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The Hele-Shaw flow and moduli of holomorphic discs

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Abstract

We present a new connection between the Hele-Shaw flow, also known as twodimensional Laplacian growth, and the theory of holomorphic discs with boundary contained in a totally real submanifold. Using this, we prove short-time existence and uniqueness of the Hele-Shaw flow with varying permeability both when starting from a single point and also when starting from a smooth Jordan domain. Applying the same ideas, we prove that the moduli space of smooth quadrature domains is a smooth manifold whose dimension we also calculate, and we give a local existence theorem for the inverse potential problem in the plane.

1. Introduction

The Hele-Shaw flow is a model for describing the propagation of fluid in a Hele-Shaw cell. Such a cell consists of two parallel plates separated by a small gap, and the fluid is confined to the narrow space between them. This moving boundary model has been intensely studied for over a century, and is a paradigm for understanding more complicated systems such as the flow of water in a porous medium, the melting of ice and models of tumour growth.

This flow is essentially two dimensional, and one identifies the region occupied by fluid with a subset Ω_t of the plane \mathbb{R}^2 . In this paper we will consider the case of a viscous incompressible fluid that is surrounded by air while new fluid is injected at a constant rate at the origin. If p is the pressure in the fluid, then the velocity V of the fluid at that point (or really the mean velocity along the gap between the plates) is calculated as

$$V = -\nabla p. \tag{1}$$

Here we have neglected some physical constants. The pressure in the fluid is harmonic except at the origin, where it will have a logarithmic singularity, and is zero on the boundary since we assume that both the air pressure and the surface tension are zero.

To model this, let $\{\Omega_t\}$ be a family of domains in \mathbb{R}^2 containing the origin, and let p_t denote the function which is zero on $\partial\Omega_t$ and which solves

$$\Delta p_t = -\delta_0$$

on Ω_t , where δ_0 is the Dirac measure at the origin. Then Ω_t is called a solution to the (classical) Hele-Shaw flow if for all t

$$V_t = -\nabla p_t \quad \text{on } \partial \Omega_t, \tag{2}$$

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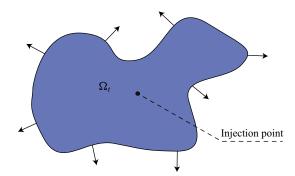


Figure 1. (Colour online) Dynamics of the Hele-Shaw flow.

where V_t is the normal outward velocity of $\partial \Omega_t$. Clearly, we need some regularity of the family $\{\Omega_t\}$ in order for this to make sense; thus, the question of local existence of a classical solution to the Hele-Shaw flow with a given initial domain Ω_0 is non-trivial.

Similarly, one can model the case of a Hele-Shaw cell where the fluid moves through a porous material. If the permeability of this material is given by a positive function κ , then, by Darcy's law, the equation of motion of the fluid in the cell becomes

$$V_t = -\kappa \nabla p_t \quad \text{on } \partial \Omega_t, \tag{3}$$

with p_t defined as before. This is a special case of elliptic growth of Beltrami type considered in [KMP09]. It is also equivalent to studying the classical Hele-Shaw flow on a Riemann surface, with the Riemannian metric encoding the permeability [HS02] (see Figure 1).

There is a vast literature on the Hele-Shaw flow (see [GV06] and the references therein). The main short-time existence and uniqueness result for classical solutions to the Hele-Shaw flow in the case $\kappa \equiv 1$ is due to Vinogradov and Kufarev [VK48] and dates from 1948. It states that if Ω_0 is a simply connected domain with real analytic boundary, then there exists a unique (indeed real analytic) solution $\{\Omega_t\}_{t\in(-\epsilon,\epsilon)}$ to the Hele-Shaw flow for some $\epsilon>0$. Observe here that the solution extends both forwards and backwards in time. In [RvW93], Reissig and von Wolfersdorf gave a new proof of this result using a non-linear version of the Cauchy–Kovalevskaya theorem due to Nishida. Tian [Tia96] provided yet another proof relying on properties of the Cauchy integral of the free boundary, and recently Lin [Lin11] proved the same result using a result of Gustafsson on rational solutions [Gus84] combined with a new perturbation theorem to get to the general case.

There is also a slightly different setting of the Hele-Shaw flow, where the source of fluid is not a point but a curve inside the starting domain (see e.g. [AGM02, EJ81, ES96]). In [ES97b], Escher and Simonett proved short-time existence of classical solutions to the Hele-Shaw flow in this setting, and in [ES96, ES97a] they proved short-time existence of classical solutions to the Hele-Shaw flow with surface tension. There is also related work of Hanzawa [Han81] on classical solutions to the Stefan problem.

Less has been written about the case of varying permeability. In [HS02], Hedenmalm and Shimorin proved short-time existence under the assumption that κ is real analytic and the starting domain has real analytic boundary. They also proved short-time existence when the starting domain is empty, under an additional assumption that $\Delta \log \kappa > 0$, which translates to saying that the Riemann surface in question has negative curvature. See also [HO05] for related results.

2. Summary of results

Our first main result concerns the existence of the Hele-Shaw flow with empty initial condition.

THEOREM 2.1. Let κ be a positive smooth function. Then there are an $\epsilon > 0$ and a family Ω_t of domains in \mathbb{C} containing the origin that satisfies the Hele-Shaw flow with permeability κ and such that

$$Area(\Omega_t) = t$$
 for $0 < t < \epsilon$

(i.e. the limit of Ω_t as t tends to zero is just the origin).

We remark that this improves on the results of Hedenmalm and Shimorin, since we only assume that κ is smooth. Despite this having a rather natural physical interpretation, there appear to be few other results with empty initial condition. This may be because many of the techniques in the study of the Hele-Shaw flow rely on identifying the starting domain with the unit disc (say through the Riemann mapping theorem) and thus cannot be applied.

Our second result on the Hele-Shaw flow is short-term existence and uniqueness from a non-empty initial condition.

THEOREM 2.2. Let Ω_0 be smooth Jordan domain containing the origin and let κ be a smooth positive function defined in a neighbourhood of $\partial\Omega_0$. Then there exists an $\epsilon > 0$ such that there exists a unique smooth increasing family of domains $\{\Omega_t\}_{t\in[0,\epsilon)}$ which solves the Hele-Shaw flow with permeability κ forwards in time.

We remark that this goes beyond the results of Hedenmalm and Shimorin, since we do not require κ or the boundary of the initial domain to be real analytic. However, if we do make these assumptions then we get an alternative proof of their result that holds both forwards and backwards in time.

Our approach will involve controlling the mean values of holomorphic functions along the flow Ω_t , which fits into the more general framework of quadrature domains (as advocated by Gustafsson and Shapiro). We say that a bounded domain Ω is a quadrature domain if there are points z_1, \ldots, z_m in Ω and complex coefficients c_{kj} for $1 \leq k \leq m$ and $0 \leq j \leq n_k - 1$ such that the quadrature identity

$$\int_{\Omega} f \, dA = \sum_{k=1}^{m} \sum_{j=1}^{n_k - 1} c_{kj} f^{(j)}(z_k)$$

holds for all integrable holomorphic functions f in Ω . Then the integer $n = \sum_{k=1}^{m} n_k$ is called the order of the domain.

Using the same ideas that we use to study the Hele-Shaw flow, we shall prove the following result about such objects.

THEOREM 2.3. The moduli space of smooth quadrature domains of order n and connectivity c is a smooth manifold of real dimension 4n + c - 2.

The fact that the moduli space of smooth quadrature domains is a manifold appears to be previously unknown. At a generic point its dimension can be seen in the following way. Suppose that the points z_k are all distinct and $n_k = 1$ for all k. Then the quadrature identity becomes

$$\int_{\Omega} f \, dA = \sum_{k=1}^{m} c_k f(z_k) \tag{4}$$

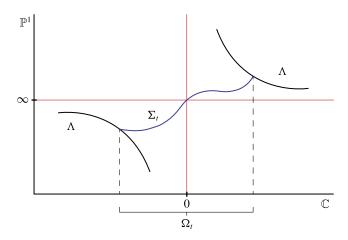


FIGURE 2. (Colour online) Lifting the Hele-Shaw flow.

for some $c_k \in \mathbb{C}$ and points z_1, \ldots, z_m , where now n=m is the order of Ω . It was proved by Gustafsson that a generic smooth Ω of connectivity c satisfying (4) moves in at least a (c-1)-dimensional family that still satisfies (4) (see [GP07, p. 11] and [Gus83, Theorem 12]). Then we have a further 2n real parameters available by moving the points z_k , and a further 2nreal parameters available by moving the complex coefficients c_k , subject to the constraint that $c_1 + \cdots + c_n \in \mathbb{R}$, coming from putting f = 1 into (4) and noting that the area of Ω must be real valued. Thus, in total we have 4n + c - 2 real parameters, and the above theorem implies that there are no more, as well as proving this dimension at a non-generic point.

In our opinion, the interest of this work lies not only in the particulars of the above theorems but also in the techniques introduced for their proof. We shall show that a solution to the Hele-Shaw flow is equivalent to being able to lift $\Omega_t \subset \mathbb{R}^2 = \mathbb{C}$ to a family of holomorphic discs Σ_t in $\mathbb{C} \times \mathbb{P}^1$ such that:

- (i) Ω_t is the image of the projection of Σ_t to \mathbb{C} ; and
- (ii) the discs Σ_t attach along their boundaries to a certain totally real submanifold Λ of $\mathbb{C}^2 \subset \mathbb{C} \times \mathbb{P}^1$; and
- (iii) the closure of Σ_t intersects $\mathbb{C} \times \{\infty\} \subset \mathbb{C} \times \mathbb{P}^1$ only at the point $p := (0, \infty) \in \mathbb{C} \times \mathbb{P}^1$ (see Figure 2).

This correspondence comes about through thinking of the lifts Σ_t as the graph of certain 'Schwarz' functions on Ω_t that are holomorphic except for a simple pole at the origin. Starting with t=0, we construct a smooth strictly subharmonic function ϕ (that encodes the permeability by $\kappa=1/\Delta\phi$) such that Ω_0 admits such a Schwarz function S_0 . Then, setting

$$\Lambda = \left\{ \left(z, \frac{\partial \phi}{\partial z} \right) : \right\} \subset \mathbb{C}^2,$$

the graph of S_0 will be a holomorphic disc Σ_0 whose boundary lies in Λ .

Once this is done, we are in a position to apply the well-developed theory of embedded holomorphic discs. For the proof of the existence of the Hele-Shaw flow with empty initial condition, we will rely on a connection between holomorphic discs and solutions to the homogeneous Monge-Ampère equation, ultimately relying on an openness theorem of Donaldson. For the other short-time existence theorem we will consider the moduli space of embedded discs near Σ_0 that are attached to Λ and that pass through $p = (0, \infty) \in \mathbb{C} \times \mathbb{P}^1$. We shall show that

this moduli space is a smooth manifold of real dimension one (which immediately gives both the existence and uniqueness), which relies on a standard argument using the associated Schottky double.

