# Higher-order narrowing with definitional trees* 

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#### Abstract

Functional logic languages with a sound and complete operational semantics are mainly based on an inference rule called narrowing. Narrowing extends functional evaluation by goal solving capabilities, as in logic programming. Due to the huge search space of simple narrowing, steadily improved narrowing strategies have been developed in the past. Needed narrowing is currently the best narrowing strategy for first-order functional logic programs due to its optimality properties wrt the length of derivations and the number of computed solutions. In this paper, we extend the needed narrowing strategy to higher-order functions and $\lambda$-terms as data structures. By the use of definitional trees, our strategy computes only independent solutions. Thus, it is the first calculus for higher-order functional logic programming which provides for such an optimality result. Since we allow higher-order logical variables denoting $\lambda$-terms, applications go beyond current functional and logic programming languages. We show soundness and completeness of our strategy with respect to LNT reductions, a particular form of higher-order reductions defined via definitional trees. A general completeness result is only provided for terminating rewrite systems due to the lack of an overall theory of higher-order reduction which is outside the scope of this paper.


## Capsule Review

This paper extends previous work on first-order needed narrowing by Antoy et al. (1994). This narrowing strategy is sound and complete (wrt rewriting), it computes incomparable solutions, and it does so with narrowing derivations of minimal length (assuming sharing). These properties are obviously important for the efficient implementation of functional logic languages, and they can be proved on the basis of a well-stablished theory, namely Hullot's theory of neededness and sequentiality of reductions for orthogonal rewriting systems. In fact, first-order needed narrowing is defined for the class of constructor-based strongly sequential term rewriting systems, which can be conveniently characterized by so-called definitional trees.

No sufficiently general theory of neededness and sequentiality is known yet for the case of higher-order rewriting systems. The aim of this paper is not to develop such a theory, but rather to obtain a higher-order extension of needed narrowing in a more ad hoc way. The authors have chosen to define a suitable notion of higher-order definitional tree and

[^0]to develop an extension of needed narrowing for those higher-order rewriting systems that can be described by such trees. The presentation is achieved through several calculi which are carefully formalized and clearly illustrated by means of simple examples. Higher-order narrowing with definitional trees enjoys a weak completeness result wrt to rewriting (Theorem 6.19); completeness wrt rewriting in the usual sense is known only for the case of terminating rewriting systems (Theorem 6.20). No repeated solutions are computed (Theorem 7.1), but optimality wrt the length of narrowing derivations is currently only a conjecture. Of course, all the known properties of needed narrowing are preserved for the first-order case. In summary, the paper provides a well-formalized presentation of a pragmatically useful strategy, which should be complemented in the future by a deeper theory of higher-order needed reductions.

## 1 Introduction

Functional logic languages (Hanus, 1994) with a sound and complete operational semantics are mainly based on narrowing. Narrowing, originally introduced in automated theorem proving (Slagle, 1974), is used to solve goals by finding appropriate values for variables occurring in arguments of functions. A narrowing step instantiates variables in a goal and applies a reduction step to a redex of the instantiated goal. The instantiation of goal variables is usually computed by unifying a subterm of the goal with the left-hand side of some rule.

## Example 1.1

Consider the following rules defining the less-or-equal predicate on natural numbers which are represented by terms built from 0 and $s$ :

$$
\begin{array}{rlrl}
0 \leqslant X & & \rightarrow \text { true } \\
s(X) \leqslant 0 & & \rightarrow & \text { false } \\
s(X) \leqslant s(Y) & & \rightarrow X \leqslant Y
\end{array}
$$

To solve the goal $s(X) \leqslant Y$, we perform a first narrowing step by instantiating $Y$ to $s\left(Y_{1}\right)$ and applying the third rule, and a second narrowing step by instantiating $X$ to 0 and applying the first rule:

$$
s(X) \leqslant Y \quad \leadsto \rightsquigarrow_{\left\{Y \mapsto s\left(Y_{1}\right)\right\}} \quad X \leqslant Y_{1} \quad \leadsto \rightsquigarrow_{\{X \mapsto 0\}} \quad \text { true }
$$

Since the goal is reduced to true, the computed solution is $\left\{X \mapsto 0, Y \mapsto s\left(Y_{1}\right)\right\}$.
Due to the huge search space of simple narrowing, steadily improved narrowing strategies have been developed in the past. Needed narrowing (Antoy et al., 1994) is based on the idea to evaluate only subterms which are needed in order to compute some result. For instance, in a goal $t_{1} \leqslant t_{2}$, it is always necessary to evaluate $t_{1}$ (to some head normal form) since all three rules in Example 1.1 have a non-variable first argument. On the other hand, the evaluation of $t_{2}$ is only needed if $t_{1}$ is of the form $s(\cdots)$. Thus, if $t_{1}$ is a free variable, needed narrowing instantiates it to a constructor, here 0 or $s$. Depending on this instantiation, either the first rule is applied or the second argument $t_{2}$ is evaluated. Needed narrowing is the currently best narrowing strategy for first-order functional logic programs due to its optimality properties
wrt the length of derivations and the number of computed solutions (Antoy et al., 1994). Since needed narrowing is defined for inductively sequential rewrite systems (Antoy, 1992) (these are constructor-based rewrite systems with discriminating lefthand sides, i.e. typical functional programs), it can be efficiently implemented by pattern-matching and unification due to its local computation of a narrowing step (see, e.g. (Antoy, 1996; Hanus, 1995; Loogen et al., 1993)).

On ground terms, needed narrowing falls back to the classical notion of 'needed reduction' in the sense of Huet and Lévy (1991). Evaluation by needed narrowing has also some similarities to pattern matching and lazy evaluation in functional languages like Haskell (Hudak et al., 1992) or Miranda (Peyton Jones, 1987). Note, however, that needed narrowing or needed reduction is a more powerful evaluation strategy than the simpler left-to-right pattern matching in current functional languages. For instance, consider the rules

$$
\begin{aligned}
f(0,0) & \rightarrow 0 \\
f(X, s(N)) & \rightarrow 0
\end{aligned}
$$

and a non-terminating function $\perp$. Since only the evaluation of the second argument of $f$ is needed in order to apply a reduction rule, needed narrowing does not evaluate the first argument of the function call $f(\perp, s(0))$. Thus, needed narrowing reduces this expression to 0 , in contrast to Miranda or Haskell which do not terminate on this function call. In general, needed narrowing/rewriting always computes a normal form if it exists (Antoy, 1992).

In this paper, we extend the needed narrowing strategy to higher-order functions and $\lambda$-terms as data structures (the idea to use $\lambda$-terms as data structures stems from $\lambda$ Prolog (Nadathur and Miller, 1988)). In contrast to current functional languages, we permit free (existentially quantified) variables and $\lambda$-abstractions in expressions, and the latter also in left-hand sides of rewrite rules. This allows one to manipulate objects, such as formulas and programs, whose representation requires structures containing abstractions or bound variables. For instance, this has interesting applications in the verification and synthesis of software and hardware (Prehofer, 1995b; Prehofer, 1996; Prehofer, 1997). Furthermore, universally quantified goals are possible, as a goal $\forall x . s=\forall x . t$ is equivalent to $\lambda x . s=\lambda x . t$.

As a simple example of such higher-order functional logic programs, we define the differential of a function at some point.

## Example 1.2

Consider the following rules defining a higher-order function diff, where $\operatorname{diff}(F, X)$ computes the differential of $F$ at $X$ (we abbreviate $s(0)$ by 1 ):

$$
\begin{array}{ll}
\operatorname{diff}(\lambda y \cdot y, X) & \rightarrow 1 \\
\operatorname{diff}(\lambda y \cdot \sin (F(y)), X) & \rightarrow \cos (F(X)) * \operatorname{diff}(\lambda y \cdot F(y), X) \\
\operatorname{diff}(\lambda y \cdot \ln (F(y)), X) & \rightarrow \\
\operatorname{diff}(\lambda y \cdot F(y), X) / F(X)
\end{array}
$$

With these rules, we can compute the differential of the double application of the
function $\sin$ :

$$
\begin{aligned}
\lambda x \cdot \operatorname{diff}(\lambda y \cdot \sin (\sin (y)), x) & \rightarrow \lambda x \cdot \cos (\sin (x)) * \operatorname{diff}(\lambda y \cdot \sin (y), x) \\
& \rightarrow \lambda x \cdot \cos (\sin (x)) * \cos (x) * \operatorname{diff}(\lambda y \cdot y, x) \\
& \rightarrow \lambda x \cdot \cos (\sin (x)) * \cos (x) * 1
\end{aligned}
$$

Since we also allow free variables in expressions which are solved by narrowing, our calculus is able to synthesize new functions satisfying some goal. For instance, the equation

$$
\lambda x \cdot \operatorname{diff}(\lambda y \cdot \sin (F(x, y)), x)=\lambda x \cdot \cos (x)
$$

is solved by instantiating the higher-order variable $F$ by the projection function $\lambda x, y . y$.

The interesting point in this example is the structure of the left-hand side of the rules. In order to apply a rule for diff, the first argument must always be evaluated to the form $\lambda y . v(\cdots)$ with $v \in\{y, \sin , \ln \}$, whereas the second argument can be arbitrary. In this sense, the first argument of diff is needed in contrast to the second. This property provides an efficient evaluation strategy similar to the first-order case. To summarize, the main contributions of this paper are as follows.

- We introduce a class of higher-order inductively sequential rewrite rules which can be defined via definitional trees. Although this class is a restriction of general higher-order rewrite systems, it covers higher-order functional languages.
- As higher-order rewrite steps can be expensive in general, we show that finding a redex with inductively sequential rules can be performed as in the first-order case. Furthermore, so-called flex-flex pairs do not have to be considered in this case, in contrast to general higher-order unification.
- Since our narrowing calculus LNT is oriented towards previous work on higher-order narrowing (Prehofer, 1997), we show that LNT coincides with needed narrowing in the first-order case. Note that steps of classic narrowing strategies (Hullot, 1980; Slagle, 1974) are defined as a variable instantiation followed by the reduction of some subterm, whereas more recent lazy narrowing strategies (Hölldobler, 1989; Ida and Nakahara, 1997; Martelli et al., 1989; Middeldorp et al., 1996; Nakahara et al., 1995) manipulate equation systems in the style of Martelli and Montanari's unification algorithm (Martelli and Montanari, 1982) and always reduce outermost function symbols instead of subterms. Thus, we present, for the first time, a needed narrowing calculus in the Martelli/Montanari style and show its equivalence with the original formulation. This leads to a better understanding and a formal comparison of the different calculi. In contrast to Ida and Nakahara (1997) and Middeldorp et al. (1996), we integrate the pattern matching into the narrowing steps via definitional trees. As a consequence, our calculus is completely deterministic on ground terms, whereas Ida and Nakahara (1997) and Middeldorp et al. (1996) implement pattern matching by non-deterministic search.
- For the higher-order case, we show soundness and completeness with respect to LNT reductions, a particular form of higher-order reductions which we
define via definitional trees. A general completeness result wrt arbitrary reduction would be interesting but is outside the scope of this paper, since an overall theory of higher-order needed reduction has not been developed up to now. Nevertheless, we strongly conjecture that LNT reductions are in fact normalizing which is witnessed by the following facts:
- LNT reductions are needed for reduction to a constructor normal form.
- LNT reductions fall back to (first-order) needed reductions, which are known to be normalizing (Huet and Lévy, 1991), if the higher-order features are not used.

For terminating higher-order inductively sequential rewrite systems, we show that LNT reductions compute a ground constructor normal form, if one exists. This implies a general completeness result for our strategy wrt arbitrary reduction. Note that termination is also required for other higher-order narrowing calculi (Prehofer, 1997). In the context of functional logic languages, the definition of infinite data structures does not need non-terminating rules because infinite data structures can also be defined by terminating rules and the use of existential variables (see Prehofer, 1997, Section 8.1.5). Nevertheless, a demand-driven evaluation strategy like ours is also useful for terminating rewrite systems since it evaluates subterms only when needed.

- We show that the calculus is optimal wrt the solutions computed, i.e. no solution is produced twice. Since optimality of higher-order needed reductions is subject of current research, we show that LNT reductions are in fact needed for reduction to a constructor normal form. Thus, this strategy is the first calculus for higher-order functional logic programming which provides for optimality results. Moreover, it falls back to the optimal needed narrowing strategy if the higher-order features are not used, i.e. our calculus is a conservative extension of an optimal first-order narrowing calculus.
- Since we allow higher-order logical variables denoting $\lambda$-terms (similar to $\lambda$ Prolog (Nadathur and Miller, 1988) or Escher (Lloyd, 1994)), applications go beyond current functional and logic programming languages. In general, our calculus can compute solutions for variables of functional type. Although this is very powerful, we show that the incurring higher-order unification can sometimes be avoided by techniques similar to Avenhaus and Loría-Sáenz (1994).

After recalling basic notions from the $\lambda$-calculus and term rewriting, we relate in section 3 the original first-order needed narrowing calculus with the lazy narrowing calculus LNT in the style of Martelli and Montanari and show the equivalence of both calculi. Section 4 introduces higher-order inductively sequential rewrite systems and the extension of our calculus LNT to such programs is shown in section 5 . We proof soundness and completeness results in section 6 and an optimality result in section 7. Finally, section 8 discusses criteria to avoid the sometimes operationally complex higher-order unification features of LNT.

## 2 Preliminaries

We briefly introduce the simply typed $\lambda$-calculus (Hindley and Seldin, 1986). The set of types $\mathscr{T}$ for the simply typed $\lambda$-terms is generated by a set $\mathscr{T}_{0}$ of base types (e.g. int, bool) and the function type constructor $\rightarrow$. Note that $\rightarrow$ is right-associative, i.e. $\alpha \rightarrow \beta \rightarrow \gamma=\alpha \rightarrow(\beta \rightarrow \gamma)$. We assume for all types $\tau \in \mathscr{T}$ a set of variables $V_{\tau}$ and a set of (function) constants $C_{\tau}$, where $V_{\tau} \cap V_{\tau^{\prime}}=C_{\tau} \cap C_{\tau^{\prime}}=\{ \}$ for $\tau \neq \tau^{\prime}$. If $f \in C_{\tau_{1} \rightarrow \cdots \rightarrow \tau_{n} \rightarrow \tau_{0}}$ where $\tau_{0} \in \mathscr{T}_{0}$, then we call $n$ the arity of $f$. We assume the following variable conventions:

- $F, G, H, P, X, Y$ denote free variables,
- $a, b, c, f, g$ (function) constants, and
- $x, y, z$ bound variables.

Further, we often use $s$ and $t$ for terms and $u, v, w$ for constants or bound variables.
The syntax for $\lambda$-terms is given by

$$
t=F|x| c|\lambda x . t|\left(t_{1} t_{2}\right)
$$

Type judgments are written as $t: \tau$. The following inference rules inductively define the set of simply typed $\lambda$-terms:

$$
\begin{array}{cc}
\frac{x \in V_{\tau}}{x: \tau} & \frac{c \in C_{\tau}}{c: \tau} \\
\frac{s: \tau \rightarrow \tau^{\prime} \quad t: \tau}{(s t): \tau^{\prime}} & \frac{x: \tau \quad s: \tau^{\prime}}{(\lambda x . s): \tau \rightarrow \tau^{\prime}}
\end{array}
$$

In the following, we only consider simply typed $\lambda$-terms (substitutions, equations etc). We write $\lambda x_{1}, x_{2}, \ldots, x_{n} . t$ for $\lambda x_{1} .\left(\lambda x_{2} \ldots .\left(\lambda x_{n} . t\right) \ldots\right)$. A list of syntactic objects $s_{1}, \ldots, s_{n}$ where $n \geqslant 0$ is abbreviated by $\overline{s_{n}}$. For instance, $n$-fold abstraction and application are written as $\lambda \overline{x_{n}} \cdot s=\lambda x_{1}, \ldots, x_{n} . s$ and $a\left(\overline{s_{n}}\right)=\left(\left(\cdots\left(a s_{1}\right) \cdots\right) s_{n}\right)$, respectively. Substitutions are finite mappings from variables to terms, denoted by $\left\{\overline{X_{n} \mapsto t_{n}}\right\}$, and extend homomorphically from variables to terms. The composition $\varphi \sigma$ of two substitutions $\varphi$ and $\sigma$ is defined as $(\varphi \sigma)(t)=\varphi(\sigma(t))$. Free and bound variables of a term $t$ will be denoted as $\mathscr{F} \mathscr{V}(t)$ and $\mathscr{B} \mathscr{V}(t)$, respectively. A term $t$ is ground if $\mathscr{F} \mathscr{V}(t)=\{ \}$. The conversions in $\lambda$-calculus are defined as (where $\{x \mapsto y\} t$ denotes the result of replacing every free occurrence of $x$ in $t$ by $y$ ):

- $\alpha$-conversion: $\lambda x . t={ }_{\alpha} \lambda y .(\{x \mapsto y\} t)$ if $y \notin \mathscr{F} \mathscr{V}(t)$,
- $\beta$-conversion: $(\lambda x . s) t=\beta\{x \mapsto t\} s$, and
- $\eta$-conversion: $\lambda x .(t x)={ }_{\eta} t$ if $x \notin \mathscr{F} \mathscr{V}(t)$.

The long $\beta \eta$-normal form (Nipkow, 1991) of a term $t$, denoted by $t \downarrow_{\beta}^{\eta}$, is the $\eta$ expanded form of the $\beta$-normal form of $t$. It is well known (Hindley and Seldin, 1986) that $s={ }_{\alpha \beta \eta} t$ iff $s \uparrow_{\beta}^{\eta}={ }_{\alpha} t \uparrow_{\beta}^{\eta}$. As long $\beta \eta$-normal forms exist for typed $\lambda$-terms, we will in general assume that terms are in long $\beta \eta$-normal form. For brevity, we may write variables in $\eta$-normal form, e.g. $X$ instead of $\lambda \overline{x_{n}} \cdot X\left(\overline{x_{n}}\right)$. We assume that the transformation into long $\beta \eta$-normal form is an implicit operation, e.g. when applying a substitution to a term.

A substitution $\theta$ is in long $\beta \eta$-normal form if all terms in the image of $\theta$ are in long $\beta \eta$-normal form. The convention that $\alpha$-equivalent terms are identified and that free and bound variables are kept disjoint (see also Barendregt (1984)) is used in the following. Furthermore, we assume that bound variables with different binders have different names.

Define $\mathscr{D} o m(\theta)=\{X \mid \theta X \neq X\}$ and $\mathscr{R} n g(\theta)=\bigcup_{X \in \mathscr{O} o m(\theta)} \mathscr{F} \mathscr{V}(\theta X)$. Two substitutions are equal on a set of variables $W$, written as $\theta={ }_{W} \theta^{\prime}$, if $\theta X=\theta^{\prime} X$ for all $X \in W$. The restriction of a substitution to a set of variables $W$ is defined as $\theta_{\mid W} X=\theta X$ if $X \in W$ and $\theta_{\mid W} X=X$ otherwise. A substitution $\theta$ is idempotent iff $\theta=\theta \theta$. A substitution $\theta^{\prime}$ is more general than $\theta$ over a set of variables $W$, written as $\theta^{\prime} \leqslant{ }_{W} \theta$, if $\theta={ }_{W} \sigma \theta^{\prime}$ for some substitution $\sigma$. Two terms $s$ and $t$ are unifiable if there exists a substitution $\sigma$, also called a unifier for $s$ and $t$, with $\sigma s=\sigma t$. A unifier $\sigma$ for $s$ and $t$ is called most general if for each other unifier $\sigma^{\prime}$ for $s$ and $t$ there exists a substitution $\varphi$ with $\sigma^{\prime}=\varphi \sigma$.

