## COMPUTING THE TOPOLOGICAL DEGREE OF POLYNOMIAL MAPS

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Let $C$ be a cube in $\mathbf{R}^{n+1}$ and let $F=\left(f_{1}, \cdots, f_{n+1}\right)$ be a polynomial vector field. In this note we propose a recursive algorithm for the computation of the degree of $F$ on $C$. The main idea of the algorithm is that the degree of $F$ is equal to the algebraic sum of the degrees of the map $\left(f_{1}, f_{2}, \cdots, f_{i-1}, \widehat{f}_{i}, f_{i+1}, \cdots, f_{n+1}\right)$ over all sides of $C$, thereby reducing an $(n+1)$-dimensional problem to an $n$-dimensional one.

## 1. Introduction

Let $\left(x_{1}, x_{2}, \cdots, x_{k}\right)$ be a point in $\mathbf{R}^{k}, k \geqslant 1$. In the sequel we shall denote such a point by $x$. Let

$$
F(x):=\left(f_{1}(x), f_{2}(x), \cdots, f_{n+1}(x)\right): \mathbf{R}^{n+1} \rightarrow \mathbf{R}^{n+1}
$$

be a differentiable mapping. A zero of $F$ is a point $x_{0} \in \mathbf{R}^{n+1}$ such that $F\left(x_{0}\right)=0=$ $(0,0, \cdots, 0)$. Let $a \in \mathbf{R}^{n+1}$ be a zero of $F$ and suppose that the sphere $S(a, \varepsilon)$ centred at $a$ of radius $\varepsilon$ isolates $a$ and it is such that no zero of $F$ lies on $S(a, \varepsilon)$. We then can consider the (Gauss) map

$$
\begin{equation*}
G_{a}: S(a, \varepsilon) \rightarrow S^{n}, \quad G_{a}(x)=\frac{F(x)}{\|F(x)\|} \tag{1}
\end{equation*}
$$

where $S^{n}$ is the unit sphere in $\mathbf{R}^{n+1}$. Then the degree, $\operatorname{deg} G_{a}$, of $G_{a}$ is an integer which, roughly speaking, tells us the (algebraic) number of times $G_{a}$ wraps $S(a, \varepsilon)$ around $S^{n}$ with respect to specified orientations on $S(a, \varepsilon)$ and $S^{n}$. We give $S^{n}$ the following orientation, which we shall call the positive orientation. We think of $S^{n}$ as the boundary of the unit ball $B(0,1)=\left\{x \in \mathbf{R}^{n+1} \mid\|x\| \leqslant 1\right\}$ centred at 0 of radius 1 . Let $e_{1}, e_{2}, \cdots, e_{n+1}$ be the standard basis of $\mathbf{R}^{n+1}$. At each point of the open unit ball $\operatorname{Int}(B(0,1))$ the orientation is given by that basis. Therefore, its boundary inherits an orientation by the following rule. Let $y$ be a point on $S^{n}$ and let $v_{n+1}$ be the unit normal vector to $S^{n}$ that points towards the origin 0 . Let $v_{1}, v_{2}, \cdots, v_{n}$ be a basis for the tangent space of $S^{n}$ at $y$. We call this basis positive if and only if $\operatorname{det}\left(v_{1}, v_{2}, \cdots, v_{n}, v_{n+1}\right)=1$. By applying this rule to every point $y$ on the sphere we get the positive orientation of $S^{n}$. We also give $S(a, \varepsilon)$ the same orientation.

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Definition 1.1: We call $\operatorname{deg} G_{a}$ the local degree of $F$ at $a$, and denote $\operatorname{deg} G_{a}=$ l.d. $F(a)$.

It is well known that the local degree of $F$ at $a$ is independent of the chosen sphere $S(a, \varepsilon)$ as long as the sphere we choose isolates the zero $a$ of $F$.

We define a cube $C$ (or a box) in $\mathbf{R}^{n+1}$ as the boundary of the set:

$$
C=\left[a_{1}, b_{1}\right] \times \cdots \times\left[a_{n+1}, b_{n+1}\right], a_{i}<b_{i}, i=1, \cdots, n+1 .
$$

We define the "upper", $C_{i}^{+}$("lower", $C_{i}^{-}$) $i$-th side of $C$ as follows:

$$
\begin{align*}
C_{i}^{+} & =\left[a_{1}, b_{1}\right] \times \cdots \times\left[b_{i}\right] \times \cdots \times\left[a_{n+1}, b_{n+1}\right]  \tag{2}\\
C_{i}^{-} & =\left[a_{1}, b_{1}\right] \times \cdots \times\left[a_{i}\right] \times \cdots \times\left[a_{n+1}, b_{n+1}\right] .
\end{align*}
$$

Since $C$ is homeomorphic to $S^{n}$ we orient each side of $C$ the same way we oriented the sphere $S^{n}$, namely, at each side $C_{i}^{+}$and $C_{i}^{-}$the normal vector points inside the cube $C$.