This lifting interpretation of the Hele-Shaw flow through Schwarz functions comes about through looking at the integrals

$$I(h,t) = \int_{\Omega_t} h \frac{1}{\kappa} dA,$$

where h is an integrable holomorphic function on Ω_t and dA denotes the Lebesgue measure on \mathbb{C} . It is known that the Hele-Shaw flow is characterised by the condition that for all such h

$$I(h,t) - I(h,t_0) = (t-t_0)h(0)$$

for any fixed t_0 and $t > t_0$. When $h = z^k$, $k \ge 0$, the integrals

$$M_k(t) := I(z^k, t) = \int_{\Omega_t} z^k \frac{1}{\kappa} dA$$

are called the complex moments of Ω_t . One can study the problem of flows Ω_t for which the complex moments are allowed to vary in a particular way, and this puts the Hele-Shaw flow into the more general picture of 'inverse potential problems'. We use the same approach as above to prove a statement about these more general flows.

THEOREM 2.4. Let Ω be a smooth Jordan domain and V be a smooth, nowhere-vanishing outward pointing normal vector field on $\partial\Omega$. Then there exists a smooth variation Ω_t for $t \in [0, \epsilon)$ for some $\epsilon > 0$ such that

$$\left. \frac{d}{dt} \right|_{t=0} \partial \Omega_t = V$$

and whose moments vary linearly in t.

Note that this theorem is not immediately obvious since a priori there could be relations among the higher moments; thus, we think of it as showing a kind of independence among them. In fact, it is known that if κ is real analytic and Ω has real analytic boundary, then the moments M_k for $k \geq 1$ provide parameters for the space of domains with analytic boundary near to Ω . We refer the reader to Theorem 8.2 for a more precise version of Theorem 2.4 in this setting. If we set $V = -\nabla p$ in the above theorem, where p denotes the Green function of Ω , we recover the Hele-Shaw flow, and thus this result generalises Theorem 2.2.

2.1 Terminology

We identify \mathbb{R}^2 with the complex plane \mathbb{C} in the standard way. A domain $\Omega \subset \mathbb{R}^2$ is a set that is open and connected and its boundary is $\partial \Omega = \overline{\Omega} - \Omega$, where the bar denotes the topological closure. The connectivity of Ω is the number of connected components of $\partial \Omega$. If $\partial \Omega$ can be written locally as the graph of a smooth function, then we shall say that Ω has smooth boundary or simply that Ω is smooth, with analogous definitions if this graph can be taken to be real analytic, and in this case there is a well-defined unit outward normal vector field n on $\partial \Omega$. We say that Ω is a smooth Jordan domain if it is the interior region determined by a smooth Jordan curve (i.e. a smooth non-self-intersecting loop in \mathbb{R}^2).

If $I \subset \mathbb{R}$ is an interval, then a family of domains Ω_t for $t \in I$ is increasing if $\Omega_t \subset \Omega_{t'}$ for t < t' and the family Ω_t is said to be *smooth* if the boundary $\partial \Omega_t$ can be written locally as the graph of a smooth function that depends smoothly on t. If Ω_0 is smooth with unit normal

vector field n on $\partial\Omega_0$, then an increasing smooth family Ω_t for $t \in (-\epsilon, \epsilon)$ is determined by $\partial\Omega_t = \{x + f(x,t)n_x : x \in \partial\Omega_0\}$ for some positive smooth function $f_t(x) = f(x,t)$ on $\partial\Omega_0$, and the normal outward velocity of Ω_t at t = 0 is

$$V_0 := \frac{d}{dt} \bigg|_{t=0} \partial \Omega_t := \frac{df_t}{dt} \bigg|_{t=0} n.$$

3. Lifting the Hele-Shaw flow

3.1 Complex moments

Let Ω_t be a family of domains in $\mathbb{R}^2 = \mathbb{C}$ and κ be a positive smooth function. For $k \geq 0$, the kth complex moment of Ω_t is

$$M_k(t) := \int_{\Omega_t} z^k \frac{1}{\kappa} \, dA,$$

where dA denotes Lebesgue measure. Clearly then, $M_0(t)$ is just the area of Ω_t , and we refer to the $M_k(t)$ for $k \ge 1$ as the higher moments.

An important discovery by Richardson [Ric72] is that these moments are conserved by the Hele-Shaw flow. Since we are assuming that the fluid is injected at a constant rate, we may as well reparametrise t so that $M_0(t) = \text{Area}(\Omega_t) = M_0(0) + t$.

Similarly, if h is an integrable holomorphic function on Ω_t for some t, one can consider the integral

$$I(h,t) := \int_{\Omega_t} h \frac{1}{\kappa} \, dA.$$

The upshot is that the variation in t of these integrals characterises the Hele-Shaw flow.

THEOREM 3.1. If Ω_t is any smooth increasing family of simply connected domains for $t \in (a, b)$ that contain the origin, then it is the Hele-Shaw flow if and only if for any $a < t_0 < t < b$ and any integrable holomorphic function on Ω_t we have

$$I(h,t) - I(h,t_0) = (t - t_0)h(0).$$

The first direction is Richardson's calculation, namely that if the Hele-Shaw equation (3) is satisfied and h is holomorphic on $\overline{\Omega_t}$, then

$$\frac{d}{dt}I(h,t) = \frac{d}{dt} \int_{\Omega_t} h \frac{1}{\kappa} dA = \int_{\partial \Omega_t} h \frac{V_t}{\kappa} ds = -\int_{\partial \Omega_t} h \frac{\partial p_t}{\partial n} ds$$
$$= \int_{\Omega_t} (p_t \Delta(h) - h(\Delta p_t)) dA - \int_{\partial \Omega_t} p_t \frac{\partial h}{\partial n} ds = h(0),$$

since $p_t = 0$ on $\partial \Omega_t$ and $\Delta(p_t) = -\delta_0$. The second statement says in effect that this calculation can be reversed (and is, as far as we know, due to Gustafsson [GV06, p. 22] or [HS02]).

3.2 Schwarz functions

We next discuss how the above characterisation of the Hele-Shaw flow can be recast in terms of the existence of Schwarz functions. To describe this, fix a pair (Ω, ϕ) , where Ω is a domain in $\mathbb{R}^2 = \mathbb{C}$ and ϕ is a smooth function defined in some neighbourhood of $\partial\Omega$ that is strictly subharmonic (i.e. such that $\Delta\phi$ is positive).

DEFINITION 3.2. We say that a function S is a Schwarz function of (Ω, ϕ) if S is a meromorphic function on Ω which extends continuously to $\partial\Omega$ and is such that

$$S(z) = \frac{\partial \phi(z)}{\partial z}$$
 on $\partial \Omega$.

Remark 3.3. The model case usually considered is where $\phi = |z|^2$, so $S(z) = \overline{z}$ on $\partial\Omega$. We remark that what we define above is sometimes referred to as an interior Schwarz function, since we are requiring that it be defined on all of Ω . Much of the work of Schwarz functions asks instead that S be defined, and holomorphic, on some neighbourhood of $\partial\Omega$. It turns out, in the model case $\phi(z) = |z|^2$, that such an S exists in this restricted sense if and only if Ω has real analytic boundary (see e.g. the book [Sha92] by Shapiro), and extends to a meromorphic function on Ω if and only if Ω is a quadrature domain [AS76].

The connection between Schwarz functions in the model case $\phi(z) = |z|^2$ and the Hele-Shaw flow is well known (see e.g. [GV06, 3.7.1]). The following proposition generalises this to suit our needs.

PROPOSITION 3.4. Let ϕ be a smooth and strictly subharmonic function defined in a domain D. Suppose that $\Omega_t, t \in (a, b)$, is a smooth increasing family of Jordan domains containing 0 such that for all $t \in (a, b)$, $\partial \Omega_t \subset D$, and for each t there exists a Schwarz function S_t of the pair (Ω_t, ϕ) that is holomorphic on Ω_t except for having a simple pole at 0. Then, after some reparametrisation s = s(t), Ω_s is a solution to the Hele-Shaw flow with varying permeability $\kappa = 1/\Delta \phi$.

Proof. Pick $t_0 \in (a, b)$ and let $t \in (t_0, b)$. Let h be integrable and holomorphic on Ω_t for some $t > t_0$. Then we have that

$$\int_{\Omega_{t}\backslash\Omega_{t_{0}}} h \frac{dA}{\kappa} = \int_{\Omega_{t}\backslash\Omega_{t_{0}}} h\Delta\phi \, dA = -\frac{i}{2} \int_{\Omega_{t}\backslash\Omega_{t_{0}}} hd\left(\frac{\partial\phi}{\partial z} \, dz\right)
= -\frac{i}{2} \int_{\partial\Omega_{t}} h \frac{\partial\phi}{\partial z} \, dz + \frac{i}{2} \int_{\partial\Omega_{t_{0}}} h \frac{\partial\phi}{\partial z} \, dz
= -\frac{i}{2} \int_{\partial\Omega_{t}} hS_{t} \, dz + \frac{i}{2} \int_{\partial\Omega_{t_{0}}} hS_{t_{0}} \, dz
= -\frac{i}{2} \int_{\Omega_{t}} h\bar{\partial}S_{t} \, dz + \frac{i}{2} \int_{\Omega_{t_{0}}} h\bar{\partial}S_{t_{0}} \, dz
= h(0)\pi \operatorname{Res}_{0}(S_{t} - S_{t_{0}}),$$

which after reparametrisation of time so that $(d/dt)\text{Res}_0(S_t) = 1/\pi$ is equal to $(t-t_0)h(0)$. Thus, from Theorem 3.1, we see that this means that (the reparametrised) Ω_t is a classical solution to the Hele-Shaw flow.

Thus, we wish to prove the existence of Schwarz functions S_t , which is made easier through the freedom of choice in the subharmonic function ϕ . Our next aim is to construct a suitable ϕ that solves this problem for t = 0. To guide the subsequent discussion, we first recall a classical argument in the case where $\phi = |z|^2$. Consider the Cauchy integral

$$f(z) := \frac{1}{2\pi i} \int_{\partial \Omega_0} \frac{\bar{\zeta} \, d\zeta}{\zeta - z}.$$

Define f_+ as the restriction of f to Ω_0 and f_- as the restriction of f to the complement of $\overline{\Omega}_0$. Clearly, f_+ and f_- are both holomorphic in their respective domains of definition. A careful

analysis shows that both f_+ and f_- extend smoothly to $\partial\Omega_0$ and the Sokhotski–Plemelj formula states that on the boundary

$$f_{+}(z) = \bar{z} + f_{-}(z) \tag{5}$$

(see, for example, the book [Gak66] by Gakhov). Moreover, it can be shown that the boundary of Ω_0 is real analytic if and only if both f_+ and f_- extend holomorphically to a neighbourhood of $\partial\Omega_0$, and in this case $S:=f_+-f_-$ is holomorphic on this neighbourhood and $S(z)=\overline{z}$ on $\partial\Omega$.

We state first a simple version of what we shall prove.

PROPOSITION 3.5. Let Ω_0 be a smooth Jordan domain containing 0. Then there exists a smooth strictly subharmonic function ϕ defined on a neighbourhood U of the complement of Ω_0 such that $\Delta \phi = 1$ on $U - \Omega_0$ and so that (Ω_0, ϕ) admits a Schwarz function S_0 that is holomorphic except for having a simple pole at 0.

For the problem of varying permeability, we need something a little stronger.