We describe positions in $\lambda$-terms by sequences over natural numbers. The subterm of $s$ at position $p$, written as $\left.s\right|_{p}$, is defined as

- $\left.s\right|_{\epsilon}=s$
- $\left.v\left(\overline{t_{m}}\right)\right|_{i . p}=\left.t_{i}\right|_{p}$ if $1 \leqslant i \leqslant m$
- $\left.\lambda \overline{x_{m}} \cdot t\right|_{1 . p}=\left.\left(\lambda x_{2}, \ldots, x_{m} \cdot t\right)\right|_{p}$
- undefined otherwise

A term $t$ with the subterm at position $p$ replaced by $s$ is written as $t[s]_{p}$.
A term $t$ in $\beta$-normal form is called a higher-order pattern if every free occurrence of a variable $F$ is in a subterm $F\left(\overline{u_{n}}\right)$ of $t$ such that the $\overline{u_{n}}$ are $\eta$-equivalent to a list of distinct bound variables. Unification of patterns is decidable and a most general unifier exists if they are unifiable (Miller, 1991). Examples of higher-order patterns are $\lambda x, y \cdot F(x, y)$ and $\lambda x . f(G(\lambda z . x(z)))$, where the latter is at least third-order. Non-patterns are for instance $\lambda x, y . F(a, y)$ and $\lambda x . G(H(x))$.

A rewrite rule (Nipkow, 1991) is a pair $l \rightarrow r$ such that $l$ is a higher-order pattern but not a free variable, $l$ and $r$ are long $\beta \eta$-normal forms of the same base type, and $\mathscr{F} \mathscr{V}(l) \supseteq \mathscr{F} \mathscr{V}(r)$. Assuming a rule $l \rightarrow r$ and a position $p$ in a term $s$ in long $\beta \eta$-normal form, a rewrite step from $s$ to $t$ is defined as

$$
\left.s \longrightarrow{ }_{p, \theta}^{l \rightarrow r} t \Leftrightarrow s\right|_{p}=\theta l \wedge t=s[\theta r]_{p} .
$$

For a rewrite step we often omit some of the parameters $l \rightarrow r, p$ and $\theta$. It is a standard assumption in functional logic programming that constant symbols are divided into free constructor symbols and defined symbols. A symbol $f$ is called a defined symbol or operation, if a rule $f(\cdots) \rightarrow t$ exists. A constructor term is a term without defined symbols. Constructor symbols and constructor terms are denoted by $c$ and $d$. A term $f\left(\overline{t_{n}}\right)$ is called operation-rooted (respectively constructor-rooted) if $f$ is a defined symbol (respectively constructor). A higher-order rewrite system (HRS) $\mathscr{R}$ is a set of rewrite rules. A term is in $\mathscr{R}$-normal form if no rule from $\mathscr{R}$ applies and a substitution $\theta$ is $\mathscr{R}$-normalized if all terms in the image of $\theta$ are in $\mathscr{R}$-normal form.

By applying rewrite steps, we can compute the value of a functional expression. Similarly to current functional languages, we consider only (first-order) constructor terms (and not arbitrary normal forms) as values which can be observed by the user. To simplify our calculi, we consider only the evaluation of expressions to 0 -ary constructor constants, i.e. an evaluation of a term $t$ has the form $t \rightarrow \cdots \rightarrow c$ where $c$ is a 0 -ary constructor. In the presence of free variables, it might be necessary to compute values for these free variables such that the instantiated expression is reducible. This can be done by narrowing which will be precisely defined in the following sections.

This notion of evaluation to 0 -ary constructors is general enough to cover a variety of different evaluation tasks occurring in functional logic languages. For instance, if we are interested in the reduction of an expression to a constructor term $c$, we add the rule $f(c) \rightarrow o k$, where $f$ and $o k$ are new symbols. Then, $t$ is reducible to $c$ iff $f(t)$ is reducible to the constructor $o k$. For instance, the equation shown in Example 1.2 above can be solved by adding the rule

$$
f(\lambda x \cdot \cos (x)) \rightarrow o k
$$

and evaluating the term $f(\lambda x \cdot \operatorname{diff}(\lambda y \cdot \sin (F(x, y)), x))$. If this term is evaluated (by narrowing) to $o k$, then the computed binding for the free variable $F$ is a solution of the equation.

When we are interested to evaluate expressions to (first-order) ground constructor terms, we could add new symbols true, $\wedge$, and ground (more precisely, one ground symbol for each base type), together with the following rules, where $\wedge$ is assumed to be a right-associative infix symbol, and $c$ is a constructor of arity 0 in the first rule and arity $n>0$ in the second rule. Then, $t$ is reducible to a first-order ground constructor term $s$ if $\operatorname{ground}(t)$ is reducible to true.

$$
\begin{aligned}
\operatorname{ground}(c) & \rightarrow \text { true } \\
\operatorname{ground}\left(c\left(X_{1}, \ldots, X_{n}\right)\right) & \rightarrow \operatorname{ground}\left(X_{1}\right) \wedge \cdots \wedge \operatorname{ground}\left(X_{n}\right) \\
\text { true } \wedge X & \rightarrow X
\end{aligned}
$$

Finally, we can use a similar technique to cover the equation solving capabilities of current functional logic languages with a lazy operational semantics, like BABEL (Moreno-Navarro and Rodríguez-Artalejo, 1992) or K-LEAF (Giovannetti et al., 1991), since the strict equality ' $\approx$ ' $\left(t_{1} \approx t_{2}\right.$ holds if $t_{1}$ and $t_{2}$ are reducible to a same ground constructor term) can be defined as a binary operation by a set of orthogonal rewrite rules. For this purpose, consider a family of (infix) symbols $\approx$ (one operation for each base type) defined by the following rules (as above, $c$ is a constructor of arity 0 in the first rule and arity $n>0$ in the second rule):

$$
\begin{aligned}
c \approx c & \rightarrow \text { true } \\
c\left(X_{1}, \ldots, X_{n}\right) \approx c\left(X_{1}, \ldots, X_{n}\right) & \rightarrow\left(X_{1} \approx Y_{1}\right) \wedge \cdots \wedge\left(X_{n} \approx Y_{n}\right) \\
\text { true } \wedge X & \rightarrow X
\end{aligned}
$$

A strict equation is valid if it can be rewritten to true with these rules (see Antoy et al. (1994), Giovannetti et al. (1991) and Moreno-Navarro and RodríguezArtalejo (1992)) for more details about strict equality, where in Moreno-Navarro
and Rodríguez-Artalejo (1992), additional rules for disequalities are added to derive the result false for an equation). Note that normal forms may not exist in general due to non-terminating rewrite rules. As a particular case, a first-order ground constructor normal form of an expression $t$ can be computed by solving the equation $t \approx X$ where $X$ is a free variable, since $t \approx s$ is reducible to true iff $t$ and $s$ are reducible to a same ground constructor term (see Antoy et al. (1994, Proposition 1).

This interpretation of equality in goals is also taken in functional logic languages with higher-order features (several authors (González-Moreno et al., 1992) propose a slightly extended definition without explicit rewrite rules). Although this explicit definition of strict equality only supports equalities between first-order terms, higherorder terms (i.e. functions) can occur in data structures as long as these data structures are not checked for equality. For instance, it is possible in our framework to compute the length of a list of functions since the functional elements do not occur in the result of this computation. Furthermore, higher-order terms may occur as arguments in the left-hand sides of rewrite rules so that new functions may be synthesized by our higher-order narrowing strategy (in contrast to current purely functional languages), as shown in Example 1.2.

We often consider a goal as an expression of Boolean type that should be reduced to the constant true. A substitution $\sigma$ is a solution of a goal $G$ iff $\sigma(G)$ can be rewritten to true. Note, however, that we will present our soundness and completeness results for more general terms rather than goals.

Notice that a subterm $\left.s\right|_{p}$ may contain free variables which used to be bound in $s$. For rewriting it is possible to ignore this, as only matching of a left-hand side of a rewrite rule is needed. For narrowing, we need unification and hence we use the following construction to lift a rule into a binding context. An $\overline{x_{k}}$-lifter of a term $t$ away from $W$ is a substitution $\sigma=\left\{F \mapsto(\rho F)\left(\overline{x_{k}}\right) \mid F \in \mathscr{F} \mathscr{V}(t)\right\}$ where $\rho$ is a renaming such that $\mathscr{D} o m(\rho)=\mathscr{F} \mathscr{V}(t), \mathscr{R} n g(\rho) \cap W=\{ \}$ and $\rho F: \tau_{1} \rightarrow \cdots \rightarrow \tau_{k} \rightarrow \tau$ if $x_{1}: \tau_{1}, \ldots, x_{k}: \tau_{k}$ and $F: \tau$. A term $t$ (rewrite rule $l \rightarrow r$ ) is $\overline{x_{k}}$-lifted if an $\overline{x_{k}}$-lifter has been applied to $t(l$ and $r)$. For example, $\left\{G \mapsto G^{\prime}(x)\right\}$ is an $x$-lifter of $g(G)$ away from any $W$ not containing $G^{\prime}$.

## 3 First-order definitional trees

Definitional trees are introduced by Antoy (1992) to define efficient normalization strategies for (first-order) term rewriting. The idea is to represent all rules for a defined symbol in a tree and to control the selection of the next redex by this tree. This technique is extended to narrowing in Antoy et al. (1994), where it is shown that a narrowing strategy based on definitional trees is optimal in the length of narrowing derivations and the number of computed solutions. We will extend definitional trees to the higher-order case in order to obtain a similar strategy for higher-order narrowing. To state a clear relationship between the first-order and the higher-order case, we review the first-order case in this section and present the needed narrowing calculus in a new form, which is more appropriate with regard to the extension to the higher-order case. Thus, we assume in this section that all terms are first-order, i.e. $\lambda$-abstractions, functional variables and partial applications
(i.e. applications to less arguments than the arity of a symbol, which correspond to $\lambda$-abstractions after $\eta$-expansion) do not occur.

A traditional narrowing step (Hanus, 1994) is defined by computing a most general unifier of a subterm of the current term and the left-hand side of a rewrite rule, applying this unifier to the current term and replacing the subterm by the instantiated right-hand side of the rule. More precisely, a term $t$ is narrowed into a term $t^{\prime}$ if there exist a non-variable position $p$ in $t$ (i.e. $\left.t\right|_{p}$ is not a free variable), a variant $l \rightarrow r$ of a rewrite rule with $\mathscr{F} \mathscr{V}(t) \cap \mathscr{F} \mathscr{V}(l \rightarrow r)=\{ \}$ and a most general unifier $\sigma$ of $\left.t\right|_{p}$ and $l$ such that $t^{\prime}=\sigma\left(t[r]_{p}\right)$. In this case we write $t \rightsquigarrow_{\sigma_{\mid \mathscr{F} \mathcal{N}^{(t)}}} t^{\prime}$ (since we are interested only in the instantiation of the goal variables, we omit the bindings of the other local variables in the narrowing steps). We write $t_{0} \leadsto \overbrace{\sigma}^{*} t_{n}$ if there is a narrowing derivation $t_{0} \leadsto_{\sigma_{1}} t_{1} \leadsto \leadsto_{\sigma_{2}} \cdots \leadsto_{\sigma_{n}} t_{n}$ with $\sigma=\sigma_{n} \cdots \sigma_{2} \sigma_{1}$. In order to compute all solutions by narrowing, we have to apply all rules at all non-variable subterms in parallel. Since this simple method leads to a huge and often infinite search space, many improvements have been proposed in the past (see Hanus (1994) for a survey). A narrowing strategy determines the position where the next narrowing step should be applied. As shown in Antoy et al. (1994), an optimal narrowing strategy can be obtained by dropping the requirement for computing a most general unifier in each narrowing step and controlling the instantiation of variables and selection of narrowing positions by a data structure, called definitional tree. For instance, consider the rules of Example 1.1 together with the rule

$$
f(0) \rightarrow 0
$$

and the goal $X \leqslant f(Y)$. The second argument $f(Y)$ needs only to be evaluated if $X$ is bound to a term of the form $s(\cdots)$. Therefore, needed narrowing instantiates $X$ either to 0 (and reduces the goal to true without evaluating $f(Y)$ ) or to $s(Z)$. In the latter case, $f(Y)$ must be evaluated. However, the resulting needed narrowing step

$$
X \leqslant f(Y) \rightsquigarrow_{\{X \mapsto s(Z), Y \mapsto 0\}} s(Z) \leqslant 0
$$

is not a traditional narrowing step with a most general unifier. On the other hand, traditional lazy narrowing (Moreno-Navarro and Rodríguez-Artalejo, 1992) narrows the second argument $f(Y)$ since it is a demanded argument and binds in the subsequent narrowing step $X$, i.e. the derivation

$$
X \leqslant f(Y) \quad \rightsquigarrow_{\{Y \mapsto 0\}} \quad X \leqslant 0 \quad \rightsquigarrow_{\{X \mapsto 0\}} \quad \text { true }
$$

is a lazy narrowing derivation in the sense of Moreno-Navarro and RodríguezArtalejo (1992) which unnecessarily evaluates the subterm $f(Y)$. Thus, this derivation is not optimal.

To provide a precise definition of this needed narrowing strategy, we first recall the notion of a definitional tree (the following definition slightly differs from Antoy's (1992) original definition, since we ignore exempt nodes). $\mathscr{T}$ is a definitional tree with pattern $\pi$ (where $\pi$ has the form $f\left(\overline{t_{n}}\right)$ with $f$ defined symbol and $\overline{t_{n}}$ constructor terms and each variable in $\pi$ occurs only once) iff its depth is finite and one of the following cases holds:
$\mathscr{T}=\operatorname{rule}(l \rightarrow r)$, where $l \rightarrow r$ is a variant of a rule in $\mathscr{R}$ such that $l=\pi$.
$\mathscr{T}=\operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)$, where $o$ is an occurrence of a variable in $\pi, \overline{c_{k}}$ are pairwise different constructors of the type of $\left.\pi\right|_{o}(k>0)$, and, for $i=1, \ldots, k, \mathscr{T}_{i}$ is a definitional tree with pattern $\pi\left[c_{i}\left(\overline{X_{n_{i}}}\right)\right]_{o}$, where $n_{i}$ is the arity of $c_{i}$ and $\overline{X_{n_{i}}}$ are new distinct variables.

We denote by $\operatorname{pat}(\mathscr{T})$ the pattern of the definitional tree $\mathscr{T}$. A definitional tree of an $n$-ary function $f$ is a definitional tree $\mathscr{T}$ with pattern $f\left(\overline{X_{n}}\right)$, where $\overline{X_{n}}$ are distinct variables, such that, for each rule $l \rightarrow r \in \mathscr{R}$ with $l=f\left(\overline{t_{n}}\right)$, there is a node rule $\left(l^{\prime} \rightarrow r^{\prime}\right)$ in $\mathscr{T}$ with $l \rightarrow r$ variant of $l^{\prime} \rightarrow r^{\prime}$. For instance, the rules in Example 1.1 can be represented by the following definitional tree:

$$
\begin{aligned}
& \operatorname{branch}(X \leqslant Y, 1, \operatorname{rule}(\mathbf{0} \leqslant Y \rightarrow \text { true }) \\
& \qquad \operatorname{branch}\left(\boldsymbol{s}\left(X^{\prime}\right) \leqslant Y, 2, \operatorname{rule}\left(s\left(X^{\prime}\right) \leqslant \mathbf{0} \rightarrow \text { false }\right)\right. \\
& \left.\left.\operatorname{rule}\left(s\left(X^{\prime}\right) \leqslant \boldsymbol{s}\left(Y^{\prime}\right) \rightarrow X^{\prime} \leqslant Y^{\prime}\right)\right)\right)
\end{aligned}
$$

This tree can be illustrated by the following picture:


A definitional tree starts always with the most general pattern $f\left(\overline{X_{n}}\right)$ for a defined symbol $f$ and branches on the instantiation of a variable to constructor-headed terms, here 0 and $s\left(X^{\prime}\right)$. It is essential that each rewrite rule occurs only once as a leaf of the tree. Thus, when evaluating the arguments of a term $f\left(\overline{t_{n}}\right)$ to constructor terms, the tree can be incrementally traversed to find the matching rule.

A function $f$ is called inductively sequential if there exists a definitional tree of $f$. The term rewriting system $\mathscr{R}$ is called inductively sequential if each function defined by $\mathscr{R}$ is inductively sequential. Thus, inductively sequential rewrite rules are a subclass of constructor-based orthogonal rewrite systems which are appropriate to reflect current (first-order) functional languages.

### 3.1 Narrowing with definitional trees

A definitional tree defines a strategy to evaluate functions by applying narrowing steps. Since there may exist more than one definitional tree for a given function, we assume in the following that a definitional tree is fixed for each function, i.e. we talk about the definitional tree of a function. Note that the soundness and completeness results are independent of the chosen definitional trees. Different trees
may only influence the failure behavior of needed narrowing. An algorithm for the construction of definitional trees can be found in Hanus (1997).

To narrow a term $t$, we consider the definitional tree $\mathscr{T}$ of the outermost function symbol of $t$ (note that, since we consider only evaluations to 0 -ary constructors, the outermost symbol of a term to be evaluated is always a defined function).
$\mathscr{T}=$ rule $(l \rightarrow r)$ : Apply rule $l \rightarrow r$ to $t$ (note that $t$ is always an instance of $l$ ).
$\mathscr{T}=\operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)$ : Consider the subterm $\left.t\right|_{o}$.

1. If $\left.t\right|_{o}$ has a function symbol at the top, we narrow this subterm (to a term without a defined symbol at the top) by recursively applying our strategy to $\left.t\right|_{o}$.
2. If $\left.t\right|_{o}$ has a constructor symbol at the top, we narrow $t$ with $\mathscr{T}_{j}$, where the pattern of $\mathscr{T}_{j}$ matches $t$, otherwise (if no pattern matches) we fail.
3. If $\left.t\right|_{o}$ is a variable, we non-deterministically select a subtree $\mathscr{T}_{j}$, unify $t$ with the pattern of $\mathscr{T}_{j}$ (i.e. $\left.t\right|_{o}$ is instantiated to the constructor of the pattern of $\mathscr{T}_{j}$ at position $o$ ), and narrow this instance of $t$ with $\mathscr{T}_{j}$.

For instance, consider the rules of Example 1.1 and the goal $0 \leqslant f(Z)$. Since the definitional tree of $\leqslant$ is a branch on the first argument and the actual first argument is the constructor 0 , we proceed the evaluation of $0 \leqslant f(Z)$ with the subtree $\operatorname{rule}(0 \leqslant Y \rightarrow$ true $)$, which is the only subtree whose pattern matches the goal. Since this subtree is a rule, we apply the rule (without evaluating $f(Z)$ ) and obtain the result true.

This strategy, called needed narrowing (Antoy et al., 1994), is the currently best narrowing strategy due to its optimality wrt the length of derivations (if terms are shared) and the number of computed solutions.

