Journal of the Marine Biological Association of the United Kingdom

cambridge.org/mbi

Research Article

Cite this article: Rayner J, Embling CB, Ryan C, Hartny-Mills L (2024). Minke whale entanglement in static fishing gear: identifying consistent areas of high risk in Western Scotland. Journal of the Marine Biological Association of the United Kingdom 104, e15, 1–12. https://doi.org/10.1017/S0025315423000930

Received: 6 November 2022 Revised: 1 October 2023 Accepted: 17 November 2023

Keywords

bycatch; conservation; entanglement; fisheries; habitat modelling; management; risk; Scotland; static gear; whale

Corresponding author:

Jessica Rayner; Email: jessicarayner1@gmail.com

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Minke whale entanglement in static fishing gear: identifying consistent areas of high risk in Western Scotland

Jessica Rayner¹, Clare B. Embling¹, Conor Ryan^{2,3} and Lauren Hartny-Mills³

¹Marine Conservation Research Group, School of Biological and Marine Sciences, University of Plymouth, Drake Circus, Plymouth PL4 8AA UK; ²Scottish Association for Marine Science (SAMS), Argyll PA37 1QA, UK and ³Hebridean Whale and Dolphin Trust, 28 Main Street, Tobermory PA75 6NU, UK

Abstract

Entanglement in static fishing gear is the largest cause of non-natural mortality for minke whales (Balaenoptera acutorostrata) in Scottish waters. To mitigate whale entanglement, one priority is to identify areas where the risk of entanglement is consistently high. Sightings data for minke whales and creel fleets were collected by the Hebridean Whale and Dolphin Trust, during vessel line transect surveys conducted between 2008 and 2014. Habitat modelling was used to relate survey, environmental, and temporal variables to the co-occurrence of minke whales and creels in coastal waters of western Scotland. This revealed that minke whale occurrence was related to depth, peaking around 70 m. Using predictive habitat modelling, the overlap between minke whale habitat and the creel fishery was measured as risk of entanglement. A method was developed to quantify the consistency of risk over the seven-year time period. This allowed for the identification of areas where there had been a consistently low, medium, or high risk of entanglement from 2008 to 2014. The three areas with a consistent high risk of entanglement were identified: Inner Sound and Sound of Raasay, east of North and South Uist, and north of The Small Isles. The method presented here could be used to guide management to areas where mitigation efforts will be the most consistently effective over time.

Introduction

Entanglement in static fishing gear is one of the leading causes of whale mortality globally (Read et al., 2006; Parsons et al., 2010; Meyers et al., 2011; Berkenbusch et al., 2013; Thomas et al., 2016). In particular, creel (also known as the crate or pot) fisheries have been frequently associated with baleen whale entanglement (Kraus, 1990; Lien, 1994; Caswell et al., 1999; Robbins and Mattila, 2001; Johnston et al., 2005; Neilson et al., 2009; Meyers et al., 2011; Kraus et al., 2014) given their spatial overlap with whale habitats. Whale entanglement is a concern for animal welfare as well as conservation. During an entanglement, if unable to free itself, a whale may die of: asphyxiation through failure to reach the surface to breathe (Laist, 1987); an inability to forage (Cassoff et al., 2011; Moore and Van der Hoop, 2012); or in the case of larger whales, increased energy expenditure due to trailing gear (Van der Hoop et al., 2016). Entanglement in creel lines can also cause severe injuries such as haemorrhaging, blood vessel lacerations, or the embedding of rope into bone, all of which can be fatal (Meyers et al., 2011). Moreover, the high stress of an entanglement incident can have chronic effects, such as reduced reproductive output and life span (Meyers et al., 2011). Certain whale populations are seriously threatened by entanglement, such as the endangered North Atlantic right whale (Eubalaena glacialis) population in the Northwest Atlantic, and humpback whale (Megaptera novaeangliae) populations in Southeast Alaska and east coast of the USA (Cole et al., 2006; Cassoff et al., 2011; Knowlton et al., 2022).

In Scotland, entanglement is the largest cause of non-natural mortality in baleen whales and is unsustainable in the case of humpback whales (Northridge et al., 2010; Ryan et al., 2016; MacLennan et al., 2020). From interviewing fishers, it was estimated that 30 minke whales are entangled annually in Scottish waters (MacLennan et al., 2020) with an 84% fatality rate accounting for 2.3% of regional abundance estimates (Leaper et al., 2022). While a willingness exists among the fishers to address this problem (MacLennan et al., 2020, 2021; Leaper et al., 2022), a full scientific understanding of the impact of entanglement on whale populations is greatly limited by underreporting, and the low likelihood of retrieving whale carcasses (Cole et al., 2006; Northridge et al., 2010; Cassoff et al., 2011). Therefore, reported figures for entanglement-related whale mortality are likely to be only a small fraction of the actual number (Ryan et al., 2016; MacLennan et al., 2020). To date, global efforts to understand and prevent whale entanglement have included research into the ability of whales to detect and avoid fishing gear (Kot et al., 2012), and potential gear alterations (Kraus et al., 2014; Knowlton et al., 2016). Ground lines, that often float, are the source of 83% of minke entanglements in Scotland (Leaper et al., 2022). The use of sinking ground lines, as mandated in the US lobster fishery (NMFS et al., 2007) has been suggested as one possible mitigation measure in

