Bull. Austrai. Math. Soc.
Vol. 39 (1989) [129-139]

# HIGHER ORDER SCHEMES AND RICHARDSON EXTRAPOLATION FOR SINGULAR PERTURBATION PROBLEMS 

Dragoslav Herceg, Relja Vulanović and Nenad Petrović


#### Abstract

Semilinear singular perturbation problems are solved numerically by using finite-difference schemes on non-equidistant meshes which are dense in the layers. The fourth order uniform accuracy of the Hermitian approximation is improved by the Richardson extrapolation.


## 1. Introduction

We consider the following singularly perturbed boundary value problem:

$$
\begin{equation*}
-\varepsilon^{2} u^{\prime \prime}+c(x, u)=0, x \in I=[0,1], u(0)=u(1)=0 \tag{1}
\end{equation*}
$$

with a small parameter $\varepsilon, \varepsilon \in\left(0, \varepsilon_{0}\right)$. Our assumptions are

$$
\begin{gather*}
c \in C^{8}(I \times \mathbf{R}),  \tag{2.1}\\
g(x) \leqslant c_{u}(x, u) \leqslant G(x),(x, u) \in I \times \mathbf{R},  \tag{2.2}\\
\delta:=\min \{5 g(x)-2 G(x): x \in I\}>0,  \tag{2.3}\\
0<\gamma^{2}<g(x),\left|g^{\prime}(x)\right| \leqslant L,\left|G^{\prime}(x)\right| \leqslant L, x \in I . \tag{2.4}
\end{gather*}
$$

It is well-known that under the given conditions there exists a unique solution, $u \in$ $C^{10}(I \times \mathbf{R})$, to the problem (1), and that the following representation holds:

$$
\begin{equation*}
u(x)=v_{0}(x)+v_{1}(x)+y(x) \tag{3.1}
\end{equation*}
$$

where

$$
\begin{align*}
& v_{0}(x)=\exp (-\gamma x / \varepsilon)  \tag{3.2}\\
& v_{1}(x)=\exp (\gamma(x-1) / \varepsilon) \tag{3.3}
\end{align*}
$$

and

$$
\begin{equation*}
\left|y^{(o)}(x)\right| \leqslant M, s=0,1, \ldots, 8, x \in I \tag{3.4}
\end{equation*}
$$

## Received 14 April 1988

This research was partly supported by NSF and SIZ for Science of SAP Vojvodina through funds made available to the U.S.- Yugoslav Joint Board on Scientific and Technological Cooperation (grant JF 799).

Copyright Clearance Centre, Inc. Serial-fee code: 0004-9729/89 \$A2.00+0.00.
(see $[6,7]$ ). Here and throughout the paper $M$ denotes any positive constant independent of $\varepsilon$.

As well as in [6] and [7], problem (1) was solved numerically in [1, 5, 3, 4] - just to mention some of the papers. For other references see [3, 4].

Our aim is to solve (1) numerically by using classical finite difference schemes on special non-equidistant meshes which are dense in the layers of $u$, located at $x=0$ and $x=1$. The same approach can be found in the papers we have mentioned. In this paper we combine the methods from [ 7 ] and [4] to obtain high order convergence uniform in $\varepsilon$. In [7] Richardson extrapolation was applied to the central difference scheme and high accuracy uniform in $\varepsilon$ was proved. In [4] (see [3] as well) the Hermite scheme was used and fourth order uniform convergence was proved. Here we shall apply Richardson extrapolation to the Hermite scheme. We shall give a proof of sixth order convergence uniform in $\varepsilon$. We believe that a general theory can be developed in the same way as in [7] and that even higher order uniform convergence can be obtained. Numerical experiments confirm this.

Conditions (2.2) and (2.3) are the same as in [3, 4] and they guarantee stability uniform in $\varepsilon$. In a forthcoming paper we shall avoid these constraints on the function c.

In Section 2 the discretisation is given and stability uniform in $\varepsilon$ is proved. In Section 3 we give a representation of the consistency error, which justifies the use of Richardson extrapolation. We end the paper by giving some numerical results in Section 4.