Let now $F=\left(f_{1}, \cdots, f_{n+1}\right)$ be a polynomial vector field in $\mathbf{R}^{n+1}$ and consider a cube $C$ so that no zero of $F$ lies on $C$. In that case we can again define the Gauss map, which we call $G$,

$$
G: C \rightarrow S^{n}, \quad G(x)=\frac{F(x)}{\|F(x)\|}
$$

Suppose now that all zeros of $F$ that lie in the interior $\operatorname{Int}(C)$ are isolated. Then the following holds:

Proposition 1.1. For $C, F, G$ as above, we have

$$
\begin{equation*}
\operatorname{deg} G=\sum_{a} l \cdot d \cdot F(a) \tag{3}
\end{equation*}
$$

where the above sum is taken over all $a$ such that $F(a)=0$ and $a \in \operatorname{Int}(C)$.
Definition 1.2: We call $\operatorname{deg} G$ the degree of $F$ on $C$, and denote $\operatorname{deg} G=\operatorname{deg} F_{C}$.
Our aim is to compute $\operatorname{deg} F_{C}$ given the cube $C$ and the polynomial map $F$. Various methods of computing this degree have been proposed. O'Neal and Thomas [4] use quadrature methods to evaluate the Kronecker integral formula for the degree. Stenger [6] has a method, derived from the Kronecker integral formula as well. Kearfortt describes two methods, one that is related to Stenger's method [1], and one that is recursive, repeatedly reducing by one the functions to be considered [2]. Our method is also recursive and uses the idea of Gröbner basis.

In the next section we describe the method and prove the main result. The last section gives an implementation of the algorithm, as well as examples, in dimension 3.

## 2. A Procedure for Computing deg $F_{C}$

We begin by defining some "special" points on $S^{n}$ that we shall need later:

$$
\begin{equation*}
N_{i}=e_{i}, \quad S_{i}=-e_{i}, \quad i=1,2, \cdots, n+1 \tag{4}
\end{equation*}
$$

We shall call the $N_{i}, S_{i}$ the $i$-th "north" and "south" poles of $S^{n}$, respectively. It is easy to see that a local orienting basis at $N_{i}\left(S_{i}\right)$, is the following:

$$
\begin{aligned}
& \left(e_{1}, e_{2}, \cdots, e_{i-1}, \widehat{e}_{i}, e_{i+1}, \cdots,(-1)^{n-i} e_{n+1},-e_{i}\right) \\
& \left(e_{1}, e_{2}, \cdots, e_{i-1}, \widehat{e}_{i}, e_{i+1}, \cdots,(-1)^{n-i+1} e_{n+1}, e_{i}\right)
\end{aligned}
$$

respectively, where ${ }^{\wedge}$ denotes omission.
Let now $U_{i}=\left\{\left(x_{1}, \cdots, x_{n+1}\right) \mid 0<x_{i} \leqslant 1\right\}$, and $L_{i}=\left\{\left(x_{1}, \cdots, x_{n+1}\right) \mid-1 \leqslant x_{i}<0\right\}$ be the upper, lower $i$-th hemisphere of $S^{n+1}$, respectively. We can then define the natural charts from these sets to the unit open ball $B(0,1):=\{x \mid\|x\|<1\} \subset \mathbf{R}^{n}$, as follows:

$$
\begin{array}{ll}
g_{i}: U_{i} \rightarrow \mathbf{R}^{n}, & g_{i}(x)=\left(x_{1}, \cdots, x_{i-1}, \widehat{x}_{i}, x_{i+1}, \cdots, x_{n+1}\right)  \tag{5}\\
h_{i}: L_{i} \rightarrow \mathbf{R}^{n}, & h_{i}(x)=\left(x_{1}, \cdots, x_{i-1}, \widehat{x}_{i}, x_{i+1}, \cdots, x_{n+1}\right) .
\end{array}
$$

