THE ANALYTIC CHARACTER OF THE BIRKHOFF INTERPOLATION POLYNOMIALS

G. G. LORENTZ

1. Introduction. Let *E* be an $m \times (n + 1)$ regular interpolation matrix with elements $e_{i,k} = (E)_{i,k}$ which are zero or one, with n + 1 ones. Then for each $f \in C^n[a, b]$ and each set of knots $X: a \leq x_1 < \ldots < x_m \leq b$, there is a unique interpolation polynomial P(f, E, X; t) of degree $\leq n$ which satisfies

(1)
$$P^{(k)}(x_i) = f^{(k)}(x_i), e_{i,k} = 1.$$

A recent paper [1] discussed the continuity of P, as a function of x_1, \ldots, x_m (with coalescences allowed). We would like to study in this note the analytic character of P as a function of real or complex knots $X: x_1, \ldots, x_m$. This is easy for the Lagrange or the Hermite interpolation. In this case P is a polynomial in x_1, \ldots, x_m if f is a polynomial, and an entire function in x_1, \ldots, x_m if f is entire. This follows, for example, from the Hermite formula, which represents P by means of a contour integral. No formula of this type is known to exist in the general case of Birkhoff, non-Hermite interpolation.

We shall assume that the reader is acquainted with the terminology and the fundamental results of Birkhoff interpolation (see [5], [3], [4]).

For a set of functions $G = \{g_0, \ldots, g_n\}$ we have the determinant

$$D(E, X; G) = \det \left[g_0^{(k)}(x_i), \ldots, g_n^{(k)}(x_i); e_{i,k} = 1 \right];$$

its rows are labeled by n + 1 pairs *i*, *k* with $e_{i,k} = 1$, and ordered lexicographically. In particular, for the system

$$G_s = \left\{1, \frac{x}{1!}, \ldots, \frac{x^{s-1}}{(s-1)!}, f, \ldots, \frac{x^n}{n!}\right\}$$

we have the determinant $D_{\varepsilon}(E, X) = D(E, X; G_s)$

$$D_{s}(E,X) = \det \frac{x_{i}^{-k}}{(-k)!}, \dots, \frac{x_{i}^{s-1-k}}{(s-1-k)!}, f^{(k)}(x_{i}), \dots, \frac{x_{i}^{n-k}}{(n-k)!}, e_{i,k} = 1.$$

(terms containing r! with r < 0 are to be replaced by zero). We write D(E, X) for the determinant with $G = \{1, x/1!, \ldots, x^n/n!\}$. The poly-

Received April 28, 1981. This work was partly supported by NSF grant MCS-7904685.

nomial P given by (1) has the representation

(2)
$$P(f, E, X; t) = \frac{1}{D(E, X)} \sum_{s=0}^{n} \pm \frac{t^{s}}{s!} D(E, X; G_{s}).$$

It follows from this that if f is a fixed polynomial (of an arbitrary degree), then P is a rational function of X, and if f is an entire function, then P is meromorphic. We would like to improve these statements. It is essential to assume here that the function f remains fixed. For example, if f is a linear function with values c_1 , c_2 at x_1 , x_2 , then $P = c_1l_1 + c_2l_2$, where l_1 , l_2 are the fundamental Lagrange functions. Here P is only rational, and f depends on x_1 , x_2 . We prove:

THEOREM 1. In order that P should be a polynomial (or an entire function) in X whenever f is a polynomial (or an entire function), it is necessary and sufficient that the canonical decomposition of E should consist only of Hermite and of two-row matrices.

In other words, P has this property if and only if the matrix E is complex regular. This follows from a theorem of Lorentz and Riemenschneider [6], which is a natural generalization of D. Ferguson's theorem [2].

2. Proof of the theorem. The sufficiency of the conditions is easy to establish. From [7] it follows that the determinants D = D(E, X) and $D_s = D(E, X; G_s)$ are divisible by $(x_i - x_j)^{\alpha_{ij}}$, $i, j = 1, \ldots, m, i \neq j$, if α_{ij} is the collision number of rows *i* and *j*. In the case when *f* is entire, the latter statement means that D_s is a product of $(x_i - x_j)^{\alpha_{ij}}$ with an entire function of *X*. The polynomial D(E, X) is divisible by the product

$$\prod = \prod_{1 \leq i < j \leq m} (x_i - x_j)^{\alpha_{ij}}.$$

On the other hand, it is known ([3], [5]) that the degree of D(E, X) in one of the variables x_i is at most δ_i , which is the collision number of row i in E with the rest of the matrix E. Under the assumptions of Theorem 1 (see [6]), $\delta_i = \sum_{j \neq i} \alpha_{ij}$. This shows that $D = \text{Const } \prod$. Therefore, the denominator in (2) cancels out.

The necessity requires a careful treatment of determinants D(E, X; G)and of their derivatives. For the minors of D = D(E, X; G) we use the notation

 $D(E, X; G)_{(i,k),s}.$

This is the signed subdeterminant of D corresponding to its row, labelled (i, k) (with $e_{i,k} = 1$), and the column $s, s = 0, \ldots, n$.

