# APPROXIMATELY ANGLE PRESERVING MAPPINGS 

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#### Abstract

We study linear mappings which preserve vectors at a specific angle. We introduce the concept of $(\varepsilon, c)$ angle preserving mappings and define $\widehat{\varepsilon}(T, c)$ as the 'smallest' number $\varepsilon$ for which $T$ is an $(\varepsilon, c)$-angle preserving mapping. We derive an exact formula for $\widehat{\varepsilon}(T, c)$ in terms of the norm $\|T\|$ and the minimum modulus $[T]$ of $T$. Finally, we characterise approximately angle preserving mappings.


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## 1. Introduction

Throughout this paper, $\mathscr{H}, \mathscr{K}$ denote real Hilbert spaces with dimensions greater than or equal to two and $\mathbb{B}(\mathscr{H}, \mathscr{K})$ denotes the Banach space of all bounded linear mappings between the Hilbert spaces $\mathscr{H}$ and $\mathscr{K}$. We write $\mathbb{B}(\mathscr{H})$ for $\mathbb{B}(\mathscr{H}, \mathscr{H})$.

As usual, vectors $x, y \in \mathscr{H}$ are said to be orthogonal, $x \perp y$, if $\langle x, y\rangle=0$, where $\langle.,$. denotes the inner product of $\mathscr{H}$. A mapping $T: \mathscr{H} \longrightarrow \mathscr{K}$ is called orthogonality preserving if it preserves orthogonality, that is,

$$
x \perp y \Longrightarrow T x \perp T y \quad(x, y \in \mathscr{H})
$$

Orthogonality preserving mappings may be nonlinear and discontinuous (see [2]). Under the additional assumption of linearity, a mapping $T$ is orthogonality preserving if and only if it is a scalar multiple of an isometry, that is, $T=\gamma U$, where $U$ is an isometry and $\gamma \geq 0$ (see [5]).

It is natural to consider approximate orthogonality ( $\varepsilon$-orthogonality), $x \perp^{\varepsilon} y$, defined by $|\langle x, y\rangle| \leq \varepsilon\|x\|\|y\|$. For $\varepsilon \geq 1$, it is clear that every pair of vectors are $\varepsilon$-orthogonal, so the interesting case is when $\varepsilon \in[0,1)$.

A mapping $T: \mathscr{H} \longrightarrow \mathscr{K}$ is an approximately orthogonality preserving mapping, or an $\varepsilon$-orthogonality preserving mapping, if

$$
x \perp y \Longrightarrow T x \perp^{\varepsilon} T y \quad(x, y \in \mathscr{H}) .
$$

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Obviously, if $\varepsilon=0$, then $T$ is orthogonality preserving. A natural question is whether a linear $\varepsilon$-orthogonality preserving mapping $T$ must be close to a linear orthogonality preserving mapping (see $[1,4,7]$ ).

In a Hilbert space $\mathscr{H}$ we can define a relation connected to the notion of angle. Fix $c \in(-1,1)$. For $x, y \in \mathscr{H}$, we say that $x \iota_{c} y$ if $\langle x, y\rangle=c\|x\|\|y\|$. Thus, $c=\cos (\alpha)$, where $\alpha$ is the angle between $x$ and $y$ if $x, y \in \mathscr{H} \backslash\{0\}$.

A mapping $T: \mathscr{H} \longrightarrow \mathscr{K}$ is $c$-angle preserving if it preserves the angle $c$, that is,

$$
x \angle_{c} y \Longrightarrow T x \angle_{c} T y \quad(x, y \in \mathscr{H})
$$

Angle preserving mappings may be far from linear and continuous. There is an (infinite-dimensional) Euclidean space $\mathscr{H}$ and an injective map $T: \mathscr{H} \longrightarrow \mathscr{H}$ such that the condition $x \angle_{1 / 2} y$ implies that $T x \angle_{1 / 2} T y$, while the map $T$ is discontinuous at all points (see [6, Remark 3]). A characterisation of angle preserving mappings on finite-dimensional Euclidean spaces was obtained in [6] and Chmieliński [3] studied stability of angle preserving mappings on the plane.

In the next section, we present some characterisations of linear mappings preserving certain angles. We show (Theorem 2.4) that a nonzero linear map $T$ is $c$-angle preserving if and only if $T$ is a scalar multiple of an isometry, generalising [2, Theorem 1] and [12, Theorem 3.8].

Fix $\varepsilon \in[0,1)$ and define $x L_{c}^{\varepsilon} y$ by

$$
\mid\langle x, y\rangle-c\|x\|\|y\|\|\leq \varepsilon\| x\| \| y \|
$$

which is equivalent to $c-\varepsilon \leqslant \cos \alpha \leqslant c+\varepsilon$, where $\alpha$ is the angle between $x$ and $y$. If $c=0$, then $\angle_{0}=\perp$ and $\angle_{0}^{\varepsilon}=\perp^{\varepsilon}$. It is easy to see that $\angle_{c}$ and $\angle_{c}^{\varepsilon}$ are weakly homogeneous in the sense that $x L_{c} y \Leftrightarrow \alpha x L_{c} \beta y$ and $x L_{c}^{\varepsilon} y \Leftrightarrow \alpha x L_{c}^{\varepsilon} \beta y$ for all $\alpha, \beta \in \mathbb{R}^{+}$. For $\varepsilon \geq 1+|c|$, it is obvious that $x L_{c}^{\varepsilon} y$ for all $x, y \in \mathscr{H}$. Hence, we shall only consider the case $\varepsilon \in[0,1+|c|)$.