A formal description of this strategy in terms of an inference system is shown in figure 1. If we want to narrow the operation-rooted term $t$ to some constructor, we apply inference steps to the term $t$ until we obtain the constructor or we fail. ${ }^{1}$ An $\mathscr{E}$ val-goal is any sequence obtained from such an initial goal by applying inference steps of this calculus. The inference rule Initial decorates the initial term with the appropriate definitional tree. If this tree is a rule, then the inference rule Apply applies an instance of this rule to the current term. Select selects the appropriate subtree of the current definitional tree, and Instantiate non-deterministically selects a subtree of the current definitional tree and instantiates the variable at the current position to the appropriate pattern. The rule Eval Subterm initiates the evaluation of the subterm at the current position by creating a new $\mathscr{E}$ val-goal for this subterm. As in proof procedures for logic programming, we assume that we take a definitional tree with fresh variables in each such evaluation step. This implies that all computed substitutions are idempotent (we will implicitly assume this property in the following). If a rewrite rule has been applied to this subterm (by inference rule

[^1]
## Initial

$$
t \Rightarrow\{\quad \mathscr{E} v a l(t, \mathscr{T})
$$

if $t=f\left(\overline{t_{n}}\right)$ and $\mathscr{T}$ is the definitional tree of $f$
Apply

$$
\mathscr{E} v a l(t, r u l e(l \rightarrow r)), G \quad \Rightarrow \quad \sigma(r), G
$$

$$
\text { if } \sigma(l)=t
$$

## Select

$\mathscr{E} \operatorname{val}\left(t, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right), G \quad \Rightarrow\left\{\mathscr{E} v a l\left(t, \mathscr{T}_{i}\right), G\right.$
if $\left.t\right|_{o}=c\left(\overline{t_{n}}\right)$ and $\left.\operatorname{pat}\left(\mathscr{T}_{i}\right)\right|_{o}=c\left(\overline{X_{n}}\right)$

## Instantiate

$\mathscr{E} \operatorname{val}\left(t, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right), G \quad \Rightarrow^{\sigma} \quad \sigma\left(\mathscr{E} \operatorname{val}\left(t, \mathscr{T}_{i}\right), G\right)$
if $\left.t\right|_{o}=X$ (variable) and $\sigma=\left\{\left.X \mapsto \operatorname{pat}\left(\mathscr{T}_{i}\right)\right|_{o}\right\}$

## Eval Subterm

$$
\begin{aligned}
\mathscr{E} \operatorname{val}\left(t, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right), G \quad \Rightarrow_{\}}^{\{ } \quad & \mathscr{E} \operatorname{val}\left(\left.t\right|_{o}, \mathscr{T}\right), \mathscr{E} \operatorname{val}\left(t, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right), G \\
& \text { if }\left.t\right|_{o}=f\left(\overline{t_{n}}\right) \text { and } \mathscr{T} \text { is the definitional tree of } f
\end{aligned}
$$

## Replace Subterm

$$
\begin{aligned}
t^{\prime}, \mathscr{E} \operatorname{val}\left(t, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right), G \quad \Rightarrow & \mathscr{E} \operatorname{val}\left(t\left[t^{\prime}\right]_{o}, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right), G \\
& \text { if } t^{\prime} \neq \mathscr{E} \operatorname{val}(\ldots, \ldots)
\end{aligned}
$$

Fig. 1. Calculus for needed narrowing.

Apply), the rewritten subterm is inserted at the current position by the inference rule Replace Subterm.

## Example 3.1

Consider the rules of Example 1.1 and the initial goal $s(X) \leqslant Y$. The following derivation shows the computation of the answer $\left\{X \mapsto 0, Y \mapsto s\left(Y_{2}\right)\right\}$ in the needed narrowing calculus. In contrast to traditional narrowing steps, where a subterm is directly unified with the left-hand side of some rewrite rule, the derivation steps in the needed narrowing calculus explicitly show the selection of the subterm and the instantiation of the goal variables.

$$
\begin{aligned}
& s(X) \leqslant Y \\
& \Rightarrow_{\text {Initial }} \\
& \mathscr{E} \operatorname{val}\left(s(X) \leqslant Y, \operatorname{branch}\left(X_{1} \leqslant Y_{1}, 1, \operatorname{rule}(\cdots), \operatorname{branch}\left(s\left(X_{2}\right) \leqslant Y_{1}, \ldots\right)\right)\right) \\
& \Rightarrow_{\text {Select }} \\
& \mathscr{E} v a l\left(s(X) \leqslant Y, \operatorname{branch}\left(s\left(X_{2}\right) \leqslant Y_{1}, 2, \operatorname{rule}\left(s\left(X_{2}\right) \leqslant 0 \rightarrow \text { false }\right),\right.\right. \\
& \left.\left.\operatorname{rule}\left(s\left(X_{2}\right) \leqslant s\left(Y_{2}\right) \rightarrow X_{2} \leqslant Y_{2}\right)\right)\right) \\
& \Rightarrow \begin{array}{l}
\left\{Y \mapsto s\left(Y_{2}\right)\right\} \\
\text { Instantiate }
\end{array} \\
& \mathscr{E} \operatorname{val}\left(s(X) \leqslant s\left(Y_{2}\right), \text { rule }\left(s\left(X_{2}\right) \leqslant s\left(Y_{2}\right) \rightarrow X_{2} \leqslant Y_{2}\right)\right) \\
& \Rightarrow{ }_{\text {Apply }} \\
& X \leqslant Y_{2} \\
& \Rightarrow_{\text {Initial }}
\end{aligned}
$$

$$
\begin{aligned}
& \mathscr{E v a l}\left(X \leqslant Y_{2}, \operatorname{branch}\left(X_{3} \leqslant Y_{3}, 1, \operatorname{rule}\left(0 \leqslant Y_{3} \rightarrow \operatorname{true}\right), \operatorname{branch}\left(s\left(X_{4}\right) \leqslant Y_{3}, \ldots\right)\right)\right) \\
& \quad \Rightarrow\{X \mapsto 0\} \\
& \mathscr{E} \operatorname{Val}\left(0 \leqslant Y_{2}, \operatorname{rule}\left(0 \leqslant Y_{3} \rightarrow \operatorname{true}\right)\right) \quad \Rightarrow_{\text {Apply }} \quad \operatorname{true}
\end{aligned}
$$

### 3.2 Narrowing with case expressions

In order to extend this strategy to higher-order functions, another representation is useful since an explicit representation of the structure of definitional trees in the rewrite rules provides more explicit control which leads to a simpler calculus. Also, it is shown in Prehofer (1994) that the direct application of narrowing steps to inner subterms should be avoided in the presence of $\lambda$-bound variables. This new representation will lead to an interesting comparison of needed rewrite sequences and leftmost outermost rewriting with case expressions.

For this purpose we transform the needed narrowing calculus into a lazy narrowing calculus in the spirit of Martelli/Montanari's inference rules. In a first step, we integrate the definitional trees into the rewrite rules by extending the language of terms and by providing case constructs to express the concrete narrowing strategy. A case expression has the form

$$
\text { case } X \text { of } c_{1}\left(\overline{X_{n_{1}}}\right): \mathscr{X}_{1}, \ldots, c_{k}\left(\overline{X_{n_{k}}}\right): \mathscr{X}_{k}
$$

where $X$ is a variable, $c_{1}, \ldots, c_{k}$ are different constructors of the type of $X$, and $\mathscr{X}_{1}, \ldots, \mathscr{X}_{k}$ are terms possibly containing case expressions. The variables $\overline{X_{n_{i}}}$ are called pattern variables and are local variables which occur only in the corresponding subexpression $\mathscr{X}_{i}$.

Using case expressions, each inductively sequential function symbol can be defined by exactly one rewrite rule, where the left-hand side consists always of the function symbol applied to different variables and the right-hand side is a representation of the corresponding definitional tree by case expressions. For instance, the rules for the function $\leqslant$ defined in Example 1.1 are represented by the following rewrite rule:

$$
\begin{array}{lllllll}
X \leqslant Y \rightarrow \text { case } X \text { of } & 0 & : & \text { true, } & & \\
& s\left(X_{1}\right) & : & \text { case } Y \text { of } & 0 & : & \text { false, } \\
& & & & s\left(Y_{1}\right) & : & X_{1} \leqslant Y_{1}
\end{array}
$$

Although this is not a rewrite rule in the traditional sense (due to the fresh pattern variables), we will provide a unique operational reading by specifying a particular semantics to case expressions. A case expression can be considered as a function symbol whose semantics is defined by a set of rewrite rules. For instance, the last case expression is considered as a function of arity 5 ('case $\left(X, 0, \operatorname{true}, s\left(X_{1}\right)\right.$, $\left.\operatorname{case}(Y, \ldots)\right)$ ', but we still use the mixfix notation in this paper) together with the following rewrite rules (where ' $\_$' denotes an arbitrary anonymous variable):

$$
\begin{array}{lllll}
\text { case } 0 & \text { of } 0: T, & :_{-} & \rightarrow & T \\
\operatorname{case} s(X) \text { of } & -:_{-}, & s(X): T & \rightarrow & T
\end{array}
$$

Although the left-hand side of the last rule is not linear, the multiple occurrence of the variable $X$ will be only used to pass subterms from one place to another and not
for comparing terms. This will become clear from the special use of case expressions (see below).

We formalize the mapping of a definitional tree $\mathscr{T}$ into a term with case expressions by the use of the translation function $\mathscr{C}$ ase $(\mathscr{T})$ :

$$
\begin{aligned}
\mathscr{C a s e}(\operatorname{rule}(l \rightarrow r)) & = \\
\mathscr{C a s e}\left(\operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right)= & \left.\operatorname{case} \pi\right|_{o} \text { of }\left.\operatorname{pat}\left(\mathscr{T}_{1}\right)\right|_{o}: \mathscr{C a s e}\left(\mathscr{T}_{1}\right), \\
& \\
& \\
& \left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \mathscr{C a s e}\left(\mathscr{T}_{k}\right)
\end{aligned}
$$

If $\mathscr{T}$ is the definitional tree with pattern $f\left(\overline{X_{n}}\right)$ of the $n$-ary function $f$, then

$$
f\left(\overline{X_{n}}\right) \rightarrow \mathscr{C} \operatorname{ase}(\mathscr{T})
$$

is the new rewrite rule for $f$. A case expression case $X$ of $\overline{p_{n}: \mathscr{X}_{n}}$ can be considered as a function with arity $2 n+1$ with the following $n$ rewrite rules: ${ }^{2}$

$$
\begin{aligned}
& \text { case } p_{1} \text { of } p_{1}: X, \ldots,:_{-} \\
& \vdots \\
& \text { case } p_{n} \text { of }{ }_{-}:{ }_{-}, \ldots, p_{n}: X \\
&
\end{aligned}
$$

If we apply a narrowing step to an expression of the form case tof $p_{1}: t_{1}, \ldots, p_{n}: t_{n}$, there are two principal possibilities:

1. If $t$ is a variable, we can apply any of the $n$ defining rules for case, i.e. there are $n$ possible narrowing steps

$$
\text { case } t \text { of } p_{1}: t_{1}, \ldots, p_{n}: t_{n} \rightsquigarrow_{\sigma} \sigma\left(t_{i}\right)
$$

with $\sigma=\left\{t \mapsto p_{i}\right\}(i \in\{1, \ldots, n\})$. This corresponds to an instantiation step in the needed narrowing calculus.
2. If $t$ is a constructor-rooted term $c\left(\overline{s_{k}}\right)$ and $p_{i}=c\left(\overline{X_{k}}\right)$ for some $i \in\{1, \ldots, n\}$, then

$$
\text { case } t \text { of } p_{1}: t_{1}, \ldots, p_{n}: t_{n} \leadsto\{ \} \sigma\left(t_{i}\right)
$$

for $\sigma=\left\{\overline{X_{k} \mapsto s_{k}}\right\}$. We write $\leadsto \leadsto_{\{ }$instead of $\leadsto_{\sigma}$ since we are interested only in the instantiation of goal variables and the pattern variables occur only locally in the expression $t_{i}$. This step corresponds to a selection step in the needed narrowing calculus.

In the following, we denote by $\mathscr{R}$ an inductively sequential rewrite system, by $\mathscr{R}^{\prime}$ its translated version containing exactly one rewrite rule for each function defined by $\mathscr{R}$, and by $\mathscr{R}_{\text {case }}$ the additional case rewrite rules. We will show a strong correspondence between derivations in the needed narrowing calculus and leftmost-outermost narrowing derivations. Leftmost-outermost narrowing means that the selected subterm is the leftmost-outermost one among all possible narrowing

[^2]positions, where we call a position $p$ leftmost-outermost in a set $P$ of positions if there is no $p^{\prime} \in P$ with $p^{\prime}$ prefix of $p$, or $p^{\prime}=q \cdot i \cdot q^{\prime}$ and $p=q \cdot j \cdot q^{\prime \prime}$ and $i<j$.

## Example 3.2

Consider again the rules of Example 1.1 and the initial goal $s(X) \leqslant Y$. The following derivation is a sequence of leftmost-outermost narrowing steps to compute the answer $\left\{X \mapsto 0, Y \mapsto s\left(Y_{1}\right)\right\}$. The applied rewrite rules are the single rule for $\leqslant$ together with the rewrite rules for case expressions as shown above.

$$
\begin{array}{ll}
s(X) \leqslant Y & \\
\rightsquigarrow \rightsquigarrow_{\{ \}} & \text {case } s(X) \text { of } 0: \text { true, } s\left(X_{1}\right):\left(\text { case } Y \text { of } 0: \text { false, } s\left(Y_{1}\right): X_{1} \leqslant Y_{1}\right) \\
\rightsquigarrow \rightsquigarrow_{\{ \}} & \text {case } Y \text { of } 0: \text { false, } s\left(Y_{1}\right): X \leqslant Y_{1} \\
\rightsquigarrow\left\{Y \mapsto s\left(Y_{1}\right)\right\} & X \leqslant Y_{1} \\
\rightsquigarrow \rightsquigarrow_{\{ \}} & \text {case } X \text { of } 0: \text { true, } s\left(X_{2}\right):\left(\text { case } Y_{1} \text { of } 0: \text { false, } s\left(Y_{2}\right): X_{2} \leqslant Y_{2}\right) \\
\rightsquigarrow\{X \mapsto 0\} & \text { true }
\end{array}
$$

The equivalence of needed narrowing wrt $\mathscr{R}$ and leftmost-outermost narrowing wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ is stated in the following theorem. The proof can be found in the appendix.

## Theorem 3.3

Let $t$ be a term and $c$ be a 0 -ary constructor. For each needed narrowing derivation $t \rightsquigarrow{ }_{\sigma}^{*} c$ wrt $\mathscr{R}$ there exists a leftmost-outermost narrowing derivation $t \rightsquigarrow{ }_{\sigma}^{*} c$ wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$, and vice versa.

As mentioned above, in the higher-order case we need a narrowing calculus which always applies narrowing steps to the outermost function symbol. This is often different from the leftmost-outermost narrowing position. For instance, the term $s(X) \leqslant X+X$ has the outermost function symbol $\leqslant$ which is different from the symbol + at the leftmost-outermost narrowing position. In order to obtain a calculus which always applies steps at the 'top level', we transform a leftmostoutermost narrowing derivation wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ into a derivation on a goal system $G$ (a sequence of goals of the form $t \rightarrow{ }^{?} X$ ) where narrowing rules are only applied to the outermost function symbol of the leftmost goal. This is the purpose of the inference system LNT shown in figure 2. The Bind rule propagates a term to the subsequent case expression. The Case rules correspond to the case distinction in the definition of needed narrowing, where the narrowing of a function is integrated in the Case Eval rule. Note that the only possible non-determinism during computation with these inference rules is in the Case Guess rule. Since we are interested in evaluating expressions to a 0 -ary constructor $c$, we assume that the initial goal $\mathscr{I}_{c}(t)$ for a term $t$ has always the form case t of $c: c \rightarrow{ }^{?} T$ where $T$ is a variable not occurring in $t$. We use this representation in order to provide a calculus with fewer inference rules. Note that $T$ will be bound to $c$ if such a goal can be reduced to the empty goal system.

## Bind

$$
\begin{aligned}
e \rightarrow^{?} Z, G \Rightarrow & \sigma(G) \\
& \text { where } \sigma=\{Z \mapsto e\} \text { and } e \text { is not a case term }
\end{aligned}
$$

## Case Select

$$
\begin{aligned}
\text { case } c\left(\overline{t_{n}}\right) \text { of } \overline{p_{k}: \mathscr{X}_{k}} \rightarrow ? ~ Z, G \Rightarrow\{ & \sigma\left(\mathscr{X}_{i}\right) \rightarrow ? ?, G \\
& \text { if } p_{i}=c\left(\overline{X_{n}}\right) \text { and } \sigma=\left\{\overline{X_{n} \mapsto t_{n}}\right\}
\end{aligned}
$$

## Case Guess

$$
\begin{aligned}
\text { case } X \text { of } \overline{p_{k}: \mathscr{X}_{k}} \rightarrow^{?} Z, G \Rightarrow^{\sigma} & \sigma\left(\mathscr{X}_{i}\right) \rightarrow^{?} Z, \sigma(G) \\
& \text { where } \sigma=\left\{X \mapsto p_{i}\right\}
\end{aligned}
$$

## Case Eval

$$
\text { case } \begin{aligned}
f\left(\overline{t_{n}}\right) \text { of } \overline{p_{k}: \mathscr{X}_{k}} \rightarrow^{?} Z, G \Rightarrow \Rightarrow^{\{ } & \sigma(\mathscr{X}) \rightarrow ? \text { ? } \text {, case } X \text { of } \overline{p_{k}: \mathscr{X}_{k}} \rightarrow ? ~ Z, G \\
& \text { if } f\left(\overline{X_{n}}\right) \rightarrow \mathscr{X} \in \mathscr{R} \text { ' is a rule with fresh variables, } \\
& \sigma=\left\{\overline{X_{n} \mapsto t_{n}}\right\}, \text { and } X \text { is a fresh variable }
\end{aligned}
$$

Fig. 2. Calculus LNT for lazy narrowing with definitional trees in the first-order case.

## Example 3.4

The following LNT-derivation corresponds to the leftmost-outermost narrowing derivation shown in Example 3.2.

$$
\text { case } s(X) \leqslant Y \text { of true : true } \rightarrow{ }^{?} T \quad\left(=\mathscr{I}_{\text {true }}(s(X) \leqslant Y)\right)
$$

$$
\Rightarrow_{\text {Case Eval }}
$$

case $s(X)$ of $0:$ true, $s\left(X_{1}\right):\left(\right.$ case $Y$ of $0:$ false, $\left.s\left(Y_{1}\right): X_{1} \leqslant Y_{1}\right) \rightarrow{ }^{?} Z$, case $Z$ of true : true $\rightarrow$ ? $T$

$$
\Rightarrow_{\text {Case Select }}
$$

```
case \(Y\) of \(0:\) false, \(s\left(Y_{1}\right): X \leqslant Y_{1} \rightarrow\) ? \(Z\), case \(Z\) of true : true \(\rightarrow\) ? \(T\)
    \(\Rightarrow \begin{gathered}\left\{Y \leftrightarrow s\left(Y_{1}\right)\right\} \\ \text { Case Guess }\end{gathered}\)
\(X \leqslant Y_{1} \rightarrow\) ? \(Z\), case \(Z\) of true \(:\) true \(\rightarrow\) ? \(T\)
    \(\Rightarrow{ }_{\text {Bind }}\)
case \(X \leqslant Y_{1}\) of true : true \(\rightarrow{ }^{?}\) T
    \(\Rightarrow\) Case Eval
```

case $X$ of $0:$ true, $s\left(X_{2}\right):\left(\right.$ case $Y_{1}$ of $0:$ false, $\left.s\left(Y_{2}\right): X_{2} \leqslant Y_{2}\right) \rightarrow{ }^{?} Z^{\prime}$,
case $Z^{\prime}$ of true : true $\rightarrow$ ? $T$

$$
\Rightarrow{ }_{\text {Case Guess }}^{\{X \leftrightarrow 0\}}
$$

$$
\text { true } \rightarrow^{?} Z^{\prime} \text {, case } Z^{\prime} \text { of true : true } \rightarrow^{?} T
$$

$$
\Rightarrow_{\text {Bind }}
$$

$$
\text { case true of true : true } \rightarrow ? \text { T }
$$

$$
\Rightarrow_{\text {Case Select }} \text { true } \rightarrow^{?} T \Rightarrow_{\text {Bind }}\{ \}
$$

The equivalence of leftmost-outermost narrowing and the lazy narrowing calculus LNT is stated in the following theorem. The proof can be found in the appendix.

## Theorem 3.5

Let $t$ be a term, $c$ a 0 -ary constructor, and $X$ a fresh variable. For each leftmostoutermost narrowing derivation $t \rightsquigarrow)_{\sigma}^{*} c$ wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ there exists a LNT-derivation case $t$ of $c: c \rightarrow ? ~ X ~ \stackrel{*}{\Rightarrow}{ }^{\sigma} c \rightarrow ? X$ wrt $\mathscr{R}^{\prime}$, and vice versa.

Theorems 3.3 and 3.5 imply the equivalence of needed narrowing and the calculus LNT. Since we will extend LNT to higher-order functions in the next section, the results in this section show that our higher-order calculus is a conservative extension of an optimal first-order narrowing strategy.