Scotland (MacLennan et al., 2020, 2021; Leaper et al., 2022). One method to inform entanglement mitigation is by spatial assessments of risk, to describe the overlap between whale habitat and fishing effort. This approach is already used to study the impact of shipping and coastal developments on whale populations (Hatch et al., 2008; Ritter, 2010; Williams and O'Hara, 2010; Erbe et al., 2012; Martins et al., 2013), and to assess the risk of by-catch for large marine animals (Gilman et al., 2014; Brown et al., 2015). Identifying areas of high risk to a population can aid management decisions on where preventative action may have the greatest impact, e.g., moving shipping lanes to mitigate against ship-strikes (Ward-Geiger et al., 2005). In the case of whale entanglement, Northridge et al. (2010) used this approach to identify areas with a high entanglement risk for minke whales in western Scotland. Combining this approach with modelled predictions of habitat use (for instance as in Williams and O'Hara, 2010; Martins et al., 2013) can provide more robust results for identifying high-risk areas.

Because factors such as environmental conditions, fishing activity, and animal habitat-use fluctuate over time, risk is also likely to change. Therefore, continual, dedicated long-term monitoring should strengthen risk assessments, allowing for the estimation of temporal and spatial risk. Here, we use habitat modelling to develop a method for assessing risk-level and consistency to ultimately identify areas where whale entanglement in static fishing gear has remained consistently high over a seven-year period.

Minke whales (Balaenoptera acutorostrata) are one of the most abundant cetaceans in UK waters, and the most abundant baleen whale. They are seasonally resident on the west coast of Scotland, with peak occurrence during summer months (Macleod et al., 2004; Anderwald et al., 2012). The highest densities of minke whales in Europe occur in Scottish waters where abundance has fluctuated (Hammond et al., 2017) in relation to environmental changes (Macleod et al., 2004; Anderwald et al., 2012). The area also hosts a creel fishery of significant economic importance both locally and nationally. The fishery mainly targets crustaceans such as European lobster, velvet crab, edible crab, crawfish, and Norway lobster (Northridge et al., 2010). A conservative estimate of rope deployed by the fishery is 7500 km, which poses an entanglement threat to whales (Northridge et al., 2010). Minke whales are particularly vulnerable to fatal entanglement given their high use of coastal areas where creel fisheries also operate, in addition to their small size and thus greater risk of drowning in situ (Horwood, 1990; Kim, 1999; Shrimpton and Parsons, 2000; Glass et al., 2008; Song et al., 2009; Northridge et al., 2010). Leaper et al. (2022) reported that 84% of minke whale entanglements were fatal and estimated fatal entanglement rates suggest there is a risk of localized depletion for the west coast of Scotland.

Our study applied a novel spatio-temporal risk analysis to assess the entanglement of minke whales in creel lines in western Scotland. The aim was to determine both the level and consistency of entanglement risk, over a seven-year monitoring period,

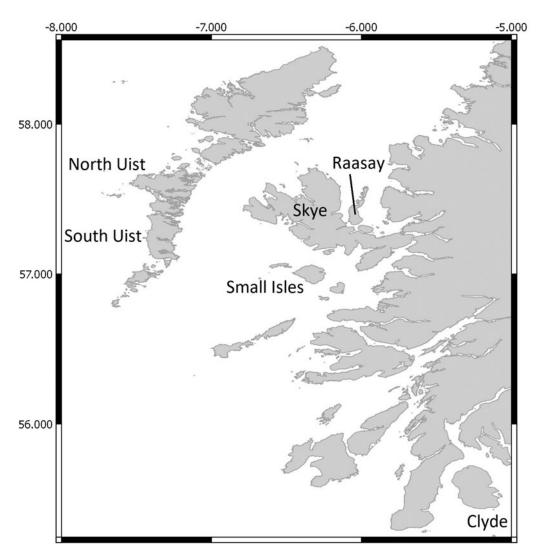


Figure 1. Surveys are in western Scotland.

based on the assumption that high co-occurrence of whales and creel fleets elevates entanglement risk.

Materials and methods

Data collection

Data were collected by the Hebridean Whale and Dolphin Trust (HWDT) from the auxiliary powered sailing research vessel *Silurian* during dedicated surveys off the west coast of Scotland (Figure 1). Surveys were conducted during the known peak in minke whale occurrence (March–October) between 2008 and 2014 (Table 1). Standard visual line transect methods were used to collect minke whale and creel sightings data (as in Embling *et al.*, 2010). The surveys aim to achieve non-biased spatial coverage throughout the survey area each season (Figure 2), however, equal coverage is not possible due to the location of anchorages and limited suitable conditions to survey certain areas (Hebridean Whale and Dolphin Trust, 2018). During survey effort, the vessel maintained an average speed of six knots, travelling by sail whenever possible.

