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INVARIANT MEASURES OF ULTIMATELY BOUNDED STOCHASTIC PROCESSES

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The author discussed in [4] the ultimate boundedness of a system which is governed by a stochastic differential equation

$$dX(t) = f(t, X(t))dt + G(t, X(t))dW(t) , \quad t \ge 0 .$$
(1)

In this paper we investigate the invariant measure of an ultimately bounded process assuming stationarity: namely we are interested in a process governed by

$$dX(t) = f(X(t))dt + G(X(t))dW(t) , \quad t \ge 0 .$$
 (2)

where X(t) and f(x) are *n*-vectors, G(x) is an $n \times m$ -matrix, and W(t) is an *m*-dimensional Wiener process. We assume that f(x) and G(x) satisfy Lipschitz continuity.

Let X(t) be a conservative Feller process defined on the state space \mathbb{R}^n . The corresponding semi-group $\{T_t\}$ of X(t) is the set of operators T_t on the space $C = \{f(x); \text{ bounded continuous function on } \mathbb{R}^n\}$ and is defined by

$$T_{\iota}f(x) = \int_{\mathbb{R}^n} f(y)P(t, x, dy) \quad \text{for } f \in C , \qquad (3)$$

where P(t, x, B) is the transition function of X(t).

A process X(t) is said to be *p*-th ultimately bounded (p > 0) if there exists a constant K such that $\overline{\lim}_{t\to\infty} M_x |X(t)|^p \leq K$ for any x, where M_x means the conditional expectation under the condition X(0) = x. An invariant measure μ of a process X(t) means that μ is a positive regular measure and satisfies $\int_{\mathbb{R}^n} P(t, x, B) d\mu(x) = \mu(B)$ for any t > 0 and Borel set B.

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THEOREM 1. If a conservative Feller process X(t) is p(>0)-th ultimately bounded, then there exists a finite invariant measure of X(t).

Proof. Fix a point $x \in \mathbf{R}^n$ and put

$$\Phi_N(f) = \frac{1}{N} \int_0^N T_t f(x) dt , \qquad N = 1, 2, \cdots .$$
 (4)

Then $\Phi_N(f)$ is a linear functional on C which satisfies

- i) $\Phi_N(f) \ge 0$, if $f \ge 0$,
- ii) $\Phi_N(1) = 1$.

Therefore Φ_N defines a probability measure on \mathbb{R}^n , which we will denote by the same notation $\Phi(\cdot)$.

We will prove that the family $\{\Phi_N\}$, $N = 1, 2, \dots$, is tight, that is

$$\lim_{k \to \infty} \inf_{N} \Phi_{N}(S_{k}) = 1 , \qquad (5)$$

where $S_k = \{x; |x| \leq k\}$, $k = 1, 2, \cdots$. From the assumption of *p*-th ultimate boundedness of X(t), there exist two constants K and t_0 such that $M_x |X(t)|^p \leq K$ for $t \geq t_0$. Using Tchebychev inequality to this inequality, we have

$$P(t, x, S_k^c) \leq rac{K}{k^p} \quad ext{for } t \geq t_0 ext{,}$$
 (6)

where S_k^c is the complement of S_k . This inequality is equivalent to

$$P(t, x, S_k) \ge 1 - \frac{K}{k^p} \quad \text{for } t \ge t_0 . \tag{7}$$

Therefore we get the following inequality;

$$\Phi_N(S_k) \ge \frac{1}{N} \int_{t_0}^N P(t, x, S_k) dt \ge \frac{1}{N} (N - t_0) \left(1 - \frac{K}{k^p}\right) \qquad (8)$$
for $N > t_0$.

From this inequality we know that when any positive number ε is given, there are two constant $k_0(\varepsilon)$ and $N_0(\varepsilon)$ such that

It is valid that there is a constant $k_1(\varepsilon)$ such that

$$\Phi_N(S_k) \ge 1 - \varepsilon \quad \text{for } k \ge k_1 \text{ and } N = 1, 2, \cdots, N_0,$$
(10)

because $\Phi_N(\cdot)$ is a probability measure. Two inequalities (9) and (10) prove (5), that is, the family $\{\Phi_N\}$, $N = 1, 2, \cdots$, is tight.

