# AN EMBEDDING THEOREM FOR BALANCED INCOMPLETE BLOGK DESIGNS 

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1. Introduction. From a symmetric balanced incomplete block design we may construct a derived design by deleting a block and its varieties. But a design with the parameters of a derived design may not be embeddable in a symmetric design. Bhattacharya (1) has such an example with $\lambda=3$. When $\lambda=1$, the derived design is a finite Euclidean plane and this can always be embedded in a corresponding symmetric design which will be a finite projective plane.

In this paper it is shown that for $\lambda=2$ as well as for $\lambda=1$ a design with the parameters of a derived design is indeed embeddable in a symmetric design. The methods used depend on techniques developed in (2). It is interesting to note that for $k=4$ the entire embedding was carried out by Nandi (3).
2. General conditions for embedding. A balanced incomplete block design with parameters $v, b, r, k$, and $\lambda$ satisfying

$$
\begin{equation*}
b k=v r, \quad r(k-1)=(v-1) \lambda \tag{2.1}
\end{equation*}
$$

is symmetric if $v=b$. From a symmetric design $S$, a derived design $D^{\prime}$ may be obtained by deleting a block $B_{0}$ and the varieties of $\mathrm{B}_{0}$ throughout. This leaves a design $D^{\prime}$ with parameters $v^{\prime}=v-k, b^{\prime}=b-1, r^{\prime}=r, k^{\prime}=k-\lambda$, and $\lambda^{\prime}=\lambda$. Since $r=k$ in the symmetric design, $r^{\prime}=k^{\prime}+\lambda^{\prime}$ in the derived design. Thus, for every derived design $D^{\prime}$ the parameters satisfy

$$
\begin{gathered}
r^{\prime}=k^{\prime}+\lambda^{\prime}, \quad v^{\prime} \lambda^{\prime}=k^{\prime}\left(k^{\prime}+\lambda^{\prime}-1\right), \\
b^{\prime} \lambda^{\prime}=\left(k^{\prime}+\lambda^{\prime}\right)\left(k^{\prime}+\lambda^{\prime}-1\right) .
\end{gathered}
$$

It is not difficult to state conditions on a design with appropriate parameters so that it is recognizable as a derived design of some symmetric design. These conditions follow:

Theorem 2.1 design $D$ with parameters satisfying

$$
\begin{equation*}
r=k+\lambda, \quad v \lambda=k(k+\lambda-1), \quad b \lambda=(k+\lambda)(k+\lambda-1) \tag{2.2}
\end{equation*}
$$

can be embedded as a derived design in a symmetric design if and only if we can find in $D$ sets of blocks $S_{j}, j=1, \ldots, k+\lambda$, such that:

[^0](1) Each $S_{j}$ consists of $k+\lambda-1$ blocks of $D$.
(2) The blocks of an $S_{j}$ together contain each variety of $D \lambda$ times.
(3) Any two distinct sets $S_{i}, S_{j}$ have exactly $\lambda-1$ blocks in common.
(4) Any block of $D$ is in precisely $\lambda$ sets $S_{j}$.

Proof. Let us adjoin to $D$ new varieties $x_{1}, \ldots, x_{k+\lambda}$ and a new block $B_{0}$ consisting of these varieties. We also adjoin the variety $x_{j}$ to all blocks of the set $S_{j}$ and to no other blocks. Then the new array $S$ contains $b^{*}=b+1$ blocks and $v^{*}=v+k+\lambda$ varieties. The block $B_{0}$ contains $k+\lambda$ varieties and by (4) we have adjoined just $\lambda$ new varieties to each old block. Hence, in $S$ each block contains $k^{*}=k+\lambda$ varieties. Each old variety appeared $r=k+\lambda$ times and each new variety $x_{j}$ appears once in $B_{0}$ and in the $k+\lambda-1$ blocks of $S_{j}$. Hence, in $S$ each variety appears $k+\lambda=r^{*}$ times. Finally, in $D$ each pair $d_{i}, d_{j}$ occurred together $\lambda$ times; by (2) a new $x_{j}$ occurs with each $d_{i}$ of $D$ $\lambda$ times and by (3) a new pair $x_{i}, x_{j}$ occurs together in $\lambda-1$ old blocks and once in the new block $B_{0}$. Thus every pair in $S$ occurs together $\lambda$ times. $S$ is seen to be a balanced incomplete block design, and as $r^{*}=k^{*}, S$ is a symmetric design.