Teams of trained observers carried out cetacean visual surveys under the supervision of an experienced marine mammal observer. During visual surveys, two observers stood on the front deck of the vessel (2 m above sea level), continuously scanning their respective windows (270° to 5° and -5° to 90° relative to the vessel transect line) using the naked eye and 7×50 mm binoculars. Each observer changed sides of the vessel for observation after 30 min, and retired for rest after 1 h of observation, in order to avoid observer fatigue. When possible short deviations from the dedicated visual survey transect line were made to capture images of cetaceans and basking sharks for photo-identification (under NatureScot research licence 159755). During these deviations, sightings of whales continued to be recorded whereas creels were not routinely documented. This data has been included in the analysis. This study focussed on the sightings of both minke whales (Balaenoptera acutorostrata) and pairs of creel marker buoys which are on the endlines of the submerged creel fleets (Figure 3). In Scotland, the gear configuration typically comprises: a buoy at each end with vertical lines on each, leading to weights on the seabed. Connecting them is a floating groundline, to which creels are attached by floating branch lines, typically 50-60 per fleet (Leaper et al., 2022). In the event of a sighting, the time, GPS coordinates, and distance to animal/creel buoy within 1 km from the boat, were recorded on a computer using software developed by the International Fund for Animal Welfare (IFAW; Logger 2000 up until 2010/2011 and Logger 2010 for remaining years). The GPS coordinates and speed of the vessel were also automatically recorded every 10 s, and additionally when survey effort changed. During visual surveys, environmental conditions known to introduce perception bias (Beaufort sea state, visibility, glare) were recorded every 15 min.

Data analysis

Habitat modelling

Using GPS data, survey transects were divided into 2 km segments, since sightings were only recorded within 1 km of the vessel. Analysis was carried out on the presence or absence (occurrence) of minke whale sightings for each 2 km segment.

Before modelling, Spearman's rank correlation tests were used to examine correlation between variables. For any two variables with a significant (P < 0.05) correlation (-0.7 > r > 0.7), only the most biologically relevant variable was retained in the model. Habitat modelling was then carried out using generalized additive modelling (GAM) techniques using R statistics software (R Core Team, 2015) and the mgcv package (Wood, 2006a). Modelling aimed to relate the occurrence of minke whales in 2 km transect segments to environmental conditions that affect sightings rates (detectability) and to associated environmental and temporal variables (Table 2). Data were divided into two temporal groupings, 2008-2011 and 2012-2014, and two different models were developed from these data groups. Model training was carried out on a 75% subsample of the data, selected at random. The remaining 25% of data was held back as a test set for model evaluation (Guisan and Zimmermann, 2000).

The minke whale occurrence data was modelled with a binomial distribution and log-link function (Wood, 2006b). The creel fleet occurrence data was modelled with a Poisson distribution. Forward stepwise selection was carried out, with term selection based on minimizing the Unbiased Risk Estimator (UBRE) score, for those variables that showed a significant relationship (P < 0.05) with minke whale occurrence (as in Embling *et al.*, 2010; Anderwald *et al.*, 2012) and contributed at least 1% to the deviance explained by the model (Embling *et al.*, 2010). Minimizing the UBRE score indicates a better model fit and is related to the similar Akaike's Information Criterion (AIC) measure (Wood, 2006b).

As in Embling *et al.* (2010), variables that affect the ability to see animals were included first in models to explain any influence on sighting probability. Sea state, visibility, swell, and glare, were all included in analysis given the potential for these variables to affect the probability of an observer sighting a minke whale or creel buoy (i.e. perception bias). Vessel speed is particularly

Table 1. Sightings (minke whales and creel fleets) and survey effort (km) for visual line transect surveys carried out by HWDT from 2008 to 2014

Year	No of minke whale sightings	No of creel fleet sightings	Distance (km)	Number of minke whale sightings/km	Number of creel fleet sightings/km
2008	45	2868	6527	0.00689	0.439
2009	56	3138	7659	0.00731	0.410
2010	38	2149	6737	0.00564	0.319
2011	63	2790	6695	0.00941	0.417
2012	34	1809	4443	0.00765	0.407
2013	28	2482	5214	0.00537	0.476
2014	51	3300	7524	0.00678	0.439
All Years	315	18,536	44,799	0.00703	0.414

The survey effort reported here refers to the distance surveyed after data had been divided into 2 km transect segments for analysis. Number of sightings/km is the number of sightings divided by distance.

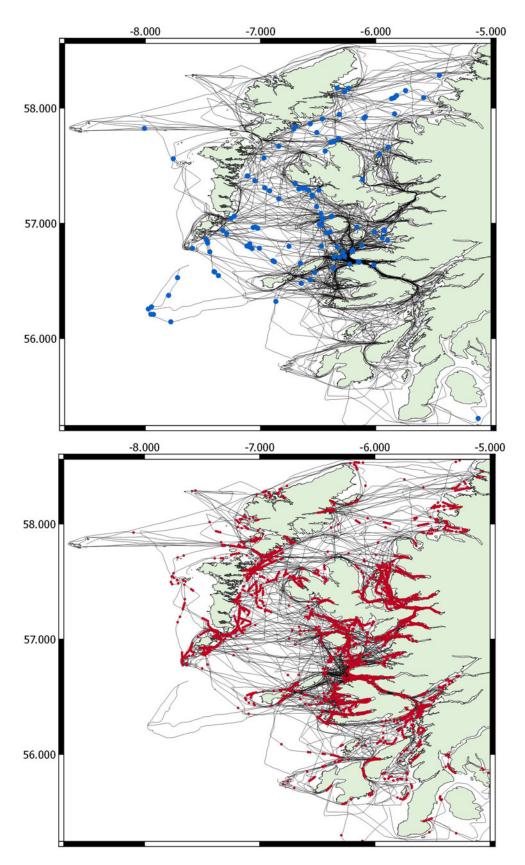


Figure 2. All sightings of minke whales (blue) and creel fleets (red) from 2008 to 2014, with survey effort track lines.

important to consider for its influence on sighting long-diving marine mammals (Barlow, 1999), since higher speeds may result in passing the animal before it surfaces (i.e. availability bias). Furthermore, Macleod *et al.* (2004) reported that it was significantly harder to sight minke whales above Beaufort Sea state 2.

