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## Robot Control

The Task Function Approach

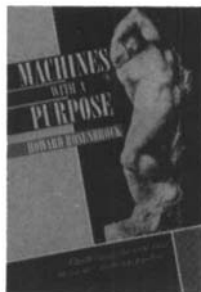
**CLAUDE SAMSON, MICHEL LE BORGNE, and  
BERNARD ESPIAU**

This book examines in depth some theoretical and applied problems in the control of rigid manipulators. Basic mathematical tools are established, and a way of properly expressing a user's goal in terms of robot tasks is given. Of particular interest is the automatic control of robot manipulators, hence particular attention is paid to the problems of stability and robustness.

*Oxford Engineering Science Series No. 22*

0 19 853805 7, 384 pp., illus., Clarendon Press, 1991

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## Machines with a Purpose HOWARD ROSENBROCK

This book shows how, by interpreting nature in terms of purpose rather than cause, man and nature become 'machines with a purpose'—armed with this view it is possible to reject the direction in which technology is taking us, towards environmental damage, without rejecting the technology itself, and its benefits.

0 19 856346 9, 234 pp., illus., October 1990

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## Brushless Servomotors

Fundamentals and Applications

**Edited by YASUHIKO DOTE and SAKAN KINOSHITA**

Rapid progress in the past three decades has made possible the use of brushless servomotors in motion control, providing high productivity and improved product quality. This book is a practical introduction for engineers and students who are not familiar with servomotors and motion control; the control methods described are useful for practising engineers who want to deepen their knowledge of motion control in manufacturing systems.

*Monographs in Electrical and Electronic Engineering No. 23*

0 19 859372 4, 280 pp., illus., November 1990

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## Kinematic Geometry of Mechanisms

**K. H. HUNT**

This paperback version of this classic text relates classical two- and three-dimensional geometry to mechanisms. The emphasis remains geometrical rather than analytical, setting down the principles and conditions with which mechanisms must comply. If anyone still holds that mechanism is an out-moded intuitive art then this book refutes such a view and reveals that kinematic geometry has much to offer today's engineer.

*Oxford Engineering Science Series No. 7*

0 19 856233 0, 484 pp., illus., paperback, Clarendon Press, June 1990

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