Conversely, if we drop from a symmetric design $S$ a block $B_{0}$ and all of the varieties of $B_{0}$, we may readily verify that the blocks of $S$ containing a suppressed variety $x_{j}$ form in the derived design $D$ a set of blocks $S_{j}$, and the sets $S_{j}$ have all of the properties mentioned in the theorem.
3. The embedding theorems for $\lambda=1$ and $\lambda=2$. Not every design $D$ with parameters satisfying the relations (2.2) satisfies the embedding conditions. Since it is known that any two distinct blocks of a symmetric design intersect in $\lambda$ varieties, a design $D$ cannot possibly be embedded if it has two blocks intersecting in more than $\lambda$ varieties. Such an example with $\lambda=3, v=16$, $b=24, r=9$, and $k=6$ was found by Bhattacharya (1) and is listed in (2). In this example there are two blocks with four varieties in common.

When $\lambda=1$, the design $D$ is readily seen to be a finite Euclidean plane and it is well known that every such plane can be embedded in a finite projective plane, this being the corresponding symmetric design. This known result and the absence of a counter-example for $\lambda=2$ comparable to that for $\lambda=3$ suggested the embedding theorem for $\lambda=2$ which is the main part of this paper. The embedding theorem for $\lambda=1$ will be included here not as a new result but as an indication of the general motivation of the more complicated embedding theorem for $\lambda=2$.

Theorem 3.1 Every design $D$ with parameters $v=k^{2}, b=k^{2}+k, r=k+1$, and $\lambda=1$ satisfies the conditions of Theorem 2.1 and has a unique embedding in a symmetric design $S$.

Proof. Let $B_{1}$ be an arbitrary block of $D$ whose varieties are $a_{1}, a_{2}, \ldots, a_{k}$. If $c$ is any variety of $D$ not in $B_{1}$, then there are $k$ blocks containing the pairs $c a_{1}, c a_{2}, \ldots, c a_{k}$ and these are distinct since no $a_{i}, a_{j}$ occur together except in
$B_{1}$. This accounts for $k$ of the $k+1$ blocks containing $c$. Thus there is exactly one block $B_{2}$ containing $c$ and no variety of $B_{1}$. Let the varieties of $B_{2}$ be $c$, $c_{2}, \ldots, c_{k}$. Then $B_{2}$ is, for each of $c_{2}, \ldots, c_{k}$, equally the unique block containing this variety and none from $B_{1}$. Hence, in all there will be blocks $B_{2}, \ldots, B_{k}$ containing the $k^{2}-k$ varieties of $D$ not in $B_{1}$, and no one of $B_{2}, \ldots, \mathrm{~B}_{k}$ intersects $B_{1}$ in a variety. Moreover, no two of these $B$ 's have a variety in common with each other since each is the unique block for each of its varieties not intersecting $B_{1}$. The blocks $B_{1}, \ldots, B_{k}$ form a set $S_{1}$ of $k$ blocks which together contain each variety once. Moreover, each block determines uniquely such a set of $k$ non-intersecting blocks and there will be in all $k+1$ sets $S_{1}, \ldots$, $S_{k+1}$ and these sets have the properties required by Theorem 2.1 . We note finally that $D$ determines these sets uniquely and so the embedding is unique.

For $\lambda=2$ the same result holds but the proof is much harder.
Theorem 3.2 Every balanced incomplete block design $D$ with parameters

$$
v=\frac{1}{2} k(k+1), \quad b=\frac{1}{2}(k+1)(k+2), \quad r=k+2, \quad \lambda=2
$$

satisfies the conditions of Theorem 2.1 and can be embedded uniquely in a symmetric design.

The proof given in the following sections will not cover the case $k=6$, shown to be impossible in (2). Nor will it cover the case $k=2$, and so we shall always exclude this case without further mention. It is easy to verify by replacement of the varieties in the blocks that the theorem is true for $k=2$. Throughout the proof we shall suppose that $D$ exists.
4. Some relations among the blocks of $\mathbf{D}$. In this section we shall quote some lemmas from (2) and shall develop one new lemma, all of which will be useful later.

Let two blocks of $D$ which have $u$ varieties in common be called " $u$ th associates." Then we may paraphrase Lemma 4.1 of (2) as follows:

Lemma 4.1 Any block of $D$ has $2 k$ first associates, $\frac{1}{2} k(k-1)$ second associates, and zero sth associates $(s \neq 1,2)$.

