# Parabolic Subgroups with Abelian Unipotent Radical as a Testing Site for Invariant Theory 

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#### Abstract

Let $L$ be a simple algebraic group and $P$ a parabolic subgroup with Abelian unipotent radical $P^{u}$. Many familiar varieties (determinantal varieties, their symmetric and skew-symmetric analogues) arise as closures of $P$-orbits in $P^{u}$. We give a unified invariant-theoretic treatment of various properties of these orbit closures. We also describe the closures of the conormal bundles of these orbits as the irreducible components of some commuting variety and show that the polynomial algebra $k\left[P^{u}\right]$ is a free module over the algebra of covariants.


## Introduction

Let $L$ be a simple algebraic group over an algebraically closed field $k$ of characteristic zero and $P$ a parabolic subgroup with Abelian unipotent radical ( $=$ with aura). In this case Lie $L=\mathfrak{I}$ admits a Z-grading with only three nonzero parts:

$$
\mathfrak{I}=\mathfrak{I}(-1) \oplus \mathfrak{I}(0) \oplus \mathfrak{I}(1)
$$

Such a grading is said to be short. Here Lie $P=\mathfrak{l}(0) \oplus \mathfrak{l}(1)$ and $\exp \mathfrak{l}(1)$ is the Abelian unipotent radical of $P$.

In this paper we consider several invariant-theoretic problems related to the representation of $G:=L(0)$ on $\mathrm{I}(1)$. As is well known, $G$ has finitely many orbits in $\mathrm{I}(1)$. Let $\mathcal{O}_{i}$ be one of them, $\overline{\mathcal{O}}_{i}$ its closure, and $\mathfrak{E}_{i}$ the closure of the conormal bundle of $\mathcal{O}_{i}$. Since $\mathfrak{I}(-1)$ is $G$ equivariantly identified with the dual space $\mathfrak{I}(1)^{*}$, we have $\mathfrak{F}_{i}$ is a subvariety in $\mathfrak{I}(-1) \oplus \mathrm{I}(1)$. Our principal results are the following:

- We give a unified construction of a $G$-equivariant resolution of singularities for $\overline{\mathcal{O}}_{i}$ and $\mathfrak{E}_{i}$. In all cases, the covering smooth variety is a homogeneous bundle $G *_{R} V$, where $R$ is a parabolic subgroup of $G$ and $V$ is a completely reducible $R$-module.
- It is proved that $L \cdot \mathfrak{l}(1) \cap(\mathfrak{l}(1) \oplus \mathfrak{I}(-1))=\bigcup_{i} \mathfrak{E}_{i}$ and it is the variety of pairs $(x, y)$ $(x \in \mathfrak{l}(1), y \in \mathfrak{I}(-1))$ such that $[x, y]=0$. A relationship between the double coset space $G \backslash L / P$ and the $G$-orbit structure of $L \cdot \mathfrak{l}(1) \cap(\mathfrak{l}(1) \oplus \mathfrak{l}(-1))$ is investigated. This provides some link to results in [12].
- Let $U$ be a maximal unipotent subgroup of $G$. The (well-known) description of the algebra of covariants $k[l(1)]^{U}$ will be obtained as a consequence of "a restriction theorem for $U$-invariants" [7]. We prove that $k[I(1)]$ is a free $k[I(1)]^{U}$-module. In our context, it is equivalent to that the quotient map $\pi_{\mathrm{I}(1)}: \mathfrak{I}(1) \rightarrow \mathfrak{I}(1) / / U$ is equidimensional.

[^0]- Actually, to derive the previous result, we prove a sufficient condition for the quotient map $\pi_{X}: X \rightarrow X / / U$ to be flat, where $X$ is an affine $G$-variety. As a by-product, we classify the irreducible representations of simple algebraic groups with this property. The main part of the list consists of representations arising from parabolic subgroups with aura.

The proofs are based on properties of the partition of the root system $\Delta$ determined by the short grading. We work with two specific sequences of orthogonal long roots in $\Delta(1)$ (see notation below). We call them respectively lower and upper canonical strings. The construction of them is not new, it goes back to Harish Chandra. It seems however that a systematic utilization of their properties given by Lemma 1.2 constitutes some novelty.

It is quite typical for parabolic subgroups with aura that many problems for them can be solved in a case-by-case fashion. For instance, this is true for resolution of singularities of $G$-orbits in I(1). Indeed, we meet as the orbit closures the determinantal varieties, their symmetric and skew-symmetric analogues, and quadrics, if I is classical. Associated to $\mathfrak{I}=\mathbf{E}_{7}$, one obtains a 27-dimensional representation of $\mathbf{E}_{6}$ and in this case resolutions of singularities were constructed in [3, Section 2]. Finally, the $\mathbf{E}_{6}$-case is simple enough. Our approach to this problem gives a unified description of resolutions and then a proof working for all simple Lie algebras. The same can be said about all other proofs in the paper. We never use case-by-case arguments and do not distinguish between the "tube" or "non-tube" case.

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## Notation and conventions

Lie algebras of algebraic groups are denoted by the corresponding small Gothic letters. I is a simple Lie algebra equipped with a short grading $\mathfrak{l}=\mathfrak{l}(-1) \oplus \mathfrak{l}(0) \oplus \mathfrak{l}(1) ; \mathfrak{g}:=\mathfrak{l}(0)$.
$T$ is a maximal torus in $G$ and hence in $L$.
$\Delta$ is the root system of $(\mathrm{I}, \mathrm{t})$.
$\Delta=\Delta(-1) \cup \Delta(0) \cup \Delta(1)$-the partition corresponding to the short grading.
We fix a Borel subgroup $B$ in $G$, containing $T$. This choice determines a set of positive roots $\Delta(0)^{+}$in $\Delta(0)$ and also in $\Delta: \Delta^{+}=\Delta(0)^{+} \cup \Delta(1) ; \gamma$ is the highest root in $\Delta^{+}$.
$\Pi$ is the set of simple roots in $\Delta^{+}$and $\Pi(0)=\Pi \cap \Delta(0)$.
$W$ (resp. $W(0))$ is the Weyl group of $I($ resp. $\mathfrak{g})$ with respect to $t$.
For $\alpha \in \Delta$, we let $w_{\alpha}$ denote the corresponding reflection in $W$, $\alpha^{\vee}=2 \alpha /(\alpha, \alpha)$ the corresponding coroot, and $e_{\alpha}$ a nonzero element in the root space $\mathrm{I}_{\alpha} \subset \mathrm{I}$.

For $r \in \mathbb{N}$, let $[1, r]:=\{1,2, \ldots, r\}$.
$\# M$ is the cardinality of a finite set $M$.

## 1 Canonical Strings of Roots and Their Properties

We begin with recalling some properties of short gradings. Since $I$ is simple, the representation of $\mathfrak{g}$ on $\mathfrak{l}(1)$ is faithful and irreducible. Therefore the centre of $\mathfrak{g}$ is one-dimensional, $P$
is a maximal parabolic subgroup, and $\# \Pi(0)=\# \Pi-1$. Thus, there is a unique simple root in $\Delta(1)$. Call it $\beta$. Then $\beta$ is the unique lowest weight of the $\mathfrak{g}$-module $\mathfrak{l}(1)$. The longest element in $W(0)$ takes $\beta$ to the highest weight of $\mathfrak{l}(1)$, i.e., to $\gamma$. Hence $\beta$ is long. This also proves that the $\beta$-height of $\gamma$, i.e., the coefficient $n_{\beta}$ in the sum $\gamma=n_{\beta} \beta+\sum_{\alpha \in \Pi(0)} n_{\alpha} \alpha$, is equal to 1 . Therefore the $\beta$-height of any root in $\Delta(1)$ is equal to 1 .

We shall consider two strings of pairwise orthogonal roots in $\Delta(1)$. Both strings are defined inductively. The lower canonical string (l.c.s.) is the cascade up from $\beta_{1}=\beta$ within $\Delta(1)$ : at each stage, $\beta_{i+1}$ is the minimal root in $\Delta_{i}(1)=\left\{\alpha \in \Delta(1) \mid\left(\alpha, \beta_{1}\right)=\cdots=\right.$ $\left.\left(\alpha, \beta_{i}\right)=0\right\}$. The process terminates when $\Delta_{i}(1)$ is empty. The construction is originally due to Harish Chandra and is well known nowadays. The following lemma is included for completeness and convenience of the reader.

Lemma 1.1 The above procedure is well-defined, i.e., at each stage $\Delta_{i}(1)$ contains a unique minimal element. All the roots in the string are long.

Proof It goes by induction on $i$. Consider $\Delta_{i}=\left\{\alpha \in \Delta \mid\left(\alpha, \beta_{1}\right)=\cdots=\left(\alpha, \beta_{i}\right)=0\right\}$. Then $\Delta_{i}=\Delta_{i}(-1) \cup \Delta_{i}(0) \cup \Delta_{i}(1)$. This partition corresponds to a short grading of a reductive subalgebra $\mathfrak{l}_{i} \subset \mathfrak{I}$. It is easy to see that $\Delta_{i}(1) \neq \varnothing$ if and only if $\gamma \in \Delta_{i}(1)$ and in this case $\gamma$ is the unique maximal element in $\Delta_{i}(1)$ (as an element of $\Delta_{i}$ ). Therefore the unique minimal element in $\Delta_{i}(1)$, which is $W(0)$-conjugate to $\gamma$, is long.

The upper canonical string (u.c.s.) is the cascade down from $\gamma_{1}=\gamma$ within $\Delta(1)$ : at each stage, $\gamma_{i+1}$ is the maximal element in $\Delta^{i}(1)$, where $\Delta^{i}=\left\{\alpha \in \Delta \mid\left(\alpha, \gamma_{1}\right)=\cdots=\right.$ $\left.\left(\alpha, \gamma_{i}\right)=0\right\}$. The process terminates when $\Delta^{i}(1)$ becomes empty. Obviously, the longest element in $W(0)$ takes the lower canonical string to the upper canonical one. Hence, the latter is well-defined and both strings have the same cardinality, say $r$. From now on, $\beta=$ $\beta_{1}, \beta_{2}, \ldots, \beta_{r}$ and $\gamma=\gamma_{1}, \ldots, \gamma_{r}$ are respectively the l.c.s and the u.c.s.

Remarks 1. It is easily seen that the l.c.s. and u.c.s. are sequences of orthogonal long roots of maximal length. Moreover, one can prove that if a sequence of strongly orthogonal roots has the maximal length, then all the roots in it are long.
2. By [12, 2.8], $W(0)$ is transitive on the set of sequences, of a fixed length, that consist of orthogonal long roots in $\Delta(1)$.
3. The number $r$ is an important invariant of the short grading. For instance, it is the rank of the symmetric variety $L / G$ or the Krull dimension of the algebra $k[\mathrm{l}(1)]^{U}$ or the number of nonzero $G$-orbits in $\mathrm{I}(1)$.

Given $\alpha \in \Delta$, consider two sequences of rational numbers:

$$
\begin{align*}
& \left(\alpha, \beta_{1}\right), \ldots,\left(\alpha, \beta_{r}\right)  \tag{*}\\
& \left(\alpha, \gamma_{1}\right), \ldots,\left(\alpha, \gamma_{r}\right)
\end{align*}
$$

## Lemma 1.2

(i) Let $\alpha \in \Delta(0)$. Then both $(*)$ and $(* *)$ contain at most one positive and one negative term. Moreover, $\alpha \in \Delta(0)^{+}$if and only if the first nonzero term (if any) is negative in $(*)$ and positive in $(* *)$;
(ii) Let $\alpha \in \Delta(1)$. Then $(*)$ and $(* *)$ contain at most two nonzero terms, which are necessarily positive;
(iii) The nonzero terms in (*) and (**) have the same absolute value $\frac{1}{2}(\gamma, \gamma)$.