A mapping $T: \mathscr{H} \longrightarrow \mathscr{K}$ satisfying the condition

$$
x L_{c} y \Longrightarrow T x L_{c}^{\varepsilon} T y \quad(x, y \in \mathscr{H})
$$

is called an $\varepsilon$-approximate $c$-angle preserving mapping or $(\varepsilon, c)$-angle preserving mapping.

Recently, angle preserving mappings have been studied in [8, 9] via an approach different from ours. When $\mathscr{H}, \mathscr{K}$ are finite dimensional, the third author [9] proved that for an arbitrary $\delta>0$ there exists $\varepsilon>0$ such that for any linear ( $\varepsilon, c)$-angle preserving mapping $T$ there exists a linear $c$-angle preserving mapping such that

$$
\|T-S\| \leq \delta \min \{\|T\|,\|S\|\}
$$

Our intention is to obtain a characterisation of approximate angle preserving mappings. If $0 \leq \varepsilon_{1} \leq \varepsilon_{2}<1+|c|$ and $T$ is an ( $\varepsilon_{1}, c$ )-angle preserving mapping, then $T$ is also an ( $\left.\varepsilon_{2}, c\right)$-angle preserving mapping. This fact motivates us to give the following definition (see also [13]).

Defintion 1.1. Let $c \in(-1,1)$. For each map $T: \mathscr{H} \longrightarrow \mathscr{K}$, let $\widehat{\varepsilon}(T, c)$ be the 'smallest' number $\varepsilon$ such that $T$ is $(\varepsilon, c)$-angle preserving, that is,

$$
\widehat{\varepsilon}(T, c):=\inf \{\varepsilon \in[0,1+|c|]: T \text { is an }(\varepsilon, c) \text {-angle preserving mapping }\} .
$$

Thus, $\widehat{\varepsilon}(T, c)=1+|c|$ whenever $T$ is not an approximately $c$-angle preserving mapping. Also, it is easy to see that $\widehat{\varepsilon}(T,-c)=\widehat{\varepsilon}(T, c)=\widehat{\varepsilon}(\alpha T, c)$ for all $\alpha \in \mathbb{R} \backslash\{0\}$.

In the last section, we state some basic properties of the function $\widehat{\varepsilon}(., c)$. If $T \in \mathbb{B}(\mathscr{H}, \mathscr{K})$, then we derive an exact formula for $\widehat{\varepsilon}(T, c)$ in terms of the norm $\|T\|$ and the minimum modulus $[T]$ of $T$. Here $[T]$ is the largest number $m \geq 0$ such that $\|T x\| \geq m\|x\|(x \in \mathscr{H})$. We use this formula to characterise the approximately $c$-angle preserving mappings (Corollary 3.4) and show that every nonzero linear mapping $T$ is approximately $c$-angle preserving if and only if $T$ is bounded below.

## 2. Linear mappings preserving angles

We start our work with the following lemmas. The first follows immediately from the definition of the angle between vectors.

Lemma 2.1. Let $c \in[0,1)$. If $x, y \in \mathscr{H}$ are such that $\|x\|=\|y\|=1$ and $x \perp y$, then:
(i) $(x+\sqrt{1+c / 1-c} y) \angle_{c}(-x+\sqrt{1+c / 1-c} y)$;
(ii) $(x+\sqrt{1-c / 1+c} y) \angle_{c}(x-\sqrt{1-c / 1+c} y)$.

Lemma 2.2 [10, Theorem 2.3]. Let $T \in \mathbb{B}(\mathscr{H}, \mathscr{K})$ be an injective linear map. Suppose that $\operatorname{dim} \mathscr{H}=n$. Then there exists an orthonormal basis $\left\{x_{1}, x_{2}, \ldots, x_{n}\right\}$ for $\mathscr{H}$ such that

$$
[T]=\left\|T x_{1}\right\|, \quad\left\|T x_{2}\right\|=\|T\| \quad \text { and } \quad T x_{i} \perp T x_{j} \quad(1 \leq i \neq j \leq n)
$$

Corollary 2.3. Let $T: \mathscr{H} \longrightarrow \mathscr{K}$ be a nonzero injective linear map. Suppose that unit vectors $x, y \in \mathscr{H}$ are linearly independent. Then there exist unit vectors $x_{1}, x_{2}$ such that

$$
x_{1} \perp x_{2}, \quad T x_{1} \perp T x_{2}, \quad\left\|T x_{1}\right\| \leq\|T x\| \leq\left\|T x_{2}\right\| \quad \text { and } \quad\left\|T x_{1}\right\| \leq\|T y\| \leq\left\|T x_{2}\right\| .
$$

We are now ready to characterise the $c$-angle preserving mappings. The following result is a generalisation of [2, Theorem 1].

Theorem 2.4. Let $T: \mathscr{H} \longrightarrow \mathscr{K}$ be a nonzero linear map and let $c \in(-1,1)$. Then the following statements are equivalent:
(i) $x \angle_{c} y \Longrightarrow T x \angle_{c} T y \quad(x, y \in \mathscr{H})$;
(ii) there exists $\gamma>0$ such that $\|T x\|=\gamma\|x\| \quad(x \in \mathscr{H})$.