These are diffeomorphisms $U_{i} \stackrel{g_{i}}{\approx} B(0,1)$, and $L_{i} \stackrel{h_{i}}{\approx} B(0,1)$. Let $d g_{i}(y), d h_{i}(y)$ be the corresponding linear maps that are defined between the tangent planes at a point $y$ of $U_{i}, L_{i}$ and $\mathbf{R}^{n}$, respectively, and let $\left|d g_{i}(y)\right|,\left|d h_{i}(y)\right|$ denote the determinants of these linear maps. It is then easy to see that

$$
\begin{equation*}
\operatorname{sign}\left|d g_{i}\left(N_{i}\right)\right|=(-1)^{n-i} \quad \text { while } \quad \operatorname{sign}\left|d h_{i}\left(S_{i}\right)\right|=(-1)^{n-i+1} \tag{6}
\end{equation*}
$$

where sign signifies the signature of a real number. Thus, since $g_{i}$ and $h_{i}$ are diffeomorphisms, and if $y$ is any point in $U_{i}$ or $L_{i}$, we get that

$$
\begin{align*}
& \operatorname{sign}\left|d g_{i}(y)\right|=(-1)^{n-i}, \quad \text { for all points } y \in U_{i} \\
& \operatorname{sign}\left|d h_{i}(y)\right|=(-1)^{n-i+1}, \quad \text { for all points } y \in L_{i} \tag{7}
\end{align*}
$$

For a point $b \in \mathbf{R}$ and $x \in \mathbf{R}^{n}$ we define

$$
\begin{equation*}
x^{i}(b)=\left(x_{1}, \cdots, x_{i-1}, b, x_{i+1}, \cdots, x_{n}\right) \tag{8}
\end{equation*}
$$

Let now $K_{i}$ be the image of the natural projection of the interior of either $C_{i}^{+}$or $C_{i}^{-}$on $\mathbf{R}^{n}$. We then may define the lifting maps

$$
\left.\begin{array}{rl}
p_{i}: K_{i} \rightarrow \operatorname{Int}\left(C_{i}^{+}\right), & p_{i}(x)=x^{i}\left(b_{i}\right) \\
q_{i}: K_{i} \rightarrow \operatorname{Int}\left(C_{i}^{-}\right. \tag{9}
\end{array}\right), \quad q_{i}(x)=x^{i}\left(a_{i}\right) .
$$

Since the orientation of $C_{i}^{+}\left(C_{i}^{-}\right)$is the same as the orientation at $N_{i}\left(S_{i}\right)$ of the sphere $S^{n}$, respectively, we can see from (7) that at each point $y \in K_{i}$ we have

$$
\begin{equation*}
\operatorname{sign}\left|d p_{i}(y)\right|=(-1)^{n-i}, \quad \text { while } \quad \operatorname{sign}\left|d q_{i}(y)\right|=(-1)^{n-i+1} \tag{10}
\end{equation*}
$$

Recall that we are given a cube $C$ so that no zero of $F$ lies on $C$. For each $N_{j}, S_{j}$ define

$$
\begin{array}{rlll}
X\left(N_{j}\right)_{i}^{+} & :=G^{-1}\left(N_{j}\right) \cap C_{i}^{+} & X\left(N_{j}\right)_{i}^{-}:=G^{-1}\left(N_{j}\right) \cap C_{i}^{-} \\
X\left(S_{j}\right)_{i}^{+} & :=G^{-1}\left(S_{j}\right) \cap C_{i}^{+} & X\left(S_{j}\right)_{i}^{-}:=G^{-1}\left(S_{j}\right) \cap C_{i}^{-}
\end{array}
$$

Now using the notation of (8) we define

$$
\begin{gathered}
F_{i}^{+}(x)=\left(f_{2}\left(x_{i}\left(b_{i}\right)\right), \cdots, f_{n+1}\left(x_{i}\left(b_{i}\right)\right)\right): \mathbf{R}^{n} \rightarrow \mathbf{R}^{n} \\
F_{i}^{-}(x)=\left(f_{2}\left(x_{i}\left(a_{i}\right)\right), \cdots, f_{n+1}\left(x_{i}\left(a_{i}\right)\right)\right): \mathbf{R}^{n} \rightarrow \mathbf{R}^{n} .
\end{gathered}
$$

Moreover, we call the cube $C$ good for $F$ relative to $f_{1}$ if the sets $G^{-1}\left(N_{1}\right)$ and $G^{-1}\left(S_{1}\right)$ are both finite, each point of that inverse image of $N_{1}, S_{1}$ lies in the interior of some side of $C$, and the Jacobian determinants $\left|J\left(F_{i}^{+}\right)\right|$and $\left|J\left(F_{i}^{-}\right)\right|$have isolated zeros at every point of $G^{-1}\left(N_{1}\right), G^{-1}\left(S_{1}\right)$.