PROPOSITION 3.6. Let Ω_0 be a smooth Jordan domain containing 0 and κ be a smooth positive function defined on a neighbourhood of $\partial\Omega_0$. Then there exist a smooth function κ' defined in a neighbourhood U of $\partial\Omega_0$ such that $\kappa' = \kappa$ on $U - \Omega_0$ and a smooth strictly subharmonic function ϕ defined on U with $\Delta \phi = 1/\kappa'$ such that (Ω_0, ϕ) admits a Schwarz function S_0 that is holomorphic except for having a simple pole at 0.

Moreover, if κ is real analytic and Ω_0 has real analytic boundary, then we can take $\kappa' = \kappa$.

Proof. We need only prove Proposition 3.6. We may as well assume that κ is defined on all of \mathbb{C} and is smooth and positive there. Pick some smooth function ϕ_0 on \mathbb{C} such that $\Delta \phi_0 = 1/\kappa$.

Consider the Cauchy integral

$$f(z) := \frac{1}{2\pi i} \int_{\partial \Omega_0} \frac{(\partial \phi_0 / \partial z)(\zeta)}{\zeta - z} \, d\zeta.$$

As above, we write f_+ and f_- for the restriction of f to Ω_0 and to the complement of $\overline{\Omega}_0$, respectively. Then the Sokhotski-Plemelj formula says that on $\partial\Omega_0$,

$$f_{+}(z) = \frac{\partial \phi_0}{\partial z} + f_{-}(z). \tag{6}$$

Observe next that f_{-} tends to zero as z tends to infinity. Thus, for some constant a, we have that

$$f_{-}(z) = \frac{a}{z} + \tilde{f}(z),$$

where \tilde{f} vanishes to second order at infinity. Such a holomorphic function possesses a $\partial/\partial z$ -primitive F on $\mathbb{C} - \overline{\Omega_0}$. Letting h = 2Re(F), we can rewrite (6) as

$$f_{+}(z) - \frac{a}{z} = \frac{\partial}{\partial z}(\phi_0 + h)$$
 on $\partial\Omega_0$. (7)

Now set

$$\phi = \phi_0 + h$$
 on $\mathbb{C} - \overline{\Omega}_0$,

and observe that since h is the real part of a holomorphic function, $\Delta \phi = \Delta \phi_0 = 1/\kappa$. Moreover, since f_- had a smooth extension to $\partial \Omega_0$, it follows that ϕ extends smoothly to a neighbourhood of the complement of Ω_0 and we can define $\kappa' = 1/(\Delta \phi)$, which will be positive near $\partial \Omega_0$. Finally,

 $S_0 := f_+(z) - a/z$ is a Schwarz function of (Ω_0, ϕ) , which is holomorphic except for a simple pole at 0.

If κ is real analytic and $\partial\Omega_0$ has real analytic boundary, then f_- extends to a holomorphic function over a neighbourhood U of $\partial\Omega_0$ [Isa90, 1.6.4 and 2.5.1], and h similarly extends to a harmonic function over the boundary. Thus, defining ϕ over this neighbourhood as above, we have $\Delta\phi = 1/\kappa$ over this neighbourhood as well, and so $\kappa' = \kappa$.

Remark 3.7. From the above proof, one sees that in fact the second statement holds under the condition that f_{-} extends analytically over $\partial\Omega$; the arguments below show that in this case there is a backwards solution to the Hele-Shaw flow.

Remark 3.8. In what follows we will use in an essential way that ϕ is smooth on a neighbourhood of $\partial\Omega_0$. But one should note that the Sokhotski-Plemelj formula holds for much more general domains (e.g. Lipschitz domains) and one still gets a Schwarz function of (Ω_0, ϕ) ; in this case ϕ will at least have a $C^{1,\alpha}$ extension.

3.3 Holomorphic discs

We are now ready to phrase the Hele-Shaw problem in terms of holomorphic discs. Let ϕ be the subharmonic function defined on the neighbourhood U of $\partial\Omega_0$ from Proposition 3.6, and S_0 be the Schwarz function for (Ω_0, ϕ) . Define

$$\Lambda := \left\{ \left(z, \frac{\partial \phi}{\partial z} \right) : z \in U \right\} \subset \mathbb{C} \times \mathbb{C}.$$

Since this is the graph of a real strictly subharmonic function, it enjoys various properties that will be discussed in the next section. We shall consider a meromorphic function on an open set in \mathbb{C} as a function to the Riemann sphere $\mathbb{P}^1 = \mathbb{C} \cup \{\infty\}$ in the standard way, giving it the value ∞ at its poles.

DEFINITION 3.9. Suppose that (Ω, ϕ) admits a Schwarz function S holomorphic except for having a simple pole at 0. Define

$$\Sigma = \Sigma_{\Omega} := \{ (z, S(z)) \in \mathbb{C} \times \mathbb{P}^1 : z \in \Omega \}.$$
 (8)

So, Σ_{Ω} is a holomorphic disc in $\mathbb{C} \times \mathbb{P}^1$. Moreover:

- (i) if π_1 denotes the projection to the first factor, then $\pi_1 : \Sigma \to \pi_1(\Sigma)$ is an isomorphism;
- (ii) the boundary of Σ lies in Λ ;
- (iii) the closure of Σ intersects $\{0\} \times \mathbb{P}^1$ precisely in the point $p = (0, \infty) \in \mathbb{C} \times \mathbb{P}^1$.

THEOREM 3.10. Suppose that Σ_t is a smooth family of holomorphic discs in $\mathbb{C} \times \mathbb{P}^1$ that satisfy the three conditions above and such that $\Omega_t := \pi_1(\Sigma_t)$ is an increasing family of smooth Jordan domains. Then Ω_t is a solution to the Hele-Shaw flow with permeability $\kappa' := 1/(\Delta \phi)$. Moreover, any smooth increasing family Ω_t of smooth Jordan domains that solves the Hele-Shaw flow with permeability κ' arises in this way.

Proof. The first statement just summarises what we have said thus far. Given Σ_t , it can be realised as the graph of a Schwarz function S_t for $\Omega_t := \pi_1(\Sigma_t)$. Condition (3) says that S_t is holomorphic except for having a simple pole at 0. Thus, the result we want follows from Proposition 3.4.

For the second statement, suppose that Ω_t is a smooth increasing family of smooth Jordan domains that satisfy the Hele-Shaw flow. Let $p_t(z) = p(z,t)$ be the pressure which is required to satisfy $\Delta p_t = -\delta_0$ on Ω_t and $p_t = 0$ on $\partial \Omega_t$. Now define

$$u_t(z) = u(z,t) = \int_0^t p(z,\tau) d\tau$$

and set

$$S_t = \frac{\partial \phi}{\partial z} - \frac{\partial u_t}{\partial z} - \chi_{\Omega_0} \left(\frac{\partial \phi}{\partial z} - S_0 \right),$$

where χ_{Ω_0} denotes the characteristic function of Ω_0 . Then

$$\Delta u = \kappa^{-1} (\chi_{\Omega_t} - \chi_{\Omega_0}) - t \delta_0$$

in the sense of distributions (see [GV06, 3.6], where this is considered for $\kappa \equiv 1$, or Remark 3.12 below) and one easily checks that S_t is a Schwarz function for Ω_t which is holomorphic except for a simple pole at 0. Thus, the Ω_t are induced from the corresponding family Σ_{Ω_t} , as required. \square

In the following section we show that the moduli space of such holomorphic discs has real dimension one, and thus our original disc Σ_0 deforms in a smooth one-dimensional family Σ_t . Observe that condition (1) and the property that $\pi_1(\Sigma_t)$ is a smooth Jordan domain are open conditions and thus, since they hold for Σ_0 , they will hold for Σ_t for small t as well.

Remark 3.11. In much the same way, one can interpret the Hele-Shaw flow with multiple inputs, in which case condition (3) above must be suitably modified. We leave the details to the reader.

Remark 3.12. To understand the long-time behaviour of the Hele-Shaw flow, and also for more general starting domains, one has a weak formulation of the problem. Indeed, following Elliott and Janovsky [EJ81], Gustafsson [Gus85] and Sakai [Sak82, Sak93b], it is possible to cast a weak formulation of the Hele-Shaw flow as an obstacle problem.

For simplicity, assume here that $\kappa \equiv 1$. Let f be a distribution on some domain D. A function u on D is said to solve the corresponding obstacle problem if

$$-\Delta u - f \geqslant 0, \quad u \geqslant 0, (-\Delta u - f)u = 0. \tag{9}$$

The free boundary $\Gamma(u)$ of the obstacle problem is the boundary of the coincidence $\Lambda(u) := \{x : u(x) = 0\}$. If the domain D has a boundary, one also specifies a non-negative function g on S^1 and demands that the solution u should, in addition to satisfying (9), be equal to g on the boundary.

Now let $D = \mathbb{R}^2$ and for any t > 0 set

$$f_t := \chi_{\Omega_0} - 1 + t\delta_0.$$

By general potential theory, the corresponding obstacle problem has a unique lower semicontinuous solution u_t and one calls the family

$$\Omega_t := \{z : u_t(z) > 0\}$$

the weak solution to the Hele-Shaw flow with initial domain Ω_0 . It is known that a smooth solution, if it exists, will coincide with the weak solution and, if the weak solution is regular enough, it is the smooth solution (see e.g. [GV06]). Moreover, there does exist a weak solution

that is defined for all time, but in general the Ω_t will eventually be non-smooth or cease to be simply connected.

Now suppose that S_0 is a Schwarz function of (Ω_0, ϕ) and suppose that $\Delta \phi = 1$ on the complement of Ω_0 . We have seen that such a function exists at least when Ω_0 is Lipschitz. Let Ω_t be the weak solution to the Hele-Shaw flow. We observe that for any $t \in [0, \infty)$, there exists a Schwarz function for (Ω_t, ϕ) , holomorphic except for a simple pole at 0. To see this, let u_t be a solution to the above obstacle problem described. Then one simply notes that the function

$$S_t := \left(\frac{\partial \phi}{\partial z} - \frac{\partial u_t}{\partial z}\right) - \chi_{\Omega_0} \left(\frac{\partial \phi}{\partial z} - S_0\right)$$

is the claimed Schwarz function.

Hence, using the same lifting, we thus see that there is a natural deformation of our initial holomorphic disc Σ_0 that exists for *all* positive time, but whose members need not be smooth and may have more exotic topology. However, the possibilities are constrained, as there are strong regularity results due to Sakai [Sak91, Sak93a] for the boundaries $\partial\Omega_t$ of the domains Ω_t belonging to a weak Hele-Shaw flow, which say that if $\overline{\Omega}_0 \subseteq \Omega_t$ (which, for example, is the case if $\partial\Omega_0$ is C^1), then $\partial\Omega_t$ is real analytic except for having at most a finite number of cusps or double points.

4. Short-time existence of the Hele-Shaw flow with empty initial condition

We are interested in smooth solutions to the Hele-Shaw flow with varying permeability κ and empty initial condition. That is, we wish to find a smooth solution Ω_t such that $\operatorname{Area}(\Omega_t) = t$ for $t \in (0, \epsilon)$ for some $\epsilon > 0$. Observe that this problem is homogeneous in κ , by which we mean that the solution is unchanged if κ is replaced by $c\kappa$ for some $c \in \mathbb{R}_{>0}$ (after a reparameterisation of the time variable).

Our proof is based on a connection between the Hele-Shaw flow and a certain complex homogeneous Monge-Ampère equation (HMAE). We recall that our result extends a theorem of Hedenmalm and Shimorin [HS02], who proved short-time existence under the assumption that κ is real analytic and $\log \kappa$ is strictly subharmonic.