Proof (i) Since the proofs for $(*)$ and $(* *)$ are similar, we consider only the second sequence. If $\left(\alpha, \gamma_{i}\right)>0$ and $\left(\alpha, \gamma_{j}\right)>0$ for $i \neq j$, then $\gamma_{i}-\alpha \in \Delta(1)$ and $\left(\gamma_{i}-\alpha, \gamma_{j}\right)<0$. But this is impossible, because the sum of two elements in $\Delta(1)$ is never a root. For $\alpha \in \Delta(0)^{+}$, the first nonzero term is positive by the very definition of the u.c.s. As each root is either positive or negative, the converse is also true.
(ii) \& (iii) Left to the reader.

Corollary 1.3 For any $\alpha \in \Delta(0)^{+}$and $m \in[1, r]$, we have $\left(\alpha, \beta_{1}+\cdots+\beta_{m}\right) \leq 0$ and $\left(\alpha, \gamma_{1}+\cdots+\gamma_{m}\right) \geq 0$. Moreover, $\gamma_{1}+\cdots+\gamma_{m}$ is also dominant with respect to $\Delta^{+}$.

Take an $\alpha \in \Delta(0)^{+}$such that $\left(\alpha, \beta_{i}\right)<0$ for some $i$. By Lemma 1.2, there is at most one $j>i$ such that $\left(\alpha, \beta_{j}\right)>0$. The question arises whether such a $j$ exists and is there a relationship between $i$ and $j$ ? The next result says that compensation in case of simple roots occurs as soon as possible. This plays a crucial rôle in Section 4, in the proof of flatness of the quotient map $\pi_{\mathrm{I}(1)}$.

## Theorem 1.4

1. Let $\left(\alpha, \beta_{i}\right)<0$ for some $\alpha \in \Pi(0)$ and $i<r$. Then $\left(\alpha, \beta_{i+1}\right)>0$.
2. Dually, if $\left(\alpha, \gamma_{j}\right)>0$ for some $j<r$, then $\left(\alpha, \gamma_{j+1}\right)<0$.

Proof The second claim follows from the first one by the application of the longest element in $W(0)$. So, we consider only the l.c.s.

Replacing $\Delta$ by $\Delta_{i-1}$, we may assume that $i=1$. If $r=1$, then there is nothing to prove. Suppose $r \geq 2$. By definition, $\left(\beta_{2}, \beta_{1}\right)=0$ and $\beta_{2}$ is the minimal root in $\Delta(1)$ with this property. Since $\beta_{2}$ is not simple, there is $\mu \in \Pi(0)$ such that $\beta_{2}-\mu \in \Delta(1)$. Then $\left(\beta_{2}-\mu, \beta_{1}\right)>0$. Hence $\left(\mu, \beta_{1}\right)<0$ and $\mu, \beta_{1}$ are adjacent simple roots. Now, assume that $\left(\alpha, \beta_{1}\right)<0$ and $\left(\alpha, \beta_{2}\right)=0$. Since $\left(\beta_{2}, \mu\right)>0$, we have $\alpha \neq \mu$. Thus, we have detected a fragment of the Dynkin diagram:

(At the moment, nothing is claimed about the length of $\alpha$ and $\mu$.) In particular, $(\alpha, \mu)=0$. Consider the support ${ }^{1}$ of $\beta_{2}-\mu-\beta_{1} \in \Delta(0)^{+}$. Since $\left(\beta_{2}-\mu-\beta_{1}, \alpha\right)>0$, we have $\alpha \in \operatorname{supp}\left(\beta_{2}-\mu-\beta_{1}\right)$. The support of any root is connected, hence $\mu \notin \operatorname{supp}\left(\beta_{2}-\mu-\beta_{1}\right)$ and even $\left(\mu, \beta_{2}-\mu-\beta_{1}\right)=0$. The latter equality implies $\left(\mu^{\vee}, \beta_{2}\right)=-\left(\mu^{\vee}, \beta_{1}\right)=1$, i.e., $\mu$ is long and $\beta_{2}-\mu-\beta_{1}$ is also long. Next, $\beta_{2}-\mu-\beta_{1}-\alpha \in \Delta(0)^{+} \cup\{0\}$ and $\left(\beta_{2}-\mu-\beta_{1}-\alpha, \beta_{1}^{\vee}\right)=1-2+1=0$. Hence $\alpha \notin \operatorname{supp}\left(\beta_{2}-\mu-\beta_{1}-\alpha\right)$. There are then two possibilities and we shall see that either of them leads to a contradiction.
(a) $\beta_{2}-\mu-\beta_{1}=\alpha$. Then $\alpha$ is long and $0=\left(\alpha^{\vee}, \beta_{2}\right)=\left(\alpha^{\vee}, \alpha+\mu+\beta_{1}\right)=2-1$, a contradiction.

[^1](b) $\beta_{2}-\mu-\beta_{1}-\alpha \neq 0$. The support of this positive root must then contain a simple root adjacent to $\alpha$, i.e., $\left(\beta_{2}-\mu-\beta_{1}-\alpha, \alpha\right)<0$. That is, $(\alpha, \alpha)+\left(\beta_{1}, \alpha\right)>0$ and hence $\alpha$ is long. Therefore $\alpha+\beta_{1}+\mu$ is a long root in $\Delta(1)$ and $\left(\alpha+\beta_{1}+\mu, \beta_{1}\right)=0$. Thus, $\alpha+\beta_{1}+\mu$ must be equal to $\beta_{2}$, which is again a contradiction.

Let $\varphi$ be the fundamental weight of $L$ corresponding to $\beta_{1}$, i.e., $\left(\varphi, \beta_{1}\right)=\frac{1}{2}\left(\beta_{1}, \beta_{1}\right)$ and $(\varphi, \alpha)=0$ for all $\alpha \in \Delta(0)$.

Proposition 1.5 The following conditions are equivalent:

1. $\beta_{r+1-i}=\gamma_{i}$ for $i=1, \ldots, r$;
2. $\beta_{r}=\gamma_{1}$;
3. $2 \varphi=\beta_{1}+\cdots+\beta_{r}$;
4. The element $\tilde{w}:=\prod_{i=1}^{r} w_{\beta_{i}} \in W$ takes $\Delta(1)$ to $\Delta(-1)$.

Proof $1 \Rightarrow 2$. Obvious.
$2 \Rightarrow 3$. We have $\left(\alpha, \beta_{r}\right) \geq 0$ for all $\alpha \in \Pi(0)$. It then follows from 1.2 and 1.4 that the number of $\beta_{i}$ 's that are not orthogonal to such an $\alpha$ is either 0 or 2 . Therefore $\left(\alpha, \beta_{1}+\cdots+\beta_{r}\right)=0$ and hence $\beta_{1}+\cdots+\beta_{r}=c \varphi$. Then clearly $c=2$.
$3 \Rightarrow 4$. It follows from (3) that $\tilde{w} \cdot \varphi=-\varphi$. Therefore $\tilde{w}$ takes $\Delta(0)$ to $\Delta(0)$. Hence $\tilde{w} . \alpha$ belongs to either $\Delta(-1)$ or $\Delta(1)$ for any $\alpha \in \Delta(1)$. The assumption $\tilde{w} \cdot \alpha \in \Delta(1)$ clearly implies that $\tilde{w} . \alpha=\alpha$, i.e., $\alpha$ is orthogonal to all the $\beta_{i}$ 's. But this contradicts the maximality of the l.c.s.
$4 \Rightarrow 2$. If $\beta_{r} \neq \gamma_{1}$, then $\tilde{w} \cdot \gamma_{1}=\gamma_{1}-\beta_{r} \in \Delta(0)$.
$3 \Rightarrow 1$. We have $\left(\alpha, \beta_{1}+\cdots+\beta_{r}\right)=0$ for all $\alpha \in \Delta(0)^{+}$. Then Lemma 1.2 implies that the number of $\beta_{i}$ 's that are not orthogonal to $\alpha$ is either 0 or 2 . Therefore the first nonzero value (if any) in the sequence $\left(\alpha, \beta_{r}\right), \ldots,\left(\alpha, \beta_{1}\right)$ is positive. Since also $\left(\beta_{i}, \mu\right) \geq 0$ for all $\mu \in \Delta(1)$, we have $\beta_{r}=\gamma_{1}$ and each $\beta_{i}$ is the highest root in $\left\{\nu \in \Delta \mid\left(\nu, \beta_{r}\right)=\cdots=\right.$ $\left.\left(\nu, \beta_{i+1}\right)=0\right\} \cap \Delta(1)$. It remains to note that this is just the definition of u.c.s.

Remarks 1. The equivalent conditions of 1.5 characterize the case, where the Hermitian symmetric space $G / P$ is of tube type (for $k=\mathbb{C}$ ) and/or the prehomogeneous vector space $(G, I(1))$ is regular.
2. The list of equivalent conditions can easily be extended. If one sticks to those that concern only the root system, the condition $\varphi=-w^{o} . \varphi$ should be mentioned (here $w^{0} \in$ $W$ is the longest element). It is not hard to deduce it from, say, condition 4. But I do not know a direct proof for the converse.

## 2 Resolution of Singularities of the Closures of G-Orbits in $\mathbb{I}(1)$

It follows from a result of Vinberg [15, Section 2] that the number of $G$-orbits in $I(1)$ is finite. An explicit classification has been obtained by Muller et al. [5] (see also [12]). Their description can be stated as follows.

Theorem 2.1 Let $\mu_{1}, \ldots, \mu_{r}$ be an arbitrary maximal sequence of orthogonal long roots in $\Delta(1)$. Then $\left\{\sum_{j=1}^{i} e_{\mu_{j}} \mid 1 \leq i \leq r\right\} \cup\{0\}$ is a system of representatives of the $G$-orbits in $\mathrm{I}(1)$. In particular, the total number of orbits is $r+1$.

We let $\mathcal{O}_{i}$ denote the $G$-orbit which contains the elements of the form $\sum_{j=1}^{i} e_{\mu_{j}}$. Because $\mu_{1}, \ldots, \mu_{r}$ are linearly independent, it immediately follows that $\mathcal{O}_{i} \subset \overline{\mathcal{O}_{j}}$ if and only if $i \leq j$. (This is also a result in [5].) To construct an equivariant resolution of the $\overline{\mathcal{O}}_{i}$ 's, it will be convenient to deal with the representatives given in terms of the u.c.s. Define the point $x_{i} \in \mathcal{O}_{i}$ by $x_{i}=\sum_{j=1}^{i} e_{\gamma_{j}}$. Recall that $\Delta(0)$ is the root system of $G$ and $\mathfrak{b}$ is the Borel subalgebra of $\mathfrak{g}$ that determines $\Delta(0)^{+}$.

Proposition 2.2 Define the subspace $V_{i} \subset \mathfrak{l}(1)$ by $V_{i}:=\left[\mathfrak{b}, x_{i}\right]$. Then
(i) $\quad V_{i}=\bigoplus_{\alpha \in \Gamma_{i}} \mathrm{l}(1)_{\alpha}$, where $\Gamma_{i}=\left\{\alpha \in \Delta(1) \mid\left(\alpha, \gamma_{1}+\cdots+\gamma_{i}\right)=(\gamma, \gamma)\right\}$;
(ii) $V_{i}$ is a $B$-stable subspace of $\mathrm{I}(1)$.

Proof (i) Let $\Gamma_{i}^{\prime}$ be the subset of $\Delta(1)$ consisting of all $\alpha$ such that $\alpha=\mu+\gamma_{j}$ for some $\mu \in \Delta(0)^{+} \cup\{0\}$ and $1 \leq j \leq i$. Obviously, $V_{i} \subset \bigoplus_{\alpha \in \Gamma_{i}^{\prime}} \mathrm{I}(1)_{\alpha}$. Since $\gamma_{1}, \ldots, \gamma_{i}$ are linearly independent, $\left[\mathfrak{t}, x_{i}\right]=\mathfrak{l}(1)_{\gamma_{1}} \oplus \cdots \oplus \mathfrak{l}(1)_{\gamma_{i}} \subset V_{i}$. Suppose $\alpha \notin\left\{\gamma_{1}, \ldots, \gamma_{i}\right\}$ and $\alpha-\gamma_{j}=: \mu \in \Delta(0)^{+}$for some $j \in[1, i]$. Then $\left(\alpha, \gamma_{j}\right)>0$ and $\left(\mu, \gamma_{j}\right)<0$. By Lemma 1.2, we have $\left(\mu, \gamma_{s}\right) \geq 0$, if $s \neq j$. It follows that $\left[e_{\mu}, x_{i}\right]=\left[e_{\mu}, e_{\gamma_{j}}\right]=e_{\alpha} \in V_{i}$. Thus, $V_{i}=\bigoplus_{\alpha \in \Gamma_{i}^{\prime}} \mathrm{I}(1)_{\alpha}$. It remains to prove that $\Gamma_{i}^{\prime}=\Gamma_{i}$.