Second, the following environmental variables were introduced to the model: depth, slope (degrees), seabed substrate, and a combination of tidal and wave energy. Depth and slope data were extracted from a raster bathymetry map obtained from Edina Digimaps. Substrate and combined wave and tidal energy data (CombEnergy as defined by EUNIS) were extracted from a seabed

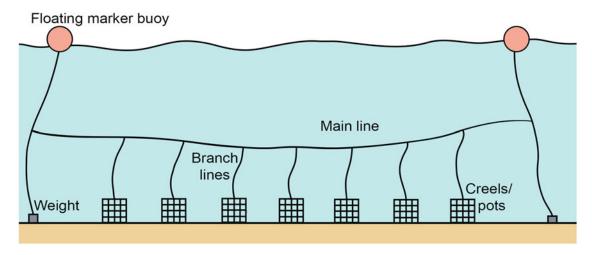


Figure 3. Generalized diagram of a creel fleet used to catch crustaceans.

habitat map for the North Sea and Celtic Sea, obtained from the European Marine Observation Data Network (EMODnet) Seabed Habitats project (funded by the European Commission's Directorate-General for Maritime Affairs and Fisheries; SeaZone Solutions Ltd). The categorical habitat descriptions in this map followed the EUNIS 2007–2011 classification system (Appendix 1 & 2). Previous research has shown a relationship between minke whale habitat and water depth, showing that occurrence peaks around 60 m depths (Skov *et al.*, 1995; Hooker *et al.*, 1999; Macleod *et al.*, 2004). Depth and seabed sediment are also known to influence the distribution of sand eels, *Ammodytes* spp. (Wright and Begg, 1997) and herring, *Clupea*

harengus (Saville et al., 1984) two of the minke whales' most important prey species in Scottish waters (Nordoy and Blix, 1992; Olsen and Holst, 2001; Pierce et al., 2004). Many studies have therefore suggested that the reported relationship between sandy sediments and minke whale habitat (Naud et al., 2003; Macleod et al., 2004) is based on the habitat of their prey. Seabed slope has previously been found to influence minke whale habitat, with highest occurrence around 15° (Macleod et al., 2004; Anderwald et al., 2012). Furthermore, there is some evidence to suggest a relationship between minke whale foraging and travelling with tidal energy (Anderwald et al., 2012). Previous research has found minke whales to be encountered more

Table 2. Description of model terms

Term	Description	Range	Mean	Median	Туре	Data source
Mpres	Minke occurrence (binary)	0-1	0.009	-	Response	Survey
Speed	Vessel speed (knots)	1.23-12.63	5.96	6.02	Smooth	Survey
SeaState	Beaufort Sea State scale in increments of 0.5	0-10	-	2.5	Factor	Survey
Depth	Depth of sea floor (m)	0.12-303.76	71.13	62.28	Smooth	Edina Digimap
Slope	Slope of sea floor (o)	0-50.66	3.03	1.61	Smooth	Edina Digimap
Substrate	Sea floor substrate 1 - mud to sandy mud 2 - sand to muddy sand 3 - coarse sediment 4 - mixed sediment 5 - mixed hard sediments 6 - rock or other hard substrates (EUNIS 2007–2011)	0–6	3	1	Factor	EMOD.net
CombEnergy	Combined tidal and wave energy. 1 – low 2 – moderate 3 – high (EUNIS 2007–2011)	1-3	-	1	Factor	EMOD.net
Year	Calendar year	2008-2014	-	-	Smooth	Survey
Month	Calendar month	3–10	-	-	If >6 smooth, If <6 factor	Survey
MidLat	Latitude at the midpoint of 2 km segment	55.178-58.6547	-	-	Tensor 2-way smooth	Survey
MidLon	Longitude at the midpoint of 2 km segment	-8.66133 to 4.83726	-	-	Tensor 2-way smooth	Survey

frequently in areas where increased tidal energy and upwelling may have attracted prey species (Johnston *et al.*, 2005; Ingram *et al.*, 2007).

Finally, temporal and spatial variables were introduced to the model. Month was related to minke whale occurrence given previous reports of minke habitat seasonality (Gill and Fairbainrns, 1995; Macleod *et al.*, 2004). Year was also included in this portion of the analysis, to include temporal changes on a larger scale. Finally, latitude and longitude were included in modelling to relate any remaining changes in spatial habitat distribution with minke whale occurrence.

Predictions of minke whale occurrence were made in R over a 4×4 km grid cell (dimensions twice the length of transect segments as suggested by Hedley, 2000) in the study area. Since we were mainly interested in spatial changes in minke whale habitat use, we assigned a single value for all temporally varying variables for spatial prediction: the average boat speed across all years in each group; Beaufort Sea State 1 (as the most minke whales were sighted at this sea state); July (given that minke sightings peaked during this month); and the year in which there were peak sightings (2011 and 2014, respectively). The other environmental variables were taken from the midpoints of each grid cell, and predictive values were calculated for both groups.

The final model was evaluated using the test set of data. The ability of the model to make predictions based on the test set (25% subsample) was tested by observing the receiver operating characteristics (ROC) graph and calculating the area under the curve (AUC) score, using the *pROC* package in R. The ROC indicates the balance between true and false positives in the predictive output of the model (Fawcett, 2006).

