# ALEXANDER POLYNOMIALS OF TWO-BRIDGE LINKS 

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#### Abstract

We provide an algorithm for calculating the Alexander polynomial of a two-bridge link by putting every two-bridge link in a special type of Conway diagram. Using this algorithm, some necessary conditions for a polynomial to be the Alexander polynomial of a two-bridge link are given, in particular, certain alternating and monotonicity conditions on the coefficients, analogous to corresponding known properties of the reduced Alexander polynomial.


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Hartley [4] gave a necessary condition for a polynomial to be the Alexander polynomial of a two-bridge knot or the reduced Alexander polynomial of a two-bridge link. He showed how the coefficients of the polynomial may be read straight from the extended diagram, which is derived from Schubert's normal form of a two-bridge knot or link, and showed the following theorem: If $\Delta(t)=\sum_{i=0}^{n}(-1)^{i} a_{i} t^{i}$ where $a_{i}>0$, is the Alexander polynomial of a two-bridge knot or the reduced Alexander polynomial of a two-bridge link, then for some integer $s, a_{0}<a_{1}<\cdots<a_{s}=a_{s+1}=\cdots=a_{n-s}>\cdots>a_{n}$. On the other hand, using surgery techniques, Bailey [1] presented an algorithm for calculating the Alexander polynomial of a two-bridge link from Conway diagram. As a corollary to this he proved a conjecture of Kidwell about the linking complexity or geometric intersection numbers of a link in the special case of two-bridge links.

The main results of this paper are Theorems 1 and 3. The former provides another algorithm for calculating the Alexander polynomial of a two-bridge link from a special type of Conway diagram. The latter gives some necessary conditions for a polynomial to be the Alexander polynomial of a two-bridge link. These

[^0]conditions are analogous to Hartley's theorem above. Theorem 2 and Corollary 1 also give some properties of the Alexander polynomial of a two-bridge link, including the Torres condition [8]. Corollary 2 is the above-mentioned conjecture of Kidwell in the case of two-bridge links.

In Section 2, we give some lemmas for Theorems 1 and 2. In Section 3, we summarize some properties of two-bridge links. In Section 4, we state the above-mentioned results. In Section 5, we prove Theorem 3.

## 1. Preliminaries

In this paper, a link $L$ will mean a piecewise linear embedding of two oriented circles $K_{1}$ and $K_{2}$ in the 3 -sphere $S^{3}$. Two links $L$ and $L^{\prime}$ are called equivalent, if there is an orientation preserving autohomeomorphism of $S^{3}$, which maps $L$ onto $L^{\prime}$. The Alexander polynomial $\Delta(x, y)$ of $L$ is an element of the polynomial ring $Z\left[x, x^{-1}, y, y^{-1}\right]=\Lambda$, and is determined only up to multiplication by a unit $\pm x^{i} y^{j}$. Let $G=\pi_{1}\left(S^{3}-L\right)$, and let $G^{\prime}$ be its commutator subgroup. Then $\Lambda=Z\left[G / G^{\prime}\right]$; the basis $\{x, y\}$ of $G / G^{\prime}$ is always taken to be represented by the meridians of $K_{1}$ and $K_{2}$ respectively.

Throughout this paper, we will often abbreviate a polynomial $f(x, y)$ in $\Lambda$ to $f$ and will use the following notation;

$$
F_{n}(x, y)=\left\{\begin{array}{lll}
\sum_{i=0}^{n-1}(x y)^{i} & \text { if } & n>0 \\
0 & \text { if } & n=0 \\
-\sum_{i=n}^{-1}(x y)^{i} & \text { if } & n<0
\end{array}\right.
$$

In the figures of this paper we will use the concept of a tangle [2], which is a portion of the link diagram containing two arcs. An integral tangle, which is represented by a circle labeled " $i$ " or " $-i$ ", where $i$ is a non-negative integer, is a 2-braid with $i$ or $-i$ crossings, in the manner indicated in Figure 1.