Proof. The implication (ii) $\Rightarrow$ (i) follows from the polarisation formula. The implication (i) $\Rightarrow$ (ii) follows from a more general theorem (see Corollary 3.5).

The following example shows that Theorem 2.4 fails if the assumption of linearity is dropped. Nonlinear mappings satisfying $x \iota_{c} y \Longrightarrow T x L_{c} T y(x, y \in \mathscr{H})$ may be very strange and even noncontinuous.

Example 2.5. Let $c \in(-1,1)$. Let $\varphi: \mathscr{H} \rightarrow \mathbb{R}$ be a fixed nonvanishing function. Define the mapping $T: \mathscr{H} \longrightarrow \mathscr{H}$ by $T(x):=\varphi(x) \cdot x$. Then $x L_{c} y \Longrightarrow T x \angle_{c} T y$ for all $x, y \in \mathscr{H}$. If $\varphi$ is not continuous, then $T$ clearly is not continuous. In particular, $T$ is clearly not a similarity.

Taking $\mathscr{K}=\mathscr{H}$ and $T=\mathrm{Id}:\left(\mathscr{H},\langle., .\rangle_{1}\right) \longrightarrow\left(\mathscr{H},\langle., .\rangle_{2}\right)$, the identity map, we obtain the following result from Theorem 2.4.

Corollary 2.6. Let $c \in(-1,1)$. Suppose that $\mathscr{H}$ is a vector space equipped with two (complete) inner products $\langle., .\rangle_{1},\langle., .\rangle_{2}$ generating the norms $\|.\|_{1},\|.\|_{2}$ and c-angle relations $\angle_{c, 1}, L_{c, 2}$, respectively. Then the following conditions are equivalent:
(i) there exists $\gamma>0$ such that $\|x\|_{2}=\gamma\|x\|_{1} \quad(x \in \mathscr{H})$;
(ii) $x \iota_{c, 1} y \Longrightarrow x \angle_{c, 2} y \quad(x, y \in \mathscr{H})$;
(iii) $\sup \left\{\left|\langle x, y\rangle_{2} /\|x\|_{2}\|y\|_{2}-c\right|: x L_{c, 1} y, x, y \in \mathscr{H} \backslash\{0\}\right\}=0$.

Corollary 2.7. Let $T \in \mathbb{B}(\mathscr{H}, \mathscr{K})$ be a bijective linear map and let $c \in(-1,1)$. Then the following statements are equivalent:
(i) $\quad x \angle_{c} y \Longrightarrow T x \angle_{c} T y \quad(x, y \in \mathscr{H})$;
(ii) $\left\|T S T^{-1}\right\| \leq\|S\|$ for all invertible linear mappings $S \in \mathbb{B}(\mathscr{H})$.

Proof. The implication (i) $\Rightarrow$ (ii) follows immediately from Theorem 2.4.
(ii) $\Rightarrow$ (i). Suppose that (ii) holds. For every $\varepsilon>0$,

$$
\left\|\varepsilon I+T(x \otimes y) T^{-1}\right\|=\left\|T(\varepsilon I+x \otimes y) T^{-1}\right\| \leq\|\varepsilon I+x \otimes y\| \quad(x, y \in \mathscr{H}) .
$$

Here, $x \otimes y$ denotes the rank-one operator in $\mathbb{B}(\mathscr{H})$ defined by $(x \otimes y)(z):=\langle z, y\rangle x$ for $z \in \mathscr{H}$. Letting $\varepsilon \rightarrow 0^{+}$yields

$$
\left\|T(x \otimes y) T^{-1}\right\| \leq\|x \otimes y\| \quad(x, y \in \mathscr{H})
$$

This implies that $\|T\|\left\|T^{-1}\right\| \leq 1$. Hence,

$$
\|T\|\|x\| \leq \frac{\|x\|}{\left\|T^{-1}\right\|} \leq\|T x\| \leq\|T\|\|x\| \quad(x \in \mathscr{H})
$$

which gives

$$
\|T x\|=\|T\|\|x\| \quad(x \in \mathscr{H})
$$

Now, the equivalence (i) $\Leftrightarrow$ (ii) of Theorem 2.4 gives (i).

## 3. Approximately angle preserving mappings

Our aim in this section is to characterise approximately angle preserving mappings. The following lemma follows immediately from Definition 1.1.

Lemma 3.1. Let $T: \mathscr{H} \longrightarrow \mathscr{K}$ be a linear map and let $c \in(-1,1)$. Then the following statements hold:
(i) $\widehat{\varepsilon}(T, c)=\sup \left\{|\langle T x, T y\rangle /\|T x\|\|T y\|-c|: x L_{c} y, x, y \in \mathscr{H} \backslash\{0\}\right\}$;
(ii) $\widehat{\varepsilon}(T, c)=\sup \left\{|\langle T x, T y\rangle /\|T x\|\|T y\|-c|: x \angle_{c} y,\|x\|=\|y\|=1, x, y \in \mathscr{H}\right\}$.

Our next theorem is a generalisation of [13, Lemma 2.2].
Theorem 3.2. Let $T: \mathscr{H} \longrightarrow \mathscr{K}$ be a nonzero linear map and let $c \in(-1,1)$. If $[T]=0$, then $\widehat{\varepsilon}(T, c)=1+|c|$.