Calculating the risk of entanglement

For both groups of years, the prediction values for minke whale occurrence and creel fleet occurrence were multiplied together to calculate an index called risk of entanglement (RoE) for each $4\times4\,\mathrm{km}$ cell within the survey area (method adapted from Northridge *et al.*, 2010). Higher predictive values indicated a greater likelihood of minke-creel co-occurrence, and thus a higher entanglement risk, while lower predictive values indicated a lower likelihood of entanglement.

Identifying areas of consistent high risk

For each 4×4 km grid cell, the mean and standard deviation between RoE from each year grouping were calculated. The mean RoE indicated the risk level, which was divided into low (60% of cells), medium (20% of cells), and high (20% of cells). Standard deviation from the mean was used to indicate the consistency of risk, where lower standard deviation indicates higher consistency. For example, areas with a high mean RoE but with a low standard deviation were considered to have the most consistent high risk of entanglement. This information was presented in a map detailing the risk level as well as the standard deviation for each grid cell across the study area.

Results

Data exploration

During the seven-year study period (2008–2014) 44,799 km of survey effort were conducted off the west coast of Scotland. There was some variation in the survey effort between years with the lowest effort in 2012 (4443 km), and the highest effort in 2009 (7659 km). However, the seasonal coverage was comparable across years between March and October. For all years, from 2008 to 2014 combined, there were 0.00703 minke whale

sightings/km and 0.414 creel fleet sightings/km. The highest density of minke whales was in 2011 (0.0094 sightings km $^{-1}$) and the highest density of creel fleets was in 2013 (0.476 sightings km $^{-1}$) (Table 1). The lowest density of minke whales was recorded in 2013 (0.00537 sightings km $^{-1}$) and the density of creel fleets was lowest in 2010 (0.319 sightings km $^{-1}$) (Table 1). Sightings of minke whales during the seven-year study period occurred throughout the survey area, whilst creel fleets were concentrated in coastal areas (Figure 2).

Habitat modelling and predictions

Spearman's rank correlation tests for both 2008–2011 and 2012–2014 revealed correlations (P < 0.05, -0.07 > r > 0.07) among sea state and swell, depth and CombEnergy, and substrate and CombEnergy. Additionally, for the years 2008–2011 there were correlations between depth and slope, and depth and substrate. Thus sea state was retained over swell, depth, and substrate over CombEnergy, and depth over slope and substrate during model training. When presented with a test set of data our models for minke whale occurrence scored AUC values of 0.882 (2008–2011) and 0.829 (2012–2014), showing good performance.

The final models revealed that minke whale occurrence was related to vessel speed, sea state, depth, month, and longitude in both year groups, and in 2012–2014 minke whale occurrence was also related to year (Figure 4). Minke whale occurrence models for 2008–2011 and 2012–2014 explained 22.7 and 23.0% deviance in the data respectively (Table 3). There was a decline in detected minke whale occurrence when vessel speed exceeded four knots (Figure 4). Minke whale occurrence also decreased as the sea state increased (Figure 4). In each year group, depth was the only environmental variable that could be related to minke whale occurrence, with peak occurrences at around 70 m and reduced occurrence at <40 m (Figure 4). Minke whale occurrence peaked in July (Figure 4).

The final models also showed that in 2008–2011 the occurrence of creel fleets was related to substrate, slope, latitude, and longitude, while in 2012–2014 they were related to slope, CombEnergy, depth, substrate, and longitude (Table 3). Final creel fleet occurrence models for 2008–2011 and 2012–2014 explained 16.9% and 25.7% deviance in the data, respectively (Table 3). There was a peak in the occurrence of creel fleets at water depths of 40 m, and a seabed slope of 10° (Figure 4). Creel fleet occurrence was related to CombEnergy with a peak of 3 (high energy), and substrate type with peak occurrence in sand and mud (Figure 4). Latitude and Longitude were also related to creel occurrence, with peaks around 57°N, 7.5°W, and 6°W (Figure 4).

Risk of entanglement

Risk of entanglement (RoE) was not evenly distributed throughout the study area, ranging from zero to 1524.7 in 2008-2011, and near zero (3.5×10^{-6}) to 5.084 in 2012-2014 for 4×4 km cells. The large discrepancy between the two-year groups was a result of different variables being used in each predictive model. For cells a with a lower RoE value, there was a lower likelihood of a minke whale coinciding with creel fishing gear, based on habitat modelling and spatial overlap. In cells with higher RoE, there was the greatest likelihood of a minke whale coinciding with creel fishing gear, and therefore the greatest risk of an entanglement event. Our results indicate that risk of entanglement was highest around Raasay and the Inner Sound (Figure 5).