Figure 1

## 2. Lemmas

Lemma 1. Let $L(q, r, s, t)$ be a link as shown in Figure 2, where $T$ is any tangle. Let $\Delta^{(q, r, s, t)}$ be the Alexander polynomial of $L(q, r, s, t)$. If we set $\Delta=\Delta^{(q, r, s, t)}$, $\Delta_{0}=\Delta^{(q, r, 0,0)}$ and $\Delta_{00}=\Delta^{(0,0,0,0)}$, then

$$
\begin{equation*}
\Delta=\left\{s(x-1)(y-1) F_{t}+1\right\} \Delta_{0}+\frac{F_{t}}{F_{r}}(x y)^{r}\left(\Delta_{0}-\Delta_{00}\right) \tag{2.1}
\end{equation*}
$$

where $r \neq 0$.


Figure 2
Lemma 2. Besides the notation in Lemma 1 , let $\Delta_{0}^{\prime}=\Delta^{(q, r, 0, t)}$ and $\Delta^{\left(t_{0}\right)}=\Delta^{\left(q, r, s, t_{0}\right)}$. Then

$$
\begin{gather*}
\Delta=s(x-1)(y-1) F_{t} \Delta_{0}+\Delta_{0}^{\prime}  \tag{2.2}\\
\Delta^{(t)}=F_{t} \Delta^{(1)}-x y F_{t-1} \Delta_{0}  \tag{2.3}\\
\Delta^{(t)}+x y \Delta^{(t-2)}=(1+x y) \Delta^{(t-1)} \tag{2.4}
\end{gather*}
$$

Remark. (1) In the above notation $\Delta^{(t)}=\Delta$ and $\Delta^{(0)}=\Delta_{0}$.
(2) (2.4) is a special case of Conway's result [2, page 338], see also [5, page 462].

Lemma 1 can be shown by using Fox's free differential calculus, see [3], [8]. The proofs of these lemmas are standard, so we omit them.

## 3. Two-bridge links

According to Conway [2], every two-bridge link can be put in the form as shown in Figure 3. It will be denoted by $C\left(a_{1}, a_{2}, \ldots, a_{n}\right)$, including the indicated orientation of each component. The diagram is slightly different in the cases $n=2 k$ and $n=2 k+1$, as indicated in Figure 3. From this projection we can see that a two-bridge link is a link with two components each of which is a trivial
knot. Moreover a two-bridge link is interchangeable, that is, there is an isotopy of $S^{3}$ which interchanges the two components. This follows immediately from Schubert's normal form [6], or Bailey [1, page 48] also proves this using Conway's diagram.




Figure 3

Let $\alpha(>0)$ and $\beta$ be the coprime integers computed from the continued fraction:

$$
\frac{\alpha}{\beta}=a_{1}+\frac{1}{a_{2}}+\cdots+\frac{1}{a_{n}}
$$

Then $\alpha$ is even and $0<|\beta|<\alpha$. This link is equivalent to the link with Schubert's normal form ( $\alpha, \beta$ ), denoted by $S(\alpha, \beta)$ endowed with suitable orientations. According to Schubert [6, page 144], $S(\alpha, \beta)$ and $S\left(\alpha^{\prime}, \beta^{\prime}\right)$ are equivalent if and only if $\alpha=\alpha^{\prime}$ and $\beta^{ \pm 1} \equiv \beta^{\prime}(\bmod 2 \alpha)$. Furthermore, if $\beta^{\prime} \equiv \beta+\alpha(\bmod 2 \alpha)$ or $\beta \beta^{\prime} \equiv \alpha+1(\bmod 2 \alpha)$, then $S(\alpha, \beta)$ differs from $S\left(\alpha, \beta^{\prime}\right)$ only by the orientation of one of the components (see [7, page 7]).

The two-fold cover of $S^{3}$ branched over $S(\alpha, \beta)$ is the lens space $L(\alpha, \beta)$, see [2], [6], [7]. If we neglect the difference between $S(\alpha, \beta)$ and $S(\alpha,-\beta)$ and the orientations of $S(\alpha, \beta)$, this sets up a one-to-one correspondence between twobridge links and the lens spaces up to homeomorphism.

We can obtain easily another continued fraction:

$$
\frac{\alpha}{\beta}=2 b_{1}+\frac{1}{2 b_{2}}+\cdots+\frac{1}{2 b_{m}}
$$

where $m$ is odd. $C\left(2 b_{1}, 2 b_{2}, \ldots, 2 b_{m}\right)$ is then equivalent to $C\left(a_{1}, a_{2}, \ldots, a_{n}\right)$ and will be denoted by $D\left(b_{1}, b_{2}, \ldots, b_{m}\right)$. In the following we will consider every two-bridge link to be put in this form (see [7, page 13]).