The constants $M$ will be independent of the discretisation mesh as well.

## 2. Discretisation

Let $I_{h}$ be the discretisation mesh with the points:

$$
\begin{gather*}
x_{i}=\lambda\left(t_{i}\right), t_{i}=i h, i=0,1, \ldots, n, h=\frac{1}{n}, n=2 m, m \in \mathbf{N},  \tag{4.1}\\
\lambda(t)=\left\{\begin{array}{cc}
\omega(t)=\frac{a e t}{q-t}, & t \in[0, \alpha], \\
\pi(t), & t \in[\alpha, 0.5] \\
1-\lambda(1-t), & t \in[0.5,1]
\end{array}\right. \tag{4.2}
\end{gather*}
$$

where

$$
\begin{equation*}
\pi(t)=A(t-\alpha)^{4}+\omega^{\prime \prime \prime}(\alpha)(t-\alpha)^{3} / 6+\omega^{\prime \prime}(\alpha)(t-\alpha)^{2} / 2+\omega^{\prime}(\alpha)(t-\alpha)+\omega(\alpha) \tag{4.3}
\end{equation*}
$$

The parameter $\alpha$ is

$$
\begin{equation*}
\alpha=t_{k} \tag{4.4}
\end{equation*}
$$

for some $k \in\{1,2, \ldots, m-1\}$,

$$
\begin{equation*}
q=\alpha+\sqrt[4]{\varepsilon} \tag{4.5}
\end{equation*}
$$

and the coefficient $A$ is determined from

$$
\begin{equation*}
\pi(0.5)=0.5 \tag{4.6}
\end{equation*}
$$

Moreover, the coefficient a should satisfy

$$
\begin{equation*}
\left(B+2 \varepsilon^{-1 / 4} q(0.5-\alpha)^{4}\right)^{-1} \leqslant a \leqslant B^{-1} \tag{4.7}
\end{equation*}
$$

where

$$
\begin{equation*}
B=2\left(\varepsilon^{3 / 4} \alpha+\varepsilon^{1 / 2} q(0.5-\alpha)+\varepsilon^{1 / 4} q(0.5-\alpha)^{2}+q(0.5-\alpha)^{3}\right) \tag{4.8}
\end{equation*}
$$

We have $\lambda: I \rightarrow I, \lambda \in C^{1}(I), \lambda \in C^{3}[0,0.5], \lambda \in C^{\infty}[0, \alpha], \lambda \in C^{\infty}[\alpha, 0.5]$. The second inequality in (4.7) implies $A \geqslant 0$, so $\pi^{\prime \prime \prime}$ is nondecreasing, and

$$
\pi^{(\theta)}(t) \geqslant \pi^{(\theta)}(\alpha)=\omega^{(\theta)}(\alpha)>0, s=3,2,1, t \in[\alpha, 0.5] .
$$

At the same time

$$
\omega^{(s)}(t)>0, s=1,2, \ldots, \quad t \in[0, q)
$$

and taking (4.5) into account we get

$$
\begin{equation*}
0<\lambda^{(s)}(t) \leqslant M, s=1,2,3, t \in[0,0.5] \tag{5.1}
\end{equation*}
$$

Moreover,

$$
\begin{equation*}
0<\lambda^{(4)}(t) \leqslant M \varepsilon^{-1 / 4}, \quad t \in[0,0.5] \backslash\{\alpha\} . \tag{5.2}
\end{equation*}
$$

The first inequality in (4.7) means that

$$
(\omega(t)-\pi(t))^{(4)} \geqslant 0, \quad t \in[\alpha, q)
$$

and it follows that

$$
\begin{equation*}
\omega^{\prime}(t) \geqslant \pi^{\prime}(t), \quad t \in[\alpha, q) . \tag{6}
\end{equation*}
$$

The inequalities (5.1) and (6) will be used later on, as well as

$$
\begin{equation*}
\exp (-\gamma \lambda(t) / \varepsilon) \leqslant M \exp (-M /(q-t)), \quad t \in(0, q) \tag{7}
\end{equation*}
$$