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From the tightness of $\{\Phi_N\}$, $N = 1, 2, \cdots$, we can conclude that there are a probability measure $\Phi(\cdot)$ and a subsequence $\{\Phi_{N_m}\}$, $m = 1, 2, \cdots$, such that

$$\lim_{m \to \infty} \Phi_{N_m}(f) = \Phi(f) \quad \text{for } f \in C .$$
(11)

Using this equality and the boundedness of $f \in C$ and $T_t f \in C$, we have

$$\begin{split} \varPhi(T_t f) &= \lim_{m \to \infty} \frac{1}{N_m} \int_0^{N_m} T_{t+s} f(x) ds \\ &= \lim_{m \to \infty} \frac{1}{N_m} \int_0^{N_m} T_s f(x) ds + \frac{1}{N_m} \left(\int_{N_m}^{N_m+t} T_s f(x) ds - \int_0^t T_s f(x) ds \right) \end{split}$$
(12)
$$&= \varPhi(f) \quad \text{for } f \in C \text{ and } t \ge 0 .$$

This equality stands for that $\Phi(\cdot)$ is an invariant measure of X(t).

(Q.E.D.)

Remark 1. We know from the proof of Theorem 1 that the invariant measure of X(t) is not unique. Every starting point x determines an invariant measure.

COROLLARY 1. If the system (2) is p(> 0)-th ultimately bounded, then it has a finite invariant measure.

Proof. It is well-known that the solution of (2) is a conservative Feller process. (cf. [2]). (Q.E.D.)

COROLLARY 2. If the system (2) is non-degenerate and p(>0)-th ultimately bounded, then it is positive recurrent.

Proof. It is proved by W. M. Wonham [6, Appendix] that the system (2) is a diffusion process in the sense of R. Z. Khas'minskii [3] if it is non-degenerate. And R. Z. Khas'miskii proved that a diffusion process is positive recurrent if and only if it is recurrent and has a finite invariant measure ([3], Theorem 3.3 and Lemma 5.3). We already knows that an ultimately bounded process is recurrent ([4], § 5) and Corollary 1 assures the existence of a finite invariant measure. (Q.E.D.)

Remark 2. We know that a p(>0)-th ultimately bounded process is weakly recurrent and that an exponentially p(>1)-th ultimately bounded process is weakly positive recurrent ([4], §5). But it is not known whether a p(>0)-th ultimately bounded process is weakly positive recurrent or not. Corollary 2 gives us a partial answer of this problem.

THEOREM 2. Let X(t) be a p-th ultimately bounded Markov process with a finite invariant measure ν . Then it satisfies

$$\int_{R^n} |x|^p \, \nu(dx) < \infty \, .$$

Proof. Put $f(x) = |x|^p$ and $f_n(x) = \chi_{[0,n]}(f(x))$, where χ is a characteristic function. We note that $f_n(x) \in L^1(\mathbb{R}^n, \nu)$. From the assumption of p-th ultimate boundedness, there is a constant K' such that

$$\varlimsup_{t \to \infty} M_x f(X_t) \leq K' \quad ext{ for any } x ext{ .}$$

By the use of Ergodic theorem for Markov process with invariant measure (cf. [5] pp. 388), there exists the limit

$$\lim_{N \to \infty} \frac{1}{N} \sum_{k=1}^{N} T_k f_n(x) = f_n^*(x) \qquad (\nu-\text{a.e.})$$
(13)

and

$$E_{\nu}f_{n}^{*}(x) = E_{\nu}f_{n}(x) , \qquad (14)$$

where $T_k f_n(x) = \int_{\mathbb{R}^n} f(y) P(k, x, dy)$ and $E_{\nu} f_n(x) = \int_{\mathbb{R}^n} f_x(x) d\nu(x)$. From the inequality $f_n(x) \leq f(x)$ and the assumption of *p*-th ultimate boundedness, we have

$$\overline{\lim_{N \to \infty}} \frac{1}{N} \sum_{k=1}^{N} T_k f_n(x) \leq \overline{\lim_{N \to \infty}} \frac{1}{N} \sum_{k=1}^{N} T_k f(x) \leq K'$$
for any $x \in \mathbb{R}^n$.
$$(15)$$

From (13) and (15) we obtain $f_n^*(x) \leq K'$ (ν -a.e.), and from this inequality we have

$$E_{\downarrow}f_{n}^{*}(x) \leq K' . \tag{16}$$

The formulas (14), (16) and the fact $f_n(x) \uparrow f(x)$ $(n \to \infty)$ imply that

$$E_{\nu}f(x) = \lim_{n \to \infty} E_{\nu}f_n(x) = \lim_{n \to \infty} E_{\nu}f_n^*(x) \leq K' . \qquad (Q.E.D.)$$

COROLLARY. If X(t) is ∞ -th ultimately bounded, then any finite invariant measure ν of X(t) satisfies $E_{\nu}|x|^{p} < \infty$ for any p > 0.

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