Proof. Since $\widehat{\varepsilon}(T,-c)=\widehat{\varepsilon}(T, c)$, we may assume that $c \in[0,1)$. We consider two cases.
Case 1. $\quad$ is not injective.
There exists a subspace $\mathscr{H}_{1}$ such that $2 \leq \operatorname{dim} \mathscr{H}_{1}<\infty$ and $\left.T\right|_{\mathscr{H}_{1}}$ is not injective, that is, $\{0\} \neq \operatorname{ker}\left(\left.T\right|_{\mathscr{H}_{1}}\right) \neq \mathscr{H}_{1}$. (Indeed, if $T$ is injective on every finite-dimensional subspace, then $T$ has to be injective.) Since the set $\operatorname{ker}\left(\left.T\right|_{\mathscr{H}_{1}}\right)$ is not dense, we can find two vectors $x \in\left(\operatorname{ker}\left(\left.T\right|_{\mathscr{H}_{1}}\right)\right)^{\perp}, y \in \operatorname{ker}\left(\left.T\right|_{\mathscr{H}_{1}}\right)$ such that $\|x\|=\|y\|=1$ and $x \perp y$. By Lemma 2.1(i),

$$
\left|\frac{\left\langle T\left(x+\sqrt{\frac{1+c}{1-c}} y\right), T\left(-x+\sqrt{\frac{1+c}{1-c}} y\right)\right\rangle}{\left\|T\left(x+\sqrt{\frac{1+c}{1-c}} y\right)\right\|\left\|T\left(-x+\sqrt{\frac{1+c}{1-c}} y\right)\right\|}-c\right|=\left|\frac{-\|T x\|^{2}}{\|T x\|^{2}}-c\right|=1+c .
$$

Thus, by Lemma 3.1(i), $\widehat{\varepsilon}(T, c)=1+c$.
Case 2. $T$ is injective.
Assume that $\widehat{\varepsilon}(T, c)<1+c$. Then there exists $\varepsilon_{0}<1+c$ such that $T$ is an $\left(\varepsilon_{0}, c\right)$ angle preserving mapping. Consider arbitrary unit vectors $x, y \in \mathscr{H}$. If $x$ and $y$ are linearly dependent, then $\sqrt{(1-c)\left(1+c-\varepsilon_{0}\right) /(1+c)\left(1-c+\varepsilon_{0}\right)}\|T y\| \leq\|T x\|$. If $x$ and $y$ are linearly independent, then, by Corollary 2.3 , there exist unit vectors $x_{1}, x_{2}$ such that

$$
\begin{equation*}
x_{1} \perp x_{2}, \quad T x_{1} \perp T x_{2}, \quad\left\|T x_{1}\right\| \leq\|T x\| \leq\left\|T x_{2}\right\| \quad \text { and } \quad\left\|T x_{1}\right\| \leq\|T y\| \leq\left\|T x_{2}\right\| . \tag{3.1}
\end{equation*}
$$

So, by Lemma 2.1(ii),

$$
T\left(x_{1}+\sqrt{\frac{1-c}{1+c}} x_{2}\right) L_{c}^{\varepsilon_{0}} T\left(x_{1}-\sqrt{\frac{1-c}{1+c}} x_{2}\right)
$$

Put $u=x_{1}+\sqrt{1-c / 1+c} x_{2}$ and $v=x_{1}-\sqrt{1-c / 1+c} x_{2}$. Then

$$
\begin{aligned}
-\left\|T x_{1}\right\|^{2}+\frac{1-c}{1+c}\left\|T x_{2}\right\|^{2} & +c\left(\left\|T x_{1}\right\|^{2}+\frac{1-c}{1+c}\left\|T x_{2}\right\|^{2}\right) \\
& \leq\left|\left\|T x_{1}\right\|^{2}-\frac{1-c}{1+c}\left\|T x_{2}\right\|^{2}-c\left(\left\|T x_{1}\right\|^{2}+\frac{1-c}{1+c}\left\|T x_{2}\right\|^{2}\right)\right| \\
& =\mid\langle T u, T v\rangle-c\|T u\|\|T v\| \| \\
& \leq \varepsilon_{0}\|T u\|\|T v\| \\
& =\varepsilon_{0}\left\|T\left(x_{1}+\sqrt{\frac{1-c}{1+c}} x_{2}\right)\right\|\left\|T\left(x_{1}-\sqrt{\frac{1-c}{1+c}} x_{2}\right)\right\| \\
& \leq \varepsilon_{0}\left(\left\|T x_{1}\right\|^{2}+\frac{1-c}{1+c}\left\|T x_{2}\right\|^{2}\right) .
\end{aligned}
$$

Hence,

$$
-\left\|T x_{1}\right\|^{2}+\frac{1-c}{1+c}\left\|T x_{2}\right\|^{2}+c\left(\left\|T x_{1}\right\|^{2}+\frac{1-c}{1+c}\left\|T x_{2}\right\|^{2}\right) \leq \varepsilon_{0}\left(\left\|T x_{1}\right\|^{2}+\frac{1-c}{1+c}\left\|T x_{2}\right\|^{2}\right)
$$

or, equivalently,

$$
\begin{equation*}
\sqrt{\frac{(1-c)\left(1+c-\varepsilon_{0}\right)}{(1+c)\left(1-c+\varepsilon_{0}\right)}}\left\|T x_{2}\right\| \leq\left\|T x_{1}\right\| . \tag{3.2}
\end{equation*}
$$