Next consider any two initial blocks of $D$, say $B_{1}$ and $B_{2}$. Any other block of $D$ is of "type 1 " if it is a second associate of both $B_{1}$ and $B_{2}$, of "type 2 " if it is a second associate of one of $B_{1}$ and $B_{2}$ but a first associate of the other, and of "type 3 " if it is a first associate of both $B_{1}$ and $B_{2}$. Now we may paraphrase Lemma 4.2 of (2), thus:

Lemma 4.2 If two initial blocks of $D$ are first associates, then there are $\frac{1}{2}(k-1)(k-2)$ blocks of type $1,2(k-1)$ blocks of type 2 , and $k$ blocks of type 3. If two initial blocks of $D$ are second associates, then there are $\frac{1}{2}(k-2)(k-3)$ blocks of type $1,4(k-2)$ blocks of type 2, and 4 blocks of type 3 .

Next we shall consider the structural matrices which correspond to three sets of blocks. In each matrix there is an unknown element, which we shall
determine under the condition that the corresponding set of blocks forms part of $D$. The first matrix is

$$
S_{6}=\left[\begin{array}{llllll}
k & 1 & 1 & 1 & 1 & 2  \tag{4.1}\\
& k & 1 & 2 & 2 & 1 \\
& & k & 2 & 2 & 1 \\
& & & k & s_{45} & 2 \\
& & & & k & 2 \\
& & & & & k
\end{array}\right]
$$

which corresponds to a set $U_{6}$ of blocks. We desire to know whether 1 or 2 or both are admissible values for $s_{45}$ to assume if $U_{6}$ forms a part of $D$.

Associated with $S_{6}$ is the characteristic matrix $C_{6}$, which has the elements $c_{j j}=2 k$ and $c_{j u}=k-2$ or $-4(j \neq u)$ according as $s_{j u}=1$ or 2 , where $j$ and $u$ refer to the $j$ th and $u$ th blocks of $U_{6}$. Hence, our problem is to decide whether $k-2$ or -4 or both are admissible values for $c_{45}$ to assume.

We obtain the determinant

$$
\begin{align*}
\left|C_{6}\right| & =4(k+2)^{3}\left(2 k-c_{45}\right)\left[(k-2) c_{45}+2(k-6)\right]  \tag{4.2}\\
& =4(k+2)^{3} f_{1} f_{2}
\end{align*}
$$

where $f_{1}=\left(2 k-c_{45}\right)$ and $f_{2}=(k-2) c_{45}+2(k-6)$. Now by Theorem 3.1 of (2) it is necessary that $\left|C_{6}\right| \geqslant 0$. For any $k, 4(k+2)^{3}>0$. Hence, either (a) $f_{1} \leqslant 0$ and $f_{2} \leqslant 0$, or (b) $f_{1} \geqslant 0$ and $f_{2} \geqslant 0$. Since (a) implies that $2 k \leqslant c_{45}$, which is impossible, we must have (b), whence

$$
\begin{equation*}
c_{45} \geqslant-2+8 /(k-2) \tag{4.3}
\end{equation*}
$$

which has the minimum, -2 . Hence it is necessary that $c_{45}=k-2$, and therefore that $s_{45}=1$. This result is contained in the following lemma.

Lemma 4.3 If $D$ contains the blocks of $U_{6}$, then in $S_{6}, s_{45}=1$.
We shall state two other lemmas, which can be proved by arguments analagous to those used in proving Lemma 4.3. Proofs of these lemmas are given in (2). Our Lemmas 4.4 and 4.5 correspond respectively to Lemmas 4.4 and 4.5 of (2).

Consider a set of blocks, $U_{5}{ }^{(1)}$, which has the structural matrix

$$
S_{5}^{(1)}=\left[\begin{array}{lllll}
k & 1 & 1 & 2 & 2  \tag{4.4}\\
& k & 1 & 1 & 1 \\
& & k & 1 & 1 \\
& & & k & s_{45} \\
& & & & k
\end{array}\right] .
$$

We may state a lemma about $s_{45}$.