## 4 Higher-order definitional trees

In the following we extend first-order definitional trees to the higher-order case. To generalize from the first-order case, it is useful to recall the main ideas: When evaluating the arguments of a term $f\left(\overline{t_{n}}\right)$ to constructor terms, the definitional tree can be incrementally traversed to find the (single) matching rule. It is essential for the application of definitional trees that each branching depends on only one subterm (or argument to the function) and that for each rigid term (non-variable headed), a single branch can be chosen. For this purpose, we need further restrictions in the higher-order case, where we employ $\lambda$-terms as data structures, e.g. higher-order terms with bound variables in the left-hand sides. For instance, we permit higherorder rules like in Example 1.2. In contrast to the original definition of needed narrowing in the first-order case, we provide a definition of higher-order definitional trees in terms of case expressions. The relationship of the original definitional trees and case expressions was extensively discussed in the previous section.

A shallow pattern is a linear term of the form $\lambda \overline{x_{n}} \cdot v\left(\overline{H_{m}\left(\overline{x_{n}}\right)}\right)$ where $v$ is a constant or some bound variable $x_{i}$. We will use shallow patterns for branching in trees. In contrast to the first-order case, we have here the additional choice that $v$ can also be a bound variable.

## Definition 4.1

$\mathscr{T}$ is a higher-order definitional tree ( $\boldsymbol{h} \boldsymbol{d} \boldsymbol{t} \boldsymbol{)}$ iff its depth is finite and one of the following cases holds:

- $\mathscr{T}=p$ : case $X$ of $\overline{\mathscr{T}_{n}}$
- $\mathscr{T}=p: r h s$,
where $p$ are shallow patterns with fresh variables, $X$ is a free variable and $\overline{\mathscr{T}}_{n}$ are $h d t$ s in the first case, and $r h s$ is a term (representing the right-hand side of a rule). Moreover, all shallow patterns of the $h d t \mathrm{~s} \bar{T}_{n}$ must be pairwise non-unifiable.

When $h d t$ s are used to represent the rules of a function, further restrictions on the occurrences of free variables will be made (see below). We write $h d t$ s as $p: \mathscr{X}$, where $\mathscr{X}$ stands for a case expression or a term. To simplify technicalities, rewrite rules $f\left(\overline{X_{n}}\right) \rightarrow \mathscr{X}$ are identified with the hdt $f\left(\overline{X_{n}}\right): \mathscr{X}$. With this latter form of a rule, we
can relate rules to the usual notation as follows. The selector of a tree $\mathscr{T}$ of the form $\mathscr{T}=p: \mathscr{X}$ is defined as $\operatorname{sel}(\mathscr{T})=p$. For a subtree $\mathscr{T}^{\prime}$ in a tree $\mathscr{T}$, the constraints in the case expressions on the path to it determine a term, which is recursively defined by the pattern function pat $\mathscr{T}^{\left(\mathscr{T}^{\prime}\right)}$ :
$\operatorname{pat}_{\mathscr{T}}\left(\mathscr{T}^{\prime}\right)= \begin{cases}\operatorname{sel}\left(\mathscr{T}^{\prime}\right) & \text { if } \mathscr{T}=\mathscr{T}^{\prime} \text { (i.e. } \mathscr{T}^{\prime} \text { is the root) } \\ \left\{X \mapsto \operatorname{sel}\left(\mathscr{T}^{\prime}\right)\right\} \operatorname{pat}_{\mathscr{T}}\left(\mathscr{T}^{\prime \prime}\right) & \text { if } \mathscr{T}^{\prime} \text { has parent } \mathscr{T}^{\prime \prime}=p \text { :case } X \text { of } \overline{\mathscr{T}_{n}}\end{cases}$
Each branch variable must belong to the pattern of this subtree, i.e. for each subtree $\mathscr{T}^{\prime}=p$ : case $X$ of $\overline{\mathscr{T}}_{n}$ in a tree $\mathscr{T}, X$ is a free variable of pat $\mathscr{T}\left(\mathscr{T}^{\prime}\right)$. Furthermore, each leaf $\mathscr{T}^{\prime}=p: r h s$ of a $h d t \mathscr{T}$ is required to correspond to a rewrite rule $l \rightarrow r$, i.e. pat $\mathscr{T}\left(\mathscr{T}^{\prime}\right) \rightarrow r h s$ is a variant of $l \rightarrow r$. $\mathscr{T}$ is called $\boldsymbol{h d} \boldsymbol{t}$ of a function $f$ if for all rewrite rules of $f$ there is exactly one corresponding leaf in $\mathscr{T}$.

As in the first-order case, rewrite rules must be constructor based. This means that in a $h d t$ only the outermost pattern has a defined symbol. An HRS where each defined symbol has a $h d t$ is called inductively sequential.

For instance, the rules for diff in Example 1.2 have the hdt

$$
\begin{aligned}
\operatorname{diff}(F, X) \rightarrow \text { case } F \text { of } \begin{array}{ll}
\lambda y \cdot y & : \\
& 1 y \cdot \sin \left(F^{\prime}(y)\right)
\end{array} & : \cos \left(F^{\prime}(X)\right) * \operatorname{diff}\left(\lambda y \cdot F^{\prime}(y), X\right), \\
\lambda y \cdot \ln \left(F^{\prime}(y)\right) & : \operatorname{diff(\lambda y\cdot F^{\prime }(y),X)/F^{\prime }(X)}
\end{aligned}
$$

For presenting definitional trees graphically, it is convenient to write $\operatorname{pat}_{\mathscr{T}}\left(\mathscr{T}^{\prime}\right)$ for each subtree $\mathscr{T}^{\prime}$. Thus we draw the tree for diff as:


A hdt can also have a more complicated branching structure, as shown by the definitional tree for Example 1.1 in section 3 which is a special case of a $h d t$.

Note that free variables in left-hand sides must have all bound variables of the current scope as arguments. Such terms are called fully extended. This important restriction, which is also applied to study optimal reductions in Oostrom (1996), allows to find redices as in the first-order case, and furthermore simplifies narrowing. For instance, flex-flex pairs (equations between non-rigid terms) do not arise here, in contrast to the full higher-order case (Prehofer, 1995a, 1997). Consider an example for some non-overlapping rewrite rules which do not have a hdt:

$$
\begin{array}{lll}
f(\lambda x . c(x)) & \rightarrow & a \\
f(\lambda x . H) & \rightarrow & b
\end{array}
$$

The problem is that for rewriting a term with these rules the full term must be scanned. For example, if the argument to $f$ is the rigid term $\lambda x \cdot c(G(t))$, it is not possible to commit to one of the rules (or branches of a tree) before checking if

## Bind

$$
e \rightarrow^{?} Z, G \quad \Rightarrow \begin{aligned}
& \sigma(G) \\
& \\
& \text { where } \sigma=\{Z \mapsto e\} \text { and } e \text { is not a case term }
\end{aligned}
$$

## Case Select

$$
\begin{array}{lll}
\lambda \overline{k_{k}} \cdot \text { case } \lambda \overline{y_{l}} \cdot v\left(\overline{t_{m}}\right) \text { of } & \Rightarrow\{ & \lambda \overline{x_{k}} \cdot \sigma\left(\mathscr{X}_{i}\right) \rightarrow ? \\
\overline{p_{n}: \mathscr{X}_{n}} \rightarrow ? \\
? & Z, G, G \\
& \text { if } p_{i}=\lambda \overline{y_{l}} \cdot v\left(\overline{X_{m}\left(\overline{x_{k}}, \overline{y_{l}}\right)}\right) \text { and } \sigma=\left\{\overline{X_{m} \mapsto \lambda \overline{x_{k}}, \overline{y_{l}} \cdot t_{m}}\right\}
\end{array}
$$

## Imitation

$$
\begin{array}{cl}
\lambda \overline{x_{k}} . \text { case } \lambda \overline{y_{l}} \cdot X\left(\overline{t_{m}}\right) \text { of } \Rightarrow^{\sigma} & \sigma\left(\lambda \overline{x_{k}} \text {. case } \lambda \overline{y_{l}} \cdot X\left(\overline{t_{m}}\right) \text { of } \overline{p_{n}: \mathscr{X}_{n}} \rightarrow ? Z, G\right) \\
\overline{p_{n}: \mathscr{X}_{n}} \rightarrow ? Z, G & \text { if } p_{i}=\lambda \overline{y_{l}} \cdot c\left(\overline{X_{r}\left(\overline{x_{k}}, \overline{y_{l}}\right)}\right) \text { and } \sigma=\left\{X \mapsto \lambda \overline{x_{m}} \cdot c\left(\overline{H_{r}\left(\overline{x_{m}}\right)}\right)\right\}
\end{array}
$$

## Function Guess

$$
\begin{array}{cl}
\lambda \overline{x_{k}} \text {.case } \lambda \overline{y_{l}} \cdot X\left(\overline{t_{m}}\right) \text { of } \Rightarrow^{\sigma} & \sigma\left(\lambda \overline{x_{k}} \text {. case } \lambda \overline{y_{l}} \cdot X\left(\overline{t_{m}}\right) \text { of } \overline{p_{n}: \mathscr{X}_{n}} \rightarrow^{?} Z, G\right) \\
\overline{p_{n}: \mathscr{X}_{n}} \rightarrow ? Z, G & \text { if } \lambda \overline{x_{k}}, \overline{y_{l}} \cdot X\left(\overline{t_{m}}\right) \text { is not a higher-order pattern, } \\
& \sigma=\left\{X \mapsto \overline{x_{m}} . f\left(\overline{H_{r}\left(\overline{x_{m}}\right)}\right)\right\}, \text { and } f \text { is a defined function }
\end{array}
$$

## Projection

$$
\begin{array}{cl}
\lambda \overline{x_{k}} \text {.case } \lambda \overline{y_{l}} \cdot X\left(\overline{t_{m}}\right) \text { of } \Rightarrow^{\sigma} & \sigma\left(\lambda \overline{x_{k}} \text {.case } \lambda \overline{y_{l}} \cdot X\left(\overline{t_{m}}\right) \text { of } \overline{p_{n}: \mathscr{X}_{n}} \rightarrow^{?} Z, G\right) \\
\overline{p_{n}}: \mathscr{X}_{n} \rightarrow ? Z, G & \text { where } \sigma=\left\{X \mapsto \lambda \overline{x_{m}} \cdot x_{i}\left(\overline{H_{r}\left(\overline{x_{m}}\right)}\right)\right\}
\end{array}
$$

## Case Eval

$$
\left.\begin{array}{cl}
\lambda \overline{x_{k}} \cdot \text { case } \lambda \overline{y_{l}} \cdot f\left(\overline{t_{m}}\right) \text { of } \Rightarrow{ }^{\{ \}} & \lambda \overline{x_{k}}, \overline{y_{l}} \cdot \sigma(\mathscr{X}) \rightarrow ? \\
\overline{p_{n}}: \mathscr{X}_{n} \rightarrow
\end{array}{ }^{?} Z, G, \overline{x_{k}} \cdot \text { case } \lambda \overline{y_{l}} \cdot X\left(\overline{x_{k}}, \overline{y_{l}}\right) \text { of } \overline{p_{n}}: \mathscr{X}_{n} \rightarrow ? Z, G\right)
$$

Fig. 3. System LNT for needed narrowing in the higher-order case.
the bound variable $x$ occurs inside $t$. In general, this may lead to an unexpected complexity wrt the term size for evaluation via rewriting.

We define the $\overline{x_{k}}$-lifting of $h d t$ s by schematically applying the $\overline{x_{k}}$-lifter to all terms in the tree, i.e. to all patterns, right-hand sides, and free variables in cases.

## 5 Narrowing with higher-order definitional trees

In the higher-order case, the rules of LNT of section 3 must be extended to account for several new cases. Compared to the first-order case, we need to maintain binding environments and higher-order free variables, possibly with arguments, which are handled by higher-order unification. For this purpose, the Imitation, Function Guess and Projection rules have been added in figure 3. These three new rules, to which we refer as the Guess Rules, are the only ones to compute substitutions for the variables in the case constructs. The Case Guess rule of the first-order case can be retained by applying Imitation plus Case Select. For all rules, we assume that newly introduced variables are fresh, as in the first-order case.

The Imitation and Projection rules are taken from higher-order unification and
compute a partial binding for some variable. For instance, if the goal has the form

$$
\text { case } \lambda x \cdot F(x) \text { of } \lambda y \cdot \sin \left(F^{\prime}(y)\right): \cdots
$$

then the Imitation rule substitutes the higher-order variable $F$ by the function $\lambda x \cdot \sin (H(x))$, which 'imitates' the top function $\sin$ in the pattern of the case expression. Thus, the Imitation rule derives the ( $\beta$-reduced) new goal

$$
\text { case } \lambda x \cdot \sin (H(x)) \text { of } \lambda y \cdot \sin \left(F^{\prime}(y)\right): \cdots
$$

to which only Case Select is applicable in the following step. If we consider the goal

$$
\text { case } \lambda x . F(x) \text { of } \lambda y . y: 1 \rightarrow^{?} Z
$$

then we can apply the Projection rule to substitute the higher-order variable $F$ by the projection function $\lambda x . x$ (this is the only possible projection function in this case since the function $\lambda x . F(x)$ has only one argument) and we obtain the ( $\beta$-reduced) new goal case $\lambda x . x$ of $\lambda y . y: 1 \rightarrow^{?} Z$ which can be further evaluated by Case Select.

The Function Guess rule covers the case of non-constructor solutions, which may occur for higher-order variables. It thus enables the synthesis of functions from existing ones. Note that the selection of a binding in this rule is only restricted by the types occurring. For instance, the goal

$$
\text { case } F(0) \text { of true : } \cdots
$$

can be derived with the Function Guess rule by replacing the higher-order variable $F$ with a function that takes a number and produces a Boolean value as the result. Hence, if $\leqslant$ is the function defined in Example 1.1, an application of Function Guess can replace $F$ with $\lambda x . H_{1}(x) \leqslant H_{2}(x)$ and derives the new goal

$$
\text { case } H_{1}(0) \leqslant H_{2}(0) \text { of true : } \cdots
$$

which can be further evaluated by applying the Case Eval rule.
Notice that for goals where only higher-order patterns occur, there is no choice between Projection and Imitation for matching with a single case branch. (For different branches, clearly Projection or Imitation can be used.) Furthermore, Function Guess does not apply. This special case is refined later in section 8.

In contrast to the first-order case, locally bound variables may occur and must be correctly handled during unification. Therefore, all rewrite rules applied by Case Eval must be lifted into its correct binding context which is necessary to compute solutions for function variables with locally bound variables (see also Prehofer (1994)). Since free variables cannot be instantiated to bound variables, it is necessary to add the variables bound in the current context to all free variables of a rewrite rule so that they can be later instantiated by projection functions to identify them with the appropriate bound variables. A more technical example showing the need for lifting is provided in Example 5.2.

For a sequence $\Rightarrow^{\theta_{1}} \cdots \Rightarrow{ }^{\theta_{n}}$ of LNT steps, we write ${ }^{*}{ }^{\theta}$, where $\theta=\theta_{n} \cdots \theta_{1}$. As in section 3 not all substitutions are recorded for $\stackrel{*}{\Rightarrow}$; only the ones produced by guessing are needed for the technical treatment. Informally, all other substitutions only concern intermediate (or auxiliary) variables similar to Prehofer (1995a).

As in the first-order case, we consider only reductions to a dedicated 0 -ary constructor $c$. Hence we assume that solving a goal $t \rightarrow ? ~ c$ is initiated with the initial goal $\mathscr{I}_{c}(t)=$ case $t$ of $c: c \rightarrow ? ~ X$.

## Example 5.1

As an example for the computation in our calculus LNT, consider the goal

$$
\lambda x \cdot \operatorname{diff}(\lambda y \cdot \sin (F(x, y)), x) \rightarrow^{?} \lambda x \cdot \cos (x)
$$

wrt the rules for diff (see Example 1.2) and the hdt for the function *:

$$
X * Y \rightarrow \text { case } Y \text { of } 1: X, s\left(Y^{\prime}\right): X+X * Y^{\prime}
$$

As discussed in section 2 , we add the rule $f(\lambda x \cdot \cos (x)) \rightarrow o k$ (for which a $h d t$ exists) and solve the goal $\mathscr{I}_{o k}(f(\lambda x \cdot \operatorname{diff}(\lambda y \cdot \sin (F(x, y)), x)))$. Since each computation step only affects the two leftmost goals, we often omit the others. Furthermore, we sometimes write expressions in $\eta$-normal form, e.g. $\cos$ instead of $\lambda x \cdot \cos (x)$.
case $f(\lambda x \cdot \operatorname{diff}(\lambda y \cdot \sin (F(x, y)), x))$ of ok $: o k \rightarrow ? X_{1}$
$\Rightarrow_{\text {Case Eval }} \quad$ (Apply the rule for $f$ )
case $\lambda x$.diff $(\lambda y \cdot \sin (F(x, y)), x)$ of $\cos : o k \rightarrow{ }^{?} X_{2}$, case $X_{2}$ of ok:ok $\rightarrow{ }^{?} X_{1}$
$\Rightarrow_{\text {Case Eval }} \quad($ Apply the rule for diff after lifting it with $x)$
$\lambda x$.case $\lambda y \cdot \sin (F(x, y))$ of $\ldots$,
$\lambda y \cdot \sin (G(x, y)): \cos (G(x, x)) * \operatorname{diff}(\lambda y \cdot G(x, y), x)$,
$\ldots \quad \rightarrow{ }^{?} X_{3}$,
case $X_{3}$ of cos: ok $\rightarrow{ }^{?} X_{2}$, case $X_{2}$ of ok:ok $\rightarrow{ }^{?} X_{1}$
$\Rightarrow$ Case Select $\quad$ (Only case selection is possible)
$\lambda x \cdot \cos (F(x, x)) * \operatorname{diff}(\lambda y . F(x, y), x) \rightarrow ? X_{3}$, case $X_{3}$ of $\cos : o k \rightarrow ? X_{2}, \ldots$
$\Rightarrow_{\text {Bind }} \quad$ (First case expression is evaluated, bind result to $X_{3}$ )
case $\lambda x \cdot \cos (F(x, x)) * \operatorname{diff}(\lambda y \cdot F(x, y), x)$ of $\cos : o k \rightarrow{ }^{?} X_{2}$, case $X_{2}$ of ok: ok $\rightarrow{ }^{?} X_{1}$
$\Rightarrow_{\text {Case Eval }} \quad$ (Apply the rule for * after lifting it with $x$ )
$\lambda x$. case diff $(\lambda y . F(x, y), x)$ of $1: \cos (F(x, x)), \ldots \rightarrow ? X_{3}$, case $X_{3}$ of cos:ok $\rightarrow{ }^{?} X_{2}, \ldots$
$\Rightarrow_{\text {Case Eval }} \quad$ (Apply the rule for diff after lifting it with $x$ )
$\lambda x$.case $\lambda y . F(x, y)$ of $\lambda y \cdot y: 1, \ldots \rightarrow{ }^{?} X_{4}$,
$\lambda x$.case $X_{4}(x)$ of $1: \cos (F(x, x)), \ldots \rightarrow ? X_{3}, \ldots$
$\Rightarrow{ }_{\text {Projection }}^{\{F \leftrightarrow \lambda x, y, y\}} \quad$ (Instantiate $F$ by the projection to the second argument)
$\lambda x . c a s e ~ \lambda y . y$ of $\lambda y . y: 1, \ldots \rightarrow ? X_{4}, \quad \lambda x . c a s e X_{4}(x)$ of $1: \cos (x), \ldots \rightarrow ? X_{3}, \ldots$
$\Rightarrow_{\text {Case Select }} \quad$ (Only case selection is possible)
$\lambda x .1 \rightarrow ? X_{4}, \quad \lambda x . \operatorname{case} X_{4}(x)$ of $1: \cos (x), \ldots \rightarrow ? X_{3}, \ldots$
$\Rightarrow_{\text {Bind }} \quad$ (Case expression is evaluated, bind result to $X_{4}$ )

גx.case 1 of $1: \cos (x), \ldots \rightarrow{ }^{?} X_{3}$, case $X_{3}$ of $\cos : o k \rightarrow{ }^{?} X_{2}, \ldots$
$\Rightarrow_{\text {Case Select }} \quad$ (Only case selection is possible)
$\lambda x \cdot \cos (x) \rightarrow{ }^{?} X_{3}$, case $X_{3}$ of cos:ok $\rightarrow{ }^{?} X_{2}$, case $X_{2}$ of ok: ok $\rightarrow{ }^{?} X_{1}$
$\Rightarrow_{\text {Bind }} \quad$ (Case expression is evaluated, bind result to $X_{3}$ )
case cos of cos:ok $\rightarrow{ }^{?} X_{2}$, case $X_{2}$ of ok:ok $\rightarrow{ }^{?} X_{1}$
$\Rightarrow$ Case Select $\quad$ (Only case selection is possible)
ok $\rightarrow$ ? $X_{2}$, case $X_{2}$ of ok:ok $\rightarrow{ }^{?} X_{1}$
$\Rightarrow_{\text {Bind }} \quad\left(\right.$ Case expression is evaluated, bind result to $\left.X_{2}\right)$
case ok of ok: ok $\rightarrow{ }^{?} X_{1} \quad \Rightarrow_{\text {Case Select }} \quad o k \rightarrow ?{ }^{?} X_{1} \quad \Rightarrow_{\text {Bind }} \quad\{ \}$
Thus, the computed solution is $\{F \mapsto \lambda x, y \cdot y\}$.
As we mentioned above, the lifting in the Case Eval inference rule is necessary to handle the application of rewrite rules and free variables in a context with bound variables correctly. For instance, consider the rewrite step

$$
\lambda x . f(x) \longrightarrow \longrightarrow_{\{Y \mapsto x\}}^{f(Y) \rightarrow g(Y)} \lambda x . g(x) .
$$

In this rewrite step, we bind the variable $Y$ to a bound variable, which can be treated as a constant here. This is possible since only matching is performed and all free variables in the rewrite rule disappear after the rewrite step.

