),y} - V_{x,V_{u,v}(y)}, \tag{2.12}$$

for $V_{u,v} = {}^+V_{u,v}$, $V_{x,y} = {}^+V_{x,y}$, $u, v, x, y \in \mathcal{A}$, and we will call $(\mathcal{A}, -)$ an *anti-structurable algebra* if the identity (2.12) is fulfilled for $V_{u,v} = {}^-V_{u,v}$, $V_{x,y} = {}^-V_{x,y}$.

If $(\mathcal{A}, -)$ is structurable then, in [35], the triple system $B_{\mathcal{A}}$ is called a *generalized Jordan triple system (GJTS)* and in [8], $B_{\mathcal{A}}$ is a GJTS of 2nd order, i.e. satisfies the identities (2.3) and (2.4). If $(\mathcal{A}, -)$ is anti-structurable then we call $B_{\mathcal{A}}$ an *anti-GJTS*.

3. δ -flexible, quasi-flexible algebras and $(-1, -1)$ -FKTSs.

3.1. δ -flexible and quasi-flexible algebras. For $\delta = \pm 1$, an algebra \mathcal{A} is called *δ -flexible* if

$$-\delta[x, y, z] = [z, y, x], \quad x, y, z \in \mathcal{A}. \tag{3.13}$$

For $\delta = 1$ then \mathcal{A} is flexible, while for $\delta = -1$ then \mathcal{A} is called *anti-flexible*.

EXAMPLE. For $\delta = \pm 1$, if \mathcal{A} is an associative algebra then it is δ -flexible. An algebra \mathcal{A} is called *quasi-flexible* if

$$[x, y, z]w + [wy, z, x] = [xy, z, w] + [w, y, z]x, \quad x, y, z, w \in \mathcal{A}. \tag{3.14}$$

REMARK. If we put $y = e$, the unit element, in (3.14) then we have $[x, z, w] = [w, z, x]$; hence, (3.14) is a generalization of the anti-flexible property.

REMARK. If we put $w = e$, the unit element, in (3.14) then we have $[x, y, z] = -[y, z, x]$; hence,

$$[x, y, z] = -[y, z, x] = (-1)^2[z, x, y] = (-1)^3[x, y, z] = -[x, y, z].$$

Then, $[x, y, z] = 0$ for $\text{char}\Phi \neq 2$; hence (3.14) is a generalization of the associative property ($\text{char}\Phi \neq 2$).

First, we outline the main result as follows.

THEOREM 3.1. *Let U be an anti-structurable and quasi-flexible algebra. Then U is a $(-1, -1)$ -FKTS.*

COROLLARY 3.1. *Let U be an anti-structurable associative algebra. Then U is a (−1, −1)-FKTS.*

EXAMPLE. Let $\mathcal{M}_{m,n}(\Phi)$ denote the vector space of $m \times n$ matrices over Φ and for $x \in \mathcal{M}_{m,n}(\Phi)$ denote by x^\top the transposed matrix. Then $\mathcal{M}_{n,n}(\Phi)$ with the product

$$\{x, y, z\} := xy^\top z - zy^\top x + zx^\top y, \quad x, y, z \in \mathcal{M}_{n,n}(\Phi) \tag{3.15}$$

is a (−1, −1)-FKTS.

Proof of theorem. We remark first that for $x, y \in U$ we have $K(x, y) \equiv A(x, y) \equiv L_{x\bar{y}+y\bar{x}}$, where $K(x, y)$ and $A(x, y)$ are defined by (2.5) and (2.6), respectively. Indeed,

$$\begin{aligned} K(x, y)z &= \{x, z, y\} + \{y, z, x\} = (x\bar{z})y - (y\bar{z})x + (y\bar{x})z + (y\bar{z})x \\ &\quad - (x\bar{z})y + (x\bar{y})z = L_{x\bar{y}+y\bar{x}} \end{aligned}$$

is valid by (2.5) and (2.10), while by (2.6) and (2.10) follows

$$\begin{aligned} A(x, y)z &= \{x, y, z\} + \{y, x, z\} = (x\bar{y})z - (z\bar{y})x + (z\bar{x})y + (y\bar{x})z \\ &\quad - (z\bar{x})y + (z\bar{y})x = L_{x\bar{y}+y\bar{x}}. \end{aligned}$$