4.1 The homogeneous Monge-Ampère equation

The complex homogeneous Monge–Ampère equation (HMAE) is a higher-dimensional analogue of the Laplace equation on complex manifolds. We first describe some work of Donaldson [Don02], building on [Sem92] by Semmes, that gives an equivalence between regular solutions of a certain HMAE and families of holomorphic discs with boundaries in a so-called 'LS submanifold', which will be defined below.

Let X be a compact Kähler manifold of complex dimension n, and let ω_0 be a Kähler form. This means that locally ω_0 is equal to $i\partial\bar{\partial}\phi$, where ϕ is a smooth strictly plurisubharmonic function. For example, if X has an ample line bundle L, and h is a positive metric on L, then the curvature form $i\Theta_h$ is a Kähler form on X which lies in the first Chern class of L. Any Kähler class in the same cohomology class as ω_0 can be written as $\omega_0 + i\partial\bar{\partial}\phi$, where ϕ is a global smooth function.

Let D denote the closed unit disc in \mathbb{C} and $D^{\times} = D - \{0\}$. Also, let Ω_0 be the pullback of ω_0 by the projection $\pi \colon D \times X \to D$. Suppose next that F is a smooth function on $S^1 \times X$. We shall write $F_{\tau}(\cdot) = F(\tau, \cdot)$, thought of as a function on X, and suppose that $\omega_0 + i\partial \bar{\partial} F_{\tau}$ is a

Kähler form for all $\tau \in S^1$. A regular solution to the associated HMAE is an extension of F to a smooth function Φ on $D \times X$ such that $\omega_0 + i\partial \bar{\partial} \Phi_{\tau}$ is a Kähler form for all $\tau \in D$ and

$$(\Omega_0 + i\partial\bar{\partial}\Phi)^{n+1} = 0$$

on $D \times X$. We observe that clearly finding a solution to this boundary value problem is unchanged if F is replaced by F + c for some constant c.

Now suppose that Φ is a regular solution to the above HMAE. Then the kernel of $\Omega_0 + i\partial\bar{\partial}\Phi$ defines a one-dimensional complex distribution, which one can show is integrable, thus giving a foliation of $D \times X$ by holomorphic discs transverse to the X fibres (see [BK77] and [Don02]).

A further connection with holomorphic discs comes about through the following idea due to Semmes [Sem92]. Let $\Theta := \Theta_1 + i\Theta_2$ denote a holomorphic 2-form on a complex manifold W, where Θ_1 and Θ_2 are real symplectic forms. A (real) submanifold Y of W is called a LS submanifold if it is Lagrangian with respect to Θ_1 while it is symplectic with respect to Θ_2 .

The point of this definition is that there exists a holomorphic fibre bundle W_X over X such that Kähler forms in the same class as ω_0 correspond to closed LS submanifolds in W_X . We sketch its construction: if ω_0 has a potential ϕ_U in some open set U, we identify W_U with the (1,0) part of the complex cotangent bundle. If z_i are local holomorphic coordinates, any (1,0)-form can be written as $\sum_i \xi_i dz_i$; thus, (z_i, ξ_j) are local holomorphic coordinates of W_U . We also have a non-degenerate holomorphic 2-form, namely $\Theta := \sum_i d\xi_i \wedge dz_i$.

If V is some other open set where ω_0 has a potential ϕ_V , then on $U \cap V$ the transition function is given by $\partial(\phi_V - \phi_U)$. It means that the section, locally defined as $\partial\phi_U$, is in fact globally defined. By a simple calculation, the graph of this section turns out to be a LS submanifold in W_X . Let ω be some other Kähler form in the same class as ω_0 . Then $\omega = \omega_0 + i\partial\bar{\partial}\psi$ for some smooth global function ψ , and the section $\partial\phi_U + \partial\psi$ defines a section of W_X . By the same reasons, this is also a LS submanifold. Donaldson showed in [Don02] that Kähler forms in the class of ω_0 are in one-to-one correspondence with the closed LS submanifolds of W_X .

Now let F be a smooth function on $S^1 \times X$ such that $\omega_0 + i\partial \bar{\partial} F_{\theta}$ is positive for all $\theta \in S^1$. For each $\theta \in S^1$, let Λ_{θ} denote the LS submanifold in W_X corresponding to $\omega_0 + i\partial \bar{\partial} F_{\theta}$.

THEOREM 4.1 [Don02, Theorem 3]. There is a regular solution to the complex HMAE with boundary values given by F if and only if there is a smooth family of holomorphic discs $g_x : D \to W_X$ parametrised by $x \in X$ with:

- (i) $\pi(g_x(0)) = x \in X$;
- (ii) for each $\theta \in S^1$ and each $x \in X$,

$$g_x(\theta) \in \Lambda_\theta;$$

(iii) for each $\tau \in D$, the map $x \mapsto \pi(g_x(\tau))$ is a diffeomorphism from X to X.

In fact, for fixed $\tau \in D$, the image of the map $x \mapsto g_x(\tau)$ is the LS submanifold Λ_τ associated to the Kähler form $\omega_0 + i\partial \bar{\partial} \Phi_\tau$.

Using this theorem, Donaldson applied the theory of the moduli spaces for embedded holomorphic discs with boundaries in a totally real submanifold to deduce the following result.

THEOREM 4.2 [Don02, Theorem 1]. The set of boundary conditions F for which the HMAE above has a regular solution Φ is open in the C^2 topology.

4.2 Short-time existence

We now return to the short-time existence problem with empty initial condition. Fix a potential ϕ in the unit ball in \mathbb{C} with $\Delta \phi = 1/\kappa$, where κ is the positive smooth function that encodes the permeability for the Hele-Shaw flow.

In the usual way, think of \mathbb{C} embedded in $\mathbb{P}^1 = \mathbb{C} \cup \{\infty\}$. We let ω_{FS} be the standard Fubini–Study metric on \mathbb{P}^1 , which has potential $\phi_{FS} = \log(1 + |z|^2)$ on \mathbb{C} . Using a partition of unity we can, without loss of generality, assume that ϕ is defined on all of \mathbb{C} and so that $\phi - \phi_{FS}$ extends to a smooth function at infinity (so, said another way, ϕ is the local potential of some globally defined potential whose curvature is in the same Kähler class as ω_{FS}).

We also consider the \mathbb{C}^* -action on \mathbb{C}^2 given by

$$\rho(\lambda): (z, w) \mapsto (\lambda z, \lambda^{-1} w), \quad \lambda \in \mathbb{C}^*,$$

which extends to an action on $\mathbb{P}^1 \times \mathbb{P}^1$. We also denote by ρ the induced action of S^1 on $S^1 \times \mathbb{P}^1$.

PROPOSITION 4.3. There exists a $c \in \mathbb{R}_{>0}$ and a smooth function \tilde{F} on $S^1 \times \mathbb{P}^1$ such that:

- (i) there exists a regular solution to the HMAE with boundary data $\omega_{FS} + i\partial \bar{\partial} \tilde{F}_{\theta}$ for $\theta \in S^1$;
- (ii) there are constants $c, r \in \mathbb{R}_{>0}$ such that for each $\theta \in S^1$, $\omega_{FS} + i\partial \bar{\partial} \tilde{F}_{\theta}$ has local potential $c\phi(\theta z)$ for $z \in B_r$, where B_r is the ball of radius r centred at the origin;
- (iii) the function \tilde{F} is invariant under the S^1 -action ρ .

Assuming this for now, we prove the short-term existence result. Let $\tilde{\Lambda}_{\theta}$ denote the LS manifold associated to $\omega_{\text{FS}} + i\partial\bar{\partial}\tilde{F}_{\theta}$. Under the natural identification of $W_{\mathbb{C}}$ with $\mathbb{C}^2 \to \mathbb{C}$, the second condition tells us that

$$\tilde{\Lambda}_{\theta} \cap (B_{\delta} \times \mathbb{C}) = \left\{ \left(z, c \frac{\partial}{\partial z} \phi(\theta z) \right) : z \in B_{\delta} \right\} = \left\{ \left(z, c \theta \frac{\partial \phi}{\partial z} (\theta z) \right) : z \in B_{\delta} \right\}.$$

Moreover, as \tilde{F} is invariant under ρ , the automorphism $\rho(\theta)$ for $\theta \in S^1$ maps the LS manifold $\tilde{\Lambda}_{\theta}$ to $\tilde{\Lambda}_1$.

By Theorem 4.1, there is an associated family of holomorphic discs g_x in $W_{\mathbb{P}^1}$. Since the function \tilde{F} is invariant under the S^1 -action ρ , the solution Φ is also invariant, and in particular the restriction Φ_0 to the central fibre is S^1 -invariant. Set $\phi_0 := \Phi_0 + \log(1+|z|^2)$. Then ϕ_0 is an S^1 -invariant strictly subharmonic function, which implies that $(\partial \phi_0/\partial z)(0) = 0$ and $(\partial \phi_0/\partial z)(z) \neq 0$ whenever $z \neq 0$. This means that $g_0(0) = (0,0)$, while, for any $x \neq 0$, the second component of $g_x(0)$ is not 0.

Furthermore, the family of discs g_x is invariant under ρ , i.e.

$$\rho(\theta)g_x(\theta\tau) = g_{\theta x}(\tau)$$
 for $\theta \in S^1, \tau \in D$.

In particular,

$$g_0(\theta) = \rho(\theta^{-1})(g_0)(1) \quad \text{for } \theta \in S^1$$
 (10)

and, since $\pi(g_0(0)) = 0$, we see that πg_0 must be the constant map to 0. So, by continuity of the family g, we have that as long as |x| is sufficiently small, the image of $g_x : D \to W_{\mathbb{P}^1}$, $x \neq 0$, lies in $W_{\mathbb{C}} \cong \mathbb{C}^2$.

So, fix such an x with $x \neq 0$. Then, by twisting the disc using the \mathbb{C}^* -action ρ , we get a new punctured disc $f_x : D^{\times} \to \mathbb{C} \times \mathbb{P}^1$ given by

$$f_x(\tau) := \rho(\tau)(g_x(\tau)).$$

Since the second coordinate of $g_x(0)$ is not zero, f_x extends to a map from D to $\mathbb{C} \times \mathbb{P}^1$. Moreover, for $\theta \in S^1$ and $\tau \in D$, we have

$$f_{\theta x}(\tau) = \rho(\tau)g_{\theta x}(\tau) = \rho(\tau\theta)g_x(\theta\tau) = f_x(\theta\tau),$$

so the holomorphic disc defined by f_x depends only on t = |x|, which we shall now denote by Σ_t . Observe that $f_x(0) = (0, \infty)$, so Σ_t meets $\{0\} \times \mathbb{P}^1$ at $p := (0, \infty) \in \mathbb{C} \times \mathbb{P}^1$. Moreover, if $\tau \in S^1$, then $g_x(\tau) \in \tilde{\Lambda}_{\tau}$. Thus, as long as t is sufficiently small, the boundary of Σ_t lies in

$$\Lambda := \left\{ \left(z, c \frac{\partial \phi}{\partial z} \right) \right\}.$$

Recall that the map $\gamma(x) := \pi g_x(1)$ is a diffeomorphism of \mathbb{P}^1 to itself. Since, by invariance, $\pi f_x(\theta) = \pi g_{\theta x}(1) = \gamma(\theta x)$ for $\theta \in S^1$, we deduce that

$$\partial \Omega_t = \{ \pi f_x(\theta) : \theta \in S^1 \} = \{ \gamma(\theta x) : \theta \in S^1 \},$$

which is precisely the image of the circle of radius t = |x| under γ . In particular, this shows that, for small t > 0, Ω_t is an increasing family of smooth Jordan domains containing the origin, and $\pi \colon \Sigma_t \to \pi(\Sigma_t)$ is an isomorphism and the limit Ω_t as t tends to zero is the origin. Hence, by Theorem 3.10, the family $\Omega_t = \pi(\Sigma_t)$ satisfies the Hele-Shaw flow with permeability $\kappa := 1/(c\Delta\phi)$. Thus, by the homogeneity of the Hele-Shaw problem with empty initial condition, this solves the Hele-Shaw flow with permeability κ as well after a reparameterisation of time.