By combining (3.1) and (3.2),

$$
\sqrt{\frac{(1-c)\left(1+c-\varepsilon_{0}\right)}{(1+c)\left(1-c+\varepsilon_{0}\right)}}\|T y\| \leq \sqrt{\frac{(1-c)\left(1+c-\varepsilon_{0}\right)}{(1+c)\left(1-c+\varepsilon_{0}\right)}}\left\|T x_{2}\right\| \leq\left\|T x_{1}\right\| \leq\|T x\| .
$$

By passing to the supremum over $y$ and to the infimum over $x$ in the above inequality, we obtain $\sqrt{(1-c)\left(1+c-\varepsilon_{0}\right) /(1+c)\left(1-c+\varepsilon_{0}\right)}\|T\| \leq[T]$. Since $\|T\|>0$ and $[T]=0$, this yields $\varepsilon_{0}=1+c$. This contradiction shows that $\widehat{\varepsilon}(T, c)=1+c$.

Next, we formulate one of our main results.
Theorem 3.3. Let $c \in(-1,1)$. Suppose that $T \in \mathbb{B}(\mathscr{H}, \mathscr{K})$ and $[T] \neq 0$. Then

$$
\widehat{\varepsilon}(T, c)=\frac{\left(1-|c|^{2}\right)\left(\|T\|^{2}-[T]^{2}\right)}{(1+|c|)\|T\|^{2}+(1-|c|)[T]^{2}}
$$

Proof. We may assume that $c \in[0,1)$. Since $[T]>0$, there exist unit vectors $x_{1}, x_{2}$ such that

$$
\begin{equation*}
x_{1} \perp x_{2}, \quad T x_{1} \perp T x_{2}, \quad[T]=\left\|T x_{1}\right\| \quad \text { and } \quad\left\|T x_{2}\right\|=\|T\| . \tag{3.3}
\end{equation*}
$$

It follows from Lemma 2.1(ii) that $\left(x_{2}+\sqrt{(1-c) /(1+c)} x_{1}\right) \angle_{c}\left(x_{2}-\sqrt{(1-c) /(1+c)} x_{1}\right)$.

Now, let us put $u=x_{2}+\sqrt{(1-c) /(1+c)} x_{1}$ and $v=x_{2}-\sqrt{(1-c) /(1+c)} x_{1}$. By (3.3),

$$
\begin{aligned}
\left|\frac{\langle T u, T v\rangle}{\|T u\|\|T v\|}-c\right| & =\left|\frac{\left\|T x_{2}\right\|^{2}-\frac{1-c}{1+c}\left\|T x_{1}\right\|^{2}}{\left\|T x_{2}\right\|^{2}+\frac{1-c}{1+c}\left\|T x_{1}\right\|^{2}}-c\right| \\
& =\left|\frac{\|T\|^{2}-\frac{1-c}{1+c}[T]^{2}}{\|T\|^{2}+\frac{1-c}{1+c}[T]^{2}}-c\right| \\
& =\left|\frac{(1+c)\|T\|^{2}-(1-c)[T]^{2}}{(1+c)\|T\|^{2}+(1-c)[T]^{2}}-c\right| \\
& =\frac{\left(1-c^{2}\right)\left(\|T\|^{2}-[T]^{2}\right)}{(1+c)\|T\|^{2}+(1-c)[T]^{2}} .
\end{aligned}
$$

By Lemma 3.1(i),

$$
\begin{equation*}
\widehat{\varepsilon}(T, c) \geq \frac{\left(1-c^{2}\right)\left(\|T\|^{2}-[T]^{2}\right)}{(1+c)\|T\|^{2}+(1-c)[T]^{2}} \tag{3.4}
\end{equation*}
$$

On the other hand, let $x, y \in \mathscr{H}$ be such that $x \angle_{c} y$ and $\|x\|=\|y\|=1$. Then

$$
\begin{aligned}
\left\|\frac{T x}{\|T x\|}+\frac{T y}{\|T y\|}\right\|^{2} & =\left\|T\left(\frac{x}{\|T x\|}+\frac{y}{\|T y\|}\right)\right\|^{2} \\
& \leq\|T\|^{2}\left\|\frac{x}{\|T x\|}+\frac{y}{\|T y\|}\right\|^{2} \\
& =\|T\|^{2}\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}+\frac{2 c}{\|T x\|\|T y\|}\right)
\end{aligned}
$$

whence

$$
\begin{equation*}
\left\|\frac{T x}{\|T x\|}+\frac{T y}{\|T y\|}\right\|^{2} \leq\|T\|^{2}\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}+\frac{2 c}{\|T x\|\|T y\|}\right) \tag{3.5}
\end{equation*}
$$

Similarly,

$$
\left\|\frac{T x}{\|T x\|}-\frac{T y}{\|T y\|}\right\|^{2} \geq[T]^{2}\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}-\frac{2 c}{\|T x\|\|T y\|}\right)
$$

and

$$
\left\|\frac{T x}{\|T x\|}-\frac{T y}{\|T y\|}\right\|^{2} \leq\|T\|^{2}\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}-\frac{2 c}{\|T x\|\|T y\|}\right)
$$

