### FIBRE BUNDLES AND YANG-MILLS FIELDS

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## 1. Introduction

Since 1954, when Yang and Mills [7] presented their idea of isotopic gauge transformation, the method of introducing interactions into field theories by using general gauge invariance has been extensively studied.

A general formalism was presented by Utiyama [6]. Reference [6] also contains the first application of the formalism to the theory of gravitation. A more general approach to the Young-Mills formalism applied to general relativity was described by Kibble [3]. In a special case of interacting Dirac field the gauge invariance group can still be enlarged, leading to the possibility of describing short-range interactions together with gravitation and electromagnetism [5]. It is, therefore important to have a definite formulation of the common geometrical content of such theories.

Differential geometers who came into contact with Young-Mills theory realized that the theory is almost identical with the theory of connections in vector bundles. Certain aspects of such relation were discussed in references [1] and [2]. Correspondence between Yang-Mills theory and differential geometry of fibre bundles is explicitly studied in the next section in a form suitable for applications. In Section 3 the formalism is applied to the Utiyama's construction of gravitational interactions. A relation between space-time metric and Yang-Mills fields is derived without the assumption about vanishing torsion of the linear connection of bundle of frames. Use of this *ad hoc* assumption in Utiyama's paper was criticized by Kibble [3], and it was one of the reasons that lead him to consider a generalized approach.

# 2. Convariant Derivative

Consider a principal fibre bundle P(B, G) (for basic definitions and theorems of the theory of fibre bundles see e.g., [4]) where B is the base manifold of dimension n, and G is the structure group.  $\pi$  denotes the projection map

482

[2] Fibre bundles and Yang-Mills fields

(1)  $\pi: x \in P \to u = \pi(x) \in B$ 

satisfying

(2) 
$$\pi(x \cdot a) = \pi(x) \text{ for all } x \in P, \ a \in G.$$

Further consider a differentiable function

$$(3) \qquad \qquad \xi \colon x \in P \to \xi(x) \in F,$$

satisfying a condition

(4) 
$$\xi(x \cdot a) = a^{-1} \xi(x), \qquad a \in G.$$

F is a (real or complex) representation space of G. Together with a cross-section

(5) 
$$\chi: u \in B \to \chi(u) \in P, \ \pi(\chi(u)) = u$$

function  $\xi$  defines an *F*-valued function  $\zeta$  on manifold *B* by

(6) 
$$\zeta(u) = \zeta(\chi(u)).$$

In physics, B is the space-time manifold and  $\zeta(u)$  is the "old" field that is to interact with "new" Yang-Mills field. The latter fields are contained in a connection  $\Gamma$  defined in P(B, G).

Any tangent vector X at point  $x_0 \in P$  can be written as

$$X = X_h + X_v,$$

where  $X_h$  and  $X_v$  are the horizontal and vertical components of X defined by connection  $\Gamma$  in P. Applying X to function  $\xi(x)$ 

(7) 
$$X\xi(x_0) = X_h\xi(x_0) + X_v\xi(x_0).$$

The best way to see explicitly how this decomposition works is to consider a differentiable curve x(t) with  $x(0) = x_0$  and tangent X at  $x_0$ . Then

(8) 
$$X\xi(x_0) = \lim_{t \to 0} (1/t)(\xi(x(t)) - \xi(x_0)).$$

If  $x_h(t)$  denotes the horizontal projection of x(t) passing through  $x_0(x_h(0) = x_0)$ then x(t) may be written as

(9) 
$$x(t) = x_{h}(t) \cdot a(t)$$

where a(t) is a differentiable curve in G, a(0) = e (the identity element). We have

$$X\xi(x_0) = \lim_{t \to 0} (1/t)(\xi(x_h(t)a(t)) - \xi(x_0))$$

483

P. K. Smrz

(10)  
$$= \lim_{t \to 0} (1/t)(a^{-1}(t) \cdot \xi(x_{h}(t)) - \xi(x_{h}(t)) + \lim_{t \to 0} (1/t)(\xi(x_{h}(t)) - \xi(x_{0})) = X_{v}\xi(x_{0}) + X_{h}\xi(x_{0})$$

where

(11) 
$$X_h \xi(x_0) = \lim_{t \to 0} (1/t) (\xi(x_h(t)) - \xi(x_0))$$

and

(12) 
$$X_{\nu}\xi(x_0) = \left(\lim_{t \to 0} (1/t)(a^{-1}(t) - e)\right) \cdot \xi(x_0)$$

Here

(13) 
$$\lim_{t \to 0} (1/t)(a^{-1}(t) - e) = A(X)$$

is an element of the Lie algebra of group G.