Clearly, $\gamma_{j}(j \leq i)$ belongs to both $\Gamma_{i}^{\prime}$ and $\Gamma_{i}$. Next, assume that $\alpha=\mu+\gamma_{j}$ with $\mu \in \Delta(0)^{+}$. By Lemma 1.2(i), the condition $\left(\mu, \gamma_{j}\right)>0$ implies that there exists a unique $m<j$ such that $\left(\mu, \gamma_{m}\right)>0$. Therefore $\left(\alpha, \gamma_{m}\right)=\left(\mu+\gamma_{j}, \gamma_{m}\right)>0$. From Lemma 1.2(ii) it then follows that $\left(\alpha, \gamma_{1}+\cdots+\gamma_{i}\right)=\left(\alpha, \gamma_{j}\right)+\left(\alpha, \gamma_{m}\right)=\frac{1}{2}(\gamma, \gamma)+\frac{1}{2}(\gamma, \gamma)=(\gamma, \gamma)$. Thus, $\Gamma_{i}^{\prime} \subset \Gamma_{i}$.

On the other side, suppose $\alpha \in \Delta(1), \alpha \notin\left\{\gamma_{1}, \ldots, \gamma_{i}\right\}$, and $\left(\alpha, \gamma_{1}+\cdots+\gamma_{i}\right)=(\gamma, \gamma)$. Since all the $\gamma_{j}$ 's are long and $\left(\alpha, \gamma_{j}\right) \geq 0$, there exist exactly two indices $m, m^{\prime} \in[1, i]$ such that $\left(\alpha, \gamma_{m}\right)=\left(\alpha, \gamma_{m^{\prime}}\right)>0$. Assume that $m>m^{\prime}$ and consider $\alpha-\gamma_{m} \in \Delta(0)$. We have $\left(\alpha-\gamma_{m}, \gamma_{m}\right)<0,\left(\alpha-\gamma_{m}, \gamma_{m^{\prime}}\right)>0$, and $\left(\alpha-\gamma_{m}, \gamma_{s}\right)=0$ for $s \neq m, m^{\prime}$. Then Lemma 1.2(i) forces that $\alpha-\gamma_{m}$ is positive. Hence $\alpha=\left(\alpha-\gamma_{m}\right)+\gamma_{m} \in \Gamma_{i}^{\prime}$.
(ii) One has to prove that if $\alpha \in \Gamma_{i}$ and $\alpha+\mu \in \Delta$ for some $\mu \in \Delta(0)^{+}$, then $\alpha+\mu \in \Gamma_{i}$. Recall from 1.3 that $\left(\mu, \gamma_{1}+\cdots+\gamma_{i}\right) \geq 0$ for each $\mu \in \Delta(0)^{+}$.
(a) If $\left(\mu, \gamma_{1}+\cdots+\gamma_{i}\right)=0$ and $\alpha+\mu$ is a root, then $\left(\alpha+\mu, \gamma_{1}+\cdots+\gamma_{i}\right)=(\gamma, \gamma)$. That is, $\alpha+\gamma \subset \Gamma_{i}$ as well.
(b) If $\left(\mu, \gamma_{1}+\cdots+\gamma_{i}\right)>0$, then $\left(\alpha+\mu, \gamma_{1}+\cdots+\gamma_{i}\right)>(\gamma, \gamma)$. However, it follows from Lemma 1.2(ii) that $\left(\nu, \gamma_{1}+\cdots+\gamma_{i}\right) \leq(\gamma, \gamma)$ for any $\nu \in \Delta(1)$. Hence $\alpha+\mu$ is not a root in this case.

Corollary 2.3 The orbit $B x_{i}$ is open and dense in $V_{i}$.
Proof One has $B x_{i} \subset V_{i}$ and $\operatorname{dim} B x_{i}=\operatorname{dim} V_{i}$.

Since $V_{i}$ is $B$-stable, its normalizer in $G$ is a parabolic subgroup. Call it $R_{i}$. Let $R_{i}=G_{i} N_{i}$ be the standard Levi decomposition and $\Delta\left(G_{i}\right)$ the root system of $G_{i}$. Define $\Delta\left(N_{i}\right)$ to be the set of weights of $T$-module $N_{i}$.

Proposition 2.4 If $\mu \in \Delta(0)$, then $\mu \in \Delta\left(G_{i}\right)$ if and only if $\left(\mu, \gamma_{1}+\cdots+\gamma_{i}\right)=0$.

Proof An equivalent formulation is that $\mu \in \Delta\left(G_{i}\right)$ if and only if either all the values $\left(\mu, \gamma_{1}\right), \ldots,\left(\mu, \gamma_{i}\right)$ are equal to zero or precisely two of them are nonzero (of different signs).
(a) Let us prove that if $\mu \in \Delta(0)^{+}$and there is a single nonzero value among $\left\{\left(\mu, \gamma_{j}\right) \mid\right.$ $j=1, \ldots, i\}$, then $e_{-\mu}$ does not preserve $V_{i}$.

Suppose $\left(\mu, \gamma_{m}\right)>0$, while all other products are equal to zero. Then $\gamma_{m}-\mu \in \Delta(1)$ and $\left(\gamma_{m}-\mu, \gamma_{j}\right)=0$ for $j \neq m$. Since $\left(\gamma_{m}-\mu\right)-\gamma_{j} \notin \Delta$ and $\left(\gamma_{m}-\mu\right)-\gamma_{m}$ is negative, $\gamma_{m}-\mu \notin \Gamma_{i}$. Thus, $e_{\gamma_{m}} \in V_{i}$ and $\left[e_{-\mu}, e_{\gamma_{m}}\right] \notin V_{i}$.
(b) It remains to prove that if $\mu \in \Delta(0)^{+}$and $\left(\mu, \gamma_{1}+\cdots+\gamma_{i}\right)=0$, then $e_{-\mu} V_{i} \subset V_{i}$.

Essentially, it was already shown at the end of the proof of 2.2: If $\alpha \in \Gamma_{i}$ and $\alpha-\mu$ is a root, then $\left(\alpha-\mu, \gamma_{1}+\cdots+\gamma_{i}\right)=(\gamma, \gamma)$ and hence $\alpha-\mu \in \Gamma_{i}$.

## Corollary 2.5

1. $\Delta\left(N_{i}\right)=\left\{\mu \in \Delta(0)^{+} \mid\left(\mu, \gamma_{1}+\cdots+\gamma_{i}\right)>0\right\}$;
2. The representation of $R_{i}$ on $V_{i}$ is completely reducible.

Proof 1. Compare 1.3 and 2.4.
2. One has to prove that $N_{i}$ acts trivially on $V_{i}$. Invoking the first assertion, we see that it was done in the proof of Proposition 2.2, part (ii)b.

The following is the principal result of this section.
Theorem 2.6 The natural mapping $\tau_{i}: G *_{R_{i}} V_{i} \rightarrow G \cdot V_{i}=\overline{\mathcal{O}}_{i} \subset \mathfrak{I}(1)$ is a G-equivariant resolution of singularities of $\overline{\mathcal{O}}_{i}$.

Proof It is well-known that $\tau_{i}$ is proper and $G \cdot V_{i}$ is closed (see e.g. [3]). The equality $G \cdot V_{i}=\overline{\mathcal{O}}_{i}$ follows from 2.3. The only assertion that still has to be proved is that $\tau_{i}$ is birational. In our situation, it is equivalent to the fact that $G_{x_{i}} \subset R_{i}$.

Recall that $x_{i}=e_{\gamma_{1}}+\cdots+e_{\gamma_{i}}$. For each $j \in[1, i]$, one may choose $e_{-\gamma_{j}} \in \mathfrak{I}(-1)$ so that $\left\{e_{\gamma_{j}}, h_{\gamma_{j}}, e_{-\gamma_{j}}\right\}$ is an $\mathfrak{s l}_{2}$-triple, where $h_{\gamma_{j}}=\left[e_{\gamma_{j}}, e_{-\gamma_{j}}\right]$. Then $\alpha\left(h_{\gamma_{j}}\right)=\left(\alpha, \gamma_{j}^{\vee}\right)$ for any $\alpha \in \Delta$. Set $y_{i}=e_{-\gamma_{1}}+\cdots+e_{-\gamma_{i}}$ and $h_{i}=h_{\gamma_{1}}+\cdots+h_{\gamma_{i}}$. Since the $\gamma_{j}$ 's are pairwise orthogonal and long, $\left[x_{i}, y_{i}\right]=h_{i}$ and $\left\{x_{i}, h_{i}, y_{i}\right\}$ is again an $\mathfrak{s l}_{2}$-triple. As is well-known, to any nilpotent element $x_{i} \in \mathbb{I}$ one associates the parabolic subgroup $P\left(x_{i}\right) \subset L$ such that $L_{x_{i}} \subset P\left(x_{i}\right)$. Although $P\left(x_{i}\right)$ depends only on $x_{i}$, the most simple description of it uses an $\mathfrak{s l}_{2}$-triple containing $x_{i}$ (see [14, III, Section 4]): The eigenvalues of ad $h_{i}$ are integral ( $\left[h_{i}, x_{i}\right]=2 x_{i}$ ) and Lie $P\left(x_{i}\right)$ is the sum of the eigenspaces corresponding to nonnegative eigenvalues. In our case, it easily follows from the definition of $h_{i}$ that Lie $P\left(x_{i}\right)=\bigoplus_{\mu} \mathrm{I}_{\mu}$, where the sum is taken over $\mu \in \Delta$ such that $\left(\mu, \gamma_{1}+\cdots+\gamma_{i}\right) \geq 0$. Comparing with the description of $R_{i}$, we see that $P\left(x_{i}\right) \cap G=R_{i}$. Thus, $G_{x_{i}}=L_{x_{i}} \cap G \subset P\left(x_{i}\right) \cap G=R_{i}$ and the mapping $\tau_{i}$ is birational.

Since the representation of $R_{i}$ on $V_{i}$ is completely reducible, it follows from [3, Thm. 0] that $\overline{\mathcal{O}}_{i}$ is normal and has rational singularities. That is, our construction of a resolution of singularities yields another proof of this well-known result.

In Proposition 2.2, the tangent space of $B x_{i}$ at $x_{i}$ was described. For future use, we compute now the tangent space of $G x_{i}$ at $x_{i}$.