Our calculus applies rewrite steps by the Case Eval rule. For this example, we first apply a lifter $\sigma=\left\{Y \mapsto Y^{\prime}(x)\right\}$ to the above rule. Then the substitution $Y^{\prime} \mapsto \lambda x . x$ is used for modeling the above rewrite step in our narrowing calculus. Note that free variables which appear directly below the outermost function symbol in rewrite rules immediately disappear when the Case Eval rule is applied. To show the need for lifting, we need a somewhat more involved example.

## Example 5.2

Consider the function $f$ defined by the rewrite rule

$$
f(\lambda y \cdot c(G(y))) \rightarrow G
$$

The corresponding $h d t$ is

$$
f(X) \rightarrow \text { case } X \text { of } \lambda y \cdot c(G(y))): G
$$

Clearly, the goal $\lambda x . f(F)) \rightarrow$ ? $\lambda x, y . y$ has the solution $\{F \mapsto \lambda y . c(y)\}$ since $\lambda x . f(\lambda y . c(y))$ reduces in one step to $\lambda x .(\lambda y . y)$.

To solve this goal in our calculus LNT, we add the rule $g(\lambda x, y . y) \rightarrow o k$ which has the $h d t$

$$
g(Y) \rightarrow \text { case } Y \text { of } \lambda x, y \cdot y: o k
$$

and solve the initial goal case $g(\lambda x . f(F))$ of ok :ok $\rightarrow{ }^{?} Z_{1}$ :
case $g(\lambda x . f(F))$ of ok:ok $\rightarrow{ }^{?} Z_{1}$
$\Rightarrow_{\text {Case Eval }}$
case $\lambda x . f(F)$ of $\lambda x, y . y: o k \rightarrow{ }^{?} Z_{2}$, case $Z_{2}$ of ok:ok $\rightarrow{ }^{?} Z_{1}$

```
\(\Rightarrow_{\text {Case Eval }} \quad \lambda x\).case \(F\) of \(\lambda y . c\left(G^{\prime}(x, y)\right): G^{\prime}(x) \rightarrow{ }^{?} Z_{3}\),
    case \(Z_{3}\) of \(\lambda x, y . y: o k \rightarrow{ }^{?} Z_{2}\), case \(Z_{2}\) of ok:ok \(\rightarrow{ }^{?} Z_{1}\)
\(\Rightarrow{ }_{\text {Imitation }}^{\{F \mapsto \lambda . c(H(y))\}} \quad \lambda x . \operatorname{case} \lambda y . c(H(y))\) of \(\lambda y . c\left(G^{\prime}(x, y)\right): G^{\prime}(x) \rightarrow{ }^{?} Z_{3}, \ldots\)
\(\Rightarrow_{\text {Case Select }} \quad \lambda x, y \cdot H(y) \rightarrow ? Z_{3}\), case \(Z_{3}\) of \(\lambda x, y \cdot y: o k \rightarrow{ }^{?} Z_{2}, \ldots\)
\(\Rightarrow_{\text {Bind }} \quad\) case \(\lambda x, y . H(y)\) of \(\lambda x, y \cdot y: o k \rightarrow{ }^{?} Z_{2}\), case \(Z_{2}\) of ok:ok \(\rightarrow{ }^{?} Z_{1}\)
\(\Rightarrow{ }_{\text {Projection }}^{\{H \leftrightarrow \lambda x . x\}}\) case \(\lambda x, y . y\) of \(\lambda x, y . y: o k \rightarrow ? Z_{2}\), case \(Z_{2}\) of ok:ok \(\rightarrow\) ? \(Z_{1}\)
\(\Rightarrow_{\text {Case Select }} \quad\) ok \(\rightarrow ? Z_{2}\), case \(Z_{2}\) of ok: ok \(\rightarrow{ }^{?} Z_{1}\)
\(\Rightarrow_{\text {Bind }} \quad \Rightarrow_{\text {Case Select }} \quad \Rightarrow_{\text {Bind }} \quad\{ \}\)
```

Thus, this derivation computes the solution $\{F \mapsto \lambda y . c(y)\}$ for the free variable $F$. Note that in the second step the $h d t$ for $f$ is applied after lifting it with $x$. This lifting replaces the free variable $G$ by $G^{\prime}(x)$ which is necessary to ensure the shallowness of the case pattern and the correct application of Case Select in subsequent steps. Moreover, an expression like $G^{\prime}(x, y)$ can be refined to one of the bound variables $x$ or $y$ by instantiating $G^{\prime}$ to the appropriate projection function (actually, $G^{\prime}$ is subsequently instantiated to project to its second argument).

The next proposition states that our higher-order lazy narrowing calculus LNT is indeed a conservative extension of (first-order) needed narrowing.

## Proposition 5.3

If all functions and goals occurring in a derivation are first-order, LNT computations correspond to needed narrowing derivations and vice versa.

## Proof

If all functions and goals are first-order, $\lambda$-abstractions and functional variables do not occur. Thus, the Function Guess rule is not applicable and the $\lambda$-binders in all rules of the calculus LNT in Figure 3 can be omitted (which makes the application of the Projection rule impossible). Thus, the rules Bind, Case Select and Case Eval become identical to the corresponding first-order rules in figure 2. Moreover, after an application of the rule Imitation, only Case Select is applicable. Thus, Imitation plus Case Select is equivalent to Case Guess in the first-order case. Therefore, first-order derivations with the rules in figure 3 are equivalent to derivations with the rules in Figure 2. This implies the proposition by Theorems 3.3 and 3.5.

## 6 Correctness and completeness

In this section we show soundness and completeness of our higher-order narrowing calculus LNT. Similarly to the completeness proof of first-order needed narrowing (Antoy et al., 1994), we show completeness wrt reductions where redexes are computed via definitional trees (called 'LNT reductions'). As in the first-order case, we show that LNT reduction steps are needed for reduction to a constructor normal form. In the first-order case, it is known that iterated reduction of needed redexes computes the normal form, if it exists (Huet and Lévy, 1991). A similar result is
strongly conjectured but not yet known for the higher-order case. Since LNT reductions compute ground constructor terms for terminating inductively sequential HRS, the completeness result wrt LNT reductions is sufficient for practical programs (note that the definition of infinite data structures does not require non-terminating rules in functional logic languages, because infinite data structures can also be defined by terminating rules and the use of existential variables (see Prehofer, 1997, Section 8.1.5).

We first define LNT reductions and then lift LNT reductions to narrowing. In the following, we assume an inductively sequential HRS $\mathscr{R}$ and a dedicated 0 -ary constructor $c$.

### 6.1 LNT reductions

We define LNT reductions as a restriction of our higher-order lazy narrowing calculus LNT. Then we show that they are in fact needed. For modeling rewriting, the Guess rules (i.e. Imitation, Function Guess, Projection) are not needed since each of these rules computes a non-identity substitution: $S \stackrel{*}{\Rightarrow}{\underset{L N T}{ }}_{\{ \}}^{y}$ if and only if no Guess rules are used in the reduction. Hence no narrowing is performed. This can also be seen as an implementation of a particular rewriting strategy.

To relate a system of LNT goals to a term, we associate a position $p$ with each case construct and a substitution $\theta$ for all newly introduced variables on the right. For each case expression $\mathscr{T}=$ case $X$ of $\ldots$ in a rule $\mathscr{T}^{\prime}=f\left(\overline{X_{n}}\right) \rightarrow \mathscr{X}$, we attach the position $p$ of $X$ in the left-hand side of the corresponding rewrite rule. Formally, we define a function $l_{\mathscr{T}}$ such that $l_{\mathscr{T}}\left(f\left(\overline{X_{n}}\right): \mathscr{X}\right)$ yields the labelled tree for a rule $\mathscr{T}=f\left(\overline{X_{n}}\right) \rightarrow \mathscr{X}:$

- $l_{\mathscr{T}}\left(p_{f}:\right.$ case $X$ of $\left.\overline{\mathscr{T}_{n}}\right)=p_{f}: \operatorname{case}_{p} X$ of $\overline{l_{\mathscr{T}}\left(\mathscr{T}_{n}\right)}$
where $p$ is the position of $X$ in $\operatorname{pat}_{\mathscr{T}}\left(p_{f}:\right.$ case $X$ of $\left.\overline{\mathscr{T}_{n}}\right)$
- $l_{\mathscr{T}}\left(p_{f}: r\right)=p_{f}: r$

We assume in the sequel that definitional trees for some inductively sequential HRS $\mathscr{R}$ are labelled. For instance, a labelled tree for the function $\leqslant$ of Example 1.1 is

$$
\begin{array}{lllllll}
X \leqslant Y \rightarrow \text { case }_{1} X \text { of } & 0 & : & \text { true, } & & & \\
& s\left(X_{1}\right) & : & \text { case }_{2} Y \text { of } & 0 & : & \text { false, } \\
& & & s\left(Y_{1}\right) & : & X_{1} \leqslant Y_{1}
\end{array}
$$

The following invariant will allow us to relate a goal system with a term:
Theorem 6.1
For an initial goal with case $_{\epsilon}$ t of $c: c \rightarrow ? X_{1} \stackrel{*}{\Rightarrow}{\underset{L N T}{ } S}_{\{ \}} S$ is of one of the following two forms:

1. $\lambda \bar{x}$. case $_{p_{n}}$ s of $\ldots \rightarrow{ }^{?} X_{n}, \lambda \bar{x}$. case $_{p_{n-1}} \lambda \bar{y} . X_{n}(\bar{x}, \bar{y})$ of $\ldots \rightarrow$ ? $X_{n-1}, \ldots$, $\lambda \bar{x}$. case $_{p_{2}} \lambda \bar{y} \cdot X_{3}(\bar{x}, \bar{y})$ of $\ldots \rightarrow{ }^{?} X_{2}$, case $_{p_{1}} X_{2}$ of $c: c \rightarrow ?{ }^{?} X_{1}$
2. $r \rightarrow{ }^{?} X_{n+1}, \lambda \bar{x}$. case $_{p_{n}} \lambda \bar{y} . X_{n+1}(\bar{x}, \bar{y})$ of $\ldots \rightarrow{ }^{?} X_{n}$, $\lambda \bar{x}$. case $_{p_{n-1}} \lambda \bar{y} . X_{n}(\bar{x}, \bar{y})$ of $\ldots \rightarrow$ ? $X_{n-1}, \ldots$, $\lambda \bar{x}$. case $_{p_{2}} \lambda \bar{y} \cdot X_{3}(\bar{x}, \bar{y})$ of $\ldots \rightarrow{ }^{?} X_{2}$, case $_{p_{1}} X_{2}$ of $c: c \rightarrow{ }^{?} X_{1}$

Furthermore, all $\overline{X_{n+1}}$ are distinct and each variable $X_{i}$ occurs only as shown above, i.e. at most twice in $\ldots, e \rightarrow{ }^{?} X_{i}$, case $X_{i}$ of $\ldots$.

Proof
Simple by induction on the LNT reduction.
Notice that the second form in the above theorem is created by a Case Select rule application, which may reduce a case term to a non-case term, or by Case Eval with a rule $f\left(\overline{X_{n}}\right) \rightarrow r$. As only the Bind rule applies on such systems, they are immediately reduced to the first form. As we will see, the Bind rule corresponds to the replacement which is part of a rewrite step. Since we now know the precise form of goal systems which may occur, bound variables as arguments and binders are sometimes omitted in goal systems if no ambiguities may arise.

Assumption. We assume in the following that all goal systems are generated by LNT from some initial goal and are hence of one of the two forms of Theorem 6.1.

The next goal is to relate LNT derivations and rewriting.
Definition 6.2
We define an associated substitution for each goal system inductively on $\stackrel{*}{*}_{L N T}$ :

- For an initial goal system of the form $S=$ case $_{\epsilon}$ t of $c: c \rightarrow{ }^{?} X$, we define the associated substitution $\theta_{S}=\{X \mapsto t\}$.
- For the Case Eval rule on $S=\lambda \bar{x}$.case $\lambda \bar{y} . f(\bar{t})$ of $\ldots \rightarrow$ ? $X, G$ with

$$
S \Rightarrow \lambda \bar{x}, \bar{y} \cdot \sigma(\mathscr{X}) \rightarrow{ }^{?} X^{\prime}, \lambda \bar{x} . \text { case }_{p} \lambda \bar{y} \cdot X^{\prime}(\bar{x}, \bar{y}) \text { of } \ldots \rightarrow^{?} X, G=: S^{\prime}
$$

we define $\theta_{S^{\prime}}=\theta_{S} \cup\left\{X^{\prime} \mapsto \lambda \bar{x} .\left.\left(\theta_{S} X\right)\right|_{p}\right\}$.
For all other rules, the associated substitution is unchanged.
For a goal system $S$, we write the associated substitution as $\theta_{S}$. Notice that the associated substitution is not a 'solution' as used in the completeness result and only serves to reconstruct the original term.

To see the need for this, consider for instance the rewrite system $g \rightarrow a$. For solving the goal $c(c(g)) \rightarrow ? ~ c(c(a))$, we first have to add the rule $f(c(c(a))) \rightarrow o k$. In order to find the first needed position in the initial goal, we have the following computation:

```
case \(_{\epsilon} f(c(c(g)))\) of ok : ok \(\rightarrow ? X_{1}\)
    \(\Rightarrow\) Case Eval
case \(_{1} c(c(g))\) of \(c\left(X_{3}\right):\) case \(_{1.1} X_{3}\) of \(c\left(X_{4}\right):\) case \(_{1.1 .1} X_{4}\) of \(a: o k \rightarrow{ }^{?} X_{2}\),
        case \(_{\epsilon} X_{2}\) of ok : ok \(\rightarrow{ }^{?} X_{1}\)
    \(\Rightarrow_{\text {Case Select }}\)
case \(_{1.1} c(g)\) of \(c\left(X_{4}\right):\) case \(_{1.1 .1} X_{4}\) of \(a: o k \rightarrow{ }^{?} X_{2}\),
        case \(_{\epsilon} X_{2}\) of ok : ok \(\rightarrow{ }^{?} X_{1}\)
    \(\Rightarrow_{\text {Case Select }}\)
case \(_{1.1 .1} g\) of \(a: o k \rightarrow{ }^{?} X_{2}\), case \(_{\epsilon} X_{2}\) of ok : ok \(\rightarrow{ }^{?} X_{1}\)
```

$$
\Rightarrow_{\text {Case Eval }}
$$

$a \rightarrow{ }^{?} X_{5}$, case $_{1.1 .1} X_{5}$ of $a: o k \rightarrow{ }^{?} X_{2}$, case $_{\epsilon} X_{2}$ of ok: ok $\rightarrow{ }^{?} X_{1}$
The associated substitution is $\left\{X_{1} \mapsto f(c(c(g))), X_{2} \mapsto f(c(c(g))), X_{5} \mapsto g\right\}$. This can now be used to reconstruct the position of the redex $g$ in the original term. Furthermore, we can translate the above goal system produced by LNT into one term. The idea is that case ${ }_{p}$ t of $\ldots \rightarrow$ ? $X$ should be interpreted as the replacement of the case argument term $t$ at position $p$ in $\theta_{S} X$, i.e. $\left(\theta_{S} X\right)[t]_{p}$. Thus we can reconstruct the initial term $f(c(c(g)))$ by the position label and the associated substitution for $X_{5}, X_{2}$ and $X_{1}$. We cannot simply use the solution for $X_{1}$, since this reconstruction has to follow the rewrite steps. For instance, in the next step the Bind rule is applied to the last goal above. This corresponds to the execution of the rewrite step $f(c(c(g))) \longrightarrow f(c(c(a)))$. Hence we need to reconstruct the term $f(c(c(a)))$ from the resulting goal system which is of the following form:

$$
\begin{equation*}
\text { case }_{1.1 .1} \text { a of } a: o k \rightarrow{ }^{?} X_{2}, \text { case }_{\epsilon} X_{2} \text { of ok : ok } \rightarrow{ }^{?} X_{1} \tag{1}
\end{equation*}
$$

Now we can apply the same reconstruction and obtain $f(c(c(a)))$. In this way, we can reconstruct a rewrite step by a sequence of LNT steps. Formalizing this reconstruction for goal systems is the goal of the following technical treatment. We first define the translation of goal systems into terms.

## Definition 6.3

For a goal system S of the form

$$
[r \rightarrow ? X,] \lambda \bar{x} . \text { case }_{p_{n}} \text { s of } \ldots \rightarrow^{?} X_{n}, \ldots, \text { case }_{p_{1}} X_{2} \text { of } c: c \rightarrow ? X_{1}
$$

(where $[r \rightarrow$ ? $X$, ] is optional) with associated substitution $\theta$, we define the associated $\operatorname{term} \mathscr{A}(S)$ as $\left(\theta X_{1}\right)\left[\left(\theta X_{2}\right)\left[\ldots\left(\theta X_{n}(\bar{x})\right)[\theta s]_{p_{n}} \ldots\right]_{p_{2}}\right]_{p_{1}}$.
For instance, if we start with a goal system $S_{1}=$ case $_{\epsilon}$ t of $c: c \rightarrow$ ? $X$, then $\mathscr{A}\left(S_{1}\right)=t$. The term associated to the goal (1) above is

$$
f(c(c(g)))\left[f(c(c(g)))[a]_{1.1 .1}\right]_{\epsilon}=f(c(c(a)))
$$

For a goal system $S$, we write $S \downarrow$ for the normal form obtained by applying Case Eval and Case Select. Observe via the last example that the steps in $S \downarrow$ correspond to finding the first, needed redex. We define an associated substitution for the intermediate variables $\overline{X_{n}}$ of a system of goals produced by LNT.

## Lemma 6.4

$S \downarrow$ is well defined, i.e. computing $S \downarrow$ terminates and yields a unique goal system.

## Proof

Termination follows easily since the size of the term used for rule selection in the leftmost case construct decreases. Note that the substitutions used for Case Select only bind variables to subterms of the leftmost term in the leftmost case construct. As Case Select and Case Eval do not apply simultaneously, uniqueness follows.