We are now ready to state the main theorem of this note.
Theorem 2.1. Let $F, C, G$ be as above, and suppose that $C$ is good relative to $f_{1}$. Then

$$
\begin{aligned}
\operatorname{deg} F_{C} & =\sum_{i=1}^{n+1}(-1)^{i+1} \text { l.d. } F_{i}^{+}\left(y_{i}^{+}\right)+\sum_{i=1}^{n+1}(-1)^{i} l . d . F_{i}^{-}\left(y_{i}^{-}\right) \\
& =\sum_{i=1}^{n+1}(-1)^{i} \text { l.d. } F_{i}^{+}\left(z_{i}^{+}\right)+\sum_{i=1}^{n+1}(-1)^{i+1} \text { l.d. } F_{i}^{-}\left(z_{i}^{-}\right)
\end{aligned}
$$

where $y_{i}^{+} \in X\left(N_{1}\right)_{i}^{+}, y_{i}^{-} \in X\left(N_{1}\right)_{i}^{-}, z_{i}^{+} \in X\left(S_{1}\right)_{i}^{+}$and $z_{i}^{-} \in X\left(S_{1}\right)_{i}^{-}$.
Before we proceed with the proof of the theorem, note that a similar result can be obtained if the north $N_{1}$ or south pole $S_{1}$ is replaced with another north ot south pole $N_{k}$ or $S_{k}$. In that case, however, the cube $C$ must be good relative to $f_{k}$.

Proof of Theorem 2.1: For the sake of clarity we prove this theorem in the case where the north pole $N_{1}$ is a regular value of $G$. That is, the points $y_{i}^{+}$and $y_{i}^{-}$are noncritical points of $G$. So, let us take a point $y_{i}^{+}=\left(y_{1}, \cdots, y_{i-1}, b_{i}, y_{i+1}, \cdots, y_{n+1}\right)$ and see what is its contribution to the degree $\operatorname{deg} F_{C}$. We define the series of maps

$$
\begin{equation*}
K_{i} \xrightarrow{p_{i}} \operatorname{Int}\left(C_{i}^{+}\right) \hookrightarrow C \xrightarrow{G} U_{i} \hookrightarrow S^{n} \xrightarrow{g_{1}} \mathbf{R}^{n} \tag{11}
\end{equation*}
$$

where $\hookrightarrow$ denotes the inclusion map. From (11) we get the composite map

$$
A:=g_{1} \circ G \circ p_{i}: K_{i} \subset \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}
$$

Let $d g_{1}, d G, d p_{i}$ be the corresponding linear maps. Let

$$
y_{0}=\left(y_{1}, \cdots, y_{i-1}, \widehat{b}_{i}, y_{i+1}, \cdots, y_{n+1}\right)
$$

Then at $y_{0}$ the Jacobian determinant of $A$ is nonzero, since $y_{i}^{+}$is a noncritical point of $G$. Moreover, we have

$$
\left|d A\left(y_{0}\right)\right|=\left|d g_{1}\left(N_{1}\right)\right| \cdot\left|d G\left(y_{i}^{+}\right)\right| \cdot\left|d p_{i}\left(y_{0}\right)\right|
$$

and thus

$$
\begin{aligned}
\left|d G\left(y_{i}^{+}\right)\right| & =\left|d g_{1}\left(N_{1}\right)\right| \cdot\left|d p_{i}\left(y_{0}\right)\right| \cdot\left|d A\left(y_{0}\right)\right| \\
& =(-1)^{n-1}(-1)^{n-i} l . d . A\left(y_{0}\right), \text { from (6), (10) } \\
& =(-1)^{i+1} l . d . A\left(y_{0}\right)
\end{aligned}
$$

But, an easy computation shows that $l . d . A\left(y_{0}\right)=l . d . F_{i}^{+}\left(y_{i}^{+}\right)$. A similar argument shows that the contribution to the degree of $F$ at a $y_{i}^{-}$is $(-1)^{i} l . d . F_{i}^{-}\left(y_{i}^{-}\right)$. Thus, when we repeat the above process over all preimages of $N_{1}$ under $G$ we get the desired expression for $\operatorname{deg} F_{C}$.