Proposition 2.7 Set $\tilde{\Gamma}_{i}=\left\{\alpha \in \Delta(1) \mid\left(\alpha, \gamma_{1}+\cdots+\gamma_{i}\right)>0\right\}$. Then

$$
\left[\mathfrak{g}, x_{i}\right]=\bigoplus_{\alpha \in \tilde{\Gamma}_{i}} \mathrm{I}(1)_{\alpha} \quad \text { and this space is B-stable. }
$$

Proof The next observations are obvious consequences of Lemma 1.2:

- if $\mu \in \Delta(0)^{+}$, then the function $\mu \mapsto\left(\mu, \gamma_{1}+\cdots+\gamma_{i}\right)$ may take only two values 0 , $\frac{1}{2}(\gamma, \gamma)$.
- if $\alpha \in \Delta(1)$, then the function $\alpha \mapsto\left(\alpha, \gamma_{1}+\cdots+\gamma_{i}\right)$ may take only values $0, \frac{1}{2}(\gamma, \gamma)$, $(\gamma, \gamma)$.
Whence $\tilde{\Gamma}_{i}$ is the subset of $\Delta(1)$ corresponding to the values $\frac{1}{2}(\gamma, \gamma)$ and $(\gamma, \gamma)$. Since $x_{i}$ belongs to the sum of weight spaces corresponding to the value $(\gamma, \gamma)$, we see that $\left[\mathfrak{g}, x_{i}\right] \subset$ $\bigoplus_{\alpha \in \tilde{\Gamma}_{i}} \mathrm{I}(1)_{\alpha}$. On the other side, $\left[\mathfrak{g}, x_{i}\right] \supset\left[\mathfrak{b}, x_{i}\right]=\bigoplus_{\alpha \in \Gamma_{i}} \mathrm{I}(1)_{\alpha}$. Next, let $\nu \in \Delta(1)$ and $\left(\nu, \gamma_{1}+\cdots+\gamma_{i}\right)=\frac{1}{2}(\gamma, \gamma)$. Take the unique $m \in[1, i]$ such that $\left(\nu, \gamma_{m}\right) \neq 0$ (i.e., $\left.\left(\nu, \gamma_{m}\right)>0\right)$. Then $\mu:=\nu-\gamma_{m} \in \Delta(0)$ and $\left[e_{\mu}, x_{i}\right]=\left[e_{\mu}, e_{\gamma_{m}}\right]=e_{\nu} \in\left[\mathfrak{g}, x_{i}\right]$.

The second assertion easily follows from the definition of $\tilde{\Gamma}_{i}$.

For a subspace $M \subset \mathfrak{l}(1)$, we let $M^{\perp}$ denote the orthogonal complement to $M$ in $\mathfrak{l}(-1)$.
Corollary 2.8 $\left[\mathfrak{g}, x_{i}\right]^{\perp}=\bigoplus_{\alpha \in \Delta^{i}(-1)} \mathfrak{I}(-1)_{\alpha}$ and this space is $B$-stable.
Proof Recall from Section 1 that $\Delta^{i}=\left\{\alpha \in \Delta \mid\left(\alpha, \gamma_{1}\right)=\cdots=\left(\alpha, \gamma_{i}\right)=0\right\}$. The above discussion about functions with at most three values implies that $\left[\mathfrak{g}, x_{i}\right]^{\perp}=\bigoplus_{\alpha} \mathfrak{l}(-1)_{\alpha}$, where $\alpha$ ranges over all roots in $\Delta(-1)$ such that $\left(\alpha, \gamma_{1}+\cdots+\gamma_{i}\right)=0$. But for $\alpha \in \Delta(-1)$ the last equality implies that $\left(\alpha, \gamma_{1}\right)=\cdots=\left(\alpha, \gamma_{i}\right)=0$.

## 3 The Commuting Variety and a Double Coset Space

Define $\eta: \mathfrak{l}(1) \oplus \mathfrak{l}(-1) \rightarrow \mathfrak{l}(0)=\mathfrak{g}$ to be the restriction of the Lie bracket in $\mathfrak{I}$ to $\mathfrak{l}(1) \oplus \mathfrak{l}(-1)$, i.e., $\eta(x+y)=[x, y]$ for $x \in \mathfrak{I}(1), y \in \mathfrak{l}(-1)$. In this section we study properties of the generalized commuting variety $\mathfrak{E}:=\eta^{-1}(0)$.

It is well-known (and easy to prove) that $\mathfrak{I}(-1)_{x}$, the centralizer of $x \in \mathfrak{I}(1)$ in $\mathfrak{I}(-1)$, is nothing but $[\mathfrak{g}, x]^{\perp}$. Therefore $\mathfrak{F}$ is the union of the conormal bundles to the $G$-orbits in $\mathfrak{I}(1)$. Since any conormal bundle is of dimension $\operatorname{dim} I(1)$ and there are finitely many $G$-orbits in $\mathfrak{I}(1)$, $\mathfrak{C}$ is a variety of pure dimension $\operatorname{dim} \mathfrak{l}(1)$ and there is a bijection between the $G$-orbits in $\mathfrak{I}(1)$ and the irreducible components of $\mathfrak{E}$ : each irreducible component is the closure of the conormal bundle of a unique $G$-orbit. By symmetry, the same is true for $G$-orbits in $I(-1)$. Consequently, there is a natural bijection (duality) between the $G$-orbits in $I(1)$ and $I(-1)$. This is a particular case of Pyasetskii's theorem [11]. Given an orbit $\mathcal{O} \subset \mathfrak{l}(1)$, the dual orbit $\mathcal{O}^{\vee} \subset \mathfrak{I}(-1)$ can directly be described as follows. For an arbitrary $x \in \mathcal{O}$, take $[\mathfrak{g}, x]^{\perp}$ and then $G \cdot[\mathfrak{g}, x]^{\perp}$. The last set is irreducible and $\mathcal{O}^{\vee}$ is the dense orbit in it.

We use for $G$-orbits in $\mathfrak{I}(-1)$ the notation similar to that for $\mathfrak{I}(1)$. Namely, define $\mathcal{O}_{i}^{*}$ to be the orbit in $\mathrm{I}(-1)$ containing representatives of the form $e_{\mu_{1}}+\cdots+e_{\mu_{i}}$, where $\mu_{1}, \ldots, \mu_{i}$ are orthogonal long roots in $\Delta(-1)$.

Lemma 3.1 $\quad\left(\mathcal{O}_{i}\right)^{\vee}=\mathcal{O}_{r-i}^{*}$.
Proof Take $x_{i} \in \mathcal{O}_{i}$. By Corollary 2.8, the set of weights of $\left[\mathfrak{g}, x_{i}\right]^{\perp}$ is $\Delta^{i}(-1)$. Since it contains a sequence of orthogonal long roots of length $r-i\left(e . g .-\gamma_{i+1}, \ldots,-\gamma_{r}\right), \mathcal{O}_{r-i}^{*}$ has a nonempty intersection with $\left[\mathfrak{g}, x_{i}\right]^{\perp}$. Hence, denoting $\left(\mathcal{O}_{i}\right)^{\vee}=\mathcal{O}_{d(i)}^{*}$, we have $d(i) \geq r-i$. Because this holds for all $i$, one must have $d(i)=r-i$.

Corollary 3.2 Let $\mu_{1}, \ldots, \mu_{i}$ be an arbitrary sequence of orthogonal long roots in $\Delta(1)$. Let $\Psi=\left\{\alpha \in \Delta(1) \mid\left(\alpha, \mu_{1}\right)=\cdots=\left(\alpha, \mu_{i}\right)=0\right\}$ and $\mathfrak{l}(1)_{\Psi}=\bigoplus_{\alpha \in \Psi} \mathfrak{I}(1)_{\alpha}$. Then $\mathcal{O}_{r-i}$ is the dense orbit in $G \cdot I(1)_{\Psi}$.

Proof The argument for a part of the u.c.s. is given in the lemma (up to switching between $\mathfrak{I}(-1)$ and $\mathfrak{l}(1))$. As is easily seen, it applies to arbitrary sequences of orthogonal long roots as well.

Define $\mathfrak{C}_{i}$ to be the irreducible component of $\mathfrak{F}$ corresponding to $\mathcal{O}_{i}$. For instance, $\mathfrak{E}_{0}=\mathfrak{I}(-1)$ and $\mathfrak{E}_{r}=\mathfrak{l}(1)$. The previous lemma says the orbit in $\mathfrak{I}(-1)$ that corresponds to $\mathfrak{E}_{i}$ is $\mathcal{O}_{r-i}^{*}$.

From the point of view of the $G$-action, $\mathfrak{E}$ is the union of conormal bundles. The following is a kind of "global" characterization:

$$
\begin{equation*}
L \cdot \mathfrak{l}(1) \cap(\mathfrak{I}(1) \oplus \mathfrak{I}(-1))=\mathfrak{E} . \tag{3.3}
\end{equation*}
$$

Actually, we shall prove a more precise statement whose consequence is the above formula. To this end, recall some results from [12] and [9]. At the very beginning, we have introduced the parabolic subgroup $P$ with aura whose standard Levi factor is $G$. Since $I(1)$ is $P$-stable and $\mathrm{I}(1) \oplus \mathrm{I}(-1)$ is $G$-stable, it suffices to work with a system of representatives of $G \backslash L / P$ while studying $L \cdot \mathrm{I}(1) \cap(\mathrm{I}(1) \oplus \mathrm{I}(-1))$. The double coset space $G \backslash L / P$ is finite and a system of representatives is described in [12, Sect. 3]:

For each $i$ let $u_{-\beta_{i}}$ be a nontrivial element in the one-parameter unipotent subgroup $U_{-\beta_{i}}$ corresponding to $-\beta_{i}$, and let $w_{\beta_{i}}$ be the reflection in $W$ corresponding to $\beta_{i}$, realized as an element of $N_{L}(T)$. For $0 \leq i \leq j \leq r$, let $z_{i j}=\prod_{t=i+1}^{j} u_{-\beta_{t}} \cdot \prod_{s=1}^{i} w_{\beta_{s}}$. Then $L=\bigsqcup_{i, j} G z_{i j} P$. This description is valid with any maximal orthogonal sequence of long roots in $\Delta(1)$. For future convenience, we have stated it with the l.c.s. $\beta_{1}, \ldots, \beta_{r}$. Let $\mathcal{K}_{i j}=G z_{i j} P \subset L$. (Our indexing and notation differ from those of [12].)

We have the irreducible decomposition $\mathfrak{E}=\bigcup_{i=1}^{r} \mathfrak{E}_{i}$. Take any $i, j \in[1, r](i \leq j)$. By $[9,5.8], \mathfrak{E}_{i j}:=\mathfrak{E}_{i} \cap \mathfrak{E}_{j}$ is irreducible and $\mathfrak{F}_{i j}=\mathfrak{E} \cap\left(\overline{\mathcal{O}}_{i} \times \overline{\mathcal{O}_{r-j}^{*}}\right)$. Moreover, if $C$ is an irreducible $G$-stable subvariety of $\mathfrak{E}$ such that the projection of $C$ to $\mathfrak{I}(1)$ is $\overline{\mathcal{O}}_{i}$ and to $\mathfrak{I}(-1)$ is $\overline{\mathcal{O}_{r-j}^{*}}$, then $C=\mathfrak{\mathfrak { F }}_{i j}$.

Theorem 3.4 For $0 \leq i \leq j \leq r$, one has $\mathcal{K}_{i j} \cdot \mathfrak{l}(1) \cap(\mathfrak{l}(1) \oplus \mathfrak{I}(-1))=\mathfrak{E}_{r-j, r-i}$.
Proof Since $\mathcal{K}_{i j} \cdot \mathfrak{l}(1) \cap(\mathfrak{l}(1) \oplus \mathfrak{l}(-1))=G z_{i j} \cdot \mathfrak{l}(1) \cap(\mathfrak{l}(1) \oplus \mathfrak{l}(-1))=G \cdot\left\{z_{i j} \cdot \mathfrak{l}(1) \cap(\mathfrak{l}(1) \oplus\right.$ $\mathfrak{I}(-1))\}$, we need to realize what is $z_{i j} \cdot \mathfrak{l}(1)$. To simplify notation, let $u_{i j}=\prod_{t=i+1}^{j} u_{-\beta_{t}}$.