Let

$$
Q=\frac{(S-1)}{S}, S=\sqrt{1+\sqrt{3}}
$$

If

$$
P=\alpha+Q \sqrt[4]{\varepsilon}-\frac{2 h}{Q}>0
$$

we denote by $j$ an index such that

$$
t_{j-1} \leqslant P<t_{j} .
$$

Let

$$
I_{h}^{\prime}=\left\{x_{i} \in I_{h}: j+1 \leqslant i \leqslant k+6 \text { or } n-k-6 \leqslant i \leqslant n-j-1\right\}
$$

(if $j>k+5$ then $I_{h}^{\prime}=\emptyset$ ).
Now we discretise problem (1) on the mesh $I_{h}$ by using the same scheme as in [3, 4]:

$$
\begin{equation*}
T_{h} w_{0}=w_{0}=0 \tag{8.1}
\end{equation*}
$$

$$
\begin{gather*}
T_{h} w_{i}=\varepsilon^{2}\left(a_{1}(i) w_{i-1}+a_{0}(i) w_{i}+a_{2}(i) w_{i+1}\right)+b_{1}(i) c_{i-1}+b_{0}(i) c_{i}+b_{2}(i) c_{i+1}=0  \tag{8.2}\\
i=1,2, \ldots, n-1, \\
T_{h} w_{n}=w_{n}=0, \tag{8.3}
\end{gather*}
$$

where $T_{h} w_{i}=\left(T_{h} w_{h}\right)_{i}, w_{h}=\left[w_{0}, w_{1}, \ldots, w_{n}\right]^{T} \in \mathbb{R}^{n+1}\left(w_{i}=w_{h, i}\right)$ is a mesh function on $I_{h}$,

$$
\begin{gathered}
c_{s}=c\left(x_{s}, w_{s}\right), s=i-1, i, i+1 \\
a_{1}(i)=\frac{-2}{h_{i}\left(h_{i}+h_{i+1}\right)}, a_{2}(i)=\frac{-2}{h_{i+1}\left(h_{i}+h_{i+1}\right)}, a_{0}(i)=\frac{2}{h_{i} h_{i+1}}
\end{gathered}
$$

$h_{i}=x_{i}-x_{i-1}, i=1,2, \ldots, n$, and

$$
\begin{gathered}
b_{1}(i)=\frac{-a_{1}(i)}{12}\left(h_{i}^{2}-h_{i+1}^{2}+h_{i} h_{i+1}\right), b_{2}(i)=\frac{-a_{2}(i)}{12}\left(h_{i+1}^{2}-h_{i}^{2}+h_{i} h_{i+1}\right), \\
b_{0}(i)=\frac{a_{0}(i)}{12}\left(h_{i}^{2}+h_{i+1}^{2}+3 h_{i} h_{i+1}\right), \text { if } x_{i} \in I_{h} \backslash I_{h}^{\prime} \\
b_{0}(i)=1, b_{1}(i)=0, b_{2}(i)=0, \text { if } x_{i} \in I_{h}^{\prime}
\end{gathered}
$$

From now on we shall consider the mesh points in ( $0,0.5$ ) only (that is $x_{i}, i=$ $1,2, \ldots, m-1$ ) since the interval $[0.5,1$ ) can be treated analogously (note that $\left.h_{i}=h_{n-i+1}, i=1,2, \ldots, m\right)$.

As in $[3,4]$ we have, for $x_{i} \in\left(I_{h 2} \backslash I_{h}^{\prime}\right) \cap(0,0.5)$,

$$
\begin{gather*}
\frac{1}{12} \leqslant b_{2}(i) \leqslant \frac{1}{6}, \quad b_{2}(i) \geqslant b_{1}(i), \quad b_{0}(i) \geqslant \frac{5}{6} \\
b_{1}(i) \geqslant-\frac{1}{6} \tag{9}
\end{gather*}
$$

We shall prove (9) here, since this proof differs from the one in [3, 4]. It is easy to see that (9) is equivalent to

$$
\frac{h_{i+1}}{h_{i}} \leqslant S^{2}
$$

and this inequality will follow from

$$
\begin{equation*}
\frac{\lambda^{\prime}\left(t_{i+1}\right)}{\lambda^{\prime}\left(t_{i-1}\right)} \leqslant S^{2} \tag{10}
\end{equation*}
$$