## 4. Main theorems

From Lemma 1, we have

Theorem 1. Let $L_{0}=D(0)$ and for $n \geqslant 1$ let

$$
L_{n}=D\left(p_{1}, q_{1}, p_{2}, q_{2}, \ldots, p_{n-1}, q_{n-1}, p_{n}\right)
$$

where $\prod_{i=1}^{n} p_{i} \prod_{j=1}^{n-1} q_{j} \neq 0$. Let $\Delta_{n}(x, y)$ be the polynomial inductively defined as follows:

$$
\begin{gather*}
\Delta_{0}=0  \tag{4.1}\\
\Delta_{1}=F_{p_{1}} ; \\
\Delta_{n}=\left\{q_{n-1}(x-1)(y-1) F_{p_{n}}+1\right\} \Delta_{n-1} \\
+(x y)^{p_{n-1}} \frac{F_{p_{n}}}{F_{p_{n-1}}}\left(\Delta_{n-1}-\Delta_{n-2}\right), \text { for } n \geqslant 2
\end{gather*}
$$

Then $\Delta_{n}(x, y)$ is the Alexander polynomial of $L_{n}$.

In the following, by the Alexander polynomial of a two-bridge link we mean the polynomial defined in Theorem 1 and we will use the following notation besides that in Theorem 1. Let $\Delta_{n}^{(p)}$ be the Alexander polynomial of $D\left(p_{1}, q_{1}, p_{2}, q_{2}, \ldots, p_{n-1}, q_{n-1}, p\right)$; thus $\Delta_{n}^{\left(p_{n}\right)}=\Delta_{n}$ and $\Delta_{n}^{(0)}=\Delta_{n-1}$. Let $l_{n}=$ $\sum_{i=1}^{n} p_{i}$, that is, the linking number of $L_{n}$. Let $\tilde{l}_{n}=\sum_{i=1}^{n}\left|p_{i}\right|$.

From Lemma 2, we have

## Theorem 2.

$$
\begin{gather*}
\Delta_{n}=q_{n-1}(x-1)(y-1) F_{p_{n}} \Delta_{n-1}+\Delta_{n-1}^{\left(p_{n-1}+p_{n}\right)}  \tag{4.2}\\
\Delta_{n}^{(p)}=F_{p} \Delta_{n}^{(1)}-x y F_{p-1} \Delta_{n-1}  \tag{4.3}\\
\Delta_{n}^{(p)}+x y \Delta_{n}^{(p-2)}=(1+x y) \Delta_{n}^{(p-1)} \tag{4.4}
\end{gather*}
$$

Using (4.4) or Theorem 1 we can easily prove each of the following formulae.

## Corollary 1.

$$
\begin{gather*}
\Delta_{n}(x, y)=\Delta_{n}(y, x)  \tag{4.5}\\
\Delta_{n}(x, y) \equiv F_{l_{n}}(x, y) \bmod (x-1)(y-1)  \tag{4.6}\\
\Delta_{n}(x, y)=(x y)^{t_{n}-1} \Delta_{n}\left(x^{-1}, y^{-1}\right) \tag{4.7}
\end{gather*}
$$

The fact that a two-bridge link is interchangeable assures us of (4.5). From (4.6), we have immediately

$$
\begin{equation*}
\Delta_{n}(x, 1)=F_{l_{n}}(x, 1) \tag{4.8}
\end{equation*}
$$

(4.7) and (4.8) constitute the Torres conditions [8] for two-bridge links.

DEFINITION 1. Let $f(x, y)$ be a polynomial in $\Lambda$. If $f(x, y) \neq 0$, then $\operatorname{deg}_{x} f=$ (maximum $x$-power of any term of $f$ ) minus (minimum $x$-power of any term of $f$ ). If $f(x, y)=0$, then $\operatorname{deg}_{x} f=-1$. We define $\operatorname{deg}_{y} f$ in the same way.