## Lemma 6.5

For a goal system $S$, the rules Case Eval and Case Select do not change the associated term.

## Proof

We first establish the following invariant: If

$$
\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow}^{\theta}{ }_{L N T} \text { case }_{p_{n}} \text { s of } \ldots \rightarrow{ }^{?} X_{n}, G=: S,
$$

then $\left.\theta \theta_{S} X_{n}\right|_{p_{n}}=s$ holds. This invariant is shown by induction on $\stackrel{*}{\Rightarrow} L N T$. It is trivial for the Guess rules and follows from the definition of $\theta_{S}$ for Case Eval and Bind. Only the Case Select rule is more involved. Case Select reduces the term in the leftmost case construct:

$$
S=\operatorname{case}_{p} v\left(\overline{t_{n}}\right) \text { of } \ldots \rightarrow^{?} X, \ldots \Rightarrow \operatorname{case}_{p \cdot p^{\prime}} t_{i} \text { of } \ldots \rightarrow ?{ }^{?} X, \ldots=: S^{\prime}
$$

Since $\left.\theta_{S} X\right|_{p}=v\left(\overline{t_{n}}\right)$ and $\left.v\left(\overline{t_{n}}\right)\right|_{p^{\prime}}=t_{i},\left.\theta_{S^{\prime}} X\right|_{p \cdot p^{\prime}}=t_{i}$ holds.
With the above invariant the theorem follows from the definition of $\mathscr{A}(S)$, since only the leftmost case construct is changed by each rule.

From this result, we can infer $\mathscr{A}(S)=\mathscr{A}(S \downarrow)$ and $\mathscr{A}\left(\mathscr{I}_{c}(t)\right)=\mathscr{A}\left(\mathscr{I}_{c}(t) \downarrow\right)$.

## Corollary 6.6

For a term $t$, we have $t=\mathscr{A}\left(\mathscr{I}_{c}(t) \downarrow\right)$.
Stability of reduction under substitution can be shown since LNT computations are outermost.

## Lemma 6.7

For a term $t$, if $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow} \underset{L N T}{\{ \}}\{ \}$, then $\mathscr{I}_{c}(\theta t) \stackrel{*}{\Rightarrow} \underset{L N T}{\{ }\{ \}$.
Proof
In $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow} \underset{L N T}{\{ }\{ \}$, no variable in $\mathscr{D} \operatorname{om}(\theta)$ can affect the LNT computation (e.g. reduction cannot take place below a free variable). Hence $\mathscr{I}_{c}(\theta t) \stackrel{*}{\Rightarrow} \underset{L N T}{\{ }\{ \}$ follows easily by induction on the length of the reduction.

The next goal is to relate a rewrite step with LNT computations. In this vein, we show that for a given (part of a) rewrite rule, LNT finds the right branch in the corresponding definitional tree. For this we first give an auxiliary lemma which establishes this result for any term which corresponds to a path in a definitional tree, as defined via the function pat ${ }_{\mathscr{T}}$.

## Lemma 6.8

Assume $\operatorname{pat}_{\mathscr{T}}\left(p_{i}: \mathscr{X}_{i}\right)=l$ for a definitional tree $\mathscr{T}$. There exists a reduction

$$
\begin{aligned}
& \lambda \bar{x} \text {.case } \lambda \bar{y} \text {.l of } \overline{\mathscr{T}}_{m} \rightarrow ? \text { ? }, G \\
& \Rightarrow_{\text {Case Eval }} \stackrel{*}{*}_{\text {Case Select }} \quad \lambda \bar{x} \text {.case } \lambda \bar{y} . p_{i} \text { of } \overline{p_{n}: \mathscr{X}_{n}} \rightarrow ? X^{\prime}, \\
& \lambda \bar{x} \text {.case } \lambda \bar{y} . X^{\prime}(\bar{x}, \bar{y}) \text { of } \overline{\mathscr{T}_{m}} \rightarrow{ }^{?} X, G \\
& \Rightarrow_{\text {Case Select }} \quad \lambda \bar{x} . \sigma\left(\mathscr{X}_{i}\right) \rightarrow{ }^{?} X^{\prime}, \lambda \bar{x} \text {.case } \lambda \bar{y} \cdot X^{\prime}(\bar{x}, \bar{y}) \text { of } \overline{\mathscr{T}}_{m} \rightarrow ? \text { X,G }
\end{aligned}
$$

for some substitution $\sigma$.
Proof
First note that Case Eval applies if $l=f(\bar{t})$ for some defined symbol $f$ with definitional tree $\mathscr{T}$. The claim follows easily by induction on the Case Select applications, by composing the substitutions computed for the variables in the selectors of $\mathscr{T}$.

Now we can show easily that LNT detects a rewrite step when invoked with an instance of a left-hand side. Recall that the Bind rule applies to the resulting goal system of the LNT-computation in the next result. As shown in the above examples, the Bind rule, roughly speaking, executes the replacement step of a rewrite rules.

## Corollary 6.9

There exists a rule $f(\bar{t}) \rightarrow r$ with $l=\sigma f(\bar{t})$ for some non-case term $r$ iff

```
\(\lambda \bar{x}\).case \(\lambda \bar{y} . l\) of \(\overline{\mathscr{T}}_{n} \rightarrow{ }^{?} X, G\)
    \(\Rightarrow_{\text {Case Eval }} \xrightarrow{*}\) Case Select \(\quad \lambda \bar{x}, \bar{y} . \sigma r \rightarrow{ }^{?} X^{\prime}, \lambda \bar{x}\).case \(\lambda \bar{y} \cdot X^{\prime}(\bar{x}, \bar{y})\) of \(\overline{\mathscr{T}}_{n} \rightarrow ?\) ?,\(G\)
```


## Proof

The proof follows easily from Lemma 6.7 and Lemma 6.8. (Recall that the rules do not overlap and hence for a position in a term, only one rule applies.)

For a goal system $S$, we write $\operatorname{Bind}(S)$ to denote the result of applying the Bind rule. Notice that the substitution of the Bind rule only affects the two leftmost goals.

## Lemma 6.10

Let $S=\mathscr{I}_{c}(t)$. If $S \downarrow$ is of the form of Invariant 2 of Theorem 6.1, then $t=\mathscr{A}(S \downarrow)$ is reducible at position $p=p_{1} \cdots p_{n}$, where $p_{i}$ are determined by the invariant of Theorem 6.1. Furthermore, if $t \longrightarrow_{p} t^{\prime}$, then $\mathscr{I}_{c}\left(t^{\prime}\right) \downarrow=\operatorname{Bind}(S \downarrow) \downarrow$.

## Proof

The only way $S$ is transformed into $S \downarrow$ of the form of Invariant 2 is when a leftmost case construct, created by Case Eval (or the initial construct), is fully reduced to a term by Case Select without any intervening Case Eval applications. Say $S$ is first transformed into

$$
\text { case }_{p_{n}} \text { s of } \ldots \rightarrow^{?} X_{n}, \ldots, \text { case }_{p_{1}} X_{2} \text { of } c: c \rightarrow ? X_{1}=: S^{\prime}
$$

with $p=p_{1} \cdots p_{n}$ and $\left.t\right|_{p}=s$ such that

Since each path of a definitional tree corresponds to a left-hand side, $\left.t\right|_{p}$ is reducible by Corollary 6.9. To show $\mathscr{I}_{c}\left(t^{\prime}\right) \downarrow=\operatorname{Bind}(S \downarrow) \downarrow$, consider the computation for $\mathscr{I}_{c}\left(t^{\prime}\right) \downarrow$. Since $t$ and $t^{\prime}$ differ only at position $p$, i.e. $t^{\prime}=t\left[\sigma r^{\prime}\right]_{p}$ for some rule $l^{\prime} \rightarrow r^{\prime}, \mathscr{I}_{c}\left(t^{\prime}\right)$ is transformed by LNT to

$$
\text { case }_{p_{n}} \sigma r^{\prime} \text { of } \ldots \rightarrow^{?} X_{n}, \ldots, \text { case }_{p_{1}} X_{2} \text { of } c: c \rightarrow ? X_{1}=: S_{1}
$$

Since $\mathscr{A}\left(S^{\prime \prime}\right)=t, \mathscr{A}\left(\operatorname{Bind}\left(S^{\prime \prime}\right)\right)=t^{\prime}$ follows from Lemma 6.5 and from the definition of the Bind rule. Hence $r=\sigma r^{\prime}$ and $S^{\prime \prime} \Rightarrow_{\text {Bind }} S_{1}$ follow. By uniqueness of normal forms, $\operatorname{Bind}(S \downarrow) \downarrow=\operatorname{Bind}\left(S^{\prime \prime}\right) \downarrow=S_{1} \downarrow=\mathscr{I}_{c}\left(t^{\prime}\right) \downarrow$ follows.

Now, we can define LNT reductions:
Definition 6.11
A term $t$ has a LNT redex at position $p$ if $\mathscr{I}_{c}(t) \downarrow$ is of Invariant 2 of Theorem 6.1 with $p=p_{1} \cdots p_{n}$ as in Theorem 6.1. We denote by $t \longrightarrow_{L N T} t^{\prime}$ a LNT reduction step, i.e. a rewrite step $t \longrightarrow_{p} t^{\prime}$ where $p$ is the position of a LNT redex.

Thus, a LNT reduction step is a rewrite step at a position determined by the definitional trees (which are computed via our calculus LNT). For instance, consider Example 1.1 together with the rule $f(0) \rightarrow 0$ and the term $t=f(0) \leqslant f(0)$. Then $t \longrightarrow{ }_{1} 0 \leqslant f(0)$ is a LNT reduction step in contrast to $t \longrightarrow{ }_{2} f(0) \leqslant 0$.

Theorem 6.12
For a term $t, \mathscr{I}_{c}(t) \stackrel{*}{*}_{L N T}^{\{ \}}\{ \}$iff $t \stackrel{*}{\longrightarrow}_{L N T} c$.
Proof
If $t \xrightarrow{*} L N T$, we can show $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow} \underset{L N T}{ }\{ \}$ easily by induction on the length of $t \xrightarrow{*}{ }_{L N T} c$ via Lemma 6.10.

Assuming $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow} \underset{L N T}{\{ \}}\{ \}$, we can show as in Lemma 6.10 that the reduction starts with computing $\mathscr{I}_{c}(t) \downarrow$ and then the Bind rule must apply. Similar to Lemma 6.10, we can show $t \longrightarrow_{L N T} t^{\prime}$. By induction this yields a reduction $t{ }^{*}{ }_{L N T} c$, since $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow}_{L N T}$ case $c$ of $c: c \rightarrow ? ~ X$ is the only way to transform $\mathscr{I}_{c}(t)$ to $\}$.

It remains to show that LNT reductions are needed to compute a constructor-headed term. For a normalization result for the first-order case, we refer to Middeldorp (1997).

Theorem 6.13
If $t$ reduces to $c$, then $t$ has a LNT redex at a position $p$ and $t$ must be reduced at $p$ eventually. Otherwise, $t$ is not reducible to $c$.

## Proof

In the computation of $\mathscr{I}_{c}(t) \downarrow$, we have goal systems of the form

$$
\text { case }_{p_{n}} \text { s of } \ldots \rightarrow ? X_{n}, \ldots, \text { case }_{p_{1}} X_{2} \text { of } c: c \rightarrow ? X_{1}
$$

where the term in the leftmost case construct, here $s$, is a subterm of $t$. We show that in this traversal of $t$, all subterms in the leftmost goals must be reduced at root position for $t$ to reduce to $c$, or are constructor/bound variable headed subterms of such a redex. We state the proof in terms of this traversal of subterms of $t$; then we argue that $\mathscr{I}_{c}(t) \downarrow$ is of Invariant 2 of Theorem 6.1 and hence $t$ has a redex by Lemma 6.10.

Starting at the root of $t, t=c$ or its root is a defined symbol. Otherwise, it is obviously not reducible to $c$. Since $R$ is inductively sequential, there is a single rewrite rule $l \rightarrow r$ such that $t \xrightarrow{*} \neq \epsilon t_{\epsilon}^{\prime} \longrightarrow_{\epsilon}^{l \rightarrow r} t^{\prime \prime}$. The traversal of $t$ either ends in Invariant 2 of Theorem 6.1, if there is a redex at the root, or reaches another defined symbol where Case Eval applies. In the latter case, we apply the same argument as above for the root, only generalized to a position $p$ where no rewrite rule applies on a position on the path to $p$. Similarly, we show that there is a single applicable rule or $t$ is not reducible to $c$.

By induction we either terminate with a redex which must be reduced for $t$ to reduce to $c$, or we have a path which cannot be contracted and hence $t$ is not reducible to $c$.

The next desirable result is to show that LNT reductions are normalizing. This is
suggested from related works (Oostrom, 1994; Klop, 1980), but is beyond the scope of this paper. However, the previous theorem implies that LNT reductions always compute the value in case of terminating rewrite systems.

## Corollary 6.14

If $\mathscr{R}$ is terminating and $t$ reduces to $c$, then $t \xrightarrow{*}{ }_{L N T} c$.

### 6.2 Lifting rewriting to narrowing

We first take a closer look at the variables involved for a LNT computation.

## Lemma 6.15

If $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta} S \Rightarrow{ }_{L N T}^{\theta^{\prime}} S^{\prime}$, then $\mathscr{D} \operatorname{om}\left(\theta^{\prime}\right) \subseteq \mathscr{F} \mathscr{V}(\theta t)$.

## Proof

The substitution $\theta$ is composed of (partial) substitutions $\sigma$ computed via one of the Guess rules. Since each such $\sigma$ maps a variable occurring in the associated term $\mathscr{A}\left(S^{\prime}\right)$, the claim follows easily by induction on $\stackrel{*}{\Rightarrow}{ }_{L N T}$.

For a goal system $S$, we call the variables that do not occur in $\mathscr{A}(S)$ dummies. In particular, all variables on the right and all variables in selectors in patterns of some tree in $S$ are dummies.

Lemma 6.16
If $S \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta}\{ \}$, then $\theta S \stackrel{*}{\Rightarrow}{ }_{L N T}\{ \}$.
Proof
By induction on the length of $\stackrel{*}{\Rightarrow}_{L N T}$. Assume $S \Rightarrow \Rightarrow^{\theta^{\prime}} S^{\prime} \stackrel{*}{\Rightarrow} \theta^{\prime \prime}\{ \}$. By induction hypothesis $\theta^{\prime \prime} S^{\prime} \stackrel{*}{\Rightarrow}{ }_{L N T}\{ \}$. First, we show $\theta^{\prime} S \stackrel{*}{\Rightarrow} S^{\prime}$ by the following case distinction: If one of the Guess rules was used in $S \Rightarrow \Rightarrow^{\theta^{\prime}} S^{\prime}$, then $\theta^{\prime} S=S^{\prime}$. Otherwise, $\theta^{\prime}=\{ \}$. Hence we have $\theta^{\prime} S \stackrel{*}{\Rightarrow}\{ \} S^{\prime}, \theta^{\prime \prime} S^{\prime} \stackrel{*}{\Rightarrow}\{ \}\{ \}$, and infer $\theta^{\prime \prime} \theta^{\prime} S \stackrel{*}{\Rightarrow}\{ \} \theta^{\prime \prime} S^{\prime} \stackrel{*}{\Rightarrow}\{ \}\{ \}$ from Lemma 6.7.

Theorem 6.17 (Correctness of LNT narrowing)
If $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta}\{ \}$ for a term t , then $\theta t \xrightarrow{*} c$.
Proof
First, $\mathscr{I}_{c}(\theta t) \stackrel{*}{\Rightarrow}_{L N T}\{ \}$ follows from Lemma 6.16 and $\theta t \stackrel{*}{\longrightarrow}_{L N T} c$ from Theorem 6.12. Since LNT reduction steps are particular rewrite steps, we conclude $\theta t \xrightarrow{*} c$.

We first state completeness wrt LNT computations.

## Lemma 6.18

If $\theta S \stackrel{*}{\Rightarrow} \underset{L N T}{\}}\}$ where $\theta$ is in $\mathscr{R}$-normal form and contains no dummies of $S$, i.e. $\mathscr{F} \mathscr{V}(\theta) \cap \mathscr{F} \mathscr{V}(S)=\mathscr{F} \mathscr{V}(\mathscr{A}(S))$, then $S \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta^{\prime}}\{ \}$ with $\theta^{\prime} \leqslant \mathscr{F} \mathscr{V}(\mathscr{A}(S))$.

## Proof

From the given derivation we construct a reduction $S \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta^{\prime}}\{ \}$, which is possibly longer, since Guess rules are interspersed. For this process to terminate, we need the following termination ordering. The ordering consists of the lexicographic combination of (A) the length of the LNT reduction $\theta S \stackrel{*}{\Rightarrow} \hat{L N T}^{\{ }\{ \}$and $(\mathrm{B})$ the sizes of the multiset of terms in the solutions for the variables in $\mathscr{D}$ om $(\theta)$. (See Baader and Nipkow (1998) and Dershowitz and Jouannaud (1990) for a definition of lexicographic orderings.) We have the following cases depending on the form of $S$ :

- If $S=e \rightarrow^{?} X, G$ and on $\theta S$ the Bind rule applies, then Bind applies to $S$ as well since $X \notin \mathscr{D} \operatorname{om}(\theta)$. Since $\theta \operatorname{Bind}(S)=\operatorname{Bind}(\theta S)$, the induction hypothesis applies with a shorter reduction, decreasing A .
- If $S=$ case $\lambda \bar{x} . v(\bar{t})$ of $\ldots, G$, then either Case Select or Case Eval must apply on $\theta S$ and hence on $S$ as well. The induction hypothesis applies as in the last case.
- If $S=\lambda \bar{x}$.case $\lambda \bar{y} \cdot X(\bar{t})$ of $\ldots, G$, then $\theta X(\bar{t})$ must be of one of the following forms:
- $\lambda \bar{x} . c\left(\overline{t^{\prime}}\right)$ such that Case Select applies on $\theta S$. In this case, Imitation is applicable with a binding $\sigma$ such that $\exists \theta^{\prime} . \theta=\theta^{\prime} \sigma$ as in proof of higherorder unification (see Snyder and Gallier (1989) and Prehofer (1997)). Since $\theta^{\prime}$ is $\mathscr{R}$-normalized and dummy free, the induction hypothesis applies with a smaller solution, decreasing B.
- $\lambda \bar{x} . x\left(\overline{t^{\prime}}\right)$ such that Case Select applies on $\theta S$. This case proceeds as the above with Projection instead of Imitation.
- $\lambda \bar{x} . f\left(\overline{t^{\prime}}\right)$ such that Case Eval applies on $\theta S$. Here, Function Guess applies. The case concludes as the two above. For the precondition of the rule we observe that if $\lambda \bar{x}, \bar{y} \cdot X(\bar{t})$ is a higher-order pattern, then $\theta \lambda \bar{x}, \bar{y} \cdot X(\bar{t})$ is not $\mathscr{R}$-reducible (as shown in Prehofer (1997)) and hence $\theta S \stackrel{*}{\Rightarrow}{ }_{L N T}^{\{ \}}\{ \}$is impossible.

Theorem 6.19 (Relative completeness of LNT narrowing)
If $\theta t \xrightarrow{*}{ }_{L N T} c$ and $\theta$ is in $\mathscr{R}$-normal form, then $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow{ }_{L N T}}\{ \}$ with $\theta^{\prime} \leqslant \mathscr{F} \cdot(t) \theta$.
Proof
Completeness follows from Theorem 6.12 and the previous lemma.
Although the normalization property of LNT reductions is only known for the first-order case (by Proposition 5.3 and the results in Antoy (1992) and Antoy et al. (1994)), we can state a completeness result of LNT narrowing in the higher-order case for terminating rewrite systems.