Then $z_{i j}=u_{i j} z_{i i}$. To understand the action of $z_{i j}$, let us introduce the partition of $\Delta(1)$ corresponding to the three values of the function $\alpha \mapsto\left(\alpha, \beta_{1}+\cdots+\beta_{i}\right)$ (cf. proof of 2.7):

$$
\Delta(1)=\bigsqcup_{m=0}^{2} \Delta(1)_{i, m}
$$

where $\Delta(1)_{i, m}:=\left\{\alpha \in \Delta(1) \left\lvert\,\left(\alpha, \beta_{1}+\cdots+\beta_{i}\right)=\frac{m}{2}(\beta, \beta)\right.\right\}$.
Consider the respective decomposition $\mathfrak{l}(1)=V_{i, 0} \oplus V_{i, 1} \oplus V_{i, 2}$. Then $z_{i i}$ acts trivially on $V_{i, 0}, z_{i i} \cdot V_{i, 1} \subset \mathfrak{I}(0)$, and $z_{i i} \cdot V_{i, 2} \subset \mathfrak{I}(-1)$. For $x=x_{0}+x_{1}+x_{2} \in \mathfrak{I}(1)$, we have $z_{i j} \cdot x=u_{i j}\left(x_{0}+z_{i i} \cdot x_{1}+z_{i i} \cdot x_{2}\right)$. The unipotent transformation $u_{i j}$ takes $x_{0}$ to $x_{0}+y+y^{\prime}$ for some $y \in \mathfrak{I}(0)$ and $y^{\prime} \in \mathfrak{I}(-1), z_{i i} \cdot x_{1}$ to $z_{i i} \cdot x_{1}+v$ for some $v \in \mathfrak{I}(-1)$, and $z_{i i} \cdot x_{2}$ to itself. It is easily seen that the summands lying in $\mathfrak{I}(0), z_{i i} \cdot x_{1}$ and $y$, are supported by disjoint sets of roots in $\Delta(0)$; see also Figure 1 . Hence the condition $z_{i j} \cdot x \in \mathfrak{l}(1) \oplus \mathfrak{l}(-1)$ forces $x_{1}=0$ and $y=0$. The last equality clearly implies that $y^{\prime}=0$. Then $z_{i j} \cdot x=x_{0}+z_{i i} \cdot x_{2}$ and the summands commute. This already proves the inclusion " $\subset$ " in 3.3. To prove the theorem in full strength, one has to look more carefully at those $x_{0} \in V_{i, 0}$ that are stabilized by $u_{i j}$. A straightforward calculation shows that $u_{i j} \cdot x_{0}=x_{0}$ if and only if $x_{0}$ is supported by those roots in $\Delta(1)_{i, 0}$ that are orthogonal to $\beta_{i+1}, \ldots, \beta_{j}$, i.e., $x_{0} \in V_{j, 0} \subset V_{i, 0}$.

Thus, the previous argument proves that $z_{i j} \cdot \mathrm{l}(1) \cap(\mathrm{l}(1) \oplus \mathrm{l}(-1))$ is the direct sum of the spaces $V_{j, 0} \subset \mathfrak{I}(1)$ and $V_{i, 2}^{*}:=z_{i i} \cdot V_{i, 2} \subset \mathfrak{I}(-1)$. I claim that both these spaces are $B$-stable, $G \cdot V_{j, 0}=\overline{\mathcal{O}}_{r-j}$, and $G \cdot V_{i, 2}^{*}=\overline{\mathcal{O}_{i}^{*}}$.
(a) For $V_{i, 2}^{*}$ : Note that the set of weights of $V_{i, 2}^{*}$ is just $-\Delta(1)_{i, 2}=\{\alpha \in \Delta(-1) \mid$ $\left.\left(\alpha,-\beta_{1}-\cdots-\beta_{i}\right)=(\beta, \beta)\right\}$. Therefore for $V_{i, 2}^{*}$ holds the analogue of Proposition 2.2: if one takes the point $y_{i}=e_{-\beta_{1}}+\cdots+e_{-\beta_{i}} \in \mathcal{O}_{i}^{*}$, then $V_{i, 2}^{*}=\left[\mathfrak{b}, y_{i}\right]$ and so on. This is because $-\beta_{1}, \ldots,-\beta_{r}$ is the u.c.s. with respect to $\mathrm{I}(-1)$.
(b) For $V_{j, 0}$ : We again perform an argument that uses "dual" (or " $I(-1)$ ") versions of some previous results. Take $y_{j}=e_{-\beta_{1}}+\cdots+e_{-\beta_{j}} \in \mathcal{O}_{j}^{*}$. Then $\left[\mathfrak{g}, y_{j}\right]^{\perp}=V_{j, 0}$ and this space is $B$-stable (analogue of 2.8). Therefore the dense orbit in $G \cdot V_{j, 0}$ is $\left(\mathcal{O}_{j}^{*}\right)^{\vee}$, i.e., $\mathcal{O}_{r-j}$ (analogue of 3.1).

The various spaces involved in the proof are depicted in Figure 1. It is the real picture for $\mathfrak{I}=\mathfrak{s l}_{N}$ and $\mathfrak{g}=\mathfrak{s l}_{N-r} \times \mathfrak{s l}_{r} \times k$ with $N-r>r$. The shaded strips have width $j-i$. These represent the space that consists of the $\mathfrak{I}(0)$-components of vectors $u_{i j} \cdot x_{0}\left(x_{0} \in V_{i, 0}\right)$. Finally, the LHS in 3.4 is $G \cdot\left(V_{j, 0} \oplus V_{i, 2}^{*}\right)$. It follows from the above claims that it is a $G$-stable closed subset in $\mathfrak{E}$ and its projection to $\mathfrak{I}(1)$ (resp. $\mathfrak{l}(-1)$ ) is the closure of $\mathcal{O}_{r-j}$ (resp. $\mathcal{O}_{i}^{*}$ ). By a result in [9, 5.8, 5.10], which is stated just before Theorem 3.4, this means the variety in question is $\mathfrak{E}_{r-j, r-i}$.

Remarks 1. As a by-product of the proof, we have the following: if $x \in \mathfrak{I}(1)$ and $g \cdot x \in$ $\mathfrak{l}(1) \oplus \mathfrak{I}(-1)$, then there exists a decomposition $x=x^{\prime}+x^{\prime \prime}\left(x^{\prime}, x^{\prime \prime} \in \mathfrak{l}(1)\right)$ such that $g \cdot x^{\prime} \in \mathfrak{I}(1)$ and $g \cdot x^{\prime \prime} \in \mathfrak{I}(-1)$.
2. One may think of $\mathcal{K}_{i j}$ 's as the $G \times P$-orbits in $L$. By [12, 3.7], $\overline{\mathcal{K}_{i j}}=\bigcup_{i \leq s \leq t \leq j} \mathcal{K}_{s t}$. On the other side, it was proved in $[9,5.10]$ that each $G$-orbit in $\mathfrak{E}$ is dense in some $\mathfrak{E}_{i j}$ and, denoting such orbit $\mathcal{O}_{i j}$, one has $\overline{\mathcal{O}_{i j}}=\bigcup_{s \leq i \leq j \leq t} \mathcal{O}_{s t}$. Theorem 3.4 establishes thus a geometric order-reversing bijection between these two posets. The respective Hasse diagrams in case $r=5$ are depicted in Figure 3.


Figure 1


Figure 2

Taking into account the previous convention on indexing the irreducible components of $\mathfrak{E}$, one sees that $\mathcal{O}_{i r}=\mathcal{O}_{i}$, the orbit in $\mathfrak{I}(1)$, and $\mathcal{O}_{0, r-i}=\mathcal{O}_{i}^{*}$, the orbit in $\mathfrak{I}(-1)$.

The set $\left\{\mathcal{O}_{i j}\right\}$ has an interesting connection with some nilpotent $L$-orbits in I. To describe it, let us look at the short grading from another point of view. The decomposition $\mathfrak{I}=\mathfrak{I}_{0} \oplus \mathfrak{I}_{1}$, where $\mathfrak{I}_{0}=\mathfrak{I}(0)$ and $\mathfrak{I}_{1}=\mathfrak{I}(1) \oplus \mathfrak{I}(-1)$, is a $\mathbb{Z}_{2}$-grading. The principal results on "orbits and invariants" associated with $\mathbb{Z}_{2}$-gradings are due to Kostant and Rallis [4]. Some complementary results, which are also valid for more general gradings, are due to E. B. Vinberg [15]. Later, we need the following properties:

- if $z \in \mathfrak{I}_{1}$, then $\operatorname{dim} L \cdot z=2 \operatorname{dim} G \cdot z$, see [4, Prop. 5].
- if $\tilde{\mathcal{O}} \subset \mathfrak{I}$ is any $L$-orbit, then each irreducible component of $\tilde{\mathcal{O}} \cap \mathfrak{l}_{1}$ is a $G$-orbit. The same is true for $\tilde{\mathcal{O}} \cap \mathfrak{l}(1)$. (See [15, Lemma in Section 2]).

Let us start with a $G$-orbit $\mathcal{O}_{i} \subset \mathfrak{I}(1)$. It generates the $L$-orbit $\tilde{\mathcal{O}}_{i}=L \cdot \mathcal{O}_{i}$. The question is what is $\tilde{\mathcal{O}}_{i} \cap \mathfrak{I}_{1}$ ? An immediate consequence of the aforementioned properties is that $\mathcal{O}_{i}$
is an irreducible component of this intersection and that $\operatorname{dim} \tilde{\mathcal{O}}_{i}=2 \operatorname{dim} \mathcal{O}_{i}$. It is also clear that $\mathcal{O}_{i}^{*}$ is another component of the intersection. The complete answer is given by the following

Theorem 3.5 $\quad \tilde{\mathcal{O}}_{i} \cap \mathfrak{l}_{1}=\bigsqcup_{s=0}^{i} \mathcal{O}_{s, r-i+s}$.

Proof By 3.3, the LHS lies in $\mathfrak{E}$. Being $G$-stable, it is the union of some $\mathcal{O}_{s t}$. To realize which $\mathcal{O}_{s t}$ do occur, it suffices to find out what is the dense $L$-orbit in $L \cdot \mathfrak{E}_{s t}$. Keep the notation of the proof of 3.4. It was shown therein that $\mathfrak{E}_{r-j, r-i}=G \cdot\left(V_{j, 0} \oplus V_{i, 2}^{*}\right)$ for $r-j \leq r-i$. Since $z_{i i} \in L$ takes $V_{i, 2}^{*}$ to $V_{i, 2}$ and $V_{j, 0}$ to itself, we have $L \cdot \mathfrak{E}_{r-j, r-i}=$ $L \cdot\left(V_{j, 0} \oplus V_{i, 2}\right)$. Invoking the definition of the sets $\Delta(1)_{i, m}$ and Lemma 1.2(ii), one sees that the set of weights of $V_{j, 0} \oplus V_{i, 2}$, say $\Gamma_{i, j}$, is contained in the set of weights in $\Delta(1)$ that are orthogonal to $\beta_{i+1}, \ldots, \beta_{j}$. On the other side, $\Gamma_{i, j}$ contains an orthogonal sequence of length $r-j+i$. It then follows from 2.1 and 3.2 that $\mathcal{O}_{r-j+i} \cap\left(V_{j, 0} \oplus V_{i, 2}\right)$ is dense in $V_{j, 0} \oplus V_{i, 2}$ and therefore $\tilde{\mathcal{O}}_{r-j+i}$ is dense in $L \cdot \mathfrak{E}_{r-j, r-i}$. Thus, $L \cdot \mathcal{O}_{r-j, r-i}=\tilde{\mathcal{O}}_{r-(r-i)+(r-j)}$, which is exactly what is needed.

Corollary 3.6 Dimension of $\mathfrak{E}_{i j}$ depends only on $j-i$.
Proof Indeed, $\operatorname{dim} \mathfrak{E}_{i j}=\operatorname{dim} \mathcal{O}_{i j}=\frac{1}{2} \operatorname{dim} \tilde{\mathcal{O}}_{r-j+i}$.

Recall that the $\mathfrak{F}_{i j}$ 's were defined as the intersection of two irreducible components of $\mathfrak{E}: \mathfrak{E}_{i j}=\mathfrak{E}_{i} \cap \mathfrak{E}_{j}$. We have thus obtained a surprising result that dimension of the intersection depends only on "distance" between irreducible components. Looking at the Hasse diagram of the poset $\mathfrak{E}$, we see that the components of the intersection $\tilde{\mathcal{O}}_{i} \cap \mathfrak{l}(1)$ occupy the $i$-th row, and the Corollary says that dimension is constant along the rows.