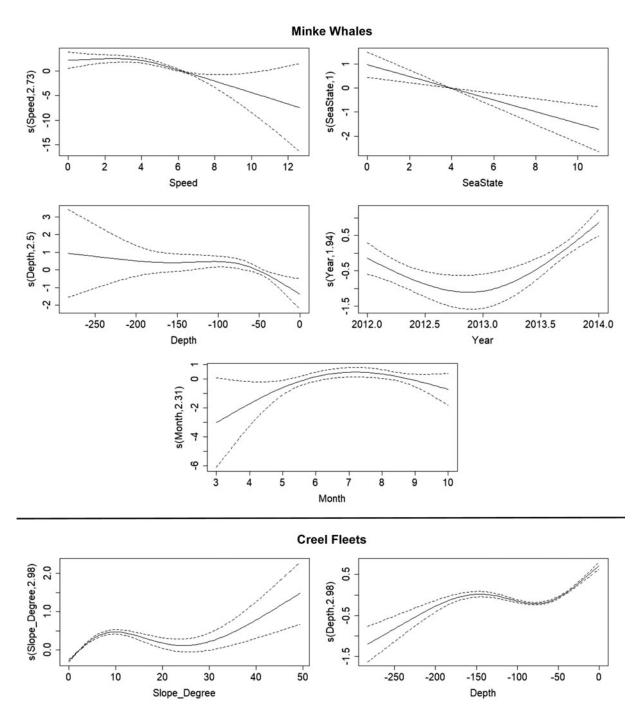


Figure 4. Relationships between model terms and minke whale or creel fleet occurrence in the Hebrides in 2012–2014. Terms were related using GAMs. Solid lines indicate smooth estimate, and dashed lines indicate ± 2 standard error intervals around the mean.

Consistent areas of high risk

Standard deviation from the mean ranged from 0 to 2.77 for highrisk cells, 0 to 0.019 for medium-risk cells, and 0 to 0.012 for low-risk cells (Figure 5). A low standard deviation from the mean indicated a greater consistency of risk level in that $4\times4\,\mathrm{km}$ cell. Three areas that were identified as having a consistently high risk of entanglement were the Inner Sound and Sound of Raasay, east of North and South Uist, and north of The Small Isles (Figure 5). The areas with more consistent RoE are concordant with, albeit less widespread than, the areas of high RoE.

Discussion

This study considered the interaction between minke whales and the creel fishery in western Scotland, where entanglement has been identified as the largest cause of anthropogenic mortality for this species (Northridge *et al.*, 2010; MacLennan *et al.*, 2020). The level and consistency of risk for minke whale entanglement in creel fishing gear was unevenly distributed around the Hebrides, from 2008 to 2014. Areas were identified with a consistently medium or high risk of entanglement throughout the study period, where there was a greater probability of minke–creel interactions which may result in entanglement. Assuming that whale distribution and fishing efforts continue to overlap, this information highlights appropriate locations to further study or mitigate against entanglement.

RoE and risk consistency

High- and medium-risk areas were highly clumped and mostly coastal, chiefly driven by higher creel densities. Three discrete

Table 3. Summary of terms selected as predictors of minke whale and creel fleet occurrence on the west coast of Scotland during step-wise forward selection, and their influence on the model (GAM)

2008–2011 Minke whales								
Speed	9.3%	3.6	<0.001	-0.89				
SeaState	5.2%	1.0	<0.001	-0.90				
Depth	2.3%	3.9	<0.001	-0.90				
Month	1.4%	2.2	0.001	-0.90				
MidLon, MidLat (tensor)	4.5%	17	<0.001	-0.90				
Total model	22.7%							
Creel fleets								
Term added to model	Deviance explained	edf	Р	UBRI				
Substrate (factor)	5.1%	6.0	<0.001	0.91				
Slope	3.2%	2.8	<0.001	0.84				
MidLat	5.3%	8.3	<0.001	0.74				
MidLon	3.3%	8.9	<0.001	0.67				
Total model	16.9%			0.67				
2012-2014								
Minke Whales								
Term added to model	Deviance explained	edf	Р	UBRE				
Speed	10.2%	2.7	<0.001	-0.92				
SeaState	1.8%	1.0	<0.001	-0.92				
Depth	2.0%	2.5	<0.01	-0.92				
Year	2.0%	1.9	<0.001	-0.92				
Month	1.8%	2.3	0.021	-0.92				
MidLon	5.2%	3.3	0.013	-0.92				
Total model	19.1%			-0.92				
Creel fleets								
Term added to model	Deviance explained	edf	Р	UBRI				
Slope	5.7%	3.0	<0.001	0.99				
CombEnergy (factor)	3.5%	3.0	<0.001	0.92				
Depth	3.3%	3.0	<0.001	0.85				
Substrate (factor)	1.0%	6.0	<0.001	0.83				
MidLat	7.6%	8.8	<0.001	0.67				
MidLon	4.6%	9.0	<0.001	0.58				
Total model	25.7%			0.58				

UBRE, unbiased risk estimator; edf, estimated degrees of freedom; $\it P$, probability. All terms were smoothers unless specified.

areas stand out for exhibiting relatively consistent high risk: the Inner Sound and Sound of Raasay, east of North and South Uist, and north of the Small Isles. As this study only used data collected during summer months, we cannot provide a year-round understanding of risk consistency throughout 2008 and 2014. However, both minke whale occurrence and creel fishing peak during the summer (Northridge *et al.*, 2010), and therefore the time period reported here is the most relevant for informing management of minke–creel entanglement.

