

SOME PROPERTIES OF ISOLATING BLOCKS FOR PLANAR SYSTEMS

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Abstract. In this paper, some qualitative properties of trajectories inside an isolating block for planar differential equations are obtained.

§1. Introduction

Consider the differential system defined in the plane

$$(1.1) \quad \begin{aligned} \frac{dx}{dt} &= X(x, y), \\ \frac{dy}{dt} &= Y(x, y). \end{aligned}$$

Suppose $X, Y \in C^1$. Let the vector field $V \equiv (X, Y)$ define a flow $f(p, t)$. Let $B \subset R^2$ be the closure of a bounded and connected open set with the boundary ∂B . In general, B is assumed to be multiply connected. Let L_1, \dots, L_n denote its boundary components, where $L_i \cap L_j = \emptyset$ for $i \neq j$, and L_1 the external boundary. Each of them is a smooth simple closed curve. Let $\text{int} B$ denote the interior of B . We define three subsets b^+, b^- and τ as follows:

$$b^+ = \{p \in \partial B \mid \exists \varepsilon > 0 \text{ with } f(p, (-\varepsilon, 0)) \cap B = \emptyset\},$$

$$b^- = \{p \in \partial B \mid \exists \varepsilon > 0 \text{ with } f(p, (0, \varepsilon)) \cap B = \emptyset\},$$

$$\tau = \{p \in \partial B \mid V \text{ is tangent to } B \text{ at } p\}.$$

DEFINITION 1.1. ([1]) If $b^+ \cap b^- = \tau$ and $b^+ \cup b^- = \partial B$, then B is called an isolating block for the flow defined by (1.1).

It follows from the above definition that if B is an isolating block, then all the tangencies to B must be external.

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DEFINITION 1.2. Suppose $B \subset R^2$ is an isolating block for the flow defined by (1.1). If a trajectory Γ_1 of (1.1) enters B at M_1 (a strict entrance point) of the external boundary L_1 of B and then leaves B at M_2 (a strict exit point) of L_1 so that $\text{int}B$ is divided into two disconnected regions B_1 and B_2 , then Γ_1 is called a cut trajectory of B .

Conley and Easton in [2] have studied generally properties of the isolating block. A special property of planar isolating blocks and an application to the existence of connecting orbits have discussed in [3] (See Lemma 1 of [3]). In the present paper, we shall discuss qualitative properties of planar flows inside the isolating block and give some new results.

§2. The main results

Suppose B is an isolating block for flow defined by (1.1) and a critical point $Q \in \text{int}B$. Our main aim is to study the existence of elliptic regions of Q (See [4, p.295] for the definition). Therefore, we consider a bounded sectorial region D contained in B with boundary consisting of the critical point Q , two semi-trajectory arcs $f(M_1, R^+)$, $f(M_2, R^-)$ and the closed subarc M_1mM_2 of ∂B from M_1 to M_2 , and such that when $t \rightarrow +\infty$ (or $-\infty$), $f(M_1, t)$ (or $f(M_2, t)$) tends to Q , and $M_1 \in b^+$, $M_2 \in b^-$. Such a sectorial region is said to be adjacent to ∂B .

DEFINITION 2.1. Suppose D is a bounded sectorial region adjacent to ∂B , as stated above. D is said to be inadmissible if there are a trajectory $\Gamma \subset D$ which tends to Q as $t \rightarrow \pm\infty$ and a circle ρ of radius r small enough with the centre Q such that the interior of each of the curvilinear triangles $Qm_1\gamma_1$ and $Qm_2\gamma_2$ is a parabolic sector of Q ([5,p.164]) in ρ , where it is assumed that ρ intersects QM_1, Γ and QM_2 at m_1, γ_1, γ_2 and m_2 , respectively (Fig.1).