Our last goal in this section is to construct a $G$-equivariant resolution of $\mathfrak{F}_{i j}$. Since $\mathfrak{E}_{i j} \subset \mathfrak{I}(1) \oplus \mathfrak{I}(-1)$ projects onto $\overline{\mathcal{O}}_{i}$ and $\overline{\mathcal{O}_{r-j}^{*}}$ respectively, it is natural to suggest that a resolution we are searching for has something to do with known resolutions of both orbit closures. And this is really so. A resolution of $\overline{\mathcal{O}}_{i}$ is constructed in Section 2 and a resolution of $\overline{\mathcal{O}_{r-j}^{*}}$ can be described in the "dual" fashion. We reproduce the essential steps just in order to fix the related notation. Let $y_{r-j}=e_{-\beta_{1}}+\cdots+e_{-\beta_{r-j}} \in \mathcal{O}_{r-j}^{*}$. The string $-\beta_{1}, \ldots,-\beta_{r}$ plays the same rôle for $\mathfrak{I}(-1)$ as the u.c.s. for $\mathfrak{I}(1)$. Therefore the following analogues of Proposition 2.2 and Theorem 2.6 hold: $V_{r-j}^{*}:=\left[\mathfrak{b}, y_{r-j}\right]$ is $B$-stable and the mapping $\tau_{j}^{*}: G *_{R_{r-j}^{*}} V_{r-j}^{*} \rightarrow \overline{\mathcal{O}_{r-j}^{*}}$, where $R_{r-j}^{*}$ is the normalizer in $G$ of $V_{r-j}^{*}$, is a $G$ equivariant resolution of singularities. Set $R_{i j}:=R_{i} \cap R_{r-j}^{*}$. It is a standard parabolic subgroup of $G$ and $V_{i} \oplus V_{r-j}^{*}$ is a $R_{i j}$-module. Before stating the next theorem, it is worth to observe a relationship between the spaces $V_{i}, V_{r-j}^{*}$ that are needed for resolutions of singularities and the spaces $V_{i, m}$ depicted in Figure 1. The proofs are easy and left to the reader.

- $V_{r-j} \subset V_{j, 0}$ and these are equal if and only if the equivalent conditions of 1.5 hold.
- $V_{i, 2}^{*}=V_{i}^{*}$.

Theorem 3.7 Let $1 \leq i \leq j \leq r$. Then
(i) The natural mapping $\tau_{i j}: G *_{R_{i j}}\left(V_{i} \oplus V_{r-j}^{*}\right) \rightarrow \mathfrak{E}_{i j}$ is a $G$-equivariant resolution of singularities;
(ii) the $R_{i j}$-module $V_{i} \oplus V_{r-j}^{*}$ is completely reducible.

Proof (i) $z_{r-j, r-j}=\prod_{s=1}^{r-j} w_{\beta_{s}}$ takes $V_{r-j}^{*}$ into I(1) and keeps $V_{i}$ intact. (The inequality $i \leq j$ is needed at this point.) Therefore $V_{i} \oplus V_{r-j}^{*} \subset \mathfrak{E}$. Hence the image of $\tau_{i j}$ is a $G$-stable irreducible subvariety of $\mathfrak{E}$. By construction, its projection to $\mathfrak{l}(1)$ (resp. $\mathfrak{l}(-1)$ ) is $\overline{\mathcal{O}}_{i}$ (resp. $\overline{\mathcal{O}_{r-j}^{*}}$ ). Thus, the image has to be equal to $\mathfrak{E}_{i j}$. Since $G_{x_{i}} \subset R_{i}$ and $G_{y_{r-j}} \subset R_{r-j}^{*}$, we have $G_{x_{i}+y_{r-j}}=G_{x_{i}} \cap G_{y_{r-j}} \subset R_{i j}$. This inclusion guarantees us birationality of $\tau_{i j}$, for the $G$-orbit of $x_{i}+y_{r-j}$ is dense in $\mathfrak{E}_{i j}$.
(ii) The unipotent radical of $R_{i j}$ is the product of the unipotent radicals of $R_{i}$ and $R_{r-j}^{*}$. By symmetry, it suffices to show that $N_{i}$, the unipotent radical of $R_{i}$, acts trivially on $V_{i} \oplus V_{r-j}^{*}$. By 2.5, $N_{i}$ acts trivially on $V_{i}$. A similar argument applies to $V_{r-j}^{*}$ : all the roots $\mu$ corresponding to $V_{r-j}^{*}$ satisfy the condition $\left(\mu, \gamma_{1}+\cdots+\gamma_{i}\right)=0$, while $\left(\nu, \gamma_{1}+\cdots+\gamma_{i}\right)>0$ for each $\nu \in \Delta\left(N_{i}\right)$. Since $\left(\alpha, \gamma_{1}+\cdots+\gamma_{i}\right) \leq 0$ for each $\alpha \in \Delta(-1)$, we have $\nu+\mu$ is never a root.

Again, as a consequence of Kempf's theorem and complete reducibility, we get the assertion that the varieties $\mathfrak{E}_{i j}$ are normal and have rational singularities. Another proof is found in [9].

## 4 The Algebra of Covariants on $I(1)$ and Beyond

Let $U$ be the unipotent radical of $B$. It is well known that the algebra of covariants $k[\mathrm{l}(1)]^{U}$ is polynomial. For instance, it already follows from the fact that $\mathrm{I}(1)$ is a spherical $G$-module (for, the $B$-orbit of $e_{\beta_{1}}+\cdots+e_{\beta_{r}}$ is dense in $I(1)$ ). There are plenty of papers, where this algebra is explicitly described, see e.g. [13], [2], [5]. Nevertheless, I believe Theorem 4.1 yet deserves to be stated and proved. In this section, the description of $k[l(1)]^{U}$ will be obtained as a consequence of a restriction theorem (see [6, Section 2] for representations and a general version in [7, Section 1]).

Denote by $F$ the subspace of $\mathrm{I}(1)$ with basis $e_{\beta_{1}}, \ldots, e_{\beta_{r}}$. Let $f_{1}, \ldots, f_{r}$ be the coordinates in this basis.

Theorem 4.1 The restriction homomorphism $k[1(1)] \rightarrow k[F]$ maps $k[\mathrm{I}(1)]^{U}$ isomorphically and $T$-equivariantly onto the subalgebra generated by $f_{1}, f_{1} f_{2}, \ldots, f_{1} \cdots f_{r}$.

We postpone a bit the proof and show that the theorem immediately implies the basic properties of $k[l(1)]^{U}$.

## Corollary 4.2

1. $k[\mathrm{I}(1)]^{U}$ is polynomial and the weights of $T$-homogeneous free generators are $\lambda_{1}, \ldots, \lambda_{r}$, where $\lambda_{i}=-\left(\beta_{1}+\cdots+\beta_{i}\right)$.
2. The $G$-module $k[\mathrm{I}(1)]$ is multiplicity free and if $\lambda=\sum_{i=1}^{r} a_{i} \lambda_{i}\left(a_{i} \in \mathbb{Z}_{\geq 0}\right)$, then the simple $G$-module with highest weight $\lambda$ occurs in the space of polynomials of degree $\sum_{i=1}^{r} i a_{i}$.

Proof of 4.1 Roughly speaking, the restriction theorem for $U$-invariants applies as follows:

1. One has to find generic stabilizer for the $G$-module $\mathfrak{l}(1) \oplus \mathfrak{l}(-1)$. Of course, such a stabilizer is determined up to a conjugation in $G$. We need the so-called "canonical" generic stabilizer that can be determined via an explicit procedure. Let $S$ be the canonical stabilizer. It is a reductive subgroup of $G$, which is normalized by $T$.
2. Form the connected reductive group $Z_{G}(S)^{0}$. Then $\tilde{U}:=U \cap Z_{G}(S)^{0}$ is a maximal unipotent subgroup in it.
3. The restriction theorem says that the restriction homomorphism $k[l(1)] \rightarrow k\left[l(1)^{S}\right]$ maps $k[\mathrm{I}(1)]^{U}$ isomorphically and $T$-equivariantly onto the algebra $\left(k\left[\mathrm{l}(1)^{S}\right]^{\tilde{U}}\right)_{\mathcal{T}}$, where $\mathcal{T}$ is the monoid consisting of those dominant weights of $G$ that vanish on $T \cap S$ and the subscript " $\mathcal{T}$ " means that one takes only weight spaces whose weights lie in $\mathcal{T}$.

An inductive procedure for finding $S$ is described in [6, Section 1]. In our case, it amounts essentially to constructing the l.c.s. Indeed, one starts with the (unique) lowest weight vector $e_{\beta_{1}} \in \mathfrak{I}(1)$. Let $\hat{G}_{1}$ be the standard Levi factor of the parabolic subgroup stabilizing the line $\left\langle e_{\beta_{1}}\right\rangle$ and let $\mathfrak{l}(1)_{1}$ be the $\hat{G}_{1}$-stable complement to [ $\left.\mathfrak{g}, e_{\beta_{1}}\right]$. Then $\Delta\left(\hat{G}_{1}\right)$ consists of all roots in $\Delta(0)$ that are orthogonal to $\beta_{1}$. A specific feature of the "Abelian" situation is that the set of weights of $\mathfrak{l}(1)_{1}$ coincide with $\Delta_{1}(1)$ (see notation in 1.1). Therefore on the second step one has the unique lowest weight vector $e_{\beta_{2}}$ and so on $\ldots$. The procedure terminates when one arrives at the Levi subgroup $\hat{G}_{r} \subset G$ and no further lowest weight vectors are available. The root system of $\hat{G}_{r}$ is $\Delta_{r}(0)$ in the notation of 1.1. Then

$$
\begin{equation*}
S=\left\{g \in \hat{G}_{r} \mid \beta_{i}(g)=1, i=1, \ldots, r\right\} \tag{4.3}
\end{equation*}
$$

Here the $\beta_{i}$ 's are being considered as characters of $\hat{G}_{r}$.

## Lemma 4.4

(i) $\mathrm{I}(1)^{S}=F$;
(ii) $Z_{G}(S)^{0}$ is the central torus in $\hat{G}_{r}$.

Proof (i) Since the roots of $\hat{G}_{r}$ are orthogonal to $\beta_{1}, \ldots, \beta_{r}$, we have $\mathfrak{l}(1)^{S} \supset F$. On the other side, $\mathfrak{l}(1)^{S \cap T}=\bigoplus_{\alpha \in M} \mathfrak{l}(1)_{\alpha}$, where $M=\Delta(1) \cap\left(\mathbb{Z} \beta_{1}+\cdots+\mathbb{Z} \beta_{r}\right)=\left\{\beta_{1}, \ldots, \beta_{r}\right\}$.
(ii) It suffices to prove that $N_{G}(S)^{0}=\hat{G}_{r}$. Clearly, $N_{G}(S)^{0} \supset \hat{G}_{r}$. Conversely, it is easy to see that the root system of $N_{G}(S)^{0}$ is $\Delta_{r}(0)=\Delta\left(\hat{G}_{r}\right)$.

It follows that $k[\mathrm{I}(1)]^{U}$ is isomorphic to $k[F]_{\mathcal{T}}$ and it remains to realize what is $\mathcal{T}$. Denote by $\mathcal{X}(T)_{+}$the monoid of dominant weights of $G$ (relative to $U$ ). It follows from Equation 4.3 and part 3 in the exposition of the restriction theorem that $\mathcal{T}=X(T)_{+} \cap$ $\left(\mathbb{Z} \beta_{1}+\cdots+\mathbb{Z} \beta_{r}\right)$.