(see (5.1)). Now if $k+6<i(<m)$ we have

$$
t_{i-1} \geqslant \alpha+6 h
$$

Let

$$
p(t)=S^{2} \pi^{\prime}(t)-\pi^{\prime}(t+2 h),\left(t=t_{i-1}\right)
$$

It follows that

$$
p^{(s)}(t) \geqslant 0, s=3,2,1, \quad t \in[\alpha+6 h, 0.5]
$$

so (10) holds in this case. Let us now consider the case $i<j+1$, that is,

$$
\begin{equation*}
t_{i-1} \leqslant P \tag{11}
\end{equation*}
$$

and $t_{i+1}<q$. If $t_{i-1} \leqslant \alpha$ from (11) we have

$$
\frac{\omega^{\prime}\left(t_{i+1}\right)}{\omega^{\prime}\left(t_{i-1}\right)}=\left(\frac{q-t_{i-1}}{q-t_{i+1}}\right)^{2} \leqslant S^{2}
$$

and (10) follows because of (6). If $t_{i-1}>\alpha$, the inequality

$$
\frac{\omega^{\prime}\left(t_{i+1}\right)}{\omega^{\prime}(\alpha)} \leqslant S^{2}
$$

holds because of (11) and (10) is proved again.
Thus, in the same way as in [4] we can prove

Theorem 1. Let (2.1)-(2.4) hold and let the discrete problem (8.1)-(8.3) be given on the mesh (4.1)-(4.8) with

$$
\begin{equation*}
n>\frac{2 L \pi^{\prime}(1)}{\delta} \tag{12}
\end{equation*}
$$

Then the problem (8.1)-(8.3) has a unique solution $w_{h}$, which is a point of attraction of SOR-Newton and Newton-SOR methods with the relaxation parameter in $(0,1]$. Moreover, for any $v_{h}^{1}, v_{h}^{2} \in \mathbf{R}^{n+1}$, the following stability inequality holds:

$$
\begin{equation*}
\left\|v_{h}^{1}-v_{h}^{2}\right\|_{\infty} \leqslant \sigma^{-1}\left\|T_{h} v_{h}^{1}-T_{h} v_{h}^{2}\right\|_{\infty} \tag{13}
\end{equation*}
$$

where $\sigma$ is a positive constant, independent of $\varepsilon$.
Remark. Note that the right-hand-side of (12) is bounded uniformly in $\varepsilon$.

## 3. Richardson extrapolation

Let us consider the consistency error

$$
r_{h}=T_{h} u_{h}-T_{h} w_{h}=T_{h} u_{h}
$$

where $u_{h}=\left[u\left(x_{0}\right), u\left(x_{1}\right), \ldots, u\left(x_{n}\right)\right]^{T} \in \mathbf{R}^{n+1}$ is the restriction of the solution $u$ to the problem (1) on the mesh $I_{h}$. The components of the vector $r_{h}$ are