Definition 2. $\Lambda^{+1}(r, s)$ denotes the set of all polynomials $f(x, y)=$ $\Sigma_{r \leqslant i, j \leqslant s} a_{i j} x^{i} y^{j}$ in $\Lambda$ satisfying the following conditions.
(i) $\operatorname{deg}_{x} f=\operatorname{deg}_{y} f=s-r$.
(ii) Both

$$
\left[\begin{array}{ccc}
a_{s r} & \cdots & a_{s s} \\
\vdots & & \vdots \\
a_{r r} & \cdots & a_{r s}
\end{array}\right] \text { and }\left[\begin{array}{ccc}
a_{r r} & \cdots & a_{r s} \\
\vdots & & \vdots \\
a_{s r} & \cdots & a_{s s}
\end{array}\right]
$$

are symmetric matrices.
(iii) $a_{i j} \geqslant 0$ if $i+j$ is even, and $a_{i j} \leqslant 0$ if $i+j$ is odd.
(iv) Let $b_{i j}=a_{i+r, j+r}$. Then $\left|b_{k, 0}\right| \leqslant\left|b_{k-1,1}\right| \leqslant \cdots \leqslant\left|b_{k-u, u}\right|$, and $\left|b_{k, 0}\right| \leqslant$ $\left|b_{k+1,1}\right| \leqslant \cdots \leqslant\left|b_{k+v, v}\right|$ for $0 \leqslant k \leqslant s-r$, where $u=[k / 2]^{*}$ and $v=[(s-r-$ $k) / 2]$.

Furthermore $\Lambda^{-1}(r, s)$ denotes the set of all polynomials $f(x, y)$ in $\Lambda$ such that $-f(x, y) \in \Lambda^{+1}(r, s)$.

Theorem 3. For $n \geqslant 1, \Delta_{n} \in \Lambda^{\varepsilon_{n}}\left(r_{n}, s_{n}\right)$, where

$$
\varepsilon_{n}=\prod_{i=1}^{n} \frac{p_{i}}{\left|p_{i}\right|} \prod_{j=1}^{n-1} \frac{q_{j}}{\left|q_{j}\right|}, \quad r_{n}=\frac{l_{n}-\tilde{l}_{n}}{2} \quad \text { and } \quad s_{n}=\frac{l_{n}+\tilde{l}_{n}}{2}-1
$$

[^1]Note that $r_{n} \leqslant 0 \leqslant s_{n}, r_{n}-r_{n-1}=\frac{1}{2}\left(p_{n}-\left|p_{n}\right|\right)$ and $s_{n}-s_{n-1}=\frac{1}{2}\left(p_{n}+\left|p_{n}\right|\right)$. The proof of Theorem 3 will be given in Section 5.

Let $\Delta(t)=\sum_{i=0}^{m}(-1)^{i} a_{i} t^{i}$, where $m$ is odd, be the reduced Alexander polynomial of $L_{n}$. Since $\Delta(t)=\varepsilon_{n} t^{-2 r_{n}}(1-t) \Delta_{n}(t, t)$, we have $0<a_{0} \leqslant a_{1} \leqslant \cdots \leqslant$ $a_{(m-1) / 2}$ and $a_{k}=-a_{m-k}$ from Theorem 3. This is a weaker result than that of Hartley [4] stated in the beginning of this paper.

For the sake of Corollary 2 below, we need some preliminaries.

Definition 3. Let $L=K_{1} \cup K_{2}$ be a link and $S$ be a Seifert surface for $K_{1}$ with $S$ and $K_{2}$ in general position. If $\gamma_{S}=2$ (genus of $S$ ) plus (the number of times $K_{2}$ intersects $S$ ), then $\gamma_{1}=\min _{S} \gamma_{S}$ is the linking complexity of $K_{2}$ with $K_{1}$. We define $\gamma_{2}$ in the same way. We call the ordered pair ( $\gamma_{1}, \gamma_{2}$ ) the linking complexity of the link $L$.

This definition follows Bailey [1, page 45], see also [5].

Proposition. (Kidwell) If $\Delta(x, y)$ is the Alexander polynomial of a link $L$ with linking complexity $\left(\gamma_{1}, \gamma_{2}\right)$, then $\gamma_{1}-1 \geqslant \operatorname{deg}_{x} \Delta(x, y)$.