Our results are comparable with previous research by Northridge et al. (2010) and MacLennan et al. (2021), who

identified areas of high risk for minke whale entanglement in creel gear around Scotland, and MacLennan *et al.* (2020, 2021), who investigated incidents of whale entanglement in Scotland. Our findings are consistent with these studies in finding the highest risk levels and incidence of entanglement around Skye, Raasay, and the Uists. MacLennan *et al.* (2021) reported the same highrisk areas to the East of North Uist, around Rasaay, and the Small Isles that have been identified here. Northridge *et al.* (2010) showed that there were greater amounts of creel fishing gear around South Uist as well as the Inner Sound near Skye. This is supported by our results, which show medium and high

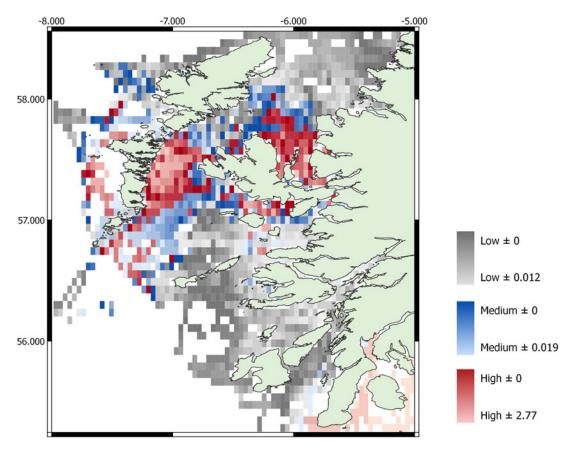


Figure 5. Consistent risk of entanglement in the Hebrides (2008–2014) based on habitat modelling and risk analysis. Darker cells within each risk level colour band indicate greater consistency of risk (lower standard deviation from the mean).

consistent RoE cells in each of these areas (Figure 5). Northridge et al. (2010) also reported high-risk areas around the Small Isles, similar to the high-risk areas we identified there, most notably to the north. The Clyde region was also classed as high risk, albeit with a higher standard deviation (Figure 5), as effort was minimal in this area (Figure 3). The predictions generated for the Clyde region and any other areas with limited survey data should be interpreted with caution. Despite taking effort into consideration (by removing low effort grids), the Clyde area only had one minke whale sighting and relatively low density of creel fleets. Further refinement of the methodology outlined here, for example, using stricter rules on the exclusion of low effort or low sightings areas, may improve the predictions.

High RoE areas generally match the areas with the highest amount of minke whale strandings and reported entanglements in Scotland (Northridge et al., 2010; MacLennan et al., 2021; Leaper et al., 2022). Leaper et al. (2022) presented all the stranded minke whale entanglement cases determined and assessed by the Scottish Marine Animal Stranding Scheme (SMASS) between 2008 and 2019 and those documented from fisher interviews. Our results are in accordance with the distribution of reports of entanglement cases from interviews, but not those from strandings found and reported to SMASS (Figure 3 in Leaper et al., 2022). The discrepancy between interview-based and strandingsbased cases appears to be greatest along the eastern coasts of North and South Uist and western Skye: areas where our analysis predicted a high risk of entanglement (Figure 5). It is possible that strong tides in this area drift carcasses away from here, coupled with a lower probability of strandings being found and reported to SMASS due to the inaccessible nature of these coastlines.

The consistently high-risk areas around the Small Isles and South Uist, fall within a designated Marine Protected Area

(MPA) for minke whales (NatureScot, 2020), however, the areas identified around Raasay do not. Risk ought to be continually monitored as it is likely to change with the fluctuating distribution of whales and creel fleets, in addition to evolving fisheries management scenarios. The introduction of management measures in this region should be implemented in a way that ensures fishing effort is not displaced into other areas with high densities of animals, or around the MPA boundary (as in Burke, 2015; Rees *et al.*, 2021).

Risk analysis can be used to observe spatial overlap between two potentially conflicting components. In marine mammal ecology, risk analysis has been used to study interactions between whale populations and human activity such as shipping, coastal development, and by-catch (Hatch et al., 2008; Ritter, 2010; Williams and O'Hara, 2010; Erbe et al., 2012; Martins et al., 2013; Gilman et al., 2014; Brown et al., 2015). Studying spatial overlap is of value to conservation and management actions, as it provides a means to locate areas of high risk where preventative efforts would be the most effective (Brown et al., 2015). Whilst previous cetacean research has used modelling and spatial overlap techniques to identify high-risk areas (Hatch et al., 2008; Herr et al., 2009; Ritter, 2010; Williams and O'Hara, 2010; Erbe et al., 2012; Martins et al., 2013; Redfern et al., 2013; Sims et al., 2008) to inform management (Brown et al., 2015), the consistency of risk levels over time has not been considered. Given that human use of the marine environment is constantly changing, it is important not to rely on temporal snapshots of data when assessing risk. Here we have developed a methodology for measuring risk consistency, which can be used to observe changes in risk, temporally as well as spatially.

Understanding the ways in which risk levels can vary or persist in different areas may be of importance in policy-making,

conservation, and fisheries management, since it is more cost and effort efficient to take preventative action in areas where high risk is consistent, rather than where risk levels have fluctuated. Measuring risk consistency could be applied to a wide range of risk interactions in the marine environment, including those currently predominant in the literature such as cetacean-shipping conflicts (e.g. Ritter, 2010; Williams and O'Hara, 2010; Erbe et al., 2012; Redfern et al., 2013). This method will be the most effective when used with quantitative data on environmental factors. Lastly, it is beyond the scope of this study to suggest mitigation measures to reduce the risk of entanglement in minke whales. However, efforts are ongoing in an industry-led approach through the Scottish Entanglement Alliance¹ to determine what measures will be most appropriate to mitigate against whale entanglement in this fishery. Lessons learned from where this issue has arisen elsewhere indicate that successful approaches are likely to be those led by fishers. Indeed, there is currently a willingness to do so in Scotland, with mitigation measures such as the use of sinking lines as well as ropeless gear being tested (MacLennan et al., 2021; Leaper et al., 2022). The modelling approach used here to assess entanglement risk is a useful tool to identify areas where these mitigation methods will be the most effective.