Then, by (2.4), it is enough to show $A(A(a, b)c, d) = L(d, c)A(a, b) + A(a, b)L(c, d)$. Thus, by (2.6), we must show

$$L(A(a, b)c, d) + L(d, A(a, b)c) = L(d, c)A(a, b) + A(a, b)L(c, d). \tag{3.16}$$

We note now that by (2.7),

$$A(a, b)L(c, d) = L(A(a, b)c, d) - L(c, A(a, b)d) + L(c, d)A(a, b), \tag{3.17}$$

and then replacing the last term on the right-hand side of equation (3.16) with the right-hand side of (3.17) and cancelling, (3.16) becomes

$$L(d, A(a, b)c) + L(c, A(a, b)d) = (L(d, c) + L(c, d))A(a, b) = A(c, d)A(a, b). \tag{3.18}$$

Denote $h := a\bar{b} + b\bar{a}$. Then, (3.18) can be written as

$$L(d, hc) + L(c, hd) = (L(d, c) + L(c, d))A(a, b) = A(c, d)h, \tag{3.19}$$

or equivalently, by (2.5) and (2.10),

$$(d(\bar{h}c))u - (u(\bar{h}c))d + (u\bar{d})(hc) + (c(\bar{h}d))u - (u(\bar{h}d))c + (u\bar{c})(hd) = (c\bar{d} + d\bar{c})(hu), \tag{3.20}$$

for all $a, b, c, d, u \in U$. Furthermore, since $\bar{}$ is an involution and $\bar{\bar{h}} = h$, (3.20) is equivalent to

$$(d(\bar{c}h))u - (u(\bar{c}h))d + (u\bar{d})(hc) + (c(\bar{d}h))u - (u(\bar{d}h))c + (u\bar{c})(hd) = (c\bar{d})(hu) + (d\bar{c})(hu), \tag{3.21}$$

that is

$$(d(\bar{c}h))u - (d\bar{c})(hu) - (u(\bar{c}h))d + (u\bar{c})(hd) + (u\bar{d})(hc) - (u(\bar{d}h))c + (c(\bar{d}h))u - (c\bar{d})(hu) = 0.$$

If we put now $d = x, \bar{c} = y, h = z, u = w$, in the last line, then (3.21) is equivalent to

$$(x(yz))w - (xy)(zw) - (w(yz))x + (wy)(zx) + (w\bar{x})(z\bar{y}) - (w(\bar{x}z))\bar{y} + (\bar{y}(\bar{x}z))w - (\bar{y}\bar{x})(zw) = 0. \tag{3.22}$$

If we denote $E(x, y, z, w) := (x(yz))w - (xy)(zw) - (w(yz))x + (wy)(zx)$, then (3.22) holds if

$$E(x, y, z, w) = 0, \tag{3.23}$$

for all $x, y, z, w \in U$ since the identity (3.22) is equivalent to $E(x, y, z, w) - E(w, \bar{x}, z, \bar{y}) = 0$.

The identity (3.23) holds if and only if

$$[x, yz, w] + x((yz)w) - (xy)(zw) - [w, yz, x] - w((yz)x) + (wy)(zx) = 0,$$

that is

$$[x, yz, w] + x[y, z, w] + x(y(zw)) - (xy)(zw) - [w, yz, x] - w[y, z, x] - w(y(zx)) + (wy)(zx) = 0,$$

or equivalently

$$[x, yz, w] + x[y, z, w] - [x, y, zw] - [w, yz, x] - w[y, z, x] + [w, y, zx] = 0. \tag{3.24}$$

In general, we have $[a, b, c]d + [a, bc, d] = [ab, c, d] + [a, b, cd] - a[b, c, d]$. Hence, we have

$$[x, yz, w] + x[y, z, w] - [x, y, zw] = [xy, z, w] - [x, y, z]w \tag{3.25}$$

and

$$-[w, yz, x] - w[y, z, x] + [w, y, zx] = [w, y, z]x - [wy, z, x]. \tag{3.26}$$

Then, by (3.25) and (3.26), it follows that the identity is equivalent to the quasi-flexible property (3.14). Hence, an anti-structurable and quasi-flexible algebra is a $(-1, -1)$ -FKTS. \square

REMARK. We note that an anti-structurable algebra which is quasi-flexible is Lie admissible. The proof will be given elsewhere.