Now, let

$$
\begin{equation*}
\left\|\frac{T x}{\|T x\|}-\frac{T y}{\|T y\|}\right\|^{2}=\mu[T]^{2}\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}-\frac{2 c}{\|T x\|\|T y\|}\right) \tag{3.6}
\end{equation*}
$$

with $1 \leq \mu \leq\|T\| /[T]$. It follows from (3.5) and (3.6) that

$$
\begin{aligned}
4 & =\left\|\frac{T x}{\|T x\|}+\frac{T y}{\|T y\|}\right\|^{2}+\left\|\frac{T x}{\|T x\|}-\frac{T y}{\|T y\|}\right\|^{2} \\
& \leq\left(\|T\|^{2}+\mu[T]^{2}\right)\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}\right)+\left(\|T\|^{2}-\mu[T]^{2}\right) \frac{2 c}{\|T x\|\|T y\|} \\
& \leq\left(\|T\|^{2}+\mu[T]^{2}\right)\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}\right)+c\left(\|T\|^{2}-\mu[T]^{2}\right)\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}\right) \\
& =\left((1+c)\|T\|^{2}+(1-c) \mu[T]^{2}\right)\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}\right) .
\end{aligned}
$$

Hence,

$$
\begin{equation*}
\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}} \geq \frac{4}{(1+c)\|T\|^{2}+(1-c) \mu[T]^{2}} \tag{3.7}
\end{equation*}
$$

From (3.6) and (3.7),

$$
\begin{aligned}
\left\langle\frac{T x}{\|T x\|}, \frac{T y}{\|T y\|}\right\rangle-c & =1-c-\frac{1}{2}\left\|\frac{T x}{\|T x\|}-\frac{T y}{\|T y\|}\right\|^{2} \\
& =1-c+\frac{\mu c[T]^{2}}{\|T x\|\|T y\|}-\frac{1}{2} \mu[T]^{2}\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}\right) \\
& \leq 1-c+\frac{1}{2} \mu c[T]^{2}\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}\right)-\frac{1}{2} \mu[T]^{2}\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}\right) \\
& =1-c-\frac{1}{2}(1-c) \mu[T]^{2}\left(\frac{1}{\|T x\|^{2}}+\frac{1}{\|T y\|^{2}}\right) \\
& \leq 1-c-\frac{2(1-c) \mu[T]^{2}}{(1+c)\|T\|^{2}+(1-c) \mu[T]^{2}} \\
& =\frac{\left(1-c^{2}\right)\|T\|^{2}-\left(1-c^{2}\right) \mu[T]^{2}}{(1+c)\|T\|^{2}+(1-c) \mu[T]^{2}} \quad(\text { since } 1 \leq \mu) \\
& \leq \frac{\left(1-c^{2}\right)\left(\|T\|^{2}-[T]^{2}\right)}{(1+c)\|T\|^{2}+(1-c)[T]^{2}} .
\end{aligned}
$$

Hence,

$$
\sup \left\{\left|\frac{\langle T x, T y\rangle}{\|T x\| \mid T y \|}-c\right|: x \iota_{c} y,\|x\|=\|y\|=1, x, y \in \mathscr{H}\right\} \leq \frac{\left(1-c^{2}\right)\left(\|T\|^{2}-[T]^{2}\right)}{(1+c)\|T\|^{2}+(1-c)[T]^{2}}
$$

From Lemma 3.1(ii),

$$
\begin{equation*}
\widehat{\varepsilon}(T, c) \leq \frac{\left(1-c^{2}\right)\left(\|T\|^{2}-[T]^{2}\right)}{(1+c)\|T\|^{2}+(1-c)[T]^{2}} \tag{3.8}
\end{equation*}
$$

Combining (3.4) and (3.8) gives the formula for $\widehat{\varepsilon}(T, c)$.
As an immediate consequence of Theorem 3.3, we get a characterisation of the $(\varepsilon, c)$-angle preserving mappings.

Corollary 3.4. Suppose that $T \in \mathbb{B}(\mathscr{H}, \mathscr{K}) \backslash\{0\}$ and $c \in(-1,1)$. Then there exists an $\varepsilon \in[0,1+|c|)$ such that $T$ is an $(\varepsilon, c)$-angle preserving mapping if and only if $T$ is bounded below.

Corollary 3.5. Let $c \in(-1,1)$ and $\varepsilon \in[0,1+|c|)$. Suppose that $T \in \mathbb{B}(\mathscr{H}, \mathscr{K}) \backslash\{0\}$ is an ( $\varepsilon, c$ )-angle preserving mapping. Then $T$ is injective and the following statements hold:
(i) $\sqrt{(1+|c|)(1-|c|-\varepsilon) /(1-|c|)(1+|c|+\varepsilon)}||T|| \leq[T]$;
(ii) $\quad \sqrt{(1+|c|)(1-|c|-\varepsilon) /(1-|c|)(1+|c|+\varepsilon)}\|T x\|\|y\| \leq\|T y\|\|x\| \quad(x, y \in \mathscr{H})$;
(iii) $\quad \sqrt{(1+|c|)(1-|c|-\varepsilon) /(1-|c|)(1+|c|+\varepsilon)}|T|\|\|x\| \leq\| T x\|\leq\| T\|\|x\| \quad(x \in \mathscr{H})$.