$$
r_{0}=r_{n}=0,
$$

and for $i=1,2, \ldots, n$, if $x_{i} \in I_{h} \backslash I_{h}^{\prime}$

$$
\begin{align*}
r_{i} & =\varepsilon^{2}\left[\frac{u^{(5)}\left(x_{i}\right)}{180}\left(h_{i+1}-h_{i}\right)\left(2 h_{i}^{2}+2 h_{i+1}^{2}+5 h_{i} h_{i+1}\right)\right.  \tag{14.1}\\
& +\frac{u^{(6)}\left(x_{i}\right)}{720}\left(3 h_{i}^{4}+3 h_{i+1}^{4}-7 h_{i}^{2} h_{i+1}^{2}+2 h_{i}^{3} h_{i+1}+2 h_{i} h_{i+1}^{3}\right) \\
& +\frac{u^{(7)}\left(x_{i}\right)}{7!}\left(h_{i+1}-h_{i}\right)\left(7 h_{i} h_{i+1}\left(h_{i}^{2}+h_{i+1}^{2}\right)+5\left(h_{i}^{4}+h_{i+1}^{4}\right)-2 h_{i}^{2} h_{i+1}^{2}\right) \\
& -2 \frac{u^{(8)}\left(\vartheta_{i}^{1}\right)\left(h_{i}^{7}+h_{i+1}^{7}\right)}{8!\left(h_{i}+h_{i+1}\right)}+\frac{u^{(8)}\left(\vartheta_{i}^{2}\right) h_{i}^{5}\left(h_{i}^{2}-h_{i+1}^{2}+h_{i} h_{i+1}\right)}{6 \cdot 6!\left(h_{i}+h_{i+1}\right)} \\
& \left.+\frac{u^{(8)}\left(\vartheta_{i}^{3}\right) h_{i+1}^{5}\left(h_{i+1}^{2}-h_{i}^{2}+h_{i} h_{i+1}\right)}{6 \cdot 6!\left(h_{i}+h_{i+1}\right)}\right]
\end{align*}
$$

and for $x_{i} \in I_{h}^{\prime}$

$$
\begin{equation*}
r_{i}=\varepsilon^{2}\left(u^{\prime \prime}\left(x_{i}\right)-u^{\prime \prime}\left(\vartheta_{i}^{4}\right)\right) \tag{14.2}
\end{equation*}
$$

where $\vartheta_{i}^{e} \in\left(x_{i-1}, x_{i+1}\right), s=1,2,3,4$.

Theorem 2. Let (2.1)-(2.4) hold. On the mesh (4.1)-(4.8) we have, for $i=$ $1,2, \ldots, n$,

$$
\begin{gather*}
r_{i}=K_{i} h^{4}+R_{i},\left|R_{i}\right| \leqslant M h^{6}, \text { for } x_{i} \in I_{h} \backslash I_{h}^{\prime}  \tag{15.1}\\
\left|r_{i}\right| \leqslant M h^{8}, \text { for } x_{i} \in I_{h}^{\prime} \tag{15.2}
\end{gather*}
$$

where $K_{i}$ is independent of $h$.
Proof; We shall use (14.1)-(14.2) and the representation (3.1)-(3.4). Again, we shall give the proof for $i=1,2, \ldots, m-1$ only. Note that for $x \in[0,0.5]$

$$
\begin{equation*}
\left|z^{(s)}(x)\right| \leqslant M, s=0,1, \ldots, 8, \quad z=v_{1}+y \tag{16}
\end{equation*}
$$

Let us prove (15.1). Let $q_{\text {o }}$ denote the coefficient at $u^{(o)}\left(x_{i}\right)$ in (14.1), $s=5,6,7$, and let $q_{8}^{p}$ be the coefficient at $u^{(8)}\left(\vartheta_{i}^{p}\right), p=1,2,3$. By expanding $\lambda$ (note that $\left.\lambda \in C^{\infty}\left(x_{i}, x_{i+1}\right)\right)$ we get

$$
\begin{aligned}
& q_{5}=\varepsilon^{2} \lambda^{\prime}\left(t_{i}\right)^{2} \lambda^{\prime \prime}\left(t_{i}\right) h^{4} / 20+r_{i}^{1} \\
& q_{6}=\varepsilon^{2} \lambda^{\prime}\left(t_{i}\right)^{4} h^{4} / 240+r_{i}^{2}
\end{aligned}
$$

(see [7] for the technique). Thus we have (15.1) with

$$
R_{i}=r_{i}^{1} u^{(5)}\left(x_{i}\right)+r_{i}^{2} u^{(6)}\left(x_{i}\right)+q_{7} u^{(7)}\left(x_{i}\right)+\sum_{p=1}^{3} q_{8}^{p} u^{(8)}\left(\vartheta_{i}^{p}\right)
$$

By using (3.1)-(3.4), (5.1), (7) and the technique from [6] (see [7, 3, 4] as well) we can prove

$$
\begin{equation*}
\left|R_{i}\right| \leqslant M h^{6}, \quad x_{i} \in I_{h} \backslash I_{h}^{\prime} \tag{17}
\end{equation*}
$$