3.2. $(-1, -1)$ -FKTSs with left unit element. We outline first the main result as follows.

THEOREM 3.2. *A $(-1, -1)$ -FKTS U with product (\cdot) and left unit element e can be determined in terms of the bilinear product of U defined by*

$$x \cdot y = (exy), \quad x, y \in U. \tag{3.27}$$

Let U be a triple system with product (\cdot) . An element $e \in U$ is called a left unit element if

$$(eex) = x. \tag{3.28}$$

An element $e \in U$ is called a tripotent if

$$(eee) = e. \tag{3.29}$$

Let us denote

$$Q(x) := (exe), \quad R(x) := (xee), \quad x \in U. \tag{3.30}$$

LEMMA 3.1. Let U be a $(−1, −1)$ -FKTS with a left unit element e . Then

$$Q^2(x) = R^2(x) = x, \quad RQ(x) = QR(x), \quad x \in U.$$

Proof. We remark first that by (2.5) and (3.29) we have $K(e, e)e = 2e$. Moreover, by (2.4),

$$K(K(e, e)e, x)e - 2L(x, e)K(e, e)e - K(e, e)L(e, x)e = 0,$$

hence $2K(e, x)e - 2L(x, e)e - 2(eQ(x)e) = 0$. Thus, by (2.5), $(eex) + (xee) - (xee) - Q^2(x) = 0$, that is $Q^2(x) = (eex) = x$ for all $x \in U$. Furthermore, by (2.3),

$$(xe(eee)) = ((xee)ee) - (e(exe)e) + (ee(xee)),$$

or equivalently, by (3.29), $(xee) = ((xee)ee) - (e(exe)e) + (xee)$, that is $Q^2(x) = R^2(x)$.

Finally, by (2.3), it follows that $(ex(eee)) = ((exe)ee) - (e(xee)e) + (ee(exe))$, or equivalently, by (3.29), $(exe) = RQ(x) - QR(x) + (exe)$, that is $RQ(x) = QR(x)$. \square

REMARK. By [38], we note that for a $(−1, 1)$ -FKTS U with product (\cdot) and left unit element e can be determined in terms of the bilinear product of U defined by $x \circ y = (xey)$, $x, y \in U$, that is, by Theorem 3.3 [38], $U = U_{11}^+ \oplus U_{11}^- \oplus U_{13}^+ \oplus U_{13}^-$ with the product

$$(xyz) = (Q^{-1}(y) \circ x) \circ z + x \circ (Q^{-1}(y) \circ z) - Q^{-1}(y) \circ (x \circ z),$$

where $Q(x) = \begin{cases} \pm x, & \text{if } x \in U_{11}^\pm \\ \pm 3x, & \text{if } x \in U_{13}^\pm \end{cases}$ and $U_{1i} := \{x \in U \mid R(x) = ix\}$.

Proof of theorem. By (2.3), it follows that $(xe(eey)) = ((xee)ey) - (e(exe)y) + (ee(xey))$, or equivalently, $(xey) = ((xee)ey) - (e(exe)y) + (xey)$, that is, by (3.30),

$$(eQ(x)y) = (R(x)ey), \quad x, y \in U. \tag{3.31}$$

Now, by Lemma 3.1, $Q^2(x) = x$ and by replacing x by $Q(x)$ in (3.31) we have, by (3.27),

$$x \cdot y = (exy) = (RQ(x)ey), \quad x, y \in U. \tag{3.32}$$

Furthermore, by Lemma 3.1, $Q^2(x) = R^2(x) = x$ and by replacing x by $QR(x)$ in (3.32), we have