Proof. Since $T$ is an $(\varepsilon, c)$-angle preserving mapping, we have $\widehat{\varepsilon}(T, c)<1+|c|$. Theorem 3.2 ensures that $T$ is injective. From Theorem 3.3,

$$
\widehat{\varepsilon}(T, c)=\frac{\left(1-|c|^{2}\right)\left(\|T\|^{2}-[T]^{2}\right)}{(1+|c|)\|T\|^{2}+(1-|c|)[T]^{2}} \leq \varepsilon
$$

or, equivalently,

$$
\sqrt{\frac{(1+|c|)(1-|c|-\varepsilon)}{(1-|c|)(1+|c|+\varepsilon)}}\|T\| \leq[T]
$$

From the above inequality, for $x, y \in \mathscr{H}$,

$$
\begin{aligned}
\sqrt{\frac{(1+|c|)(1-|c|-\varepsilon)}{(1-|c|)(1+|c|+\varepsilon)}}\|T x\|\|y\| & \leq \sqrt{\frac{(1+|c|)(1-|c|-\varepsilon)}{(1-|c|)(1+|c|+\varepsilon)}}\|T\|\|x\|\|y\| \\
& \leq[T]\|y\|\|x\| \leq\|T y\|\|x\|
\end{aligned}
$$

and

$$
\sqrt{\frac{(1+|c|)(1-|c|-\varepsilon)}{(1-|c|)(1+|c|+\varepsilon)}}\|T\|\|x\| \leq[T]\|x\| \leq\|T x\| \leq\|T\|\|x\| .
$$

Corollary 3.6. Let $c \in(-1,1)$. For $T, S \in \mathbb{B}(\mathscr{H}) \backslash\{0\}$, the following statements hold:
(i) if $T, S$ are left invertible, then $\widehat{\varepsilon}(S T, c)<1+|c|$;
(ii) if $S$ is a scalar multiple of an isometry, then $\widehat{\varepsilon}(S T, c)=\widehat{\varepsilon}(T, c)$;
(iii) if $T^{-1} \in \mathbb{B}(\mathscr{H}) \backslash\{0\}$, then $\widehat{\varepsilon}\left(T^{-1}, c\right)=\widehat{\varepsilon}(T, c)$.

Proof. (i) Since $T$ and $S$ are left invertible, $[T S] \geq[T][S]>0$ and, by Theorem 3.3, $\widehat{\varepsilon}(T S, c)<1+|c|$.
(ii) This follows because $\|S\|=[S],\|S T\|=\|S\|\|T\|$ and $[S T]=[S][T]$.
(iii) To see this, note that $\left\|T^{-1}\right\|=1 /[T]$ and $\left[T^{-1}\right]=1 /\|T\|$.

The next corollary gives another property of the function $\widehat{\varepsilon}(., c)$.
Corollary 3.7. Let $c \in(-1,1)$. The function $T \mapsto \widehat{\varepsilon}(T, c)$ is norm continuous at each $T \in \mathbb{B}(\mathscr{H}, \mathscr{K})$ with $[T]>0$.

Proof. Suppose that $T_{n} \in \mathbb{B}(\mathscr{H}, \mathscr{K})$ are such that $\lim _{n \rightarrow \infty}\left\|T_{n}-T\right\|=0$. Since $T \neq 0$, we may assume that $T_{n} \neq 0$ for all $n \in \mathbb{N}$. Then

$$
\lim _{n \rightarrow \infty}\left\|T_{n}\right\|=\|T\|, \quad \lim _{n \rightarrow \infty}\left[T_{n}\right]=[T] \quad \text { and } \quad(1+c)\left\|T_{n}\right\|^{2}+(1-c)\left[T_{n}\right]^{2} \neq 0
$$

Thus, by Theorem 3.3,

$$
\begin{aligned}
\lim _{n \rightarrow \infty} \widehat{\varepsilon}\left(T_{n}, c\right) & =\lim _{n \rightarrow \infty} \frac{\left(1-|c|^{2}\right)\left(\left\|T_{n}\right\|^{2}-\left[T_{n}\right]^{2}\right)}{(1+|c|)\left\|T_{n}\right\|^{2}+(1-|c|)\left[T_{n}\right]^{2}}=\frac{\left(1-|c|^{2}\right)\left(\|T\|^{2}-[T]^{2}\right)}{(1+|c|)\|T\|^{2}+(1-|c|)[T]^{2}} \\
& =\widehat{\varepsilon}(T, c)
\end{aligned}
$$

Remark 3.8. The function $\widehat{\varepsilon}(., c)$ is not continuous at 0 even in the case $c=0$. Take any mapping $T$ which is not orthogonality preserving. Thus, $\widehat{\varepsilon}(T, c) \neq 0$. Let $T_{n}=T / n$. Then $\lim _{n \rightarrow \infty}\left\|T_{n}\right\|=0$, but, for every $n, \widehat{\varepsilon}\left(T_{n}, c\right)=\widehat{\varepsilon}(T, c) \neq 0$ (see [13, Remark 2.7]).

Next, we prove that every injective operator preserves approximate orthogonality.
Theorem 3.9. Suppose that $T \in \mathbb{B}(\mathscr{H}, \mathscr{K})$ and $0<[T] \leq\|T\|$. Then $T$ satisfies

$$
x \perp y \Longrightarrow T x \perp^{\varepsilon_{T}} T y \quad(x, y \in \mathscr{H})
$$

with $\varepsilon_{T}=1-[T]^{2} /\|T\|^{2}$.
Proof. Fix two arbitrary nonzero vectors $x, y \in \mathscr{H}$ such that $x \perp y$. Since $0<[T]$, it follows that $T$ is injective. From Corollary 2.3, there exist unit vectors $a, b \in \operatorname{span}\{x, y\}$ such that

$$
\begin{equation*}
a \perp b, \quad T a \perp T b, \quad\|T a\| \leq\|T x\| \leq\|T b\| \quad \text { and } \quad\|T a\| \leq\|T y\| \leq\|T b\| . \tag{3.9}
\end{equation*}
$$