[^1]Lemma 4.4 If $D$ contains the blocks of $U_{5}^{(1)}$, then in $S_{5}^{(1)}, s_{45}=1$.
Finally, consider a set of blocks, $U_{5}{ }^{(2)}$, which has the structural matrix

$$
S_{5}^{(2)}=\left[\begin{array}{lllll}
k & 1 & 1 & 1 & 2  \tag{4.5}\\
& k & 1 & 2 & 1 \\
& & k & 2 & 1 \\
& & & k & s_{45} \\
& & & & k
\end{array}\right]
$$

The related lemma follows:
Lemma 4.5 If $D$ contains the blocks of $U_{5}{ }^{(2)}$, then in $S_{5}{ }^{(2)}, s_{45}=2$.
5. The sets which are determined by a block and its first associates. We shall consider an arbitrary block $B_{1}$ of $D$ and its $2 k$ first associates. It will be shown that these $2 k+1$ blocks are uniquely separable into two sets $S_{1}$ and $S_{2}$ of $k+1$ blocks which pairwise are first associates and which have only $B_{1}$ in common. To show this we shall determine the structural matrix of a certain set of $k+2$ blocks.

Let any block be $B_{1}$. Then, by Lemma $4.1, B_{1}$ has $2 k$ first associates: $B_{2}$, $B_{3}, \ldots, B_{2 k+1}$. Let us focus our attention on any one of these, say $B_{2}$. By Lemma 4.2, regarding $B_{1}$ and $B_{2}$ as initial blocks, there are $\frac{1}{2}(k-1)(k-2)$ blocks of type $1,2(k-1)$ blocks of type 2 , and $k$ blocks of type 3 among the remaining blocks of $D$. So without loss of generality we may write down two rows of the structural matrix $S_{b}$ of $D$ as follows:

$$
\begin{array}{lll|l|l|l|l}
k & 1 & 1 & 1 \ldots & 1 \ldots 1 & 2 \ldots 2 & 2 \ldots 2  \tag{5.1}\\
1 & k & 1 & \ldots .1 & 2 \ldots 2 & 2 \ldots 2 & \ldots \ldots 1
\end{array}
$$

where the columns correspond in left-to-right order to blocks $B_{1}, B_{2}, \ldots, B_{b}$. For convenience we have partitioned $S_{b}$ in left-to-right order into submatrices $A, B, C, D, E$, where $A$ contains 3 columns, $D$ contains $\frac{1}{2}(k-1)(k-2)$ columns, and $B, C, E$ each contain $k-1$ columns.

Let the blocks $B_{3}, \ldots, \mathrm{~B}_{k+2}$ comprise a set $M$, and the blocks $B_{k+3}, \ldots$, $B_{0_{k+1}}$ comprise a set $N$. We shall show that there exists one block of $M$ which is a first associate of two or more blocks of $N$. To show this we shall count the number of ones in the submatrix $C^{*}$ which consists of rows $3, \ldots, k+2$ of $C$. Since every block of $N$ is a first associate of $B_{1}$, it follows from Lemma 4.2 and the observation that there are $k-1$ twos in row 2 of $C$ that there are $(k-1)(k-2)$ twos and hence $2(k-1)$ ones in $C^{*}$. But there are $k$ rows in $C^{*}$, and so there is at least one row of $C^{*}$, say the row corresponding to $B_{3}$, which contains two or more ones.

Now consider how the third row of $S_{b}$ may be filled up. By considering $B_{1}$ and $B_{3}$ as initial blocks, Lemma 4.2 applies. Also, by considering $B_{2}$ and $B_{3}$ as initial blocks, the lemma applies. These considerations do not fully determine the third row of $S_{b}$, but do exclude all possibilities except the following. If there
are $j$ twos in row 3 of $C(j=0, \ldots, k-3)$, then there are $k-j-1$ twos in row 3 of $B, \frac{1}{2}(k-1)(k-2)-j$ twos in row 3 of $D$, and $j$ twos in row 3 of $E$.

Now consider $S_{k+2}$, the structural matrix of the blocks which correspond to the columns of $A$, the $j$ columns of $C$ which have 2 in row 3 , and the $k-j-1$ columns of $E$ which have 1 in row 3 , i.e.,

$$
S_{k+2}=\left[\begin{array}{ccc|c|c}
k & 1 & 1 & 1 \ldots 1 & 2 \ldots 2  \tag{5.2}\\
& k & 1 & 2 \ldots 2 & 1 \ldots 1 \\
& & k & 2 \ldots 2 & 1 \ldots 1 \\
\hline & & & F & G \\
\hline & & & & H
\end{array}\right]
$$

where $F$ and $H$ have $k$ in the main diagonal, but the other elements of $F, G$, and $H$ are so far unknown but will now be determined. Comparisons of the structure of $S_{k+2}$ with the structures of $S_{6}, S_{5}^{(1)}, S_{5}^{(2)}$ shows that Lemmas 4.3, 4.4, and 4.5 apply, and hence the non-diagonal elements of $F$ and $H$ are 1, and the elements of $G$ are 2.