$$QR(x) \cdot y = (xey). \tag{3.33}$$

On the other hand, by (2.3), it follows that $(ex(eye)) = ((exe)ye) - (e(xey)e) + (ey(exe))$, or equivalently, by (3.30), $(exQ(y)) = (Q(x)ye) - Q(xey) + (eyQ(x))$. Hence, by (3.27) and (3.33) follows $x \cdot Q(y) = (Q(x)ye) - Q(QR(x) \cdot y) + y \cdot Q(x)$ or equivalently, by Lemma 3.1, $x \cdot Q(y) = (Q(x)ye) - Q(RQ(x) \cdot y) + y \cdot Q(x)$ for all $x, y \in U$. Replacing x by $Q(x)$ in the last line follows $Q(x) \cdot Q(y) = (Q^2(x)ye) - Q(RQ^2(x) \cdot y) + y \cdot Q^2(x)$; hence by Lemma 3.1,

$$(xye) = Q(x) \cdot Q(y) + Q(R(x) \cdot y) - y \cdot x. \tag{3.34}$$

Finally, by (2.3) follows $(ex(yze)) = ((exy)ze) - (y(xez)e) + (yz(exe))$, or equivalently, by (3.30), $(yzQ(x)) = (ex(yze)) - ((exy)ze) + (y(xez)e)$, for all $x, y, z \in U$. Replacing x by $Q(x)$ in the last line follows, by Lemma 3.1, $(yzx) = (eQ(x)(yze)) - ((eQ(x)y)ze) + (y(Q(x)ez)e)$, or equivalently,

$$(xyz) = (eQ(z)(xye)) - ((eQ(z)x)ye) + (x(Q(z)ey)e), \quad x, y, z \in U. \tag{3.35}$$

Hence, the product (xyz) can be characterized in terms of the bilinear product (3.27). □

We now give a corollary which first appeared in [7] but without using the notion of quadratic algebra [7]. First, we need a remark and two lemmas.

REMARK. We shall remark that the balanced property gives

$$x + \bar{x} = T(x)e, \quad \text{where } \bar{x} := R(x) = (xee), \quad T(x)e := 2 \langle x | e \rangle e, \tag{3.36}$$

and

$$e \cdot x = x \cdot e = x, \quad [e, x, y] = 0 = [x, e, y], \quad x, y \in U. \tag{3.37}$$

Indeed, by (2.8), $(xyx) = \langle x | x \rangle y$, $x, y \in U$; hence, $(xyz) + (zyx) = 2 \langle x | z \rangle y$, by the symmetry of the bilinear form. Then, $(xee) + (eex) = 2 \langle x | e \rangle e$ so, by (3.28), it follows that (3.36) is fulfilled. Also by (2.8), $(exe) = \langle e | e \rangle x$, $x \in U$, that is, by (3.27), $x \cdot e = x$ since e is a tripotent. Then, $x \cdot e = x = e \cdot x$, by (3.28). Moreover, the last identity gives $[e, x, y] = (e \cdot x) \cdot y - e \cdot (x \cdot y) = x \cdot y - x \cdot y = 0$ as well as $[x, e, y] = (x \cdot e) \cdot y - x \cdot (e \cdot y) = x \cdot y - x \cdot y = 0$, so (3.37) is fulfilled.

LEMMA 3.2. *Let U be a balanced $(-1, -1)$ -FKTS with product (\cdot) and left unit element e . Then the bilinear product (3.27) is flexible.*

Proof. Indeed, by (2.8),

$$(ex(eyx)) + (xe(eyx)) = 2 \langle x | e \rangle (eyx) = 2 \langle x | e \rangle y \cdot x = T(x)(y \cdot x), \quad x, y \in U. \tag{3.38}$$

On the other hand, by (2.3), it follows that $(xe(eyx)) = ((xee)yx) - (e(exy)e) + (ey(xex))$, or equivalently, by (2.8)

$$(e(exy)e) = -(xe(eyx)) + ((xee)yx) + (ey(xex)) = -(xe(eyx)) + (\bar{y}yx) + \langle x | x \rangle y \cdot e,$$

that is $(e(exy)e) = -(xe(eyx)) + ((T(x) - x)yx) + \langle x | x \rangle y \cdot e$; hence,

$$(e(exy)e) = -(xe(eyx)) + T(x)(y \cdot x) - (xyx) + \langle x | x \rangle y = -(xe(eyx)) + T(x)(y \cdot x). \tag{3.39}$$