THEOREM 2.1. *Let B be an isolating block for flow defined by (1.1) and a critical point $Q \in \text{int}B$. Let D be an inadmissible sectorial region adjacent to ∂B and let D do not contain any internal boundary components of ∂B . Let $D_1 = D \setminus \overline{G}$, where G is the region enclosed by Γ and Q . Then there must be at least one critical point of (1.1) in D_1 (Fig.1).*

point $x \in 1^+$ tends to Q in D as $t \rightarrow +\infty$, then it must enter the parabolic sector $Qm_1\gamma_1$ (see Fig.1). So, from the continuity (the solutions depend continuously on initial conditions) it follows that the positive semi-trajectory originating from every point in a small neighbourhood of x on 1^+ also tends to Q in D as $t \rightarrow +\infty$. The same argument implies that the positive semi-trajectory through a point x of M_1A_1 sufficiently close to M_1 must tend to Q in D as $t \rightarrow +\infty$. Thus there is a maximal open segmental arc M_1h of M_1A_1 such that for every point $x \in M_1h$, the positive semi-trajectory $f(x, R^+)$ tends to Q in D as $t \rightarrow +\infty$, while the positive semi-trajectory $f(h, R^+)$ does not tend to Q in D as $t \rightarrow +\infty$. On the other hand, the same argument used in case $1 < k < n$ implies that the positive semi-trajectory originating from every point in a small neighbourhood of A_1 on 1^+ must leave D_1 from some point on the segmental arc 1^- . Moreover, the set of such points is an open set on the segmental arc M_1A_1 . This implies that $h \neq A_1$, and the positive semi-trajectory $f(h, R^+)$ can neither tend to Q in D nor leave D_1 from a point on 1^- for increasing time. Hence, for $k = 1$, we have proved that there is a nonempty set $\beta_1^+ \subset 1^+$ such that for each point $x \in \beta_1^+$, the positive semi-trajectory $f(x, R^+)$ can neither tend to Q in D nor leave D_1 from a point on 1^- for increasing time. For $k = n$, a similar conclusion holds.

Choose arbitrarily n points $a_i^+ \in \beta_i^+ (i = 1, 2, \dots, n)$. We now can prove that there is at least one among the positive semi-trajectories $\{f(a_i^+, R^+) | i = 1, 2, \dots, n\}$ such that it stays in D_1 for all $t > 0$ and does not tend to Q as $t \rightarrow +\infty$. The following proof proceeds by reduction to absurdity. Suppose that each of the semi-trajectories $\{f(a_i^+, R^+) | i = 1, 2, \dots, n\}$ either leaves D_1 from some point on the segmental arc M_1mM_2 for increasing time or tends to Q as $t \rightarrow +\infty$. Thus, since the positive semi-trajectory $f(a_1^+, R^+)$ can not tend to Q (note $a_1^+ \in \beta_1^+$), it must leave D_1 from a point on M_1mM_2 for increasing time. Let it leave D_1 from some point on k^- , where $1 < k \leq n$. But this means that each of $\{f(a_i^+, R^+) | i = 2, \dots, k\}$ can not tend to Q as $t \rightarrow +\infty$ for, otherwise it must meet $f(a_1^+, R^+)$ at a point for increasing time and which contradicts uniqueness of solutions. Therefore, each of $\{f(a_i^+, R^+) | i = 2, \dots, k\}$ must leave D_1 from a point on M_1mM_2 for increasing time. However, we note that the semi-trajectory $f(a_2^+, R^+)$ can not leave D_1 from a point on 1^- or 2^- because $a_2^+ \in \beta_2^+$, hence, it can only leave D_1 from a point on $i^- (i \geq 3)$. This implies that the positive semi-trajectory $f(a_3^+, R^+)$ can not leave D_1 from a point on 1^- for increasing time for, otherwise it must meet $f(a_2^+, R^+)$ and which

contradicts uniqueness of solutions, hence, it can only leave D_1 from a point on i^- ($i \geq 4$). Further, this also implies that the semi-trajectory $f(a_4^+, R^+)$ can not leave D_1 from a point on 2^- , hence it can only leave D_1 from a point on i^- ($i \geq 5$) for increasing time. Repeating an argument used above, one implies that the semi-trajectory $f(a_i^+, R^+)$ can only leave D_1 from a point on j^- ($k \geq j \geq i + 1$) (i.e., on the segmental arc with greater subscript). From this, it follows that the semi-trajectory $f(a_k^+, R^+)$ can not leave D_1 from a point on M_1mM_2 for increasing time. Moreover, as stated above, it can not also tend to Q as $t \rightarrow +\infty$, therefore, this contradicts the preceding hypothesis. Thus, there must be a positive semi-trajectory γ^+ such that it can neither tend to Q nor leave D_1 from a point on M_1mM_2 for increasing time. By the Poincaré-Bendixson theory of planar systems, the ω -limit set of γ^+ must contain critical points or closed orbits. Further, since a closed orbit contains at least one critical point of (1.1) in its interior, this implies that there must be at least one critical point of (1.1) in D_1 . Hence Theorem 2.1 is proved.

