Real-time interactive ptychography from electron event representation data

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The arrival of direct electron detectors (DED) with high frame-rates in the field of scanning transmission electron microscopy has enabled many experimental techniques that require the collection of a full diffraction pattern at each scan position, a field which is subsumed under the name 4D-STEM.

DED frame rates approaching 100kHz place stringent requirements on data transmission rates and computing infrastructure. Current commercial DEDs allow the user to make compromises in pixel bit depth, detector binning or windowing to reduce the per-fame file size and allow higher frame rates.

This change in detector specifications requires decisions to be made before data acquisition that may reduce or lose information that could have been advantageous during data analysis. The 4D Camera, a DED with 87kHz frame-rate developed at Lawrence Berkeley National Laboratory, reduces the raw data to a linear-index encoded electron event representation (EER) [1].

In this talk we show with experimental data from the 4D camera that linear-index encoded EER [2,3] and its direct use in 4D-STEM phase-contrast imaging methods enables real-time, interactive phase-contrast from large-area 4D-STEM datasets.

We detail the computational complexity advantages of the EER and the necessary computational steps to achieve real-time interactive ptychography using commonly available hardware accelerators.

Real-time reconstruction with direct phase-contrast imaging methods allows fast data exploration during the experiment and generation of an accurate initial guess for probe aberrations in iterative reconstruction methods.

Fig. 1 shows the current timings achieved for a 4Dcamera dataset with 512 x 512 scan positions. The centering and cropping step can be performed directly on the electron events, allowing a 40-100x speedup over the dense format for sparse electron events. The data is then binned to < 32x32 detector pixels and densified to prepare for the single-sideband reconstruction [4]. The single-sideband reconstruction consists of an element-wise multiplication and 4D->2D reduction step and can be parallelized efficiently on the GPU. By keeping the data on the GPU all the time, we achieve reconstruction times < 1s, allowing for interactive tuning of aberrations and performing interactive virtual defocus-scans. The code is complemented with a Jupyter graphical user interface, such that all computation can be done remotely. [5]

References

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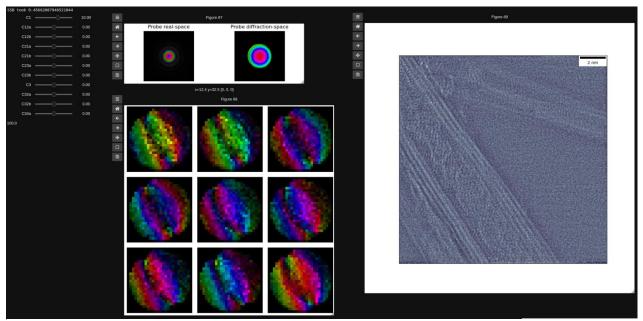


Figure 1. Fig 1: Graphical user-interface for real-time ptychography running in a jupyter-notebook. Left panel: interactive aberration tuning. Middle top panel: display of the current real- and diffraction-space probe aberrations. Middle bottom panel: Panel of the 9 most intensive double-overlap regions for aberration tuning feedback. Right panel: single-sideband reconstruction with the current aberrations.

Current timing for 512 x 512 scan:

Operation	time
Load from RAM into analysis PC GPU RAM	<1s
Centering & cropping	24ms
Sparse to dense 4d cube	17ms
SSB ptychography	17ms

Total: <1s

Figure 2. Fig 2: Processing times for interactive ptychography. The sparse linear-index EER format allows small file size of < 2GB for a 512x521 4DSTEM-scan. Loading into GPU memory takes less than 1s, and the subsequent processing steps can be achieved with custom GPU kernels in under 100ms. This allows live updates of aberration parameters.

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