Theorem 6.20 (Completeness of LNT narrowing)
If $\mathscr{R}$ is terminating, $\theta t \xrightarrow{*} c$, and $\theta$ is in $\mathscr{R}$-normal form, then $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta^{\prime}}\{ \}$ with $\theta^{\prime} \leqslant \mathscr{F}^{\boldsymbol{V}(t)}$.

Proof
Follows from the previous theorem and Corollary 6.14.

## 7 Optimality regarding solutions

We show here another important aspect, namely uniqueness of the computed solutions. Compared to the more general case in Prehofer (1997), optimality of solutions is possible here, since we only evaluate to constructor-headed terms. For this to hold for all subgoals in a narrowing process, our requirement of constructor-based rules is also essential. For these reasons, we never have to chose between Case Select and Case Eval in our setting and optimality follows easily from the corresponding result of higher-order unification.

We call two substitutions $\sigma$ and $\sigma^{\prime}$ independent on a set of variables $V$ if there exists a variable $x \in V$ such that $\sigma x$ and $\sigma^{\prime} x$ are not unifiable. Now we can show that different derivations of our calculus always compute independent solutions.

## Theorem 7.1 (Optimality)

If $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta}\{ \}$ and $\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta^{\prime}}\{ \}$ are two different derivations, then $\theta$ and $\theta^{\prime}$ are independent on $\mathscr{F} \mathscr{V}(t)$.

## Proof

The claim follows from examining the substitutions computed. First, it is to observe that, except for the Guess rules, no rule overlap, i.e. apply simultaneously to a particular goal system. Thus, the two derivations have the form

$$
\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta_{0}} S \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta_{1}} S_{1} \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta_{1}^{\prime}}\{ \}
$$

and

$$
\mathscr{I}_{c}(t) \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta_{0}} S \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta_{2}} S_{2} \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta_{2}^{\prime}}\{ \}
$$

where the steps $S \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta_{1}} S_{1}$ and $S \stackrel{*}{\Rightarrow}{ }_{L N T}^{\theta_{2}} S_{2}$ are different applications of a Guess rule (otherwise, the derivations cannot be different). These different applications of a Guess rule compute independent bindings for a variable $X$, where the following bindings are possible:

$$
\begin{array}{ll}
\left\{X \mapsto \lambda \overline{x_{n}} \cdot c\left(\overline{H_{m}\left(\overline{x_{n}}\right)}\right)\right\} & \text { (Imitation) } \\
\left\{X \mapsto \lambda \overline{x_{n}} \cdot f\left(\overline{H_{m}\left(\overline{x_{n}}\right)}\right)\right\} & \text { (Function Guess) } \\
\left\{X \mapsto \lambda \overline{x_{n}} \cdot x_{i}\left(\overline{H_{m}\left(\overline{x_{n}}\right)}\right)\right\} & \text { (Projection) }
\end{array}
$$

By Lemma 6.15, these independent bindings are bindings for a variable $X \in$ $\mathscr{F} \mathscr{V}\left(\theta_{0} t\right)$. Thus, there is a variable $Y \in \mathscr{F} \mathscr{V}(t)$ such that $\left\{Y \mapsto \theta_{1}\left(\theta_{0}(Y)\right\}\right.$ and $\left\{Y \mapsto \theta_{2}\left(\theta_{0}(Y)\right\}\right.$ are independent on $\mathscr{F} \mathscr{V}(t)$. As a consequence, $\theta=\theta_{1}^{\prime} \theta_{1} \theta_{0}$ and $\theta=\theta_{2}^{\prime} \theta_{2} \theta_{0}$ are independent on $\mathscr{F} \mathscr{V}(t)$.

It is also conjectured that our notion of needed reductions is optimal (this is subject to current research (Asperti and Laneve, 1994; Oostrom, 1994; Oostrom, 1996)). Note, however, that sharing is needed for optimality, as shown for the first-order case in Antoy et al. (1994).

## 8 Avoiding function synthesis

Although the synthesis of functional objects by full higher-order unification in LNT is very powerful, it can also be expensive and operationally complex. There is an
interesting restriction on rewrite rules which entails that full higher-order unification is not needed in LNT for (quasi) first-order goals.

We show that the corresponding result in Avenhaus and Loría-Sáenz (1994) is easy to see in our context, although lifting over binders obscures the results somewhat unnecessarily. ${ }^{3}$ Lifting may instantiate a first-order variable by a higher-order one, but this is only needed to handle the context correctly.

A term $t$ is quasi first-order if $t$ is a higher-order pattern without free higher-order variables. A rule $f\left(\overline{X_{n}}\right) \rightarrow \mathscr{X}$ is called weakly higher-order, if every higher-order free variable which occurs in $\mathscr{X}$ is in $\left\{\overline{X_{n}}\right\}$. In other words, higher-order variables may only occur directly below the root and these are immediately eliminated when hdts are introduced in the Case Eval rule. For instance, the rule

$$
\operatorname{map}(F,[X \mid R]) \rightarrow[F(X) \mid \operatorname{map}(F, R)]
$$

is weakly higher-order, if $X$ and $R$ are first-order.

## Theorem 8.1

If $\mathscr{I}_{c}(t) \stackrel{*}{*}_{L N T} S$ where $t$ is quasi first-order wrt weakly higher-order rules, then $\mathscr{A}(S)$ is quasi first-order.

## Proof

We establish the claim by induction on $\stackrel{*}{\Rightarrow}$. Assume $S \Rightarrow S^{\prime}$. First, we show that only higher-order patterns occur in $S^{\prime}$. The only rule where non-patterns are involved is the Case Eval rule. In this rule, all $\overline{X_{n}}$ of a weakly higher-order rule $f\left(\overline{X_{n}}\right) \rightarrow \mathscr{X}$ are bound to quasi first-order terms by $\sigma$, hence all terms in $\sigma \mathscr{X}$ are higher-order patterns.

Furthermore, it is to show that $\mathscr{A}\left(S^{\prime}\right)$ is quasi first-order. Since the Guess rules are first-order in this case, only the Bind rule must be considered: As all variables in the right-hand side in the leaf must occur in the selectors on the path to the leaf, all its variables must have been bound before Bind applies. Since the variables in selectors are only bound to (sub-)terms of $\mathscr{A}\left(S^{\prime}\right)$ (in the Case Select rule), the right-hand side is instantiated to a quasi first-order term.

As a consequence of the last result, Function Guess and Projection do not apply and Imitation is only used as in the first-order case. For instance, a term like map $(f, l)$ can be solved without higher-order unification (i.e. as in section 3) provided that $f$ is a defined function symbol and $l$ is a list of first-order objects.

## 9 Conclusions

We have presented an effective model for the integration of higher-order functional and logic programming with completeness and optimality results. The completeness results are stated wrt LNT reductions which we have defined via definitional trees. In the first-order case, LNT reductions are identical to needed reductions. In the higherorder case, our computation model is complete for terminating rewrite systems,

[^3]complete wrt LNT reductions in the presence of non-terminating functions, and optimal wrt the number of computed solutions. Since we permit higher-order logical variables and $\lambda$-abstractions, our strategy is a suitable basis for truly higher-order functional logic languages, i.e. declarative languages that provide the synthesis of values for first-order as well as higher-order variables. Moreover, our strategy reduces to an optimal first-order strategy if the higher-order features are not used. Further work will focus on adapting the explicit model for sharing using goal systems from Prehofer (1997) to this refined context.

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## A Appendix

This appendix contains the proofs omitted in section 3.

## A.1 Proof of Theorem 3.3

In order to prove the equivalence of needed narrowing and leftmost-outermost narrowing with case expressions, we have to relate both kinds of derivations. For this purpose, we define the following translation $\mathscr{E} \mathscr{C}$ from $\mathscr{E}$ val-goals into terms with case expressions.

$$
\begin{aligned}
& \mathscr{E} \mathscr{C}(t)=t \\
& \mathscr{E} \mathscr{C}(\mathscr{E} \operatorname{val}(t, \mathscr{T})) \quad=\sigma(\mathscr{C} \operatorname{ase}(\mathscr{T})) \quad \text { where } \sigma(\operatorname{pat}(\mathscr{T}))=t \\
& \mathscr{E} \mathscr{C}\left(G, \mathscr{E} \operatorname{val}\left(t, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right)\right)=\operatorname{case} \mathscr{E} \mathscr{C}(G) \text { of } \overline{p_{k}: \mathscr{X}_{k}} \\
& \text { where } \mathscr{E} \mathscr{C}\left(\mathscr{E} v a l\left(t, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right)\right)=\operatorname{case} \ldots \text { of } \overline{p_{k}: \mathscr{X}_{k}}
\end{aligned}
$$

Hence, a single $\mathscr{E}$ val-goal is translated into the definitional tree represented by case expressions and instantiated with the arguments of the goal. A sequence of $\mathscr{E}$ valgoals, which may occur due to nested function evaluations, is folded into a single case expression by inserting the first goals into the first argument of the final case expression. For instance, the $\mathscr{E}$ val-goal

$$
\begin{aligned}
0, \mathscr{E v a l}\left(0+0 \leqslant Y, \operatorname{branch}\left(X_{1} \leqslant Y_{1}, 1,\right.\right. & \operatorname{rule}\left(0 \leqslant Y_{1} \rightarrow \operatorname{true}\right) \\
& \left.\left.\operatorname{branch}\left(s\left(X_{2}\right) \leqslant Y_{1}, \ldots\right)\right)\right)
\end{aligned}
$$

is translated by $\mathscr{E} \mathscr{C}$ into the term

$$
\text { case } 0 \text { of } 0: \text { true, } s\left(X_{1}\right):\left(\text { case } Y \text { of } 0: \text { false, } s\left(Y_{1}\right): X_{1} \leqslant Y_{1}\right)
$$

The following lemma shows that each inference step in the needed narrowing calculus wrt $\mathscr{R}$ corresponds to zero or one leftmost-outermost narrowing steps wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$.

## Lemma A. 1

Let $G$ be an $\mathscr{E}$ val-goal, $t=\mathscr{E} \mathscr{C}(G)$, and $G \Rightarrow^{\sigma} G^{\prime}$ be an inference step in the needed narrowing calculus. Then, either $\mathscr{E} \mathscr{C}\left(G^{\prime}\right)=t$ and $\sigma=\{ \}$, or there exists a unique leftmost-outermost narrowing step $t \rightsquigarrow_{\sigma} t^{\prime}$ wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ with $\mathscr{E} \mathscr{C}\left(G^{\prime}\right)=t^{\prime}$.

## Proof

We distinguish the different cases for the applied inference rule of the needed narrowing calculus. Note that $G$ has the form $\mathscr{E} \operatorname{val}(s, \mathscr{T}), G_{0}$ except for the inference rules Initial and Replace Subterm.

1. The inference rule Initial is applied: Then $G=t=f\left(\overline{t_{n}}\right)$ for some function $f$. Let $\mathscr{T}$ be the definitional tree for $f$ with pattern $f\left(\overline{X_{n}}\right)$ and $\varphi=\left\{\overline{X_{n} \mapsto t_{n}}\right\}$. Then $t \rightsquigarrow\} \varphi(\mathscr{C}$ ase $(\mathscr{T}))$ is a unique leftmost-outermost narrowing step wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$. Moreover, $\mathscr{E} \mathscr{C}\left(G^{\prime}\right)=\mathscr{E} \mathscr{C}(\mathscr{E} \operatorname{Val}(t, \mathscr{T}))=\varphi(\mathscr{C} \operatorname{ase}(\mathscr{T}))$.
2. The inference rule Apply is used: Then $\sigma=\{ \}, \mathscr{T}=$ rule $(l \rightarrow r), \varphi(l)=s$ for some substitution $\varphi$, and $G^{\prime}=\varphi(r), G_{0}$. If $G_{0}=\{ \}$, then $t=\mathscr{E} \mathscr{C}(G)=\varphi(r)=$ $\mathscr{E} \mathscr{C}\left(G^{\prime}\right)$ by definition of $\mathscr{E} \mathscr{C}$. If $G_{0} \neq\{ \}$, then, by definition of $\mathscr{E} \mathscr{C}, t$ and $\mathscr{E} \mathscr{C}\left(G^{\prime}\right)$ may only differ in the case argument of some case expression, where $t$ contains the subterm $\mathscr{E} \mathscr{C}(\mathscr{E} v a l(s, \mathscr{T}))$ and $\mathscr{E} \mathscr{C}\left(G^{\prime}\right)$ contains the subterm $\varphi(r)$ at this case argument. However, $\mathscr{E} \mathscr{C}(\mathscr{E}$ val $(s, \mathscr{T}))=\varphi(r)$ by definition of $\mathscr{E} \mathscr{C}$.
3. The inference rule Select is applied: Then $\mathscr{T}=\operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right),\left.s\right|_{o}=c\left(\overline{t_{n}}\right)$, $\sigma=\{ \}$, and $G^{\prime}=\mathscr{E} \operatorname{val}\left(s, \mathscr{T}_{i}\right), G_{0}$ where $\operatorname{pat}\left(\mathscr{T}_{i}\right)=c\left(\overline{X_{n}}\right)$. First, consider the case $G_{0}=\{ \}$. Then

$$
t=\varphi\left(\text { case }\left.\pi\right|_{o} \text { of } \overline{\left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \mathscr{C} \operatorname{ase}\left(\mathscr{T}_{k}\right)}\right)
$$

with $\varphi(\pi)=s$. Since $\left.s\right|_{o}=c\left(\overline{t_{n}}\right),\left.\varphi(\pi)\right|_{o}=c\left(\overline{X_{n}}\right)$. Due to the form of the case rules, exactly one case rule (the $i$-th rule) can be applied to $t$, i.e. $t \leadsto \rightsquigarrow_{\{ \}}$ $\varphi^{\prime}\left(\varphi\left(\mathscr{C}\right.\right.$ ase $\left.\left.\left(\mathscr{T}_{i}\right)\right)\right)$ with $\varphi^{\prime}=\left\{\overline{X_{n} \mapsto t_{n}}\right\}$ and $\operatorname{pat}\left(\mathscr{T}_{i}\right)=\pi\left[c\left(\overline{X_{n}}\right)\right]_{o}$. Since $\varphi(\pi)=s$ and $\left.s\right|_{o}=c\left(\overline{t_{n}}\right), \varphi^{\prime}\left(\varphi\left(\operatorname{pat}\left(\mathscr{T}_{i}\right)\right)\right)=s$. Thus, $\mathscr{E} \mathscr{C}\left(\mathscr{E} v a l\left(s, \mathscr{T}_{i}\right)\right)=\varphi^{\prime}\left(\varphi\left(\mathscr{C a s e}\left(\mathscr{T}_{i}\right)\right)\right)$. If $G_{0} \neq\{ \}, t$ is a term consisting of nested case expressions and $\mathscr{E} \mathscr{C}\left(\mathscr{E} \operatorname{Val}\left(s, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}}_{k}\right)\right)\right)$ is the leftmost-outermost position in $t$ where a narrowing step can be applied (by definition of $\mathscr{E C}$ ). Hence we apply a leftmost-outermost narrowing step to this subterm of $t$ analogously to the case $G_{0}=\{ \}$.
4. The inference rule Instantiate is applied: Then $\mathscr{T}=\operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right),\left.s\right|_{o}=X$, $\sigma=\left\{X \mapsto \operatorname{pat}\left(\mathscr{T}_{i}\right)\right\}$, and $G^{\prime}=\sigma\left(\mathscr{E} \operatorname{val}\left(s, \mathscr{T}_{i}\right), G_{0}\right)$. Consider the case $G_{0}=\{ \}$ (the case $G_{0} \neq\{ \}$ can be treated analogously as in the previous case). Then

$$
t=\varphi\left(\text { case }\left.\pi\right|_{o} \text { of } \overline{\left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \mathscr{C} \operatorname{ase}\left(\mathscr{T}_{k}\right)}\right)
$$

with $\varphi(\pi)=s$. Since $\left.s\right|_{o}=X$ and due to the form of the case rules, exactly one case rule (the $i$-th rule) can be applied to $t$ in order to instantiate $X$ to the same pattern, i.e. $t \mathfrak{m}_{\sigma} \sigma\left(\varphi\left(\mathscr{C}\right.\right.$ ase $\left.\left.\left(\mathscr{T}_{i}\right)\right)\right)$. Since $\varphi(\pi)=s$ and $\sigma\left(\left.s\right|_{o}\right)=\sigma(X)=$ $\left.\operatorname{pat}\left(\mathscr{T}_{i}\right)\right|_{o}, \sigma\left(\varphi\left(\operatorname{pat}\left(\mathscr{T}_{i}\right)\right)\right)=s$. Thus, $\mathscr{E} \mathscr{C}\left(\mathscr{E} v a l\left(s, \mathscr{T}_{i}\right)\right)=\sigma\left(\varphi\left(\mathscr{C} \operatorname{ase}\left(\mathscr{T}_{i}\right)\right)\right)$.
5. The inference rule Eval Subterm is applied: Then $\mathscr{T}=\operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right),\left.s\right|_{o}=$ $f\left(\overline{t_{n}}\right), \sigma=\{ \}$, and $G^{\prime}=\mathscr{E} \operatorname{val}\left(\left.s\right|_{o}, \mathscr{T}^{\prime}\right), \mathscr{E} \operatorname{val}(s, \mathscr{T}), G_{0}$ where $\mathscr{T}^{\prime}$ is the definitional
tree of $f$. Consider the case $G_{0}=\{ \}$ (the case $G_{0} \neq\{ \}$ can be treated analogously). Then

$$
t=\varphi\left(\text { case }\left.\pi\right|_{o} \text { of } \overline{\left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \mathscr{C} \operatorname{ase}\left(\mathscr{T}_{k}\right)}\right)
$$

with $\varphi(\pi)=s$. Since $\left.s\right|_{o}=f\left(\overline{t_{n}}\right)=\left.\varphi(\pi)\right|_{o}$, no case rule is applicable to the root of $t$. Thus, $\varphi\left(\left.\pi\right|_{o}\right)$ is the subterm at the leftmost-outermost narrowing position, and the only applicable rule is $f\left(\overline{X_{n}}\right) \rightarrow \mathscr{C}$ ase $\left(\mathscr{T}^{\prime}\right)$ (if $f\left(\overline{X_{n}}\right)$ is the pattern of $\mathscr{T}^{\prime}$ ). Thus,

$$
t \leadsto\left\} \text { case } \tau\left(\mathscr{C} \text { ase }\left(\mathscr{T}^{\prime}\right)\right) \text { of } \overline{\left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \varphi\left(\mathscr{C} \operatorname{ase}\left(\mathscr{T}_{k}\right)\right)}\right.
$$

with $\tau=\left\{\overline{X_{n} \mapsto t_{n}}\right\}$ is the only possible leftmost-outermost narrowing step. Moreover,

$$
\begin{aligned}
& \mathscr{E} \mathscr{C}\left(\mathscr{E} \operatorname{Eal}\left(\left.s\right|_{o}, \mathscr{T}^{\prime}\right), \mathscr{E} \operatorname{val}(s, \mathscr{T})\right) \\
& =\operatorname{case} \mathscr{E} \mathscr{C}\left(\mathscr{E} v a l\left(\left.s\right|_{o}, \mathscr{T}^{\prime}\right)\right) \text { of } \overline{\left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \varphi\left(\mathscr{C} \operatorname{ase}\left(\mathscr{T}_{k}\right)\right)} \\
& =\operatorname{case} \tau\left(\mathscr{C} \operatorname{ase}\left(\mathscr{T}^{\prime}\right)\right) \text { of } \overline{\left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \varphi\left(\mathscr{C} \operatorname{ase}\left(\mathscr{T}_{k}\right)\right)} .
\end{aligned}
$$

The last equality holds by definition of $\mathscr{E} \mathscr{C}$ since $\tau\left(\operatorname{pat}\left(\mathscr{T}^{\prime}\right)\right)=\tau\left(f\left(\overline{X_{n}}\right)\right)=$ $f\left(\overline{t_{n}}\right)=\left.s\right|_{o}$.
6. The inference rule Replace Subterm is applied: Then $G=r, \mathscr{E} v a l(s, \mathscr{T}), G_{0}$, $\mathscr{T}=\operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right), \sigma=\{ \}$, and $G^{\prime}=\mathscr{E} \operatorname{val}\left(s[r]_{o}, \mathscr{T}\right), G_{0}$. Consider the case $G_{0}=\{ \}$ (the case $G_{0} \neq\{ \}$ can be treated analogously). Then

$$
\begin{aligned}
t & =\mathscr{E} \mathscr{C}(r, \mathscr{E} v a l(s, \mathscr{T})) \\
& =\operatorname{case} \mathscr{E} \mathscr{C}(r) \text { of } \overline{\left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \varphi\left(\mathscr{C} \operatorname{ase}\left(\mathscr{T}_{k}\right)\right)} \\
& =\operatorname{case} r \text { of } \overline{\left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \varphi\left(\mathscr{C} \operatorname{ase}\left(\mathscr{T}_{k}\right)\right)}
\end{aligned}
$$

with $\varphi(\pi)=s$. On the other hand,

$$
\begin{aligned}
& \mathscr{E} \mathscr{C}\left(\mathscr{E} \operatorname{val}\left(s[r]_{o}, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right)\right) \\
& =\operatorname{case} \varphi^{\prime}\left(\left.\pi\right|_{o}\right) \text { of } \overline{\left.\operatorname{pat}\left(\mathscr{T}_{k}\right)\right|_{o}: \varphi^{\prime}\left(\mathscr{C} \operatorname{ase}\left(\mathscr{T}_{k}\right)\right)}
\end{aligned}
$$

with $\varphi^{\prime}(\pi)=s[r]_{o}$. Hence the only difference between $\varphi$ and $\varphi^{\prime}$ is the instantiation of the variable $\left.\pi\right|_{o}: \varphi^{\prime}\left(\left.\pi\right|_{o}\right)=r$ and $\varphi\left(\left.\pi\right|_{o}\right)=\left.s\right|_{o}$. W.1.o.g. we can assume that the case variable $\left.\pi\right|_{o}$ does not occur in any subtree $\overline{\mathscr{T}_{k}}$ (we can always construct the definitional tree in such a way). Thus, both terms $t$ and $\mathscr{E} \mathscr{C}\left(\mathscr{E} \operatorname{val}\left(s[r]_{o}, \operatorname{branch}\left(\pi, o, \overline{\mathscr{T}_{k}}\right)\right)\right)$ are identical (i.e. it is not necessary to perform a leftmost-outermost narrowing step).