Thus, it remains to prove Proposition 4.3. Observe that if ϕ happened to be rotation invariant, i.e. $\phi(\tau z) = \phi(z)$ for all $\tau \in S^1$, then the function

$$F(\theta, z) := \phi(\theta z) - \phi_{FS}(z) \tag{11}$$

would also be invariant and the HMAE has a trivial regular solution, namely $\Phi(\tau, z) := \phi(z) - \log(1 + |z|^2)$ (this reflects the elementary observation that if the permeability κ is radially symmetric, then the Hele-Shaw flow with empty initial condition will be the trivial solution in which Ω_t is a disc centred at the origin). Of course, this need not be the case, but we will show that any potential ϕ is close (in a precise sense) to one that is invariant, at which point we can apply Donaldson's openness theorem.

We will need the following regularisation of the maximum of two smooth functions, which we prove for completeness.

LEMMA 4.4. Let $\alpha = \alpha(z)$ and $\beta = \beta(z)$ be real-valued smooth functions on the closure of a bounded open subset U of \mathbb{C} . Let f be a smooth non-negative bump function on the real line with unit integral and support in (-a, a) for some a > 0 and define $u: U \to \mathbb{C}$ by

$$u = \int_{\mathbb{R}} \max\{\alpha, \beta + \lambda\} f(\lambda) d\lambda.$$

- (i) If z is such that $\alpha(z) > \beta(z) + a$, then $u(z) = \alpha(z)$. Similarly, if $\alpha(z) < \beta(z) a$, then $u(z) = \beta(z)$.
 - (ii) The function u is smooth on U and

$$||u - \alpha||_{C^2} \leqslant a + ||\alpha - \beta||_{C^2} + ||d\alpha - d\beta||_{C^0}^2 ||f||_{C^0}.$$

Proof. If $\alpha(z) > \beta(z) + a$, then $\sup\{\alpha, \beta + \lambda\} = \alpha$ for all $\lambda \in (-a, a)$ and so $u(z) = \int_{\lambda} \alpha(z) f(\lambda) d\lambda = \alpha(z)$. The case when $\alpha(z) < \beta(z) - a$ is similar.

Now, setting $\gamma = \alpha - \beta$, we have

$$u = \int_{-\infty}^{\gamma} \alpha f(\lambda) d\lambda + \int_{\gamma}^{\infty} (\beta + \lambda) f(\lambda) d\lambda,$$

which shows that u is smooth and

$$u - \alpha = \int_{\gamma}^{\infty} (\beta - \alpha) f(\lambda) d\lambda + \int_{\gamma}^{\infty} \lambda f(\lambda) d\lambda,$$

since $\int_{\lambda} \alpha f(\lambda) d\lambda = \alpha$. Since $\lambda f(\lambda) = 0$ if $|\lambda| > a$, this implies that

$$||u - \alpha|| \leqslant ||\alpha - \beta||_{C^0} + a.$$

Now, for any any smooth functions α, β, γ on U, we have from the chain rule

$$d\int_{-\infty}^{\gamma} \alpha f(\lambda) d\lambda = \int_{-\infty}^{\gamma} d\alpha f(\lambda) d\lambda + \alpha (f \circ \gamma) d\gamma$$

and similarly

$$d\int_{\gamma}^{\infty} (\beta + \lambda) f(\lambda) d\lambda = \int_{\gamma}^{\infty} d\beta f(\lambda) d\lambda - (\beta + \gamma) (f \circ \gamma) d\gamma.$$

Thus, putting $\gamma = \alpha - \beta$, we have $\alpha(f \circ \gamma) d\gamma = (\beta + \gamma)(f \circ \gamma) d\gamma$, giving

$$du = \int_{-\infty}^{\gamma} (d\alpha) f(\lambda) d\lambda + \int_{\gamma}^{\infty} (d\beta) f(\lambda) d\lambda$$
 (12)

and hence

$$du - d\alpha = \int_{\alpha}^{\infty} (d\beta - d\alpha) f(\lambda) d\lambda, \tag{13}$$

yielding $|du - d\alpha| \leq ||\alpha - \beta||_{C^1}$.

For the second order derivative, a further differentiation of (13) gives that when $D = \frac{\partial^2}{\partial x \partial y}$,

$$Du - D\alpha = \int_{\gamma}^{\infty} (D\beta - D\alpha) f(\lambda) \, d\lambda + (f \circ \gamma) \frac{\partial(\beta - \alpha)}{\partial u} \frac{\partial \gamma}{\partial x},$$

where again $\gamma = \alpha - \beta$, and similarly for the other second order derivatives. Thus,

$$|Du - D\alpha| \le ||\alpha - \beta||_{C^2} + ||d\alpha - d\beta||_{C^0}^2 ||f||_{C^0},$$

which completes the proof.

Returning to the Hele-Shaw flow, the initial data consists of a real-valued smooth strictly subharmonic ϕ , which we may write locally as

$$\phi(z) = \text{Re}(\alpha_0 + \alpha_1 z + \alpha_2 \bar{z} + \alpha_3 z^2 + \alpha_4 \bar{z}^2) + \beta |z|^2 + o(|z|^2),$$

where β is a real positive number. Our requirement on ϕ was that $\Delta \phi = 1/\kappa$, so without loss of generality we can assume that this first term is zero since it is harmonic. By rescaling, there is no loss of generality if we assume that $\beta = 1$ and so in fact

$$\phi(z) = |z|^2 + o(|z|^2).$$

Now let ψ be an S^1 -invariant smooth strictly subharmonic function on $\mathbb C$ that is equal to $|z|^2$ on the unit disc, and such that $\psi - \log(1+|z|^2)$ extends to a smooth function as |z| tends to infinity.

LEMMA 4.5. For all $\epsilon > 0$, there exist a smooth strictly subharmonic function ϕ^{ϵ} and $\delta_1, \delta_2, r > 0$ such that:

- (i) $\phi^{\epsilon} = (1 \delta_1)\phi \delta_2$ on the ball $B_r = \{|z| < r\}$;
- (ii) $\phi^{\epsilon} = \psi$ for |z| > 1;
- (iii) $\|\phi^{\epsilon} \psi\|_{C^2} < \epsilon$.

Proof. Let $\epsilon > 0$ be small. Write $\phi(z) = |z|^2 + g(z)$, where $g(z) = O(|z|^3)$, so say $|g(z)| < C|z|^2$ on the unit ball. Fix a small $R \in (0, 1/5)$ so that $||g||_{C^2} < \epsilon/20$ on B_R . By shrinking R if necessary, we may assume also that $CR < \epsilon/20$. We observe for later use that the C^2 -bound actually implies that $|g'(z)| \leq \epsilon R/20$ on B_R .

Now let $\delta_1 := \epsilon/20$, $\delta_2 := \epsilon R^2 < \epsilon/20$ and $a := \delta_2/2$. Fix a smooth non-negative bump function f with unit integral and support in [-a,a] and $||f||_{C^2} \le 2a^{-1}$. Putting $\alpha = \psi$ and

$$\beta = (1 - \delta_1)\phi - \delta_2$$

into Lemma 4.4, consider the function on B_R given by

$$\phi^{\epsilon} = \int_{\lambda} \max\{\psi, (1 - \delta_1)\phi - \delta_2 + \lambda\} f(\lambda) d\lambda,$$

which is smooth. Moreover it is strictly subharmonic since both ψ and ϕ are.

If
$$|z| = R$$
, then $(1 - \delta_1)|g(z)| < 2CR^3 \le \epsilon R^2/20 = \delta_1 R^2$, and so

$$\alpha(z) = \psi(z) = R^2 > (1 - \delta_1)(R^2 - g(z)) - \delta_2/2 = \beta(z) + a$$
 on ∂B_R .

Thus, $\alpha > \beta$ on a neighbourhood of ∂B_R , and so by Lemma 4.4 $\phi^{\epsilon} = \alpha = \psi$ on this neighbourhood. Hence, by declaring ϕ^{ϵ} to be equal to ψ outside of B_R , we get that ϕ^{ϵ} is a smooth strictly subharmonic function on all of \mathbb{C} , and (2) certainly holds. We next notice that $(1 - \delta_1)\phi(0) - \delta_2 = -\delta_2 = -2a = \psi(0) - 2a$. Thus, there exists a small ball B_r around a for which $\beta = (1 - \delta_1)\phi - \delta_2 < \psi - a$, and so $\phi^{\epsilon} = \beta$ on B_r by Lemma 4.4, which gives (1).

It remains to bound the C^2 -norm of $\phi^{\epsilon} - \psi$. Observe that there is nothing to show outside of B_R . On the other hand, on B_R we have

$$\alpha - \beta = \psi - ((1 - \delta_1)\phi - \delta_2) = \delta_1 |z|^2 - (1 - \delta_1)g(z) + \delta_2.$$

Thus, the C^2 -norm of $\alpha - \beta$ is bounded by $4\delta_1 + 2\epsilon/20 + \delta_2 < \epsilon/2$. Moreover, since $|g'(z)| \le \epsilon R/20$ on B_R , we have

$$|d\alpha - d\beta| \le \delta_1 3R + 2\epsilon R/20 \le \epsilon R/4.$$

Thus, as $||f||_{C^0} \le 2a^{-1} = 2/\delta_2$, Lemma 4.4 gives

$$\|\phi^{\epsilon} - \psi\|_{C^2} \le \epsilon/2 + (\epsilon R/4)^2 \|f\|_0 \le \frac{\epsilon}{2} + \frac{\epsilon^2 R^2}{8\delta_2} = \epsilon/2 + \frac{\epsilon^2 R^2}{8\epsilon R^2} < \epsilon,$$

which gives (3).

Proof of Proposition 4.3. Let ψ be as above, so it is an S^1 -invariant potential. Then the function

$$F_0(\theta, z) := \psi(z) - \phi_{FS}(z)$$

is independent of θ , and so there certainly exists a regular solution to the HMAE with boundary data given by

$$\omega_{\tau} := \omega_{\text{FS}} + i\partial\bar{\partial}F_0 = i\partial\bar{\partial}\psi,$$

namely the trivial one obtained by pulling $i\partial\bar{\partial}\psi$ to the product. Thus, by Donaldson's openness theorem, there exist an $\epsilon > 0$ and a regular solution to the HMAE with boundary data determined by any smooth function G with $||G - F_0||_{C^2} < \epsilon$.