Proof. See [1, page 46].

Corollary 2. Let $\left(\gamma_{1}, \gamma_{2}\right)$ be the linking complexity of $L_{n}$. Then

$$
\begin{equation*}
\gamma_{1}=\gamma_{2} \tag{4.9}
\end{equation*}
$$

$$
\begin{equation*}
\operatorname{deg}_{x} \Delta_{n}(x, y)+1=\gamma_{1}=\tilde{l}_{n} \tag{4.10}
\end{equation*}
$$

Remark. The first equality of (4.10) is Proposition 6 of [1, page 57].

Proof. (4.9) follows from interchangeability of a two-bridge link or (4.10). For (4.10), from the diagram of $L_{n}$, we see that $\gamma_{1} \leqslant \tilde{l}_{n}$. By Theorem 3, $\operatorname{deg}_{x} \Delta_{n}+1=$ $\tilde{l}_{n}$ and by Proposition, $\gamma_{1} \geqslant \operatorname{deg}_{x} \Delta_{n}+1$.

## 5. Proof of Theorem 3

In this section we use the following trivial lemma without mention.

Lemma 3. Let $f \in \Lambda^{\epsilon}(r, s)$ and $g \in \Lambda^{\epsilon}(r-k, s+k)(k \geqslant 0)$. Then $f+g \in$ $\Lambda^{\varepsilon}(r-k, s+k)$.

Lemma 4. Let $f \in \Lambda^{e}(r, s)$. Then

$$
\begin{gathered}
F_{n} f \in \begin{cases}\Lambda^{\varepsilon}(r, s+n-1) & \text { if } n>0 \\
\Lambda^{-\varepsilon}(r+n, s-1) & \text { if } n<0\end{cases} \\
G_{n} f \in \Lambda^{(-1)^{n-1} \varepsilon}(r, s+n-1) \quad \text { if } n>0,
\end{gathered}
$$

where $G_{n}(x, y)=x^{n-1} F_{n}\left(x^{-1}, y\right)$.
Proof. We show that $f \in \Lambda^{+1}(r, s)$ implies $F_{n} f \in \Lambda^{+1}(r, s+n-1)$ if $n>0$. The other cases can be proved similarly. It is clear that $F_{n} f$ satisfies the conditions (i), (ii), (iii) and the first inequality of (iv) in Definition 2 for $\Lambda^{+1}(r, s+n-1)$. The second inequality of (iv) can be reduced to the sublemma below.

Sublemma. Let $f(x)=\sum_{i=0}^{n} a_{i} x^{i}$, where $a_{i}=a_{n-i}$ and $0<a_{0} \leqslant a_{1} \leqslant \cdots \leqslant$ $a_{[n / 2]}$. Let $\left(\sum_{j=0}^{m} x^{j}\right) f(x)=\sum_{k=0}^{m+n} b_{k} x^{k}$. Then $b_{k}=b_{m+n-k}$ and $0<b_{0} \leqslant b_{1} \leqslant$ $\cdots \leqslant b_{[(m+n) / 2]}$.

We omit the proof, as it is straightforward to prove it directly.
Lemma 5. If $\Delta_{n-1} \in \Lambda^{-\varepsilon}(r, s-1)$ and $\Delta_{n}^{(1)} \in \Lambda^{\varepsilon}(r, s)$, then

$$
\Delta_{n}^{(p)} \in \begin{cases}\Lambda^{\varepsilon}(r, s+p-1) & \text { if } p>0 \\ \Lambda^{-\varepsilon}(r+p, s-1) & \text { if } p<0\end{cases}
$$

Proof. (4.2) in Theorem 2 states that $\Delta_{n}^{(p)}=F_{p} \Delta_{n}^{(1)}-x y F_{p-1} \Delta_{n-1}$. The case $p=1$ is the hypothesis. If $p \geqslant 2$, then using Lemma $4, F_{p} \Delta_{n}^{(1)} \in \Lambda^{\varepsilon}(r, s+p-1)$ and $-x y F_{p-1} \Delta_{n-1} \in \Lambda^{\epsilon}(r+1, s+p-2)$. Thus $\Delta_{n}^{(p)} \in \Lambda^{\epsilon}(r, s+p-1)$. If $p \leqslant$ -1 , then $F_{p} \Delta_{n}^{(1)},-x y F_{p-1} \Delta_{n-1} \in \Lambda^{-\varepsilon}(r+p, s-1)$, so $\Delta_{n}^{(p)} \in \Lambda^{-\varepsilon}(r+p, s-1)$.