The equivalence of needed narrowing wrt $\mathscr{R}$ and leftmost-outermost narrowing wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ is based on the previous lemma:

## Theorem 3.3

Let $t$ be a term and $c$ be a 0 -ary constructor. For each needed narrowing derivation $t \leadsto{ }_{\sigma}^{*} c$ wrt $\mathscr{R}$ there exists a leftmost-outermost narrowing derivation $t \leadsto \overbrace{\sigma}^{*} c$ wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$, and vice versa.

## Proof

By induction on the derivation steps and applying Lemma A.1, we can construct for each needed narrowing derivation starting from $t$ a unique leftmost-outermost narrowing derivation starting from $\mathscr{E} \mathscr{C}(t)=t$ which computes the same solution for the variables in $t$. On the other hand, it is straightforward to show (by a case distinction similar to the proof of Lemma A.1) that each leftmost-outermost narrowing derivation $t \leadsto \leadsto_{\sigma}^{*} c$ wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ corresponds to a needed narrowing derivation $t \leadsto{ }_{\sigma}^{*} c$ wrt $\mathscr{R}$.

## A.2 Proof of Theorem 3.5

To prove the equivalence of leftmost-outermost narrowing and the lazy narrowing calculus LNT, we need a few notions and technical lemmas to establish the precise equivalence between leftmost-outermost narrowing derivations and derivation in the lazy narrowing calculus LNT. First, note that the inference rules of the calculus LNT keep the following important invariant on goal systems:
(*) If $G_{1}, l \rightarrow{ }^{?} r, G_{2}$ is a goal system, then $r$ is a variable not occurring in $G_{1}$ and $l$.
There is a strong correspondence between terms with case expressions and goal systems, since each single equation $t \rightarrow$ ? $X$ can be "flattened" into a goal system by the following function $\mathscr{F}$ lat $\mathbf{}^{4}$

$$
\begin{aligned}
& \mathscr{F} \operatorname{lat}\left(f\left(\overline{t_{n}}\right) \rightarrow ? X\right)=f\left(\overline{t_{n}}\right) \rightarrow ? X \\
& \mathscr{F} \text { lat }\left(\text { case } t \text { of } \overline{p_{n}: X_{n}} \rightarrow ? X\right) \\
& = \begin{cases}\mathscr{F} \text { lat }(t \rightarrow ? Y) \text {, case } Y \text { of } \overline{p_{n}: \mathscr{X}_{n}} \rightarrow ? X & \text { if } t=\text { case } \ldots \text { and } Y \text { fresh variable } \\
\text { case } t \text { of } \overline{p_{n}: \mathscr{X}_{n}} \rightarrow ? X & \text { otherwise }\end{cases}
\end{aligned}
$$

For instance, if we apply the function $\mathscr{F}$ lat to the goal

$$
\text { case (case } X \leqslant Y \text { of true : true) of true : true } \rightarrow{ }^{?} T \text {, }
$$

we obtain the "flattened" goal system

$$
\text { case } X \leqslant Y \text { of true : true } \rightarrow \text { ? } Z \text {, case } Z \text { of true : true } \rightarrow^{?} T .
$$

On the other hand, goal systems satisfying invariant (*) can be "folded" by the following function $\mathscr{F}$ old into a single equation representing a term with nested case expressions:

$$
\begin{array}{ll}
\mathscr{F} \operatorname{old}(t \rightarrow ? X) & =t \rightarrow{ }^{?} X \\
\mathscr{F} \operatorname{old}\left(t \rightarrow{ }^{?} X, G\right) & =\mathscr{F} \operatorname{old}(\sigma(G)) \quad \text { with } \sigma=\{X \mapsto t\}
\end{array}
$$

The following lemma shows that, for each leftmost-outermost narrowing step in a derivation wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$, there is a corresponding LNT-derivation wrt $\mathscr{R}^{\prime}$.

[^4]
## Lemma A. 2

Let $t \rightsquigarrow_{\sigma} t^{\prime}$ be a leftmost-outermost narrowing step in a derivation of the initial term case $t_{0}$ of $c: c$ wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ and $X$ a fresh variable. Then there exists a LNT-step $\mathscr{F} \operatorname{lat}\left(t \rightarrow{ }^{?} X\right) \Rightarrow^{\sigma} G$ wrt $\mathscr{R}^{\prime}$ such that $\mathscr{F} \operatorname{old}(G)=t^{\prime} \rightarrow^{?} X$.

## Proof

Since $t \rightsquigarrow_{\sigma} t^{\prime}$ is a leftmost-outermost narrowing step in a derivation of the initial term case $t_{0}$ of $c: c, t$ has a case symbol at the top. Moreover, since it was derived by leftmost-outermost narrowing steps wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}, t$ has the structure

$$
t=\text { case }_{1}\left(\ldots\left(\text { case }_{n-1}\left(\text { case }_{n} \text { s of } \overline{p_{k}: \mathscr{X}_{k}}\right) \text { of } \ldots\right) \ldots\right) \text { of } \ldots
$$

where $s$ has not a case symbol at the top (here we use indices to distinguish the different case symbols). By definition of $\mathscr{F}$ lat,

$$
\mathscr{F} \operatorname{lat}(t \rightarrow ? X)=\text { case }_{n} \text { s of } \overline{p_{k}: \mathscr{X}_{k}} \rightarrow ? Y_{n-1}, \ldots, \text { case }_{1} Y_{1} \text { of } \ldots \rightarrow ? X
$$

There are the following possibilities for $s$ :

1. $s$ is operation-rooted, i.e. $s=f\left(\overline{t_{n}}\right)$. Then $s$ is the subterm reduced by the leftmost-outermost narrowing step, $\sigma=\{ \}$, and

$$
t^{\prime}=\operatorname{case}_{1}\left(\ldots\left(\text { case }_{n-1}\left(\operatorname{case}_{n} \varphi(\mathscr{X}) \text { of } \overline{p_{k}: \mathscr{X}_{k}}\right) \text { of } \ldots\right) \ldots\right) \text { of } \ldots
$$

if $f\left(\overline{X_{n}}\right) \rightarrow \mathscr{X}$ is a rewrite rule and $\varphi=\left\{\overline{X_{n} \mapsto t_{n}}\right\}$. Since $s$ is operation-rooted, we can only apply the Case Eval rule to the goal system $\mathscr{F} \operatorname{lat}\left(t \rightarrow{ }^{?} X\right)$ :

$$
\begin{aligned}
& \mathscr{F} \operatorname{lat}(t \rightarrow ? \text { ? } X) \Rightarrow\{ \\
& \varphi(\mathscr{X}) \rightarrow{ }^{?} Y_{n}, \text { case }_{n} Y_{n} \text { of } \overline{p_{k}: \mathscr{X}_{k}} \rightarrow ? Y_{n-1}, \ldots, \text { case }_{1} Y_{1} \text { of } \ldots \rightarrow ? \text { ? } X=: G
\end{aligned}
$$

By definition of $\mathscr{F}$ old, $\mathscr{F}$ old $(G)=t^{\prime} \rightarrow$ ? $X$.
2. $s$ is a variable: Then $\operatorname{case}_{n} s$ of $\overline{p_{k}: \mathscr{X}_{k}}$ is the subterm reduced by applying a case-rule in the leftmost-outermost narrowing step, and

$$
t^{\prime}=\sigma\left(\text { case }_{1}\left(\ldots\left(\text { case }_{n-1} \mathscr{X}_{i} \text { of } \ldots\right) \ldots\right) \text { of } \ldots\right)
$$

with $\sigma=\left\{s \mapsto p_{i}\right\}$ for some $i \in\{1, \ldots, k\}$. To compute the same result by a LNT-step, we apply the Case Guess rule to this goal system:

$$
\mathscr{F} \operatorname{lat}\left(t \rightarrow{ }^{?} X\right) \Rightarrow^{\sigma} \sigma\left(\mathscr{X}_{i} \rightarrow^{?} Y_{n-1}, \ldots, \text { case }_{1} Y_{1} \text { of } \ldots \rightarrow^{?} X\right)=: G
$$

By definition of $\mathscr{F}$ old, $\mathscr{F}$ old $(G)=t^{\prime} \rightarrow{ }^{?} X$.
3. $s$ has a constructor at the top: Then case $_{n} s$ of $\overline{p_{k}: \mathscr{X}_{k}}$ is the subterm reduced by applying a case-rule in the leftmost-outermost narrowing step, $\sigma=\{ \}$ (since only pattern variables are instantiated), and

$$
t^{\prime}=\operatorname{case}_{1}\left(\ldots\left(\text { case }_{n-1} \varphi\left(\mathscr{X}_{i}\right) \text { of } \ldots\right) \ldots\right) \text { of } \ldots
$$

where $p_{i}=c\left(\overline{X_{n}}\right)$ for some $i \in\{1, \ldots, k\}$ and $\varphi=\left\{\overline{X_{n} \mapsto t_{n}}\right\}$. Since $s$ is constructor-rooted, we can only apply the Case Select rule to the goal system $\mathscr{F} \operatorname{lat}\left(t \rightarrow{ }^{?} X\right)$ :

$$
\mathscr{F} \operatorname{lat}\left(t \rightarrow{ }^{?} X\right) \Rightarrow{ }^{\{ \}} \varphi\left(\mathscr{X}_{i}\right) \rightarrow{ }^{?} Y_{n-1}, \ldots, \text { case }_{1} Y_{1} \text { of } \ldots \rightarrow^{?} X=: G
$$

By definition of $\mathscr{F}$ old, $\mathscr{F}$ old $(G)=t^{\prime} \rightarrow$ ? $X$.

We can extend this lemma to entire leftmost-outermost narrowing derivations.

## Lemma A. 3

Let $t \leadsto{ }_{\sigma}^{*} c$ be a leftmost-outermost narrowing derivation wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ for the term $t=$ case $t_{0}$ of $c: c$ and $X$ a fresh variable. Then there exists a LNT-derivation $\mathscr{F} \operatorname{lat}\left(t \rightarrow{ }^{?} X\right) \stackrel{*}{\Rightarrow}{ }^{\sigma} c \rightarrow ? ~ X$ wrt $\mathscr{R}^{\prime}$.

## Proof

The proof is done by induction on the length $n$ of the leftmost-outermost derivation $t \leadsto{ }_{\sigma}^{*} c$.
$n=1$ : Then $t \rightsquigarrow_{\sigma} c$. By Lemma A.2, there exists a LNT-step $\mathscr{F} \operatorname{lat}\left(t \rightarrow{ }^{?} X\right) \Rightarrow^{\sigma} G$ wrt $\mathscr{R}$ ' such that $\mathscr{F}$ old $(G)=c \rightarrow{ }^{?} X$. By definition of $\mathscr{F}$ old, $G=c \rightarrow{ }^{?} X$.
$n>1$ : Then $t \leadsto \leadsto_{\sigma}^{*} c$ has the form $t \rightsquigarrow_{\varphi} t^{\prime} \rightsquigarrow_{\tau}^{n-1} c$ with $\sigma=\tau \varphi$. By Lemma A.2, there exists a LNT-step $\mathscr{F} \operatorname{lat}(t \rightarrow ? X) \Rightarrow^{\varphi} G$ wrt $\mathscr{R}^{\prime}$ such that $\mathscr{F} \operatorname{ld}(G)=t^{\prime} \rightarrow^{?} X$. By induction hypothesis, there exists a LNT-derivation $\mathscr{F} \operatorname{lat}\left(t^{\prime} \rightarrow ? ~ X\right) \stackrel{*}{\Rightarrow} c \rightarrow^{\tau} X$. If $G=\mathscr{F} \operatorname{lat}\left(t^{\prime} \rightarrow ? X\right)$, we can join the first LNT-step with this LNT-derivation to the requested LNT-derivation. Hence, consider the case $G \neq \mathscr{F} \operatorname{lat}\left(t^{\prime} \rightarrow ? ~ X\right)$. Since $\mathscr{F} \operatorname{old}(G)=t^{\prime} \rightarrow ? X, G$ can be transformed into $\mathscr{F} \operatorname{lat}\left(t^{\prime} \rightarrow ? X\right)$ by applying Bind rules.

The following lemma shows that each inference step in the calculus LNT wrt $\mathscr{R}^{\prime}$ corresponds to zero or one leftmost-outermost narrowing steps wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$.

## Lemma A. 4

Let $t$ be a term, $X$ a variable which does not occur in $t$, and $\mathscr{F} \operatorname{lat}\left(t \rightarrow{ }^{?} X\right) \Rightarrow^{\sigma} G$ a LNT-step with $G \neq\{ \}$. Then, either $\mathscr{F}$ old $(G)=t \rightarrow$ ? $X$ or there exists a leftmostoutermost narrowing step $t \leadsto{ }_{\sigma} t^{\prime}$ wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ such that $\mathscr{F} \operatorname{old}(G)=t^{\prime} \rightarrow ?$.

Proof
Let $\mathscr{F} \operatorname{lat}(t \rightarrow ? ~ X)=s \rightarrow ?$ ? $Y, F$. We distinguish the different cases for the applied inference rule of the calculus LNT:

1. The Bind rule is applied: Then $\sigma=\{ \}$ and $G=\varphi(F)$ with $\varphi=\{Y \mapsto s\}$. By definition of $\mathscr{F}$ old, $\mathscr{F}$ old $(G)=t \rightarrow{ }^{?} X$.
2. The Case Select rule is applied: Then $\sigma=\{ \}$, $s=$ case $c\left(\overline{t_{n}}\right)$ of $\overline{p_{k}: \mathscr{X}_{k}}$, $p_{i}=c\left(\overline{X_{n}}\right)$ for some $i \in\{1, \ldots, k\}, \varphi=\left\{\overline{X_{n} \mapsto t_{n}}\right\}$, and $G=\varphi\left(\mathscr{X}_{i}\right) \rightarrow ?$ ?,$F$. By definition of $\mathscr{F}$ old, we can apply a leftmost-outermost narrowing step at the position of the subterm $s$ of $t$ with an appropriate case-rule, i.e. $t \leadsto\left\{t^{\prime}\right.$ is a leftmost-outermost narrowing step with $\mathscr{F} \operatorname{old}(G)=t^{\prime} \rightarrow ?$.
3. The Case Guess rule is applied: Analogously to the previous case.
4. The Case Eval rule is applied: Then $\sigma=\{ \}, s=$ case $f\left(\overline{n_{n}}\right)$ of $\overline{p_{k}: \mathscr{X}_{k}}, f\left(\overline{X_{n}}\right) \rightarrow$ $\mathscr{X}$ is a rewrite rule, $\varphi=\left\{\overline{X_{n} \mapsto t_{n}}\right\}$, and $G=\varphi(\mathscr{X}) \rightarrow$ ? $Z$, case $Z$ of $\overline{p_{k}: \mathscr{X}_{k}}$ for some fresh variable $Z$. By definition of $\mathscr{F}$ old, we can apply a leftmostoutermost narrowing step at the position of the subterm $f\left(\overline{t_{n}}\right)$ of $t$ with the same rewrite rule, i.e. $t \leadsto \overbrace{\}} t^{\prime}$ is a leftmost-outermost narrowing step with $\mathscr{F} \operatorname{old}(G)=t^{\prime} \rightarrow{ }^{?} X($ by definition of $\mathscr{F}$ old $)$.

Now we can prove the equivalence of leftmost-outermost narrowing and the lazy narrowing calculus LNT.

## Theorem 3.5

Let $t$ be a term, $c$ a 0 -ary constructor, and $X$ a fresh variable. For each leftmostoutermost narrowing derivation $t \rightsquigarrow{ }_{\sigma}^{*} c$ wrt $\mathscr{R}^{\prime} \cup \mathscr{R}_{\text {case }}$ there exists a LNT-derivation case $t$ of $c: c \rightarrow ? ~ X ~ \stackrel{*}{\Rightarrow}{ }^{\sigma} c \rightarrow ? X$ wrt $\mathscr{R}^{\prime}$, and vice versa.

Proof
First, note that a leftmost-outermost narrowing derivation $t \rightarrow{ }_{\sigma}^{*} c$ has a unique correspondence to a leftmost-outermost narrowing derivation

$$
\text { case } t \text { of } c: c \rightsquigarrow_{\sigma}^{*} \text { case } c \text { of } c: c \rightsquigarrow_{\{ \}} c \text {. }
$$

The existence of the corresponding LNT-derivation is a direct consequence of Lemma A.3, considering the fact that $\mathscr{F}$ lat (case $t$ of $\left.c: c \rightarrow{ }^{?} X\right)=$ case $t$ of $c$ : $c \rightarrow{ }^{?} X$ by definition of $\mathscr{F}$ lat. The reverse direction follows from Lemma A. 4 with a simple induction on the length of the derivations.

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[^1]:    ${ }^{1}$ This description of needed narrowing is slightly different than in Antoy et al. (1994), but more appropriate for the subsequent proofs. In Antoy et al. (1994), the term to be narrowed is always traversed from the root to the narrowing position in each narrowing step, whereas the traversal is represented here by a sequence of $\mathscr{E}$ val-goals.

[^2]:    ${ }^{2}$ To be more precise, different case functions are needed for case expressions with different patterns, i.e. the case functions should be indexed by the case patterns. However, for the sake of readability, we do not write these indices and allow the overloading of the case function symbols.

[^3]:    ${ }^{3}$ Considering liftings is missing in Loría-Sáenz (1993).

[^4]:    ${ }^{4}$ Formally, $\mathscr{F}$ lat is not a function due to the arbitrarily chosen fresh variables. However, by fixing the set of fresh variables and introducing an order on it, $\mathscr{F}$ lat can be interpreted as a function.