 $X_h\xi(x_0)$  yields the covariant derivative of function  $\zeta(u)$  by

(14) 
$$\nabla_{\pi(X)}\zeta(u_0) = X_h\xi(x_0),$$

where  $\zeta$  and  $\xi$  are related through Equation (6).  $\pi(X)$  means the projection of vector X onto base manifold B.

Let u(t) be a differentiable curve in B with tangent  $\pi(X)$  at  $u_0 = \pi(x_0)$  and x(t) a curve obtained by

 $x(t) = \chi(u(t))$ 

with tangent vector X at  $x(0) = x_0$ . Transforming  $\zeta(u)$  into

$$\tilde{\zeta}(u) = a(u)\zeta(u),$$

where  $a(u) \in G$  is differentiable, we have

$$\tilde{\zeta}(u(t)) = a(u(t))\zeta(u(t)).$$

Denoting  $a(u(t)) = a_u(t)$ 

$$\tilde{\zeta}(u(t)) = a_u(t)\xi(x(t)) = \xi(x(t) \cdot a_u^{-1}(t)).$$

But as

$$X_h\xi(x(t)\cdot a_u^{-1}(t)) = \lim_{t\to 0} (1/t)(\xi([x(t)\cdot a_u^{-1}(t)]_h) - \xi(x_0a_u^{-1}(0))).$$

and

$$[x(t) \cdot a_u^{-1}(t)]_h = x_h(t) \cdot a_u^{-1}(0)$$

we have

Fibre bundles and Yang-Mills fields

(15) 
$$[X_h \xi(x(t) \cdot a_u^{-1}(t))]_{t=0} = \lim_{t \to 0} (1/t) a_u(0) (\xi(x_h(t)) - \xi(x_0)) = a_u(0) X_h \xi(x_0)$$

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(16) 
$$\nabla_{\pi(X)}\tilde{\zeta}(u_0) = a(u_0)\nabla_{\pi(X)}\zeta(u_0).$$

Equation (16) shows that operator  $\nabla_{\pi(X)}$  has the required covariant properties. Further

(17) 
$$X\xi(x(t)) = \frac{d}{dt}\xi(x(t)) = \frac{d}{dt}\zeta(u(t)) = \pi(X)\zeta(u(t))$$

and using Equations (10) to (14)

(18) 
$$\nabla_{\pi(X)}\zeta(u) = \pi(X)\zeta(u) - A(X)\zeta(u).$$

Choosing  $\{\partial/\partial u', \dots, \partial/\partial u^n\}$  as the basis of the tangent vector space at  $u \in B$  and  $\{A_1, \dots, A_d\}$  as the basis of the Lie algebra of group G we can rewrite (18) for

$$\pi(X) = \frac{\partial}{\partial u^k} \text{ as }$$

(19) 
$$\nabla_{\pi(X)}\zeta(u) = \frac{\partial}{\partial u^k} \zeta(u) - \sum_{p=1}^d B_k^p(u)A_p\zeta(u).$$

This is the covariant derivative as introduced in Reference [6] with  $B_k(u)$  being the "new" Yang-Mills fields.

## 3. Yang-Mills Fields and Tetrads

We shall now consider a specific case of bundle of frames in the fourdimensional space-time manifold. Structure group G is then the homogeneous Lorentz group, and representation space F is to be considered as a four-dimensional real vector space with a basis  $\{e_1, e_2, e_3, e_4\}$ . Points of fibre manifold P are local frames defined by four orthogonal vectors

(20) 
$$X_k^{\mu} \frac{\partial}{\partial u^{\mu}}^{(*)} \quad k = 1, 2, 3, 4.$$

Group G acts on vectors (20) in the same way as on vectors  $e_k$  of the basis of space F.