Lemma 6. Let $\Delta_{n}^{\langle m\rangle}$ be the Alexander polynomial of

$$
D\left(p_{1}, q_{1}, \ldots, p_{n-m}, q_{n-m}, 1, q_{n-m+1}, 1, \ldots, q_{n-1}, 1\right)
$$

Then we have

$$
\begin{align*}
\Delta_{n}^{\langle m\rangle}= & G_{m+1} \Delta_{n-m}-x y G_{m} \Delta_{n-m}^{\left(p_{n-m}-1\right)}  \tag{5.1}\\
& +(x-1)(y-1) \sum_{k=1}^{m}\left(q_{n-k}+1\right) G_{k} \Delta_{n-k}
\end{align*}
$$

where the last term denotes zero if $m=0$.

Proof. We prove (5.1) by induction on $m$. For $m=0$, it is clear that $\Delta_{n}^{\langle 0\rangle}=\Delta_{n}$. Assume that (5.1) is proved for $m-1$. Substituting $p_{n-m+1}=1$ in
$\Delta_{n}^{\langle m-1\rangle}$ we have

$$
\begin{aligned}
\Delta_{n}^{\langle m\rangle}= & G_{m} \Delta_{n-m+1}^{(1)}-x y G_{m-1} \Delta_{n-m+1}^{(0)} \\
& +(x-1)(y-1) \sum_{k=1}^{m-1}\left(q_{n-k}+1\right) G_{k} \Delta_{n-k} .
\end{aligned}
$$

$\operatorname{By}(4.2), \Delta_{n-m+1}^{(1)}=q_{n-m}(x-1)(y-1) \Delta_{n-m}+\Delta_{n-m}^{\left(p_{n-m}+1\right)}$. Thus we have

$$
\begin{aligned}
\Delta_{n}^{\langle m\rangle}= & G_{m}\left\{-(x-1)(y-1) \Delta_{n-m}+\Delta_{n-m}^{\left(p_{n-m}+1\right)}\right\}-x y G_{m-1} \Delta_{n-m} \\
& +(x-1)(y-1) \sum_{k=1}^{m}\left(q_{n-k}+1\right) G_{k} \Delta_{n-k}
\end{aligned}
$$

$\operatorname{By}(4.4), \Delta_{n-m}^{\left(p_{n-m}^{m}+1\right)}=(x y+1) \Delta_{n-m}-x y \Delta_{n-m}^{\left(p_{n-m}^{-1}\right)}$. Thus we have

$$
\begin{aligned}
\Delta_{n}^{\langle m\rangle}= & \left\{(x+y) G_{m}-x y G_{m-1}\right\} \Delta_{n-m}-x y G_{m} \Delta_{n-m}^{\left(p_{n-m}-1\right)} \\
& +(x-1)(y-1) \sum_{k=1}^{m}\left(q_{n-k}+1\right) G_{k} \Delta_{n-k} .
\end{aligned}
$$

Since $(x+y) G_{m}-x y G_{m-1}=G_{m+1}$, we have (5.1).

Now we are in position to prove Theorem 3. We use induction on $n$. For $n=1$, the theorem is clear. Assume the theorem proved for $\Delta_{k}$, where $1 \leqslant k \leqslant n-1$. Without loss of generality we may suppose that $q_{n-1}<0$. By Lemma 5 we only have to prove for the case $p_{n}=1$. Then there exists an integer $m$ such that:
(I) $1 \leqslant m \leqslant n-1, p_{n-m+1}=p_{n-m+2}=\cdots=p_{n-1}=1, p_{n-m} \neq 1$ and $q_{n-m}$, $q_{n-m+1}, \ldots, q_{n-1}<0$,
(II) $1 \leqslant m \leqslant n-2, \quad p_{n-m}=p_{n-m+1}=p_{n-m+2}=\cdots=p_{n-1}=1, \quad q_{n-m}$, $q_{n-m+1}, \ldots, q_{n-1}<0$ and $q_{n-m-1}>0$, or
(III) $m=n-1, p_{1}=p_{2}=\cdots=p_{n-1}=1, q_{1}, q_{2}, \ldots, q_{n-1}<0$.