Then by (3.38) and (3.39) follows $(ex(eyx)) = (e(exy)e)$, or equivalently $x \cdot (y \cdot x) = (x \cdot y) \cdot x$; hence, $[x, y, x] = 0$, which implies the flexible identity (3.13). \square

LEMMA 3.3. *Let U be a balanced $(-1, -1)$ -FKTS with product (\cdot) and left unit element e . Then*

$$\overline{x \cdot y} = \overline{y} \cdot \overline{x}, \quad \overline{\overline{x}} = x, \quad x, y \in U, \tag{3.40}$$

where $\overline{x} := (xee)$ and $x \cdot y$ is the bilinear product of U defined by (3.27).

Proof. By definition $\overline{x \cdot y} = ((x \cdot y)ee) = ((exy)ee)$; hence, by (2.3), it follows that

$$\overline{x \cdot y} = (ex(yee)) + (y(xee)e) - (ye(exe)) = x \cdot \overline{y} + (y\overline{x}e) - \overline{y} \cdot x, \tag{3.41}$$

since by the balanced property (2.3), (3.28) and (3.30), we have $Q(x) = (exe) = (eex) = x$. Furthermore, by (3.30) we have $R(x) = (xee) = \overline{x}$; hence, by (3.34),

$$(y\overline{x}e) = y \cdot \overline{x} + \overline{y} \cdot \overline{x} - \overline{x} \cdot y. \tag{3.42}$$

Then, by (3.42) and (3.34), it follows

$$\overline{x \cdot y} = x \cdot \overline{y} + y \cdot \overline{x} + \overline{y} \cdot \overline{x} - \overline{x} \cdot y - \overline{y} \cdot x. \tag{3.43}$$

Now, by (3.36), it follows that (3.43) is equivalent to

$$\overline{x \cdot y} = (T(x)e - \overline{x}) \cdot \overline{y} + (T(y)e - \overline{y}) \cdot \overline{x} + \overline{y} \cdot \overline{x} - \overline{x} \cdot (T(y)e - \overline{y}) - \overline{y} \cdot (T(x)e - \overline{x}).$$

Then, the first identity in (3.40) follows from the last line, (3.27) and straightforward cancellations. The second identity in (3.40), that is $\overline{\overline{x}} = x$, follows from Lemma 3.1, that is from the identity $R^2(x) = x$ since we have shown above that $R(x) = \overline{x}$; hence $R^2(x) = \overline{\overline{x}}$. \square

COROLLARY 3.2. *Let U be a balanced $(-1, -1)$ -FKTS with product (\cdot) and left unit element e . Then*

$$(xyz) = (\overline{x} \cdot y) \cdot z - \overline{x} \cdot (y \cdot z) + y \cdot (\overline{x} \cdot z), \quad x, y, z \in U, \tag{3.44}$$

where $\overline{x} := (xee)$ and $x \cdot y$ is the bilinear product of U defined by (3.27).

Proof. Since by the proof of Lemma 3.3 we have $Q(x) = x$, $R(x) = \overline{x}$, then by (3.35),

$$(xyz) = (ez(xye)) - ((ezx)ye) + (x(zey)e). \tag{3.45}$$

Now, since $x \cdot y = (exy)$, $\overline{x} \cdot y = (xey)$ and, by (3.42), $(xye) = x \cdot y + \overline{x} \cdot y - y \cdot x$, then $(ez(xye)) = z \cdot (x \cdot y + \overline{x} \cdot y - y \cdot x)$, $((ezx)ye) = ((z \cdot x)ye) = (z \cdot x) \cdot y + (z \cdot x) \cdot y - y \cdot (z \cdot x)$ and $(x(zey)e) = (x(\overline{z} \cdot y)e) = x \cdot (\overline{z} \cdot y) + \overline{x} \cdot (\overline{z} \cdot y) - (\overline{z} \cdot y) \cdot x$. Hence,