We close this section with the final step of the recursion, that is, the computation of the degree in dimension 2, (see also [5]). For this, let $F=(f(x, y), g(x, y))$ be a polynomial vector field in $\mathbf{R}^{2}$ and let $C=\partial\left[a_{1}, b_{1}\right] \times\left[a_{2}, b_{2}\right]$ be a cube (rectangle) good for $F$ relative to $g . C$ has the counterclockwise (positive) orientation that it inherits as the boundary of the (open) rectangle. Let $z$ be a zero of $G$ that lies on a side of $C$. Then when we move on $C$ according to the orientation, we observe the sign of $f \cdot g$ passing through $z$. If the $\operatorname{signf} \cdot g$ changes from $+\rightarrow-$ the contribution to the degree is 1 , while if it changes from $-\rightarrow+$ the contribution is -1 . By summing up all this contributions over all sides of $C$ and dividing by 2 we get the desired degree.

## 3. The Algorithm in the Cases $n=2$ and 3

The algorithms of this section are implemented in the Axiom symbolic algebra system, but any type or object oriented language could be used to describe the process. For the computations with the real algebraic numbers we use the method of interval coding, see [3]. In this section $R$ denotes the real closure of an ordered field $K$. The algorithm is generic.
3.1. Case $n=2:$ Let $F(x, y):=\left(f_{1}(x, y), f_{2}(x, y)\right): R^{2} \rightarrow R^{2}$ be a polynomial mapping. Let $C=\left[a_{1}, b_{1}\right] \times\left[a_{2}, b_{2}\right]$ be a rectangle in $R^{2}$. The algorithm degree2 computes the degree of $F$ in $C$. The boundary $\partial C$, of box $C$, has the positive orientation. The algorithm proceeds as follows:

Algorithm 1. degree2
input: The polynomials $f_{1}(x, y), f_{2}(x, y)$, and the rectangle $C$ as above.
output: An integer equal to $\operatorname{deg} F_{C}$.
Description:
The basic steps are:

1. Call $h_{1}(x):=f_{1}\left(x, a_{2}\right), h_{2}(x):=f_{2}\left(x, a_{2}\right), g_{1}(y):=f_{1}\left(b_{1}, y\right)$ and $g_{2}(y):=$ $\left.f_{2}\left(b_{1}, y\right)\right)$.
2. Compute the real roots of $h_{1}(x)\left(g_{1}(y)\right)$ in the intervals $\left[a_{1}, b_{1}\right]\left(\left[a_{2}, b_{2}\right]\right)$, respectively. Let $\left(r_{i}\right)_{1 \leqslant i \leqslant k}$ be these real roots. If $h_{1}\left(a_{1}\right)=0$ or $g_{1}\left(a_{2}\right)=0$, or $h_{1}\left(b_{1}\right)=0$ or $g_{1}\left(b_{2}\right)=0$, or there exists an $i$ such that $h_{2}\left(r_{i}\right)=0$, or $g_{2}\left(r_{i}\right)=0$, then redefine the rectangle $C$. Else, go to step 3 .
3. Compute the sign of $h_{1}(x) h_{2}(x)$, and of $g_{1}(y) g_{2}(y)$, on the left and on the right of each real root $r_{i}$, respectively.
4. If $\operatorname{sign}\left(h_{1}(x) h_{2}(x)\right)$ changes from $+\rightarrow-$ the contribution to the degree is 1 , while if it changes from $\rightarrow+$ the contribution is -1 .
5. Start by the left contribution of the real root $r_{1}$. Sum up all the contributions over the sides $y=b_{2}$ and $x=b_{1}$; denote this sum by $l_{1}$.
6. Call $h_{1}(x):=f_{1}\left(x, b_{2}\right), h_{2}(x):=f_{2}\left(x, b_{2}\right), g_{1}(y):=f_{1}\left(a_{1}, y\right)$ and $g_{2}(y):=$ $f_{2}\left(a_{1}, y\right)$.
7. Compute the real roots of $h_{1}(x)\left(g_{1}(y)\right)$ in the intervals $\left[a_{1}, b_{1}\right]\left(\left[a_{2}, b_{2}\right]\right)$, respectively. Let $\left(s_{j}\right)_{1 \leqslant j \leqslant m}$ be these real roots. If $h_{1}\left(a_{1}\right)=0$ or $g_{1}\left(a_{2}\right)=0$, or $h_{1}\left(b_{1}\right)=0$ or $g_{1}\left(b_{2}\right)=0$, or there exists $j$ such that $h_{2}\left(s_{j}\right)=0$ or $g_{2}\left(s_{j}\right)=0$, then redefine the rectangle $C$. Else, go to step 8 .
8. Compute the sign of $h_{1}(x) h_{2}(x)$ and of $g_{1}(y) g_{2}(y)$, on the left and on the right of each real root $s_{j}$.
9. Start by the right contribution of the real root $r_{m}$. If $\operatorname{sign}\left(h_{1}(x) h_{2}(x)\right)$ changes from $+\rightarrow-$ the contribution is 1 , while if it changes from $-\rightarrow+$ the contribution is -1 .
10. Sum up all the contributions over the sides $y=b_{2}$ and $x=b_{1}$ and denote this sum by $l_{2}$.
11. The degree is equal to $\frac{l_{1}+l_{2}}{2}$.
3.2. CASE $n=3: \quad$ Let $F\left(x_{1}, x_{2}, x_{3}\right):=\left(f_{1}\left(x_{1}, x_{2}, x_{3}\right), f_{2}\left(x_{1}, x_{2}, x_{3}\right), f_{3}\left(x_{1}, x_{2}, x_{3}\right)\right)$ be a polynomial map of $R^{3} \rightarrow R^{3}$, and $C:=\prod_{i=1}^{3}\left[a_{i}, b_{i}\right]$ be a box in $R^{3}$. We use the standard implementation of the Gröbner basis of the Axiom symbolic system.