Lemma 4.5

$$
\begin{aligned}
X(T)_{+} & \cap\left(\mathbb{Z} \beta_{1}+\cdots+\mathbb{Z} \beta_{r}\right) \\
& = \begin{cases}\mathbb{Z}_{\geq 0}\left(-\beta_{1}\right)+\cdots+\mathbb{Z}_{\geq 0}\left(-\beta_{1}-\cdots-\beta_{r}\right), & \text { if } \beta_{r} \neq \gamma, \\
\mathbb{Z}_{\geq 0}\left(-\beta_{1}\right)+\cdots+\mathbb{Z}_{\geq 0}\left(-\beta_{1}-\cdots-\beta_{r-1}\right)+\mathbb{Z}\left(-\beta_{1}-\cdots-\beta_{r}\right), & \text { if } \beta_{r}=\gamma .\end{cases}
\end{aligned}
$$

Proof An equivalent formulation is: Let $l_{i} \in \mathbb{Z}$. Then $\sum_{i=1}^{r} l_{i} \beta_{i} \in \mathcal{X}(T)_{+}$if and only if $l_{1} \leq l_{2} \leq \cdots \leq l_{r} \leq 0$ in the first case or $l_{1} \leq l_{2} \leq \cdots \leq l_{r}$ in the second case.
(a) It follows from Corollary 1.3 that $\lambda_{i}=-\beta_{1}-\cdots-\beta_{i}$ lies in $\mathcal{T}$. If $\beta_{r}=\gamma$, then $\lambda_{r}=-2 \varphi$ is orthogonal to $\Delta(0)$ (see Proposition 1.5) and in this case the coefficient of $\lambda_{r}$ can be arbitrary. This proves the inclusion " $\supset$ " in both cases.
(b) Suppose $\lambda=\sum_{i} l_{i} \beta_{i} \in X(T)_{+}$. By the first part, $\lambda+a \lambda_{r} \in X(T)_{+}$for any $a \geq 0$. Taking $a \gg 0$, one may assume that all $l_{i}-a<0$. Let $\sigma$ be a permutation such that $l_{\sigma(1)} \leq l_{\sigma(2)} \cdots \leq l_{\sigma(r)}$. By [12, 2.8], any permutation of the sequence $\beta_{1}, \ldots, \beta_{r}$ can be achieved by some element in $W(0)$. Take $w \in W(0)$ that realizes the permutation $\sigma^{-1}$, i.e., $w . \beta_{i}=\beta_{\sigma^{-1}(i)}$. Then $w .\left(\lambda+a \lambda_{r}\right)=w . \lambda+a \lambda_{r}=\sum_{i=1}^{r}\left(l_{\sigma(i)}-a\right) \beta_{i}$. It then follows from the first part of proof that $w \cdot\left(\lambda+a \lambda_{r}\right) \in \mathcal{X}(T)_{+}$. Therefore $w \cdot\left(\lambda+a \lambda_{r}\right)=\lambda+a \lambda_{r}$ and hence $w \cdot \lambda=\lambda$. That is, $l_{1} \leq \cdots \leq l_{r}$. This is enough for the second case. In the first case, i.e., if $\beta_{r} \neq \gamma$, we see that there exists $\alpha \in \Delta(0)^{+}$such that $\left(\alpha, \beta_{1}\right)=\cdots=\left(\alpha, \beta_{r-1}\right)$ and $\left(\alpha, \beta_{r}\right)<0$ (by the very definition of the l.c.s.). Then the condition $(\alpha, \lambda) \geq 0$ implies $l_{r} \leq 0$.

Anyway, the dichotomy in the Lemma 4.5 does not affect the description of $k[F]_{\mathcal{T}}$, for the condition $l_{r} \leq 0$ is automatically satisfied for the weights of all monomials in $k[F]$. Since the function $f_{i}$ has weight $-\beta_{i}$, it follows that $k[F]_{\mathcal{T}}=k\left[f_{1}, f_{1} f_{2}, \ldots, f_{1} \cdots f_{r}\right]$. Thus, Theorem 4.1 is proved.

Theorem 4.6 $k[\mathrm{l}(1)]$ is a free $k[\mathrm{l}(1)]^{U}$-module.
Proof Obviously, the weights $\lambda_{i}(i=1, \ldots, r)$ are linearly independent. Another property satisfied by them is that if $\left(\alpha, \lambda_{j}\right)>0$ for some $\alpha \in \Pi(0)$ and $j \in[1, r]$, then $\left(\alpha, \lambda_{m}\right)=0$ for all $m \neq j$. Indeed, this follows from Lemma 1.2 and Theorem 1.4. For, $\left(\alpha, \lambda_{j}\right)>0$ implies $\left(\alpha, \beta_{j}\right)<0$. If $j<r$, then $\left(\alpha, \beta_{j+1}\right)>0$ and these two inner products are the only nonzero ones. If $j=r$, then one has the unique nonzero product and again everything is clear.

An equivalent formulation of the second property is that each simple reflection $w_{\alpha} \in$ $W(0)$ affects at most one weight $\lambda_{j}: \#\left\{j \mid w_{\alpha} \cdot \lambda_{j} \neq \lambda_{j}\right\} \leq 1$ for each $\alpha \in \Pi(0)$. It then follows from Theorem 5.5 and these two properties of the $\lambda_{i}$ 's that $k[\mathrm{l}(1)]$ is a flat $k[\mathrm{l}(1)]^{U}$ module. As is well known, the word "flat" can be replaced by "free" in the graded situation.

## 5 On Equidimensional Quotient Mappings

This section is completely independent of the previous parts. We will work with $G$ without an overgroup $L$ and therefore the notation will partially be changed (simplified). Here $G$ is a connected reductive algebraic group and $U \subset G$ is a maximal unipotent subgroup; $B=N_{G}(U)=T U$. For an affine $G$-variety $X$, our aim is to prove a sufficient condition for $k[X]$ to be a flat $k[X]^{U}$-module.

First, consider a special class of $G$-varieties. For any dominant weight $\lambda$, let $V_{\lambda}$ denote the corresponding irreducible $G$-module and $v_{\lambda} \in V_{\lambda}$ a highest weight vector. Let $\lambda_{1}, \ldots, \lambda_{r}$ be linearly independent dominant weights. Set $V=:\left\langle v_{\lambda_{1}}\right\rangle \oplus \cdots \oplus\left\langle v_{\lambda_{r}}\right\rangle \subset$ $V_{\lambda_{1}} \oplus \cdots \oplus V_{\lambda_{r}}$. Then $V$ is $B$-stable and its normalizer in $G$ is a standard parabolic
subgroup, say $P$. Let $C:=\overline{G \cdot V} \subset V_{\lambda_{1}} \oplus \cdots \oplus V_{\lambda_{r}}$. These and even more general varieties-when $\lambda_{1}, \ldots, \lambda_{r}$ are arbitrary-have been studied in [16]. We shall use the result that in our case the $G$-orbits in $C$ corresponds to the subsets of $[1, r]$. Namely, $\left\{v_{J}:=\sum_{j \in J} v_{\lambda_{j}} \mid J \subset[1, r]\right\}$ is a set of representatives of the $G$-orbits. Since $\lambda_{1}, \ldots, \lambda_{r}$ are linearly independent, the algebra $k[C]^{U}$ is polynomial, of Krull dimension $r$. It will be more convenient for us to work with $k[C]^{U_{-}}$, where $U_{-}$is opposite to $U$. Denoting by $x_{i}$ the coordinate in $v_{\lambda_{i}}$ for a (any) weight basis of $V_{\lambda_{i}}$, we have $k[C]^{U_{-}} \simeq k\left[x_{1}, \ldots, x_{r}\right]$. In other words, the restriction homomorphism $k[C] \rightarrow k[V]$ induces an isomorphism $k[C]^{U_{-}} \simeq k[V]$.

Let $W$ denote the Weyl group of $G, w_{1}, \ldots, w_{n}$ the simple reflections in $W$, and $l: W \rightarrow$ $\mathbb{Z}_{\geq 0}$ the usual length function.

## Theorem 5.1 The following conditions are equivalent:

(i) $\pi_{C}: C \rightarrow C / / U_{-}$is equidimensional;
(ii) $\#\left\{j \mid w_{i} \cdot \lambda_{j} \neq \lambda_{j}\right\} \leq 1$ for each $i \in[1, n]$.

We need a description of the $U_{-}$-orbits in $G / P$. It is similar with that of $U$-orbits, but the presentation requires some alterations. Let $I \subset[1, n]$ be the set corresponding to the simple roots of the standard Levi factor of $P$. Set $W_{I}=\left\langle w_{i} \mid i \in I\right\rangle$ and $W_{I}^{\prime \prime}=\{w \in W \mid$ $\left.l\left(w w_{i}\right)<l(w) \forall i \in I\right\}$. It is easy to see that $W_{I}^{\prime \prime}$ is the set of representatives of maximal length for $W / W_{I}$. For $w \in W_{I}^{\prime \prime}$, let $\mathcal{O}(w)=U_{-} w P \subset G / P$. Let $\Delta$ be the root system of $G$ and $\Delta_{I}$ the root system of the Levi factor of $P$. The following lemma is an easy consequence of the well-known properties of the set of representatives of minimal length.

## Lemma 5.2

1. If $w_{I}^{o}$ is the longest element in $W_{I}$ and $w \in W_{I}^{\prime \prime}$, then $w w_{I}^{o}$ is the representative of minimal length and $l\left(w w_{I}^{o}\right)=l(w)-l\left(w_{I}^{o}\right)=l(w)-\# \Delta_{I}^{+}$.
2. $w \in W_{I}^{\prime \prime}$ if and only if $w\left(\Delta_{I}^{+}\right) \subset \Delta^{-}$;
3. the natural map $W_{I}^{\prime \prime} \times W_{I} \rightarrow W,\left(w^{\prime \prime}, w\right) \mapsto w^{\prime \prime} w$ is bijective;
4. $G / P=\bigsqcup_{w \in W_{1}^{\prime \prime}} \mathcal{O}(w)$;
5. $\operatorname{dim} \mathcal{O}(w)=\operatorname{dim} U-l(w)$.

Proof of 5.1 Since $C$ is a cone, equidimensionality of $\pi=\pi_{C}$ is equivalent to the fact that $\operatorname{dim} \pi^{-1} \pi(0)=\operatorname{dim} C-r=\operatorname{dim} G / P$. Let $\mathfrak{N}=\pi^{-1} \pi(0)$. Our main tool for estimating $\operatorname{dim} \mathfrak{N}$ is the following diagram:

where $\phi(g * v):=g P$ and $\tau(g * v):=g \cdot v$. It is easily seen that $\tau$ is a resolution of singularities of $C$. First, deduce a useful formula related to the diagram. It is assumed that each $w \in W$
is realized as an element of $N_{G}(T)$. Let $\bar{g} \in \mathcal{O}(w) \subset G / P$, where $w \in W_{I}^{\prime \prime}$. That is, $\bar{g}=\tilde{u} w P$ for some $\tilde{u} \in U_{-}$. Then

$$
\begin{aligned}
\phi^{-1}(\bar{g}) \cap \tau^{-1}(\mathfrak{M}) & =\left\{(\tilde{u} w * v) \in G *_{P} V \mid x_{j}(\tilde{u} w \cdot v)=0 \quad \forall j\right\} \\
& =\left\{(\tilde{u} w * v) \in G *_{P} V \mid\left(w^{-1} \cdot x_{j}\right)(v)=0 \quad \forall j\right\} .
\end{aligned}
$$

It follows that $\phi^{-1}(\bar{g}) \cap \tau^{-1}(\mathfrak{R})$ is isomorphic to a subspace in $V$ of dimension $\#\left\{j \mid w . \lambda_{j} \neq\right.$ $\left.\lambda_{j}\right\}$. Therefore

$$
\begin{equation*}
\operatorname{dim}\left\{\phi^{-1}(\mathcal{O}(w)) \cap \tau^{-1}(\mathfrak{M})\right\}=\operatorname{dim} \mathcal{O}(w)+\#\left\{j \mid w \cdot \lambda_{j} \neq \lambda_{j}\right\} \tag{5.3}
\end{equation*}
$$

(ii) $\Rightarrow$ (i). Since both the number of $G$-orbits in $C$ and of $U_{-}$-orbits in $G / P$ is finite, it suffices to prove that

$$
\operatorname{dim}\left\{\tau\left(\phi^{-1}(\mathcal{O}(w))\right) \cap \mathfrak{N} \cap G \cdot v_{J}\right\} \leq \operatorname{dim} G / P
$$

for any $w \in W_{I}^{\prime \prime}$ and $J \subset[1, r]$. Actually, it will be proven that

$$
\begin{equation*}
\operatorname{dim}\left\{\phi^{-1}(\mathcal{O}(w)) \cap \tau^{-1}\left(\Re \cap G \cdot v_{J}\right)\right\} \leq \operatorname{dim} G / P \tag{5.4}
\end{equation*}
$$

These two inequalities are equivalent for the dense $G$-orbit, i.e., for $J=[1, r]$, because $\tau$ is bijective over it, while for all other $G$-orbits the second inequality is stronger.