To prove Theorem 3, it suffices to prove that $\Delta_{n-m} \in \Lambda^{\varepsilon}(r, s)$ implies $\Delta_{n} \in$ $\Lambda^{(-1)^{m} \varepsilon}(r, s+m)$, where by Lemma 6

$$
\begin{align*}
\Delta_{n}= & G_{m+1} \Delta_{n-m}-x y G_{m} \Delta_{n-m}^{\left(p_{n-m}-1\right)}  \tag{5.2}\\
& +(x-1)(y-1) \sum_{k=1}^{m}\left(q_{n-k}+1\right) G_{k} \Delta_{n-k}
\end{align*}
$$

By Lemma 4, we have

$$
\begin{equation*}
G_{m+1} \Delta_{n-m} \in \Lambda^{(-1)^{m_{\varepsilon}}}(r, s+m) \tag{5.3}
\end{equation*}
$$

By inductive hypothesis, $\Delta_{n-k} \in \Lambda^{(-1)^{m-k} \varepsilon}(r, s+m-k)$ for $1 \leqslant k \leqslant m$. Then by Lemma $4, G_{k} \Delta_{n-k} \in \Lambda^{(-1)^{m-1}}(r, s+m-1)$; hence we obtain

$$
(x-1)(y-1) \sum_{k=1}^{m}\left(q_{n-k}+1\right) G_{k} \Delta_{n-k}\left\{\begin{array}{l}
=0 \quad \text { if } q_{n-k}=-1 \text { for any } k  \tag{5.4}\\
\in \Lambda^{(-1)^{m} \xi}(r, s+m) \quad \text { otherwise }
\end{array}\right.
$$

Case (I). If $p_{n-m} \neq 1$, then by inductive hypothesis,

$$
\Delta_{n-m}^{\left(p_{n-m}^{-1)} \in\left\{\begin{array}{lll}
\Lambda^{\varepsilon}(r, s-1) & \text { if } & p_{n-m} \geqslant 2 \\
\Lambda^{\varepsilon}(r-1, s) & \text { if } & p_{n-m} \leqslant-1
\end{array} . . \begin{array}{ll}
\end{array} . \begin{array}{ll}
\end{array}\right)\right.}
$$

Thus, using Lemma 4, we have

$$
-x y G_{m} \Delta_{n-m}^{\left(p_{n-m}-1\right)} \in \begin{cases}\Lambda^{(-1)^{m} \varepsilon}(r+1, s+m-1) & \text { if } p_{n-m} \geqslant 2  \tag{5.5}\\ \Lambda^{(-1)^{m} \varepsilon}(r, s+m) & \text { if } p_{n-m} \leqslant-1\end{cases}
$$

Case (II). If $p_{n-m}=1$ and $q_{n-m-1}>0$, then by inductive hypothesis,

$$
\Delta_{n-m}^{\left(p_{n-m}-1\right)}=\Delta_{n-m-1} \in \Lambda^{\epsilon}(r, s-1) .
$$

Thus, using Lemma 4, we have

$$
\begin{equation*}
-x y G_{m} \Delta_{n-m}^{\left(p_{n-m}^{-1)}\right.} \in \Lambda^{(-1)^{m} \varepsilon}(r+1, s+m-1) \tag{5.6}
\end{equation*}
$$

Case (III). Since $m=n-1$ and $p_{1}=1$, we have

$$
\begin{equation*}
-x y G_{m} \Delta_{n-m}^{\left(p_{n}-m^{m}-1\right)}=0 \tag{5.7}
\end{equation*}
$$

From (5.2) ~(5.7), we have $\Delta_{n} \in \Lambda^{(-1)^{m} \varepsilon}(r, s+m)$. This completes the proof of Theorem 3.

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[^0]:    © 1984 Australian Mathematical Society $0263-6115 / 84 \$ A 2.00+0.00$

[^1]:    *[ ] denotes the Gaussian symbol.