Note that $x_{i} \in I_{h} \backslash I_{h}^{\prime}$ corresponds to the cases $1^{0}$ and $2^{0}$ of the proof of Theorem 2 from [6] (Theorem 1 from [7]). On the other hand, $x_{i} \in I_{h}^{\prime}$ corresponds to the case $3^{0}$. Let us illustrate the proof of (17) by showing

$$
\begin{align*}
& D_{1}=\left|r_{i}^{1} u^{(5)}\left(x_{i}\right)\right| \leqslant M h^{6},  \tag{18.1}\\
& D_{2}=\left|q_{7} u^{(7)}\left(x_{i}\right)\right| \leqslant M h^{6} . \tag{18.2}
\end{align*}
$$

We have

$$
r_{i}^{1}=\frac{\varepsilon^{2}}{180}\left[\frac{h^{4}}{24}\left(\lambda^{(4)}\left(\tau_{i}^{-}\right)+\lambda^{(4)}\left(\tau_{i}^{+}\right)\right)\left(9 h^{2} \lambda^{\prime}\left(t_{i}\right)^{2}+Z_{i}\right)+h^{2} \lambda_{i}^{\prime \prime} Z_{i}\right]
$$

where

$$
\begin{aligned}
Z_{i}= & 3 h^{4} \lambda^{\prime}\left(t_{i}\right) \lambda^{\prime \prime \prime}\left(\eta_{i}\right)+\frac{2}{9} h^{6} \lambda^{\prime \prime \prime}\left(\eta_{i}\right)^{2}+\frac{h^{6}}{36} \lambda^{\prime \prime \prime}\left(\eta_{i}^{-}\right) \lambda^{\prime \prime \prime}\left(\eta_{i}^{+}\right) \\
+ & \frac{h^{5}}{12} \lambda^{\prime \prime}\left(t_{i}\right)\left(\lambda^{\prime \prime \prime}\left(\eta_{i}^{-}\right)-\lambda^{\prime \prime \prime}\left(\eta_{i}^{+}\right)\right) \\
& \tau_{i}^{-}, \eta_{i}^{-} \in\left(x_{i-1}, x_{i+1}\right), \tau_{i}^{+}, \eta_{i}^{+} \in\left(x_{i}, x_{i+1}\right), \eta_{i} \in\left(x_{i-1}, x_{i+1}\right)
\end{aligned}
$$

Now, if $i>k+6$, that is, $t_{i-1} \geqslant \alpha+6 h$, from (5.1), (5.2), (7), (3.1)-(3.4) and (16) we have

$$
\begin{aligned}
& D_{1} \leqslant M h^{6} \varepsilon^{2}\left(\varepsilon^{-1 / 4}+1\right)\left[1+\varepsilon^{-5} \exp (-\gamma \lambda(\alpha+6 h) / \varepsilon)\right] \\
& D_{1} \leqslant M h^{6}\left[1+\varepsilon^{-13 / 4} \exp (-\gamma \omega(\alpha) / \varepsilon)\right] \leqslant M h^{6},
\end{aligned}
$$

and

$$
\begin{aligned}
& D_{2} \leqslant M h^{6} \varepsilon^{2}\left[1+\varepsilon^{-7} \exp (-\gamma \lambda(\alpha+6 h) / \varepsilon)\right] \\
& D_{2} \leqslant M h^{6}\left[1+\varepsilon^{-5} \exp (-\gamma \omega(\alpha) / \varepsilon)\right] \leqslant M h^{6}
\end{aligned}
$$

If $i<j+1$ that is, $t_{i-1} \leqslant P$ we get

$$
\begin{gather*}
D_{1} \leqslant M h^{6}\left[\varepsilon^{2}\left(\varepsilon^{-1 / 4}+1\right)+\varepsilon^{5}\left(q-t_{i+1}\right)^{-13} \varepsilon^{-5} \exp \left(-\gamma \lambda\left(t_{i-1}\right) / \varepsilon\right)\right],  \tag{19.1}\\
D_{2} \leqslant M h^{6}\left[1+\varepsilon^{7}\left(q-t_{i+1}\right)^{-11} \varepsilon^{-7} \exp \left(-\gamma \lambda\left(t_{i-1}\right) / \varepsilon\right)\right] . \tag{19.2}
\end{gather*}
$$