For the derivatives of D we have the following (see [5], [7]). The

simplest formula is

(3a)
$$\frac{d}{dx_i} D(E, X; G) = \sum_{e_i, k=1} U_{i,k} D(E, X; G),$$

where $U_{i,k}$ is the operation of differentiation of the row of D which corresponds to $e_{i,k} = 1$. A *shift* Λ of row i in E moves a one, $e_{i,k} = 1$ of this row to the next position (i, k + 1). This shift is permissible if $e_{i,k+1} = 0$. As a variation of (3a) we have

(3b)
$$\frac{d}{dx_i}D = \sum_{\Lambda} D(\Lambda E, X; G).$$

For higher derivatives we shall use

(4)
$$\frac{d^{\tau}}{dx_i^{\tau}}D = \sum_{\Lambda*} D(\Lambda^*E, X; G),$$

(5)
$$\frac{d^{r+1}D}{dx_i^{r+1}} = \sum_{\Lambda^*} \sum_{(\Lambda^* E)_{i,k=1}} U_{i,k} D(\Lambda^* E, X; G)$$

where Λ^* are *multiple shifts* of row *i* of *G* of order *r*, that is, products of *r* permissible simple shifts. After these preparations we can state and prove

LEMMA 2. Let x_1, \ldots, x_n be fixed. If for each polynomial f, all determinants $D_s = D(E, X; G_s)$ satisfy

(6)
$$\frac{d^r D_s}{dx_1^r} = 0, \quad s = 0, \ldots, n,$$

then

(7)
$$\frac{d^{r+1}}{dx_1^{r+1}}D(E,X) = 0.$$

Proof of lemma. From (6) and (3), expanding the determinants with respect to their column s,

$$0 = \frac{d^{r} D_{s}}{dx_{1}^{r}} = \sum_{\Lambda^{*}} D(\Lambda^{*}E, X; G_{s})$$

= $\sum_{\Lambda^{*}} \sum_{(\Lambda^{*}E)i,k=1} D(\Lambda^{*}E, X; G_{s})_{(i,k),s} f^{(k)}(x_{i})$
= $\sum_{(i,k)} f^{(k)}(x_{i}) \sum_{(\Lambda^{*}E)i,k=1} D(\Lambda^{*}E, X; G_{s})_{(i,k),s}.$

The minor in the last line does not contain f and is identical with $D(\Lambda^*E, X)_{(i,k),s}$. For a polynomial f of sufficiently high degree, the values $f^{(k)}(x_i)$ can be prescribed arbitrarily, hence we get from this

(8)
$$\sum_{(\Lambda^* E)_{i,k=1}} D(\Lambda^* E, X)_{(i,k),s} = 0, \quad i = 1, \ldots, m, k, s = 0, \ldots, n.$$

For the derivative (7), we use (5):

(9)
$$\frac{d^{r+1}D}{dx_1^{r+1}} = \sum_{\Lambda *} \sum_{(\Lambda * E)_{1,s}=1} D(\Lambda_s' \Lambda * E, X).$$

For a fixed s with $(\Lambda^* E)_{1,s} = 1$ and fixed Λ^* , we expand the last determinant with respect to the row which contained the old one, $(\Lambda^* E)_{1,s}$. This gives, with $\beta_k = x_1^{k-s-1}/(k-s-1)!$,

$$D(\Lambda_s'\Lambda^*E,X) = \sum_{k=0}^n \beta_k D(\Lambda^*E,X)_{(1,s),k}.$$

Rearranging the sum (9) we have

$$\frac{d^{r+1}D}{dx_1^{r+1}} = \sum_{s=0}^n \sum_{k=0}^n \beta_k \sum_{\Lambda^*} D(\Lambda^* E, X)_{(1,s),k} = 0$$

by (8). This proves the lemma.

To prove the necessity of the condition of Theorem 1, we assume that it is not satisfied. By the theorem mentioned above, E is complex singular. There exist then distinct complex x_1, \ldots, x_m for which D(E, X) = 0. Let $X^* = (x, x_2, \ldots, x_m)$ with variable x, and let r be the multiplicity of the zero $x = x_1$ of the polynomial $D(x) = : D(E, X^*)$. If one of the determinants $D_s(x) = : D(E, X^*; G_s)$ has a zero $x = x_1$ of order < r for some polynomial f, then it follows from (2) that P is not an entire function. If these zeros are always of order $\ge r$, then by the lemma, $D^{(r+1)}(x_1) = 0$, a contradiction. This completes the proof.

References

- 1. N. Dyn, G. G. Lorentz and S. D. Riemenschneider, *Continuity of the Birkhoff interpolation*, in print in SIAM J. Numer. Analysis.
- D. Ferguson, The question of uniqueness for G. D. Birkhoff interpolation problem, J. Approx. Theory 2 (1969), 1-28.
- 3. G. G. Lorentz, *Birkhoff interpolation problem*, CNA report 103, The University of Texas in Austin (1975).
- 4. Independent sets of knots and singularity of interpolation matrices, J. Approx. Theory 30 (1980), 208–225.
- G. G. Lorentz and S. D. Riemenschneider, Recent progress in Birkhoff interpolation, in: Approximation theory and functional analysis (North-Holland Publ. Co., 1979), 187-236.
- 6. Birkhoff interpolation: Some applications of coalescence, in: Quantitative approximation (Academic Press, New York, 1980), 197-208.
- 7. G. G. Lorentz and K. L. Zeller, Birkhoff interpolation problem: coalescence of rows, Arch. Math. 26 (1975), 189-192.

The University of Texas at Austin, Austin, Texas