Now let ϕ^{ϵ} , δ_1 , δ_2 , r be as in Lemma 4.5 and set

$$\tilde{F}(\theta, z) := \phi^{\epsilon}(\theta z) - \phi_{FS}(z).$$

Then, by construction, \tilde{F} is invariant under the action of ρ and by the lemma $\|\tilde{F} - F_0\|_{C^2} = \|\phi^{\epsilon} - \psi\|_{C^2} < \epsilon$. Hence, there is a solution to the HMAE with boundary data $\omega_{\text{FS}} + i\partial \partial \tilde{F}_{\tau}$. Moreover, by the properties of ϕ^{ϵ} , we know that there is a B_r so that $\phi^{\epsilon} = (1 - \delta_1)\phi + \delta_2$ on B_r . So, letting $c = (1 - \delta_1)$, this says precisely that for all $\theta \in S^1$ we have that $\omega_{\text{FS}} + i\partial \bar{\partial} \tilde{F}_{\theta}$ has local potential $c\phi(\theta z)$ for $z \in B_r$.

5. Holomorphic curves with boundaries in a totally real submanifold

To continue to exploit our connection between the Hele-Shaw flow and the theory of holomorphic discs, we now summarise the parts of the literature that we shall need.

5.1 The moduli space

Let M be a complex manifold of complex dimension n. A real submanifold Λ is said to be totally real if $T\Lambda \cap J(T\Lambda) = \{0\}$, where J denotes the complex structure on M. A totally real submanifold is said to be maximal if it has real dimension n.

Let $(\Sigma, \partial \Sigma)$ be a Riemann surface with boundary. A holomorphic non-constant map $f : \Sigma \to M$ is called a holomorphic curve in M if f extends to a C^1 function on $\partial \Sigma$. If f is an embedding, then we call the image of f an embedded holomorphic curve. By abuse of terminology, we shall refer to this image as Σ , and say that it has boundary in Λ if $f(\partial \Sigma) \subset \Lambda$. In the special case that Σ is the unit disc $D \subset \mathbb{C}$ and $f(S^1) \subset \Lambda$, we call the image an embedded holomorphic disc with boundary in Λ . By the smooth Riemann mapping theorem [CP96, Theorem 3.4], one can equivalently replace the disc D with any smooth Jordan domain.

The moduli space of holomorphic curves with boundary in a totally real maximal submanifold has been studied by numerous authors in different contexts, e.g. Bishop [Bis65], Donaldson [Don02], Forstnerič [For87] and Gromov [Gro85]. In complex analysis this is related to polynomial hulls and the homogeneous Monge–Ampère equation [Don02], while in symplectic topology it is used in the study of Lagrangian submanifolds [Gro85]. More recently, LeBrun and Mason [LM02, LeB06] have shown a connection to twistor theory.

The first step in this theory is to give the space of all (not necessarily holomorphic) embedded curves in some regularity class with boundary in Λ the structure of a Banach manifold \mathcal{B} . Let Σ be such an embedded curve, let N denote the normal bundle and let E be the normal bundle of $\partial \Sigma$ in Λ . We can identify E with a totally real subbundle of N restricted to $\partial \Sigma$. Locally around Σ the Banach manifold \mathcal{B} is modelled on the Banach space $C^{k+1,\alpha}(\Sigma,N,E)$ of sections of N with boundary values in E (this construction uses the exponential map with respect to some appropriately chosen metric; see [LeB06]).

The next step is to consider a Banach vector bundle $\pi: \mathcal{E} \to \mathcal{B}$ whose fibre over Σ is

$$C^{k,\alpha}(\Sigma,\Lambda^{0,1}\otimes N)$$

and a canonical section $S: \mathcal{B} \to \mathcal{E}$ whose zero locus $\mathcal{M} := S^{-1}(0)$ is the space of holomorphic curves. The implicit function theorem for Banach spaces says that \mathcal{M} is a smooth manifold provided that the graph of S is transverse to the zero section. This is so if and only if at any

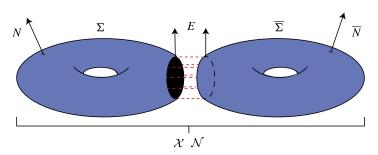


FIGURE 3. (Colour online) The Schottky double.

point Σ in \mathcal{M} , the linearisation D_{Σ} , which by definition is $D\mathcal{S}$ composed with the projection to the fibre of \mathcal{E} , is surjective and has a right inverse. Now D_{Σ} is nothing but the Cauchy–Riemann operator $\bar{\partial}$ that maps sections of N with boundary values in E to (0,1)-forms with values in N. It is well known that this operator is Fredholm, so what remains to establish transversality of \mathcal{S} is surjectivity. Thus, if the Cauchy–Riemann operator is surjective, then \mathcal{M} is a smooth manifold and its dimension is given by the index of $\bar{\partial}$.

In general, the problem of proving transversality involves picking a new generic almost complex structure on the manifold M. However, for our purposes, M has complex dimension two and then the problem becomes significantly easier and, as we shall see, reduces to the computation of a single topological invariant of a related holomorphic curve.

5.2 Dimension count and the Schottky double

Following LeBrun in [LeB06], we now discuss how to use the Schottky double to compute the dimension of the moduli space \mathcal{M} of embedded holomorphic curves in a manifold M of complex dimension two.

Let Σ be a compact Riemann surface with boundary $\partial \Sigma$. By gluing it together with its complex conjugate $\bar{\Sigma}$ along $\partial \Sigma$, we get a closed Riemann surface \mathcal{X} (assuming some regularity of Σ ; see [LeB06]). In the theory of quadrature domains $\bar{\Sigma}$ is called the Schottky double of Σ [Gus83]. The complex conjugate \bar{N} of N is a holomorphic vector bundle on $\bar{\Sigma}$, and by gluing N and \bar{N} along $\partial \Sigma$ so that $E = \bar{E}$ we get a holomorphic vector bundle \mathcal{N} on \mathcal{X} (see Figure 3).

There is an antiholomorphic involution ρ on \mathcal{X} which lifts to \mathcal{N} such that E is the fixed point set of ρ . As noted in [LeB06], this implies that E is real analytic as a subspace of \mathcal{N} . This involution thus acts on each of the vector spaces

$$C^{k+1,\alpha}(\Lambda,\mathcal{O}(\mathcal{N})) \quad \text{and} \quad H^p(\mathcal{X},\mathcal{O}(\mathcal{N})) \quad \text{for } p=0,1.$$

Let $C^{k+1,\alpha}_{\rho}(\mathcal{X},\mathcal{O}(\mathcal{N}))$ and $H^p_{\rho}(\mathcal{X},\mathcal{O}(\mathcal{N}))$ denote the invariant subspaces. Thus,

$$H^p(\mathcal{X},\mathcal{O}(\mathcal{N})) = H^p_\rho(\mathcal{X},\mathcal{O}(\mathcal{N})) \oplus i H^p_\rho(\mathcal{X},\mathcal{O}(\mathcal{N})).$$

LeBrun showed in [LeB06] that

$$C^{k+1,\alpha}(\Sigma, N, E) \cong C^{k+1,\alpha}_{\rho}(\mathcal{X}, \mathcal{O}(\mathcal{N}))$$

with a canonical isomorphism. Also [LeB06, Lemma 1], the kernel of the Cauchy–Riemann operator is canonically isomorphic to $H^0_{\rho}(\mathcal{X}, \mathcal{O}(\mathcal{N}))$ while the cokernel is canonically isomorphic to $H^1_{\rho}(\mathcal{X}, \mathcal{O}(\mathcal{N}))$. Thus, $\bar{\partial}$ is surjective if and only if $h^1(\mathcal{X}, \mathcal{O}(\mathcal{N})) = 0$, and then the index is equal to $h^0(\mathcal{X}, \mathcal{O}(\mathcal{N}))$.

Now suppose that the complex dimension of the ambient manifold M is two. Then \mathcal{N} is a complex line bundle, and so as long as $\deg \mathcal{N} > 2g - 2$, where g is the genus of \mathcal{X} , then the numbers $h^0(\mathcal{X}, \mathcal{O}(\mathcal{N}))$ and $h^1(\mathcal{X}, \mathcal{O}(\mathcal{N}))$ are topological invariants that depend only on g and the degree of \mathcal{N} .

If Λ happens to be the fixed point set of an antiholomorphic involution ρ of M, then the Schottky double \mathcal{X} of Σ can be identified with the Riemann surface $\Sigma \cup \rho(\Sigma)$, and \mathcal{N} is then identified with the normal bundle of $\Sigma \cup \rho(\Sigma)$ in M. Hence, a strategy to compute the numbers $h^0(\mathcal{X}, \mathcal{O}(\mathcal{N}))$ and $h^1(\mathcal{X}, \mathcal{O}(\mathcal{N}))$ for a general pair (Σ, Λ) in the four-dimensional case is to continuously perturb (Σ, Λ) to some (Σ', Λ') , where Λ' is the fixed point set of an involution ρ , and then use the adjunction formulae to compute the degree of the normal bundle of $\Sigma' \cup \rho(\Sigma')$.

6. Moduli spaces of quadrature domains

We digress in this section from the Hele-Shaw flow, and consider the above setup in the case $\Lambda = \{(z, \bar{z})\}$, which is related to the concept of quadrature domains.

DEFINITION 6.1. A bounded domain Ω in \mathbb{C} is called a *quadrature domain* if there exist finitely many points $a_1, \ldots, a_m \in \Omega$ and coefficients c_{kj} such that for any integrable holomorphic function f on Ω the quadrature identity holds:

$$\int_{\Omega} f \, dA = \sum_{k=1}^{m} \sum_{j=0}^{n_k - 1} c_{kj} f^{(j)}(a_k).$$

The integer $n = \sum_{k=1}^{m} n_k$ is called the *order* of the quadrature domain (assuming $c_{k,n_k-1} \neq 0$). We say that a quadrature domain is smooth if its boundary is smooth. We also recall that the *connectivity* c of a domain Ω is the number of connected components of $\partial\Omega$.

Assume that $(\Omega, \phi(z) = |z|^2)$ has a Schwarz function S. Then

$$\int_{\Omega} f \, dA = -\frac{i}{2} \int_{\Omega} f \, d(\bar{z} \, dz) = -\frac{i}{2} \int_{\partial \Omega} f \bar{z} \, dz$$

$$= -\frac{i}{2} \int_{\partial \Omega} f S \, dz = -\frac{i}{2} \int_{\Omega} f \bar{\partial} S \, dz$$

$$= \sum_{k=1}^{m} \sum_{j=0}^{n_k - 1} c_{kj} f^{(j)}(a_k),$$

where a_k are the poles of S and n_k is the order of the pole at a_k , and thus Ω is a quadrature domain. It is proved in [AS76, Lemma 2.3] that the converse holds as well. Clearly then, the order of the domain n equals the number of poles of S counted with multiplicity.

It is also clear that the Schwarz function S is uniquely determined by the domain, since if we had two Schwarz functions, their difference would be a meromorphic function that was zero on the boundary, and therefore this difference must be zero.