Algorithm 2. degree3
input: The polynomials
$f_{1}\left(x_{1}, x_{2}, x_{3}\right), f_{2}\left(x_{1}, x_{2}, x_{3}\right), f_{3}\left(x_{1}, x_{2}, x_{3}\right)$, and the box $C$, as above.
output: An integer equal to $\operatorname{deg} F_{C}$.

## Description:

Notation: If $x \in R^{3}, d \in R$ and $i=1 \ldots 3$, then we define $x^{i}(d)=(., \underbrace{d}_{i-\text { position }},$.$) ,$ and $x^{i}=(., \underbrace{\widehat{x}_{i}}_{i-\text { position }},.) \in R^{2}$, where - denotes omission, as in Section 2. If $j=1 \ldots 3$, we denote by $a_{j, i}$ the $i$-element of the $j$-interval, for example, $a_{3,2}$ is $b_{3}$, and $a_{2,1}$ is $a_{2}$. By $\left[a_{j, 1}, a_{j, 2}\right]^{j}$ we denote the rectancle in $R^{2}: \ldots \times \underbrace{\left[a_{j, 1}, a_{j, 2}\right]}_{j-\text { position }} \times \ldots$, where - denotes omission, as above.

1. For $j=1 \ldots 3$ repeat Step $_{j}$.
2. Step $_{j}$ : For $i=1 \ldots 2$, repeat
(a) Call $h_{2}\left(x^{j}\right):=f_{2}\left(x^{j}\left(a_{j, i}\right)\right), h_{3}\left(x^{j}\right):=f_{3}\left(x^{j}\left(a_{j, i}\right)\right)$. Compute the Gröbner basis of $h_{2}\left(x^{j}\right), h_{3}\left(x^{j}\right)$. Let $G$ be this base. The polynomials of $G$ form a triangular system where the last polynomial is univariate. We find and isolate the real solutions of this system.
(b) Step 1: Find the sign of $f_{1}\left(x_{1}, x_{2}, x_{3}\right)$ in the real root of the system of step 2(a). Compute the degree (see Algorithm 1), of $h_{2}\left(x^{i}\right)$ and $h_{3}\left(x^{i}\right)$ in the corresponding isolating rectangle using degree2.
(c) Step 2: $i:=i+1$.
3. Compute the degree of $F\left(x_{1}, x_{2}, x_{3}\right)$ using the formulae of Theorem 2.1.

The binary time complexity of our algorithm is unknown. The complexity is obviously dependent on the amount of the algebraic numbers generated by the real solutions and the Gröbner basis algorithm.