Habitat modelling

Habitat modelling is a powerful tool for understanding the interactions between species occurrences and the wide range of variables that influence them (Canadas et al., 2005; Redfern et al., 2006). Cetaceans are mobile species that spend the majority of their time submerged, and therefore studying occurrence based on sightings records of these animals is inherently limited, and habitat modelling can provide a more complete picture of habitat use. In this study, generalized additive modelling (GAM) was used to relate the observations of minke whales to vessel speed, sea state, depth, month, year, latitude, and longitude. Models for each year group scored AUC > 0.75, which indicates good model performance (Elith et al., 2006; Best et al., 2012). The model results also align with actual minke whale and creel sightings (Figure 2), even those not used in model training, thus the model can be considered a good fit to the data (Lobo et al., 2008). Minke whale sightings were related to boat speed and sea state, which are known to affect both availability and perception biases respectively and therefore help to compensate for these effects (Barlow, 1999; Macleod et al., 2004). Of the environmental variables, minke whale occurrence was related to depth, showing a peak around 70 m. This is consistent with previous research that suggests a peak occurrence at 60 m (Skov et al., 1995; Hooker et al., 1999; Ainley et al., 2012; Anderwald et al., 2012), though it can depend on the habitat available (Naud et al., 2003).

Our models related creel fleets to inshore areas, with peak occurrence in areas with sandy and muddy seabed, sloped at 10 degrees, around depths of 40 m, with high levels of tidal and wave movement. These findings are in line with previous sightings reports of higher densities of creel fleets in the coastal waters of western Scotland (Northridge *et al.*, 2010). Whilst minke whales eat a range of prey species in some areas, in Scottish waters they mainly feed on lesser sand eel (Nordoy and Blix, 1992; Olsen and Holst, 2001; Macleod *et al.*, 2004; Pierce *et al.*, 2004), which occupies sandy substrates during spring. Therefore, it has been suggested that minke whales are found in areas with sandy sediments (Naud *et al.*, 2003) where they can find their prey. Although our models could not relate minke occurrence to seabed

substrate, it is likely that minke whales show the same preference for the sandy substrate as the creel fishery, due to feeding. The use of categorical sediment data in this study may have prevented the relation of seabed substrate to minke whale occurrence, and future research might consider the use of continuous data (e.g. Embling *et al.*, 2010). Such an approach would need to accommodate preyswitching by minke whales from sand eel to spawning clupeids which occurs in late summer (Macleod *et al.*, 2004).

Finally, there were several temporal variables included in the final models for minke whales. The month was related to minke whale occurrence, with a peak in July, which is concurrent with previous research (Northridge *et al.*, 2010). The year was also related to minke whale occurrence, with peaks in the years 2012 and 2014. Minke whales are likely to vary inter-annually, however, sightings and survey efforts also vary with weather conditions (Teilmann, 2003). Latitude and longitude were also related to both minke whale occurrence and creel fleet sightings, showing a slight increase in occurrence towards lower and higher longitudes within the study area (Figure 4E). This indicates a preference for inshore waters, closer to land, although it could also be influenced by survey efforts.

Habitat modelling can be of great value to conservation, and there is a growing demand for this type of research to support management decisions (Redfern *et al.*, 2006). In the past, modeling has been used to support the development of marine protected areas (Hooker *et al.*, 1999; Canadas *et al.*, 2005; Embling *et al.*, 2010), as well as to understand cetacean interactions with fisheries (Torres *et al.*, 2003; Kaschner, 2004). Here, habitat modelling has allowed for a more robust understanding of minke whale habitat use and creel fleet occurrence in western Scotland, beyond the various limitations of scientific surveys.

Conclusion

Studying the overlap between potentially conflicting components is a useful tool for identifying critical areas of high risk in which to focus management (Brown et al., 2015). Whale entanglements result in economic losses to fishers, and are the leading cause of non-natural whale mortality in the UK (Northridge et al., 2010). Annual entanglement deaths were estimated to be around 2.2% of the abundance estimate for this study area (MacLennan et al., 2020). Minimizing negative human impacts on this species where possible is a welfare priority and should serve as an early warning in terms of conservation management (Papastavrou et al., 2017). Presently, any increase in minke whale density will increase minke whale mortality in the Hebrides. Our study presents a methodology for identifying key areas where entanglement mitigation measures ought to be prioritized, and a way to monitor risk on an ongoing basis as fisheries scenarios change. By estimating risk consistency, our approach could provide advice to management that accounts for changes in entanglement risk.

Supplementary Material. The supplementary material for this article can be found at https://doi.org/10.1017/S0025315423000930

Acknowledgements. We extend our thanks to all the volunteers, staff and crew, past and present, who have contributed to the Silurian monitoring programme at the Hebridean Whale and Dolphin Trust, without which this work would not have been possible. Thank you to Dan Ţicărat for illustrating a generalized creel fleet diagram.

Financial Support. The Hebridean Whale and Dolphin Trust's long-term, boat-based species monitoring programme has been supported by members, donors, and funders over the past 18 years including: Heritage Lottery Fund, The Nàdair Trust, NatureScot (formally Scottish Natural Heritage), WWF-UK, Coastal Communities Fund, William Grant Foundation and Sea-Changers.

¹https://www.scottishentanglement.org/about/

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