From now on, assume that the quadrature domain Ω has smooth boundary. Consider the graph

$$\Sigma := \{(z, S(z)) : z \in \Omega\}$$

as an embedded holomorphic curve in $\mathbb{C} \times \mathbb{P}^1$. It is attached along its boundary to the totally real submanifold

$$\Lambda = \{(z,\bar{z}): z \in \mathbb{C}\}.$$

Since Λ is the fixed point set of the antiholomorphic involution $\rho:(z,w)\mapsto(\bar{w},\bar{z})$, the Schottky double \mathcal{X} is naturally identified with $\Sigma\cup\rho(\Sigma)$ and the normal bundle \mathcal{N} is identified with the normal bundle of $\Sigma\cup\rho(\Sigma)$.

We wish to calculate the degree of \mathcal{N} . By the adjunction formula,

$$\mathcal{N} = \mathcal{O}(\mathcal{X})_{|\mathcal{X}} = (K_{\mathbb{P}^1 \times \mathbb{P}^1})^*_{|\mathcal{X}} \otimes K_{\mathcal{X}},$$

where $\mathcal{O}(\mathcal{X})$ denotes the line bundle associated to the divisor \mathcal{X} . The line bundle $K_{\mathbb{P}^1 \times \mathbb{P}^1}$ is represented by the divisor $-2(H_1 + H_2)$, where H_1 and H_2 denote the hyperplanes $\mathbb{P}^1 \times \{\infty\}$ and $\{\infty\} \times \mathbb{P}^1$, respectively. Thus,

$$\deg \mathcal{N} = 2(H_1 + H_2) \cdot \mathcal{X} + \deg K_{\mathcal{X}},$$

where the dot represents the intersection number of the relevant divisors. Clearly,

$$H_1 \cdot \mathcal{X} = H_2 \cdot \mathcal{X} = n$$

and

$$\deg K_{\mathcal{X}} = 2g - 2,$$

where g denotes the genus of \mathcal{X} . Combined, this yields that

$$\deg \mathcal{N} = 4n + 2g - 2.$$

Now n > 0, so deg $\mathcal{N} \ge 2g + 2$, which implies that $h^1(\mathcal{X}, \mathcal{N}) = 0$ and, by Riemann–Roch, that

$$h^{0}(\mathcal{X}, \mathcal{N}) = \deg \mathcal{N} - g + 1 = 4n + g - 1.$$

Finally, note that the genus g is precisely c-1, where c is the connectivity number of Ω .

Hence, the moduli space of embedded holomorphic curves with boundaries in Λ is a smooth manifold of real dimension 4n+c-2 near Σ . Any such holomorphic curve lying close enough to Σ gives a Schwarz function of a smoothly bounded quadrature domain. By the fact that all quadrature domains have unique Schwarz functions (again with respect to $\phi(z) = |z|^2$), it follows that the moduli space of smoothly bounded quadrature domains of order n > 0 and connectivity g is a manifold of real dimension 4n+c-2. We have thus proved Theorem 2.3 as stated in the introduction.

7. Short-time existence of the Hele-Shaw flow

This section completes the proof of Theorem 2.2. To ease notation, let $\Omega = \Omega_0$ be a smooth Jordan domain. We saw above that we could construct a generalised Schwarz function S of the pair (Ω, ϕ) , where $\Delta \phi = 1/\kappa$ on the complement of Ω and ϕ extends smoothly to a neighbourhood of the complement. If Σ denotes the graph of S and Λ the graph of $\partial \phi/\partial z$, we have that Σ is a holomorphic disc whose boundary lies in the totally real submanifold Λ .

We want to analyse the moduli space of holomorphic discs near Σ with boundary in Λ that intersects the hyperplane $H_1 = \mathbb{P}^1 \times \{\infty\}$ at the point $p = (0, \infty) \in \mathbb{C} \times \mathbb{P}^1$.

First we consider the moduli space of all such discs, irrespective of their intersection with H_1 . We need to calculate the numbers $h^0(\mathcal{X}, \mathcal{N})$ and $h^1(\mathcal{X}, \mathcal{N})$. As we continuously deform the domain Ω to the unit disc Ω' , the pair $(\mathcal{X}, \mathcal{N})$ and the submanifold Λ continuously deform to the pair $(\mathcal{X}', \mathcal{N}')$ and $\Lambda' = \{(z, \bar{z}) : z \in \mathbb{C}\}$, respectively. Thus, the Schwarz function for Ω' is simply 1/z, i.e. the usual (interior) Schwarz function of the unit disc thought of as a quadrature domain. Since the numbers $h^0(\mathcal{X}, \mathcal{N})$ and $h^1(\mathcal{X}, \mathcal{N})$ are invariant under continuous deformation, the calculation in the previous section yields that $h^1(\mathcal{X}, \mathcal{N}) = 0$ and $h^0(\mathcal{X}, \mathcal{N}) = 3$, since n = 1 and g = 0. Thus, the required moduli space is a smooth manifold of real dimension three near Σ .

Considering moduli spaces of holomorphic curves passing through a given point is also standard in the theory (see, for example, [MS04]). We simply replace our Banach manifold \mathcal{B} with the subspace of curves going through the point, which is locally modelled on the Banach subspace of sections to the normal bundle that vanish at that point. We will denote this space by $C^{k+1,\alpha}(\Sigma, N, E)_0$. Following [LeB06], it follows that this space is naturally isomorphic to the space of ρ invariant sections of \mathcal{N} that vanish at both p and $\rho(p)$. We denote this space by $C^{k+1,\alpha}_{\rho}(\mathcal{X},\mathcal{N})_0$. The section \mathcal{S} and its linearisation $\bar{\partial}$ are simply the restrictions of the original ones.

We check first that $\bar{\partial}$ is still surjective. Pick an arbitrary element

$$g \in C^{k,\alpha}(\Sigma, \Lambda^{0,1} \otimes N).$$

By the above, there exists a section $f \in C^{k+1,\alpha}(\Sigma, N, E)$ such that $\bar{\partial} f = g$. Since the degree of \mathcal{N} is positive and \mathcal{X} is isomorphic to \mathbb{P}^1 , we know that there is a holomorphic section, s say, of \mathcal{N} that is equal to f at p but zero at $\rho(p)$. Then the section $s + \rho(s)$ lies in $H^0_{\rho}(\mathcal{X}, N)$, and thus corresponds to an element \tilde{s} in the kernel of $\bar{\partial}$. We have that $\tilde{s} = f$ at the point p. Thus, $f - \tilde{s}$ lies in $C^{k+1,\alpha}(\Sigma, N, E)_0$ and $\bar{\partial}(f - \tilde{s}) = g$. This shows that the restriction of $\bar{\partial}$ is still surjective.

The kernel of the restricted Cauchy–Riemann operator is of course the intersection of the original kernel with the subspace $C^{k+1,\alpha}(\Sigma,N,E)_0$. Under the natural isomorphism this equals the intersection of $H^0_{\rho}(\mathcal{X},N)$ and $C^{k+1,\alpha}_{\rho}(\mathcal{X},\mathcal{N})_0$. Let $H^0(\mathcal{X},N)_0$ denote the subspace of holomorphic sections that vanish at both p and $\rho(p)$. The involution ρ acts on this space by

$$\rho(s)(x) := \rho(s(\bar{\rho(x)}))$$

and, if $H^0_{\rho}(\mathcal{X}, N)_0$ denotes the invariant real subspace, we have that

$$H^0(\mathcal{X}, N)_0 \equiv H^0_\rho(\mathcal{X}, N)_0 \oplus iH^0_\rho(\mathcal{X}, N)_0. \tag{14}$$

Clearly, $H^0(\mathcal{X}, N)_0$ is the intersection of $H^0_{\rho}(\mathcal{X}, N)$ and $C^{k+1,\alpha}_{\rho}(\mathcal{X}, \mathcal{N})_0$, and from (14) we get that the real dimension of $H^0_{\rho}(\mathcal{X}, N)_0$ is equal to the complex dimension of $H^0(\mathcal{X}, N)_0$. Since the degree of \mathcal{N} is two and $\mathcal{X} \cong \mathbb{P}^1$, the complex dimension of $H^0(\mathcal{X}, N)_0$ is one. Thus, the index of the restricted Cauchy–Riemann operator is one.

Together with the surjectivity, this implies that the moduli space of nearby holomorphic discs with boundary in Λ and going through p is a smooth manifold of real dimension one. Thus, $\Sigma_0 = \Sigma$ varies in a smooth family Σ_t for t sufficiently small and, by Theorem 3.10, it remains to prove that the family of domains $\Omega_t = \pi(\Sigma_t)$ is increasing.

The tangent space of the family of discs at Σ is given by $H^0_{\rho}(\mathcal{X}, N)_0$ restricted to Σ . Since a non-zero element in $H^0_{\rho}(\mathcal{X}, N)_0$ vanishes only at the points p and $\rho(p)$, it is non-vanishing along the boundary of Σ . The real subspace E is one dimensional and it has one direction going out of Ω_0 and one direction going in. The non-vanishing implies that a non-zero tangent points either outwards everywhere or inwards everywhere. Thus (replacing t with -t if necessary), the family Ω_t is increasing.

Remark 7.1. One sees that in fact we have proved slightly more than claimed, namely that there exist a smooth positive function κ' defined in a neighbourhood of $\partial\Omega_0$ with $\kappa=\kappa'$ outside of Ω_0 , and an $\epsilon>0$ such that there exists a smooth increasing family of domains $\{\Omega_t\}_{t\in(-\epsilon,\epsilon)}$ which solves the Hele-Shaw flow with varying permeability κ' . This extension κ' is not unique, but a given choice uniquely determines the flow, in the sense that any two such flows agree on their common domain.

In fact, if $\kappa \equiv 1$ and the initial domain is simply connected (which we always assume is the case), then it is known that the boundary of the domain being real analytic is necessary for there to be a solution backwards in time (see [Tia00] or [Gus85, Theorem 10]). Thus, we see that this issue can be circumvented if we modify the permeability appropriately (although we have little control of this modification).

8. The inverse potential problem and moment flows

Let ρ be a density function on \mathbb{C} (so we have changed notation from previous sections, in which this density was played by $1/\kappa$). The associated potential of a domain Ω is the subharmonic function

$$U^{\Omega}(z) := \int_{\Omega} \log|z - w|^2 \rho(w) \, dA(w),$$

where dA is the Lebesgue measure. Note that U^{Ω} is harmonic on the complement of Ω . Let D be some big disc containing Ω . The inverse potential problem asks whether a given harmonic function U on the complement of D (with proper growth at infinity) can be realised (uniquely) as the potential of a domain Ω in D.

To see the relationship with the complex moments, consider

$$G := \frac{\partial U}{\partial z},$$

which is holomorphic if U is harmonic. If $U = U^{\Omega}$ for some domain Ω , then

$$G(z) = \frac{\partial}{\partial z} \int_{\Omega} \log|z - w|^2 \rho(w) \, dA(w) = \int_{\Omega} \frac{\rho(w)}{z - w} \, dA(w). \tag{15}$$

Now, for large |z|, we can write this integral as a convergent power series in z^{-k} ,

$$\int_{\Omega} \frac{\rho(w)}{z - w} dA(w) = \sum_{k=1}^{\infty} a_k z^{-k},$$

where

$$a_k := \int_{\Omega} w^{k-1} \rho(w) \, dA(w).$$

Thus, the coefficients a_k of the power series of G at infinity equal the complex moments of Ω with respect to the measure ρdA . Thus, the inverse potential problem be restated as asking for a (unique) domain with prescribed complex moments.