Since, from $t_{i-1} \leqslant P<q-3 h$ it follows that

$$
q-t_{i+1} \geqslant \frac{q-t_{i-1}}{3}
$$

from (19.1), (19.2) and (7) we get (18.1), (18.2) again.
Let us now prove (15.2). From (14.2) we have

$$
\left|r_{i}\right| \leqslant M \varepsilon^{2} \max \left\{\left|u^{\prime \prime}(x)\right|: x_{i-1} \leqslant x \leqslant x_{i+1}\right\} .
$$

From $x \in I_{h}^{\prime}$ it follows that $\varepsilon \leqslant M h^{4}$, thus by using (3.1)-(3.4), (16) and (7) we get

$$
\left|r_{i}\right| \leqslant M\left[h^{8}+\exp (-\gamma \lambda(P) / \varepsilon)\right] \leqslant M\left[h^{8}+\exp (-M n)\right] \leqslant M h^{8}
$$

By using Richardson extrapolation we can eliminate the $0\left(h^{4}\right)$-term from (15.1), and, having in mind stability (13), we can prove

Theorem 3. Let the conditions of Theorem 1 hold and let $w_{h}$ and $w_{h / 2}$ be the solutions to the problem (8.1)-(8.3) with $n$ and $2 n$ mesh steps, respectively. Then we have

$$
\left\|u_{h}-\bar{w}_{h}\right\|_{\infty} \leqslant M h^{6}
$$

where $\bar{w}_{h}$ is the vector with components

$$
\bar{w}_{i}=\frac{16 w_{h / 2,2 i}-w_{h, i}}{15}, i=0,1, \ldots, n
$$

## 4. Numerical results

We shall use the following test example:

$$
\begin{gathered}
-\varepsilon^{2} u^{\prime \prime}+u+\cos ^{2} \pi x+2(\varepsilon \pi)^{2} \cos 2 \pi x=0, x \in I \\
u(0)=u(1)=0
\end{gathered}
$$

whose solution is known:

$$
u(x)=\frac{\exp (-x / \varepsilon)+\exp ((x-1) / \varepsilon)}{1+\exp (-1 / \varepsilon)}-\cos ^{2} \pi x
$$

This problem was considered in $[\mathbf{2}, \mathbf{3}, \mathbf{4}, 5,6,7]$ as well.
In Table 1 we present the error

$$
E_{h}=\left\|u_{h}-\bar{w}_{h}\right\|_{\infty}
$$

(where $\bar{w}_{h}$ is the same as in Theorem 3), and the experimental order of convergence, (see [2])

$$
\text { Ord }=\frac{\log E_{h}-\log E_{h / 2}}{\log 2}
$$

Different values of $\varepsilon$ and $n$ are considered. The corresponding values of $\alpha$ are given in Table 2. They are determined in such a way that the percentage of the mesh steps lying within the layers is the highest possible. We take the interval $[0, \varepsilon]$ to represent the left-hand layer. The percentage, $p=\left(i_{0} / n\right) * 100$, where $i_{0}$ is an index such that $x_{i_{0}} \leqslant \varepsilon<x_{i_{0}+1}$, is shown in Table 2 as well. For a given $\varepsilon$, we take the smallest value of the parameter $a$ (see (4.7))

$$
a=\left(B+2 \varepsilon^{-1 / 4} q(0.5-\alpha)^{4}\right)^{-1}
$$

Then we consider the condition

$$
t \leqslant \frac{q}{a+1}=K
$$

which is equivalent to

$$
\omega(t) \leqslant \varepsilon
$$

and determine $\alpha$ as the point satisfying (4.4), for which $K$ is maximal (note that $K$ is a function of $\alpha$ for $\varepsilon$ fixed).