Example 1: Consider the system:

$$
F(x, y, z) \quad\left\{\begin{array}{ll}
p_{1}(x, y, z) & :=x^{3}+y^{2}-z \\
p_{2}(x, y, z) & :=y^{3}+z^{2}+x \\
p_{3}(x, y, z) & :=z^{3}+x^{2}-y
\end{array}\right\}
$$

This system has the following five real solutions (aproximately):

$$
\begin{cases}1 . & {[z=0.9635, y=0.60002, x=-1.1289]} \\ 2 . & {[z=-8.715, y=-0.04635 x=-1.261]} \\ 3 . & {[z=-1, y=0, x=-1]} \\ 4 . & {[z=0, y=1, x=-1]} \\ 5 . & {[z=0, y=0, x=0]}\end{cases}
$$

We compute the degree on the boxes $[-3 / 2,-1 / 2] \times[-1 / 2,1 / 2] \times[-9,0]$ and $[-2,2]^{3}$. Consider the first box. For $y=1 / 2$, the algorithm groebner $(p 2(x, 1 / 2, z)$, p3 ( $x, 1 / 2, z$ ) ) of Axiom gives:

$$
\begin{aligned}
& g_{1}(z, x):=z-\frac{64}{31} x^{3}-\frac{56}{31} x^{2}+\frac{16}{31} x-\frac{5}{31} \\
& g_{2}(x) \quad:=x^{4}+x^{3}-\frac{5}{8} x^{2}+\frac{3}{64} x+\frac{129}{512}
\end{aligned}
$$

If $\xi$ is the first real root of $g_{2}(x)$, and $\zeta$ the real root of $g_{1}(z, \xi)$, then the sign of $p_{1}(\xi, 1 / 2, \zeta)$ is negative. The degree of $F(x, z):=\left(p_{2}(x, 1 / 2, z), p_{3}(x, 1 / 2, z)\right)$ on the rectangle $[-3 / 2,-1 / 2] \times[-9,0]$ is 1 . The point $(\xi, 1 / 2, \zeta) \in X(S)_{2}^{+}$. Thus from Theorem 2.1, the contribution to $\operatorname{deg} F_{C}$ is $(-1)^{3} * 1=-1$. The second real root of $g_{2}(x)$, $\xi^{\prime} \notin[-3 / 2,-1 / 2]$. For $x=-1 / 2$, the algorithm groebner $(\mathrm{p} 2(-1 / 2, \mathrm{y}, \mathrm{z}), \mathrm{p} 3(-1 / 2, \mathrm{y}, \mathrm{z}))$ of Axiom gives:

$$
\begin{aligned}
& g_{1}(z, y):=z-\frac{64}{31} y^{8}-\frac{16}{31} y^{7}+\ldots-\frac{68}{31} y+\frac{15}{31} \\
& g_{2}(y) \quad:=y^{9}-\frac{3}{2} y^{6}+\frac{3}{4} y^{3}+y^{2}-\frac{1}{2} y-\frac{1}{16}
\end{aligned}
$$

Let $\xi$ be the second real root of the univariate polynomial $g_{2}(y)$, and $\zeta$ the real root of $g_{1}(z, \xi)=0$. In this case, the sign of $p_{1}(-1 / 2, \xi, \zeta)$ is positive, and the degree of $D(y, z):=\left(p_{2}(-1 / 2, y, z), p_{3}(-1 / 2, y, z)\right)$ is also 1 . Since our point is in $X(N)_{1}^{-}$, it similarly follows that the contribution to the $\operatorname{deg} F_{C}$ is $(-1)^{1} * 1=-1$, as in the case where $y=1 / 2$.
All the other cases are discarded. Thus $\operatorname{deg} F_{C}=-1$
Consider now the box $\partial[-2,2]^{3}$. Let $x=-2$; if $(\xi, \zeta)$ is the solution of the system of the Gröbner basis, of the polynomials $p_{2}(-2, y, z)$ and $p_{3}(-2, y, z)$, the sign of $p_{1}(-2, \xi, \zeta)$ is negative, and the corresponding degree in $R^{2}$ is -1 . The point $(-2, \xi, \zeta) \in X(S)_{1}^{-}$. It follows that the contribution to $\operatorname{deg} F_{C}$ is $(-1)^{1+1} *(-1)=-1$. For $x=2$, the sign of $p_{1}$ in the corresponding point of $R^{3}$ is positive, and the degree in $R^{2}$ is -1 . Thus, the degree $\operatorname{deg} F_{C}$ in this case is still -1 .

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