COROLLARY 1. *If the sectorial region D in Theorem 2.1 contains the internal boundary components L_{i_1}, \dots, L_{i_k} of ∂B , then the conclusion of Theorem 2.1 still holds provided we set $D_1 = D \setminus (\overline{G} \cup \overline{G}_{i_1} \cup \dots \cup \overline{G}_{i_k})$, where G_{i_1}, \dots, G_{i_k} are the regions enclosed by L_{i_1}, \dots, L_{i_k} respectively.*

Proof of Corollary 1. We know from the proof of Theorem 2.1 that there is at least one among the positive semi-trajectories $\{f(a_i^+, R^+) | i = 1, 2, \dots, n\}$, say $f(a_j^+, R^+)$, such that it stays in $D \setminus \overline{G}$ for all $t > 0$ and does not tend to Q as $t \rightarrow +\infty$, where $a_j^+ \in \beta_j^+ \subset j^+$, A_{2j-1} and A_{2j-2} are two tangencies close to a_j^+ .

Suppose $f(a_j^+, R^+)$ intersects L_{i_0} at b_j , where L_{i_0} is one of the internal boundary components $\{L_{i_1}, \dots, L_{i_k}\}$ and b_j is a strict exit point of B . Consider the segmental arc $A_{2j-2}a_j^+A_{2j-1}$ and its segmental subarc $a_j^+A_{2j-1}$. Let $\tilde{a} = \{x \in A_{2j-2}a_j^+A_{2j-1} | \text{the point where } f(x, R^+) \text{ intersects } L_{i_0} \text{ is a strict exit point of } B\}$. From the theorem of continuity (the solutions depend continuously on initial conditions) it follows that \tilde{a} is an open set on the segmental arc $A_{2j-2}a_j^+A_{2j-1}$. Since A_{2j-1} is a tangency to B , the positive semi-trajectory originating from every point in a small neighbourhood of A_{2j-1} on $a_j^+A_{2j-1}$ must leave B from some point on the segmental arc M_1mM_2 . Hence there must be at least one boundary point of the set \tilde{a} on $a_j^+A_{2j-1}$. Let a_0 be a boundary point close to a_j^+ . Then either there is a

point $p \in f(a_0, R^+)$ such that p is a tangency to L_{i_0} or $f(a_0, R^+)$ tends to a critical point of (1.1) in D_1 as $t \rightarrow +\infty$. In the former case, it follows that there is an internal tangency to B . But this is impossible because B is an isolating block. In the latter case, it follows that Corollary 1 holds.

If $f(a_j^+, R^+)$ does not meet any one of the internal boundary components $\{L_{i_1}, \dots, L_{i_k}\}$, then by the Poincaré-Bendixson theory of planar systems it follows that there must be at least one critical point of (1.1) in D_1 , where $D_1 = D \setminus (\overline{G} \cup \overline{G}_{i_1} \cup \dots \cup \overline{G}_{i_k})$. Corollary 1 is proved.

Remark 1. Suppose Q is a unique critical point of (1.1) in B . Then, Theorem 2.1 means that the fact that there are no internal tangencies to B can imply that there are no certain type of elliptic regions of the critical point Q .

Using exactly the same argument used in the proof of Theorem 2.1, we can prove the following theorem. We suppose that the symbols $a_i^\pm, i^\pm, \beta_i^\pm$ have the same meanings as in Theorem 2.1.