Corresponding to $S_{k+2}$ is the characteristic matrix $C_{k+2}$, which has $2 k$ in the main diagonal and $k-2$ or -4 elsewhere, according as $S_{k+2}$ has 1 or 2 in the corresponding position. Calculating $\left|C_{k+2}\right|$, which is readily done with the help of Lemma 3.1 of (2), we obtain

$$
\begin{equation*}
\left|C_{k+2}\right|=j(j-k+2)(k-6)(k+2)^{k+1} . \tag{5.3}
\end{equation*}
$$

Now by Theorem 3.1 of (2), $\left|C_{k+2}\right|=0$. From (5.3), noting that $0 \leqslant j \leqslant k-3$ and that $k+2>b-v=k+1$, it follows that $\left|C_{k+2}\right|=0$ when and only when $j=0$ or $k=6$. The case $k=6$ was disposed of in (2).

Let $j=0$. Then by Lemma 4.4, the blocks of $N$ pairwise are first associates, and the blocks of $M$ other than $B_{3}$ pairwise are first associates. Thus $B_{1}$ and its $2 k$ first associates uniquely determine two sets of $k+1$ blocks which pairwise are first associates. The sets are $S_{1}\left(B_{1}, B_{2}, B_{4}, \ldots, B_{k+2}\right)$ and $S_{2}\left(B_{1}, B_{3}, B_{k+3}\right.$, $\left.\ldots, B_{2 k+1}\right)$. We summarize in the following lemma.

Lemma 5.1 Any block $B_{1}$ and its $2 k$ first associates uniquely comprise two sets $S_{1}$ and $S_{2}$ of $k+1$ blocks which pairwise are first associates and have only one common element, $B_{1}$.
6. Conclusion. We have shown that there exist sets $S_{j}$ which satisfy (1) and (4) of Theorem 2.1. To show that there are $k+2$ sets $S_{j}$ in all, we observe that since every block occurs in precisely two sets $S_{j}$, and each set contains $k+1$ blocks, the number $n$ of sets satisfies $2 b=n(k+1)$, whence $n=k+2$. Further, because any one of the $b=\frac{1}{2}(k+1)(k+2)$ blocks is the unique block in common to two unordered sets $S_{i}, S_{j}$, each of the unordered pairs of sets will have a different block in common and thus any two sets will have one and only one block in common. Thus, the sets $S_{j}$ satisfy (3) of Theorem 2.1.

To prove (2) of Theorem 2.1, let $m_{i}$ denote the number of treatments which are replicated $i$ times in an $S_{j}$. Then the following relations are necessary:

$$
\begin{aligned}
& \sum_{i=0}^{k+1} m_{i}=v=\frac{1}{2} k(k+1) \\
& \sum_{i=0}^{k+1} i m_{i}=k(k+1) \\
& \sum_{i=0}^{k+1} i(i-1) m_{i}=k(k+1)
\end{aligned}
$$

where the last relation arises because every two blocks of $S_{j}$ are first associates. Now consider the function

$$
Q(i)=\sum_{i=0}^{k+1} m_{i}(i-2)^{2}
$$

By (6.1), $Q(i)=0$, which implies that $i=2$, since $m_{i} \geqslant 0(i=0,1, \ldots$, $k+1)$ and

$$
\sum_{i=0}^{k+1} m_{i}>0
$$

This completes the proof of all properties of the sets $S_{\text {, }}$ required for Theorem 2.1 and incidentally their uniqueness and so in turn the uniqueness of the embedding.

## References

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[^0]:    Received March 19, 1953. Theorem 3.2 was proved independently by both authors. Upon learning of this by correspondence they decided to write the present joint paper, which is a synthesis of the two original manuscripts.

[^1]:    ${ }^{1}$ In (2) it was stated that "the equations of 4.6 may be solved to determine the number of blocks of types $11, \ldots, 32$." However, since the six equations 4.6 are dependent, one cannot obtain the individual $x_{i j}$ 's but only the needed linear combinations thereof.