We consider a function

(21) 
$$\xi: P \to F, \quad \xi(x) = Y_{\mu}^{k} e_{k},$$

where local frame  $x \in P$  is defined by  $X_k^{\mu}$ , and

[4]

<sup>(\*)</sup> A pair of identical indices will always mean summation.

P. K. Smrz

(22) 
$$X^{\mu}_{k}Y^{k}_{\nu} = \delta^{\mu}_{\nu}, \qquad X^{\mu}_{i}Y^{k}_{\mu} = \delta^{k}_{i}.$$

Function  $\xi$  satisfies condition (4), and besides that it defines (together with a cross-section in P) function  $\zeta$  (see Equation (6)).

(23) 
$$\zeta(u) = h_{\mu}^{k}(u)e_{k}.$$

Functions  $h^k_{\mu}(u)$  assign a local orthogonal frame to every point u of the space-time manifold and are usually called tetrads in general relativity.

The question we want to answer is as follows: Suppose we have a connection in the bundle of frames with co-ordinates  $\Gamma_{\mu\nu}^{\rho}$  defined in the usual way [4]. What is the relation between  $\Gamma_{\mu\nu}^{\rho}$  and the Yang-Mills fields of Equation (19)?

Vector  $X_{\mu} = \frac{\partial}{\partial x^{\mu}}$  has its horizontal lift given by [4]

$$X^*_{\mu} = \frac{\partial}{\partial x^{\mu}} - \Gamma^{\rho}_{\mu\nu} X^{\nu}_{k} \frac{\partial}{\partial X_{k}}.$$

Applied on function  $\xi$  this gives

(24)  $X^*_{\mu}\xi(x) = \Gamma^{\rho}_{\mu\nu}Y^k_k e_k.$ 

By definition of covariant derivative (14) with

(24) 
$$\pi(X) = X_{\mu} \text{ (i.e., } X_{h} = X^{*} \text{) and (23) we have}$$
$$\nabla_{X_{\mu}} h_{\nu}^{k}(u) e_{k} = \Gamma_{\mu\nu}^{\rho} h_{\rho}^{k}(u) e_{k}.$$

At the same time

(26) 
$$\nabla_{\boldsymbol{X}_{\nu}} h_{\nu}^{k}(u) e_{k} = \frac{\partial h_{\nu}^{k}(u)}{\partial u^{\mu}} \cdot e_{k} - \sum_{q=1}^{6} B_{\mu}^{q}(u) A_{q}(h_{\nu}^{k}(u) e_{k}).$$

 $A_{ij}$  are 4 × 4 matrices forming a basis of the Lie algebra of the homogeneous Lorentz group. Normally, index q is replaced by a pair of indices i, j = 1, 2, 3, 4and

[5]

486

Fibre bundles and Yang-Mills fields

$$A_{23} = -A_{32} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \qquad A_{31} = -A_{13} = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Such choice also corresponds to Reference [6].

A direct calculation yields

(27) 
$$\frac{1}{2}\sum_{i,j=1}^{4}B_{\mu}^{ij}A_{ij}(h_{\nu}^{k}(u)e_{k})=B_{\mu}^{kj}h_{j\nu}e_{k},$$

where  $h_{4v} = h_v^4$  and  $h_{jv} = -h_v^j$  if  $j \neq 4$ .

Comparing (25) and (27)

$$\Gamma^{\rho}_{\mu\nu}h^{k}_{\rho} = \frac{\partial h^{k}_{\nu}}{\partial u^{\mu}} - B^{kj}_{\mu}h_{j\nu}$$

which is identical to the relation obtained in Reference [6] under assumption that  $\Gamma^{\rho}_{\mu\nu} = \Gamma^{\rho}_{\nu\mu}$ . No such assumption is necessary when using the general approach described above.

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