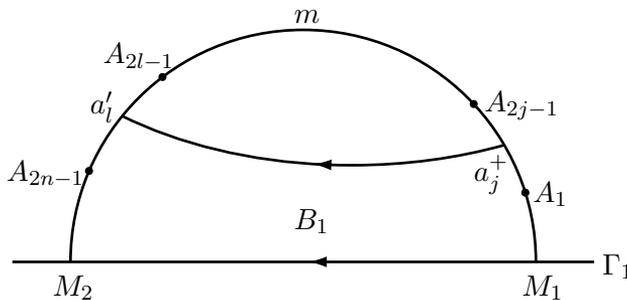
THEOREM 2.2. *Let B be an isolating block for flow defined by (1.1). Let B_1 be the region enclosed by the trajectory arc M_1M_2 of the cut trajectory Γ_1 of B and the segmental arc M_1mM_2 of the external boundary L_1 of B (Fig.2). Let $A_1, A_2, \dots, A_{2n-1}$ be the tangencies to be arranged in numerical order on the arc M_1mM_2 . If $n \geq 2$, then there must be a point $a_i^+ \in i^+$ and a point $a_i^- \in i^-$ such that the semi-trajectories $f(a_i^+, R^+)$ and $f(a_i^-, R^-)$ stay in B_1 for all $t > 0$ and $t < 0$ respectively ($i = 1, 2, \dots, n$).*

Proof. First we note, by Definition 1.2, it follows that the positive semi-trajectory originating from every point in a small neighbourhood of M_1 on 1^+ must leave B_1 from a point on n^- for increasing time. For $k = n$, a similar conclusion holds. Thus, one can consider 1^+ and n^- as two adjacent segmental arcs.

We proceed by induction. First suppose $n = 2$. That is, there are three tangencies A_1, A_2, A_3 on the arc M_1mM_2 . It is easy to see that the positive (or negative) semi-trajectory originating from any point on β_i^+ (or β_i^-) ($i = 1, 2$) stays in B_1 for all $t > 0$ (or $t < 0$). So, when $n = 2$, Theorem 2.2 holds.

Let $k > 2$ be an arbitrary positive integer. Let us now make the inductive hypothesis that Theorem 2.2 is true for $2 \leq n \leq k - 1$ (i.e., for all those odd numbers which are not greater than $2k - 3$). We need to show that it is also true for $n = k$ (i.e., for the odd number $2k - 1$).

In fact, from $n = k - 1$ to $n = k$, two tangencies A_{2k-2} and A_{2k-1} are added to the arc M_1mM_2 . The following proof proceeds by reduction to absurdity. Suppose that there is some segmental arc j^+ such that for every point $x \in j^+$, the positive semi-trajectory $f(x, R^+)$ leaves B_1 from a point on M_1mM_2 for increasing time. Take arbitrarily a point $a_j^+ \in \beta_j^+$, then, the positive semi-trajectory $f(a_j^+, R^+)$ must leave B_1 from the point a'_l on l^- for increasing time. The trajectory arc $a_j^+a'_l$ divides the segmental arc M_1mM_2 into three segmental arcs: The segmental arcs $a_j^+a'_l$, $M_1a_j^+$ and $M_2a'_l$ (Fig.2). From the fact that the semi-trajectory $f(a_j^+, R^+)$ leaves B_1 neither from a point on the adjacent segmental arcs nor from a point on any entrance segmental arc i^+ for increasing time, it follows that there are at least three tangencies on the segmental arc $a_j^+a'_l$ of M_1mM_2 , while the amount of tangencies on the arcs $M_1a_j^+$ and $M_2a'_l$ of M_1mM_2 is not less than 2. Thus the number of tangencies on the arc $a_j^+a'_l$ of M_1mM_2 is not greater than $2k - 1 - 2 = 2k - 3$. Furthermore, since a_j^+ is a strict entrance point of B_1 and a'_l is a strict exit point of B_1 , the trajectory arc $a_j^+a'_l$ possesses the same property as the arc M_1M_2 of Γ_1 . By the inductual hypothesis it follows that there must be a point q on the arc $a_j^+A_{2j-1}$ of M_1mM_2 such that the positive semi-trajectory $f(q, R^+)$ stays for all $t > 0$ in the region enclosed by the segmental arc $a_j^+a'_l$ of M_1mM_2 and the trajectory arc $a_j^+a'_l$, hence in B_1 . But since $a_j^+A_{2j-1} \subset j^+$, this contradicts the preceding hypothesis. Hence we have proved that for each $i \in \{1, 2, \dots, n\}$, there must be a point $a_i^+ \in i^+$ such that $f(a_i^+, R^+)$ stays in B_1 for all $t > 0$. Similarly, we can prove that for each $i \in \{1, 2, \dots, n\}$, there must be a point $a_i^- \in i^-$ such that $f(a_i^-, R^-)$ stays in B_1 for all $t < 0$. Thus Theorem 2.2 is proved.



(Figure 2)

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