This potential problem has a rich history, both for the plane and for higher dimensions, and also for more complicated kernels replacing the expression $\ln |z - w|^2$ above (see, for example, [Isa90] and the references therein). For this particular problem in the plane it is known that prescribing the complex moments does not uniquely determine the domain (although it appears to be unknown if this uniqueness can fail for domains with smooth boundary). However, starting with a suitable smooth domain Ω_0 , for small variations U_t of the potential U^{Ω_0} there is a unique Ω_t close to Ω such that $U_t = U^{\Omega_t}$. Thus, one can think of the set of moments as giving local parameters for the space of domains. We refer the reader to [Isa90, § 2.4] and [Che96, § 2] for precise statements. We also point out the interesting work of Wiegmann and Zabrodin in this context, which connects these parameters to an integrable system coming from the dispersionless Toda lattice [WZ99].

We have seen that the Hele-Shaw flow can be phrased as a local existence question related to the inverse potential problem. Namely, if Ω is a smooth Jordan domain containing the origin, then there is a non-trivial one-parameter family of smooth domains Ω_t , all having the same higher moments as Ω and whose area increases linearly. In this section we will prove short-time existence of a similar flow in which all the higher moments are allowed to vary linearly. Variants of the Hele-Shaw flow under some other force (e.g. gravity) were considered by Escher and Simonett [ES96, ES97a, ES97b] and this gives a physical interpretation to some of these variations.

THEOREM 8.1. Let Ω be a smooth Jordan domain, and V be a smooth, nowhere-vanishing outward pointing normal vector field on $\partial\Omega$. Then there exists a smooth variation Ω_t for $t \in [0, \epsilon)$ for some $\epsilon > 0$ such that

$$\left. \frac{d}{dt} \right|_{t=0} \partial \Omega_t = V$$

whose moments vary linearly in t.

Note that without the assumption on the vector field V pointing outwards this theorem is not true; for example, in the Hele-Shaw flow when $\rho \equiv 1$ and $V = \nabla p$, this would mean solving the Hele-Shaw flow backwards in time, which is impossible unless the boundary of Ω is real analytic.

Of course, the way in which the moments vary will depend on V. To discuss this, suppose that V is any normal vector field defined on the boundary of a smooth Jordan domain Ω . Write the measure $V\rho ds$ as the restriction of a complex one-form g(z)dz to the curve $\partial\Omega$. The complex-valued function g is then uniquely determined on $\partial\Omega$. Consider the Cauchy integral

$$f = f^{\Omega,V} = \int_{\partial\Omega} \frac{g(w)}{z - w} dw,$$

and as above let $f_+ = f_+^{\Omega,V}$ denote the restriction of f to Ω and $f_- = f_-^{\Omega,V}$ the restriction to the complement of $\overline{\Omega}$. Recall that both f_+ and f_- have a smooth extension to the boundary and

$$f_+ = g + f_-$$
 on $\partial \Omega$.

Now, if Ω_t is a smooth variation of Ω with initial direction V, the variation of the complex moments $M_k(t)$ of Ω_t satisfies

$$\left. \frac{dM_k}{dt} \right|_{t=0} = \int_{\partial \Omega} z^k V \rho \, ds.$$

Since f_+ is holomorphic in Ω , it then follows that

$$\left. \frac{dM_k}{dt} \right|_{t=0} = -\int_{\partial \Omega} z^k f_-(z) \, dz.$$

Thus, writing f_{-} as a power series in a neighbourhood of infinity,

$$f_{-} = \sum_{k=1}^{\infty} b_k z^{-k},$$

we conclude that

$$\left. \frac{dM_k}{dt} \right|_{t=0} = -2\pi i b_{k+1}.$$

We think of the condition that f_- extends to an analytic function across $\partial\Omega$ as a kind of 'growth condition' on the coefficients b_k that determines the variation of the moments. With this said, we can prove something more precise.

THEOREM 8.2. Let Ω be a smooth Jordan domain. Suppose that complex coefficients b_k for $k \geq 0$ are given with $ib_0 \in \mathbb{R}$, so that the function $f_- = \sum_k b_k z^{-k}$ defined in a neighbourhood of infinity extends to a holomorphic function across $\partial \Omega$. Then there exist a smooth density function ρ' with $\rho' = \rho$ outside of Ω and a smooth family $\{\Omega_t\}_{t \in (-\epsilon, \epsilon)}$, whose moments $M_k(t)$ taken with respect to the measure ρ' dA vary linearly as

$$M_k(t) = M_k(0) - 2\pi i b_{k+1} t.$$

If moreover Ω has real analytic boundary and ρ is real analytic, then we can take $\rho' = \rho$.

Remark 8.3. This theorem gives one precise way to state that these moments form parameters for the space of domains near Ω . The final statement, under the extra assumption that the boundary is real analytic, appears to be well known and to have been proved in a number of contexts; it follows, for instance, from [Che96, § 2]. We are not aware of a similar statement in the smooth case, or one such as Theorem 8.1 that uses the extra data that the initial normal vector field is outward pointing.

The proof starts with the following uniqueness result.

PROPOSITION 8.4. Let V_1 and V_2 be two smooth normal vector fields defined on the boundary of Ω . If for all $k \ge 0$ we have that

$$\int_{\partial\Omega} z^k V_1 \rho \, ds = \int_{\partial\Omega} z^k V_2 \rho \, ds,\tag{16}$$

then it follows that $V_1 = V_2$.

Proof. Let g_1 and g_2 be the complex-valued functions so that $V_i \rho ds = g_i dz$ on $\partial \Omega$ for i = 1, 2. By our calculations above, it follows from (16) that $g_1 - g_2$ extends holomorphically to Ω . Let u be a conformal map from the unit disc to Ω and consider the pullback of $(g_1 - g_2) dz$ to the unit disc. It will be a holomorphic one-form, which can be written as h(w) dw, where w denotes the holomorphic coordinate on the unit disc. The fact that $(g_1 - g_2) dz$ restricts to a real measure on $\partial \Omega$ implies that the restriction of h(w) dw to the unit circle is real. This in turn implies that wh(w) is real valued on the unit circle. It follows that $wh(w) \equiv 0$ and thus $g_1 = g_2$, and consequently $V_1 = V_2$.

Recall that we have a totally real submanifold Λ which is the graph of $\partial \phi/\partial z$, where $\Delta \phi = \rho$ outside of Ω . We also have a holomorphic disc Σ attached to Λ which projects down to Ω . As we saw in §7, Σ belongs to a one-parameter family of holomorphic discs attached to Λ which goes through the point $p = (0, \infty)$, and the projection of these yields the Hele-Shaw flow (the permeability being $1/\rho$).

We record the following theorem.

THEOREM 8.5. Let Σ and Λ be as above. Given any small smooth perturbation Λ_s of Λ , the family Σ_t deforms to a smooth family $\Sigma_{s,t}$ of holomorphic discs going through $p = (0, \infty) \in \mathbb{C} \times \mathbb{P}^1$ attached to Λ_s along their boundaries.

Proof. This is standard in the theory of moduli spaces of embedded holomorphic curves (see e.g. [LeB06]). Let Λ_s be a smooth parametrised perturbation of Λ , $s \in (-\epsilon, \epsilon)$. The Banach space \mathcal{B} one considers is the space of embedded discs in some regularity class together with the parameter s, where the discs pass through $p = (0, \infty)$ and are attached to Λ_s . The Banach bundle \mathcal{E} is defined just as before, and so is the section \mathcal{S} . The linearisation of S is the $\bar{\partial}$ operator which maps the tangent space of \mathcal{B} to the fibre of \mathcal{E} . Let Σ_s be a smooth family of smooth discs lying in \mathcal{B} such that $\Sigma_0 = \Sigma$ and Σ_s attaches to Λ_s . Then the tangent space of \mathcal{B} is spanned by $C^{k+1,\alpha}(\Sigma,N,E)_0$ together with the derivative of Σ_s at s=0, which we will denote by f. We have already established that the linearisation $\bar{\partial}$ is surjective, even when restricted to the subspace $C^{k+1,\alpha}(\Sigma,N,E)_0$. Therefore, there is a section g in $C^{k+1,\alpha}(\Sigma,N,E)_0$ such that $\bar{\partial}f=\bar{\partial}g$. Thus, the kernel of $\bar{\partial}$ is spanned by the kernel of the restricted $\bar{\partial}$ operator together with f-g, so it has dimension two. By the implicit function theorem for Banach manifolds, the space of holomorphic discs near Σ lying in \mathcal{B} is a manifold of real dimension two. Also, the subsets which are attached to Λ_s for a given s will be one-dimensional submanifolds.

We now prove Theorem 8.1. Let f_- be the restriction to the complement of $\bar{\Omega}$ of

$$f = \int_{\partial\Omega} \frac{g(w)}{z - w} \, dw,$$

where $V \rho ds = g(z) dz$, and choose some smooth extension to a neighbourhood U of the boundary of Ω . We will consider the smooth perturbation of Λ given by

$$\Lambda_s := \left\{ \left(z, \frac{\partial \phi}{\partial z} + s f_{-} \right) : z \in U \supset \partial \Omega \right\}.$$

By Theorem 8.5, the family of holomorphic discs corresponding to the Hele-Shaw flow Σ_t perturbs to a smooth family $\Sigma_{s,t}$ with boundary in Λ_s . For each s, select the holomorphic disc $\Sigma'_s := \Sigma_{s,t(s)}$ so that the corresponding Schwarz function S_s has the same residue as S_0 . That Σ'_s is a smooth family follows from the ordinary implicit function theorem in finite dimensions. Let Ω_s be the projection of Σ'_s ; we have for small s,

$$\int_{\Omega_{s}} z^{k} \rho \, dA - \int_{\Omega_{0}} z^{k} \rho \, dA = \int_{\partial\Omega_{s}} z^{k} \frac{\partial \phi}{\partial z} \, dz - \int_{\partial\Omega_{0}} z^{k} \frac{\partial \phi}{\partial z} \, dz$$

$$= \int_{\partial\Omega_{s}} z^{k} (S_{s} - sf_{-}) \, dz - \int_{\partial\Omega_{0}} z^{k} S_{0} \, dz = -s \int_{\partial\Omega_{s}} z^{k} f_{-} \, dz. \tag{17}$$

Here we used the facts that $S_s = \partial \phi / \partial z + s f_-$ on $\partial \Omega_s$ and that S_s and S_0 have the same residue at 0.

If V_0 is the initial normal vector field on $\partial\Omega$ corresponding to the perturbation Ω_s , then (17) implies that V_0 and V induce the same initial variation of moments. From Proposition 8.4, it thus follows that the initial direction of Ω_s is given by V. In particular, this initial direction is, by assumption, non-vanishing and outward pointing, so by smoothness $\partial\Omega_s$ will lie in the complement of $\bar{\Omega}$ for small s. But on this complement f_- is holomorphic, and

$$\int_{\partial\Omega_s} z^k f_- dz = 2\pi i b_{k+1}$$

(which in particular is independent of s). Thus, by (17) again, all the moments of Ω_s vary linearly, as required.

The proof of Theorem 8.2 is identical, only now since we do not have the hypothesis that the flow is outwards initially we must take the moments with respect to $\rho' = \Delta \phi$, which is only equal to ρ outside of Ω unless real analyticity is assumed (as in Proposition 3.6).

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