Suppose $g \cdot v_{J} \in \mathfrak{N}$ for $g=\tilde{u} w p\left(\tilde{u} \in U_{-}, w \in W_{I}^{\prime \prime}\right.$, and $\left.p \in P\right)$, that is, $x_{j}\left(w p \cdot v_{J}\right)=0$ for all $j$. This implies $w \cdot \lambda_{j} \neq \lambda_{j}$ for $j \in J$. However, it may happen that also $w \cdot \lambda_{i} \neq \lambda_{i}$ for some $i \notin J$. I claim that $l(w) \geq \#\left\{j \mid w \cdot \lambda_{j} \neq \lambda_{j}\right\}+\# \Delta_{I}^{+}$. Indeed, $l(w)=l\left(w w_{I}^{o}\right)+\# \Delta_{I}^{+}$(see Lemma 5.2(1)) and one still has $w w_{I}^{o} . \lambda_{j} \neq \lambda_{j}$ for the same set of indices $j$, since $w_{I}^{o} \cdot \lambda_{i}=\lambda_{i}$ for all $i \in[1, r]$. Now, condition (ii) implies $l\left(w w_{I}^{o}\right) \geq \#\left\{j \mid w \cdot \lambda_{j} \neq \lambda_{j}\right\}$. In other words, if $g \cdot v_{J} \in \mathfrak{N}$, then $\bar{g} \in G / P$ belongs to a $U_{-}$-orbit $\mathcal{O}(w)$ which is of codimension $\geq \#\left\{j \mid w \cdot \lambda_{j} \neq \lambda_{j}\right\}$ in $G / P$. Thus, Equation 5.4 follows from Equation 5.3.
(i) $\Rightarrow$ (ii). Suppose (ii) is not satisfied. Then there exists a subset $K \subset[1, n] \backslash I$ such that $\# K<r$ and $w \cdot \lambda_{j} \neq \lambda_{j}$ for all $j$, where $w=\prod_{i \in K} w_{i}$. Clearly $w . \alpha \in \Delta^{+}$for any $\alpha \in \Delta_{I}^{+}$. Hence $w^{\prime \prime}:=w w_{I}^{o} \in W_{I}^{\prime \prime}$ and $l\left(w^{\prime \prime}\right)<r+\# \Delta_{I}^{+}$. It then follows from Equation 5.3 and the previous part of the proof that

$$
\operatorname{dim}\left\{\phi^{-1}\left(\mathcal{O}\left(w^{\prime \prime}\right)\right) \cap \tau^{-1}\left(\mathfrak{M} \cap G \cdot v_{[1, r]}\right)\right\}=\operatorname{dim} U-l\left(w^{\prime \prime}\right)+r>\operatorname{dim} G / P
$$

Since $\tau$ is bijective over $G \cdot v_{[1, r]}$, we also have

$$
\operatorname{dim}\left\{\tau\left(\phi^{-1}\left(\mathcal{O}\left(w^{\prime \prime}\right)\right)\right) \cap \mathfrak{N} \cap G \cdot v_{[1, r]}\right\}>\operatorname{dim} G / P
$$

Thus, $\operatorname{dim} \mathfrak{N}>\operatorname{dim} G / P$.
Remarks 1. It is not hard to realize that the above proof yields the following conclusions as well: if $\pi$ is equidimensional, then each irreducible component of $\mathfrak{M}$ has a nonempty intersection with the dense $G$-orbit in $C$ and the number of irreducible components is equal to the number of $w \in W$ such that $l(w)=r$ and $w \cdot \lambda_{i} \neq \lambda_{i}$ for all $i \in[1, r]$.
2. Since $C / / U$ is an affine space and $C$ has rational singularities by [3, Thm. 0], the equidimensionality condition is equivalent to $\pi_{C}$ being flat.

The next theorem applies to a wider class of varieties. However, it provides only a sufficient condition of flatness.

Theorem 5.5 Let $X$ be an affine $G$-variety such that $k[X]^{U}$ is polynomial and $\lambda_{1}, \ldots, \lambda_{r}$ the weights of $T$-homogeneous free generators of $k[X]^{U}$. Suppose $\lambda_{1}, \ldots, \lambda_{r}$ are linearly independent and $\#\left\{j \mid w_{i} . \lambda_{j} \neq \lambda_{j}\right\} \leq 1$ for each $i \in[1, n]$. Then $k[X]$ is a flat $k[X]^{U}$-module.

Proof By the assumptions of the theorem, $k[X]$ is a multiplicity free $G$-module, i.e., $X$ is a spherical $G$-variety. In particular, $k[X]^{G}=k$ and $X$ has a dense $G$-orbit. The following argument uses deformation results from [10] (see also [8]). We refer to that paper for precise definitions and generalities concerning gr $X$, etc.

By $\left[10\right.$, Section 5], there exists a $G$-variety $Y$ and a $q \in k[Y]^{G}$ such that $k[Y] /(q-a) \simeq$ $k[X]$ for any $a \in k^{*}, k[Y]\left[q^{-1}\right] \simeq k[X]\left[q, q^{-1}\right]$, and $k[Y] /(q) \simeq k[g r X]$. One can take the last equality as a definition of the $G$-variety $\mathrm{gr} X$. But the meaning of this construction is that $\operatorname{gr} X$ can be defined directly via a filtration of $k[X]$ and that it enjoys a number of nice properties. In our case, $\operatorname{gr} X=C$ is the variety considered above. (It stems from the following facts: gr $X$ is again spherical, $k[g r X]^{U} \simeq k[X]^{U}$, and the stabilizer of a point in the dense $G$-orbit in gr $X$ contains a maximal unipotent subgroup.) We need some details concerning $Y$. One considers an ascending filtration of $k[X]$ :

$$
\{0\} \subset k[X]_{(0)} \subset k[X]_{(1)} \cdots \subset k[X]_{(n)} \cdots .
$$

The whole description is unimportant for us now, we shall only use the fact that $k[X]_{(0)} \simeq$ $k[X]^{G}$, which is just $k$ in our situation. Then $k[Y]$ is defined as the following subalgebra of $k[X][q]$ :

$$
k[Y]:=\bigoplus_{n=0}^{\infty} k[X]_{(n)} q^{n} .
$$

Let $f_{1}, \ldots, f_{r}$ be free generators of $k[X]^{U}$. Define $m_{i}$ to be the least integer such that $f_{i} \in$ $k[X]_{\left(m_{i}\right)}$. It is then easy to see that $k[Y]^{U} \simeq k\left[q, q^{m_{1}} f_{1}, \ldots, q^{m_{r}} f_{r}\right]$ is a polynomial algebra, of Krull dimension $r+1$. One has the following commutative diagram:


Looking at it, one sees that $(\Omega=) \pi_{C}^{-1}\left(\pi_{C}(0)\right)=\pi_{Y}^{-1}\left(\pi_{Y}(0)\right)$, where $0 \in C \in Y$ is the unique $G \times k^{*}$-fixed point in $Y\left(k^{*}\right.$ acts on $\mathbb{A}^{1}$ and hence on $Y$ by homotheties).

From Theorem 5.1, it then follows that $\operatorname{dim} \pi_{Y}^{-1}\left(\pi_{Y}(0)\right)=\operatorname{dim} Y-\operatorname{dim} Y / / U$. The algebra $k[Y]$ is $\mathbb{Z}_{\geq 0}$-graded and $k[Y]_{0}=k[X]_{(0)}=k$, therefore $\pi_{Y}$ is equidimensional. By [10, Thm. 6], $Y$ has rational singularities and in particular is Cohen-Macaulay. Hence $k[Y]$ is a flat $k[Y]^{U}$-module. Taking localisation, one obtains $k[Y]\left[q^{-1}\right] \simeq k[X] \otimes k\left[q, q^{-1}\right]$ and $k[Y]^{U}\left[q^{-1}\right] \simeq k[X]^{U} \otimes k\left[q, q^{-1}\right]$. Whence, $k[X]$ is a flat $k[X]^{U}$-module.

## Appendix

Now $G$ is a simple algebraic group and $U \subset G$ is as above. We give the classification of irreducible representations $V$ such that $k[V]$ is a free $k[V]^{U}$-module. As is well known, the last condition implies that $k[V]^{U}$ is polynomial. Representations with polynomial algebras of covariants were classified by M. Brion. Therefore our task is to look through the table on p .13 in [1] and to realize for which representations in it $\pi_{V}$ is equidimensional, i.e., free generators of $k[V]^{U}$ form a regular sequence in $k[V]$. Brion's table contains 19 items and we numerate them according to their ordering in the table.

1. For items $1-3,5-8,10,13,14,16$, and 18 , flatness follows by Theorem 5.5. For, $V$ is a spherical $G \times k^{*}$-module in these cases ( $k^{*}$ acts by homotheties) and the weights of the generators are as required. Note that items $1-3,5,6,10,13,14$, and 18 arise from parabolic subgroups with aura.
2. For all other items, free generators of $k[V]^{U}$ do not form a regular sequence. Namely, one can always find a triple of generators $f_{1}, f_{2}, f_{3} \in k[V]^{U}$ such that $f_{3}=d_{1} f_{2}-d_{2} f_{1}$ for some $d_{1}, d_{2} \in k[V]$. The argument, which applies to all cases, relies on the fact that there exist always 2 generators of the same fundamental weight $\varphi_{i}$ and a third generator of weight $2 \varphi_{i}-\alpha_{i}$, where $\alpha_{i}$ is the simple root corresponding to $\varphi_{i}$. For instance, consider $G=\mathrm{Sp}_{6}$ and $V=V_{\varphi_{3}}$. We exploit the following generators of $k[V]^{U}: f_{1}$ of degree 1 and weight $\varphi_{3}, f_{2}$ of degree 3 and weight $\varphi_{3}$, and $f_{3}$ of degree 4 and weight $2 \varphi_{2}$. The generators are determined, up to a scalar factor, by degree and weight in this (and any other) case. The functions $f_{1}, f_{2}$ generate isomorphic $G$-submodules in $k[V]$. Introduce "one level down" vectors $d_{i}:=e_{-\alpha_{3}} f_{i}(i=1,2)$ in these modules, $e_{\alpha}$ being a nonzero root vector in $\mathfrak{g}$. Then $d_{1} f_{2}-d_{2} f_{1}$ has degree 4 and weight $2 \varphi_{3}-\alpha_{3}=2 \varphi_{2}$. Obviously, it is a nonzero $U$-invariant and therefore, up to a scalar factor, it is equal to $f_{3}$.

A posteriori, the classification can be stated in the following nice form:
Theorem A. 1 For an irreducible representation $V$ of a simple algebraic group $G$, the following conditions are equivalent:
(1) $k[V]$ is a free $k[V]^{U}$-module;
(2) A generic $G$-orbit in $V$ is spherical.
(It is not hard to prove that the second condition implies $k[V]^{U}$ is polynomial.) However, implication $(2) \Rightarrow(1)$ is no longer true for semisimple groups. For instance, let $G=\mathrm{SL}_{4} \times \mathrm{Sp}_{4}$ and let $V$ be the tensor product of tautological 4-dimensional representations. The same idea as above allows us to isolate a suitable triple of generators and then to prove that $\pi_{V}$ is not equidimensional. It is likely that (1) always implies (2), but I was unable to find a proof.

## References

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[^1]:    ${ }^{1}$ If $\nu=\sum_{\alpha \in \Pi} n_{\alpha} \alpha$, then $\operatorname{supp}(\nu)=\left\{\alpha \mid n_{\alpha} \neq 0\right\}$.