(3.45) is equivalent to

$$(xyz) = -[z, x, y] + z \cdot (\bar{x} \cdot y) + \bar{z} \cdot (y \cdot x) - T(z) \cdot (y \cdot x) - (\bar{z} \cdot y) \cdot x \\ - (\bar{x} \cdot \bar{z}) \cdot y - \bar{x} \cdot (\bar{z} \cdot y) + T(x) \cdot (\bar{z} \cdot y) + \bar{x} \cdot (\bar{z} \cdot y) + y \cdot (z \cdot x),$$

that is

$$(xyz) = -[z, x, y] + z \cdot (\bar{x} \cdot y) - [\bar{z}, y, x] - T(z) \cdot (y \cdot x) - (\bar{x} \cdot \bar{z}) \cdot y \\ + T(x) \cdot (\bar{z} \cdot y) + y \cdot (z \cdot x).$$

Since $(\bar{x} \cdot \bar{z}) \cdot y = ((T(x)e - x) \cdot \bar{z}) \cdot y = T(x)(\bar{z} \cdot y) - (x \cdot \bar{z}) \cdot y$, then the last identity is equivalent to

$$(xyz) = -[z, x, y] + z \cdot (\bar{x} \cdot y) - [\bar{z}, y, x] - T(z) \cdot (y \cdot x) + (x \cdot \bar{z}) \cdot y + y \cdot (z \cdot x). \quad (3.46)$$

We remark now that $[z, x, y] = -[\bar{z}, x, y]$ since $z = T(z)e - \bar{z}$ and $[e, x, y] = 0$, by (3.37); hence, by (3.46), it follows that

$$(xyz) = [\bar{z}, x, y] + z \cdot (\bar{x} \cdot y) - [\bar{z}, y, x] + (x \cdot \bar{z}) \cdot y - y \cdot (\bar{z} \cdot x), \quad (3.47)$$

since $-T(z) \cdot (y \cdot x) + y \cdot (z \cdot x) = -y \cdot (\bar{z} \cdot x)$. Analogously, we have $[z, x, y] = -[z, \bar{x}, y]$, by (3.37); thus $[z, x, y] = -[z, \bar{x}, y] = -[\bar{z}, x, y]$. Hence, by (3.47), it follows that

$$(xyz) = [z, \bar{x}, y] + z \cdot (\bar{x} \cdot y) - [\bar{z}, y, x] + (x \cdot \bar{z}) \cdot y - y \cdot (\bar{z} \cdot x). \quad (3.48)$$

Now, from the identity $[\bar{z}, y, x] = -[z, y, x]$ above, it follows that $[\bar{z}, y, x] = -[z, y, T(x) - \bar{x}] = [z, y, \bar{x}]$ since, by Lemma 3.2 the flexible property is satisfied for the dot product; thus $[z, y, e] = 0$ since $[e, y, z] = 0$, by (3.37). Then the identity (3.48) is equivalent to

$$(xyz) = [z, \bar{x}, y] + z \cdot (\bar{x} \cdot y) - [z, y, \bar{x}] + (x \cdot \bar{z}) \cdot y - y \cdot (\bar{z} \cdot x), \text{ i.e.} \\ (xyz) = (z \cdot \bar{x}) \cdot y - [z, y, \bar{x}] + (x \cdot \bar{z}) \cdot y - y \cdot (\bar{z} \cdot x) \\ = (x \cdot \bar{z} + \overline{x \cdot \bar{z}}) \cdot y - y \cdot (\bar{z} \cdot x) + [\bar{x}, y, z]. \quad (3.49)$$

Furthermore, since $x \cdot \bar{z} + \overline{x \cdot \bar{z}} = T(x \cdot \bar{z})$ by the flexible property, and

$$T(x \cdot y) = T(\overline{x \cdot y}) = T(\overline{y \cdot x}) = T((T(y) - y) \cdot (T(x) - x)) = T(y \cdot x),$$

it follows that (3.49) is equivalent to

$$(xyz) = T(\bar{z} \cdot x)y - y \cdot (\bar{z} \cdot x) + [\bar{x}, y, z] = y \cdot (\overline{\bar{z} \cdot x}) = y \cdot (\bar{x} \cdot z) + [\bar{x}, y, z],$$

hence the identity (3.44) is fulfilled. \square

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