All computations have been carried out on the ATARI 1040 ST with 48 bits accuracy in floating point.
Table 1

| $n \varepsilon$ | $2^{-15}$ | $2^{-20}$ | $2^{-25}$ | $2^{-30}$ | $2^{-35}$ | $2^{-40}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | $1.565(-3)$ | - | $4.448(-2)$ | $2.779(-2)$ | $3.108(-2)$ | $1.370(-1)$ | $E_{l}$ |
|  | - | - | - | - | - | - | $O r$ |
| 20 | $1.236(-3)$ | $1.914(-3)$ | $9.826(-4)$ | $1.032(-2)$ | $1.591(-2)$ | $1.651(-2)$ |  |
|  | 3.402 | 4.446 | 5.501 | 1.429 | 0.966 | 3.053 |  |
| 40 | $3.745(-5)$ | $3.165(-5)$ | $2.581(-5)$ | $3.632(-4)$ | $6.578(-3)$ | $2.170(-3)$ |  |
|  | 5.045 | 5.918 | 5.251 | 4.829 | 1.275 | 2.928 |  |
| 80 | $5.849(-7)$ | $4.707(-7)$ | $3.243(-7)$ | $7.852(-6)$ | $3.894(-4)$ | $6.181(-4)$ |  |
|  | 6.001 | 6.071 | 6.314 | 5.532 | 4.079 | 1.812 |  |
| 160 | $9.115(-9)$ | $7.338(-9)$ | $5.012(-9)$ | $1.074(-7)$ | $6.717(-6)$ | $2.090(-7)$ |  |
|  | 6.004 | 6.004 | 6.016 | 6.192 | 5.857 | 5.702 |  |
| 320 | $3.942(-10)$ | $4.295(-10)$ | $3.121(-10)$ | $1.615(-9)$ | $1.123(-7)$ | $3.133(-9)$ |  |
|  | 4.531 | 4.095 | 4.005 | 6.056 | 5.902 | 6.060 |  |

Table 2

| $\varepsilon$ | $2^{-15}$ | $2^{-20}$ | $2^{-25}$ | $2^{-30}$ | $2^{-35}$ | $2^{-40}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\alpha$ | 0.10 | 0.15 | 0.20 | 0.20 | 0.20 | 0.25 |
| $p$ | 2.18 | 2.81 | 4.38 | 7.81 | 11.88 | 16.56 |

## References

[1] I.P. Bogalev, 'An approximate solution of a nonlinear boundary value problem with a small parameter multiplying the highest derivative', U.S.S.R. Comput. Math. and Math. Phys. 24 (1984), 30-35.
[2] E.P. Doolan, J.J.H. Miller and W.H.A. Schilders, Uniform numerical methods for problems with initial and boundary layers (Dublin Boole Press, 1980).
[3] D. Herceg and N. Petrović, 'On numerical solution of a singularly perturbed boundary value problem II', Univ. u Novom Sadu, Zb. Rad. Pirod.-Mat. Fak. Ser. Mat. 17 (1987), 163-186.
[4] D. Herceg, 'Uniform fourth order difference scheme for a singular perturbation problem' (to appear).
[5] D. Herceg, 'On numerical solution of singularly perturbed boundary value problem', in $V$ Conference on Applied Mathematics, ed. Z. Bohte, pp. 59-66 (Uniyersity of Ljubljana, Institute of Mathematics, Physics and Mechanies, Ljubljana, 1986).
[6] R. Vulanoví, 'On a numerical solution of a type of singularly perturbed boundary value problem by using a special discretization mesh', Univ. u Novom Sadu, Zb. Rad. Prirod.-Mat. Fak. Ser. Mat. 13 (1983), 187-201.
[T] R. Vulanović, D. Herceg and N. Petrović, 'On the extrapolation for a singularly perturbed boundary value problem', Computing 36 (1986), 69-79.

Dr D. Herceg
Institute of Mathematics
dr llije Djuričića 4
21000 Novi Sad
Yugoslavia
Mr N. Petrović
Advanced Technical School
Skolska 1
21000 Novi Sad
Yugoslavia

Dr R. Vulanović
Institute of Mathematics
dr Ilije Djuritića 4
21000 Novi Sad
Yugoslavia