Moreover, there exist $\alpha, \beta, \gamma, \delta \in \mathbb{R}$ such that $x=\alpha a+\beta b, y=\gamma a+\delta b$. Since $x \perp y$,

$$
\begin{equation*}
\alpha \gamma=-\beta \delta \tag{3.10}
\end{equation*}
$$

Furthermore, $T x=\alpha T a+\beta T b$ and $T y=\gamma T a+\delta T b$. If $\alpha \beta \gamma \delta=0$, then it is easy to see that $\langle T x, T y\rangle=0$ and, in particular, $T x \perp^{\varepsilon_{T}} T y$. So, now suppose that $\alpha \beta \gamma \delta \neq 0$. Denote $\theta:=\alpha / \beta=-\delta / \gamma$. It follows from (3.9) and (3.10) that

$$
\begin{aligned}
\frac{|\langle T x, T y\rangle|}{\|T x\|\|T y\|} & =\frac{\left|\alpha \gamma\|T a\|^{2}+\beta \delta\|T b\|^{2}\right|}{\sqrt{|\alpha|^{2}\|T a\|^{2}+|\beta|^{2}\|T b\|^{2}} \sqrt{|\gamma|^{2}\|T a\|^{2}+|\delta|^{2}\|T b\|^{2}}} \\
& =\frac{\left(\|T b\|^{2}-\|T a\|^{2}\right)|\alpha \gamma|}{\sqrt{|\alpha|^{2}\|T a\|^{2}+|\beta|^{2}\|T b\|^{2}} \sqrt{|\gamma|^{2}\|T a\|^{2}+|\delta|^{2}\|T b\|^{2}}} \\
& =\frac{1-\frac{\|T a\|^{2}}{\|T b\|^{2}}}{\sqrt{\frac{\|T a\|^{2}}{\|T b\|^{2}}+\frac{1}{|\theta|^{2}}} \sqrt{\frac{\|T a\|^{2}}{\|T b\|^{2}}+|\theta|^{2}}} \\
& \leq \frac{1-\frac{\|T a\|^{2}}{\|T b\|^{2}}}{\sqrt{\frac{\|T a\|^{4}}{\|T b\|^{4}}+1}} \leq 1-\frac{\|T a\|^{2}}{\|T b\|^{2}} \leq 1-\frac{[T]^{2}}{\|T\|^{2}}=\varepsilon_{T},
\end{aligned}
$$

whence $|\langle T x, T y\rangle| \leq \varepsilon_{T}| | T x\| \| T y \|$. Thus, $T x^{\perp_{T}} T y$.

The following result can be considered an extension of Theorem 3.9. More precisely, we show that every injective operator approximately preserves the inner product.

Theorem 3.10. Assume that $\operatorname{dim} \mathscr{H}<\infty$. Suppose that $T \in \mathbb{B}(\mathscr{H}, \mathscr{K})$ and $0<[T]$. Then there exists $\gamma$ such that $T$ satisfies

$$
\begin{equation*}
|\langle T x, T y\rangle-\gamma\langle x, y\rangle| \leq\left(1-\frac{[T]^{2}}{\|T\|^{2}}\right)\|T\|^{2}\|x\|\|y\| \quad(x, y \in \mathscr{H}) . \tag{3.11}
\end{equation*}
$$

Moreover, $[T]^{2} \leq|\gamma| \leq 2\|T\|^{2}-[T]^{2}$.
Proof. Combining Theorem 3.9 and [11, Theorem 5.5], we immediately get (3.11). Fix $u \in \mathscr{H}$ such that $\|u\|=1$. Putting $u$ in place of $x$ and $y$ in (3.11) gives $\left\|\|T u\|^{2}-\gamma \mid \leq\right.$ ( $\left.1-[T]^{2} /\|T\|^{2}\right)\|T\|^{2}$. Choosing $u$ as an arbitrary unit vector and passing to the supremum and infimum over $\|u\|=1$ gives $[T]^{2} \leq|\gamma| \leq 2\|T\|^{2}-[T]^{2}$.

To end this paper, we show that in the finite-dimensional case Corollary 3.5 can be strengthened. Indeed, as an immediate consequence of Corollary 3.5 and Theorem 3.10, we obtain the following result.

Corollary 3.11. Let $c \in(-1,1)$ and $\varepsilon \in[0,1+|c|)$. Suppose that $T \in \mathbb{B}(\mathscr{H}, \mathscr{K}) \backslash\{0\}$ is an $(\varepsilon, c)$-angle preserving mapping. Assume that $\operatorname{dim} \mathscr{H}<\infty$. Then there exists $\gamma$ such that $T$ satisfies

$$
|\langle T x, T y\rangle-\gamma\langle x, y\rangle| \leq\left(1-\frac{(1+|c|)(1-|c|-\varepsilon)}{(1-|c|)(1+|c|+\varepsilon)}\right)\|T\|^{2}\|x\|\|y\| \quad(x, y \in \mathscr{H}) .
$$

Moreover, $[T]^{2} \leq|\gamma| \leq 2\|T\|^{2}-[T]^{2}$.
Proof. By Corollary 3.5, $T$ is injective and, since $\operatorname{dim} \mathscr{H}<\infty,[T]>0$. The desired conclusion follows from Theorem 3.10.

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